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Contract-Based Verification of MILS-AADL Models

Stefano Tonetta
FBK-irst
tonettas@fbk.eu

D-MILS Project

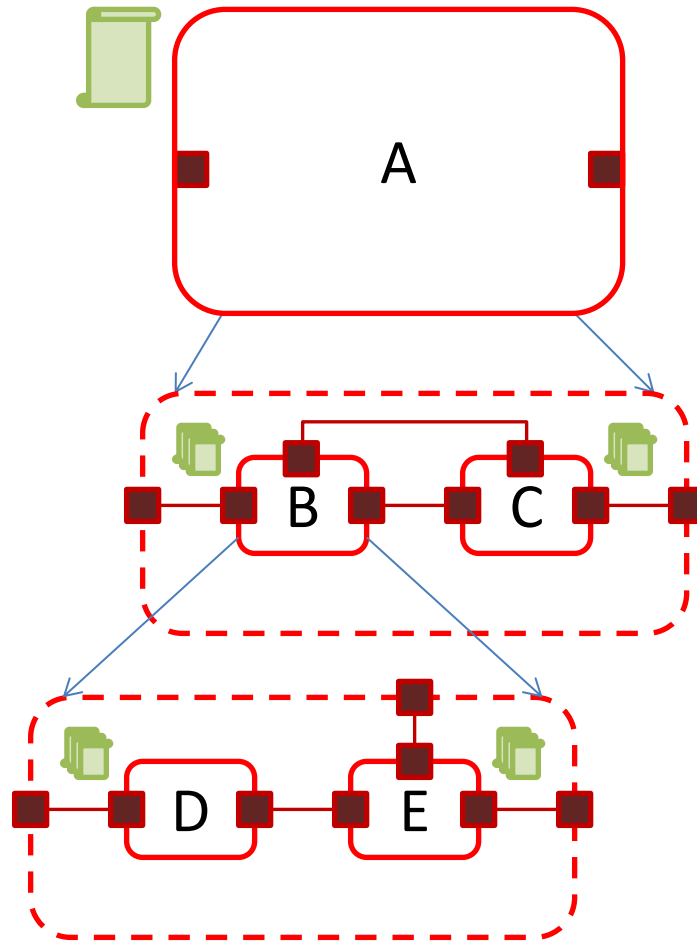
- Research based on the MILS approach
 - ◆ Component-based approach for the construction, assurance, and certification of critical systems
 - ◆ Two-phase design process
 1. **Architecture**-based design of the information flow policy
 2. **Implementation** based on a platform composed of MILS foundational components
- D-MILS focused on:
 - ◆ Extending the technology to distributed systems
 - ◆ Providing an end-to-end support to
 - Design and verification
 - Deployment
 - Assurance case
- FP7 project
- Nov. 2012-Oct. 2015
- Partners (underlined ones are present today):
 - ◆ The Open Group (UK) **Lead**
 - ◆ Fondazione Bruno Kessler (IT)
 - ◆ fortiss (DE)
 - ◆ Frequentis (AT)
 - ◆ LinuxWorks (FR)
 - ◆ RWTH Aachen University (DE)
 - ◆ TTTech (AT)
 - ◆ Université Joseph Fourier (FR)
 - ◆ University of York (UK)

**FIRST USAGE OF
COMPASS IN A NON-ESA
PROJECT**

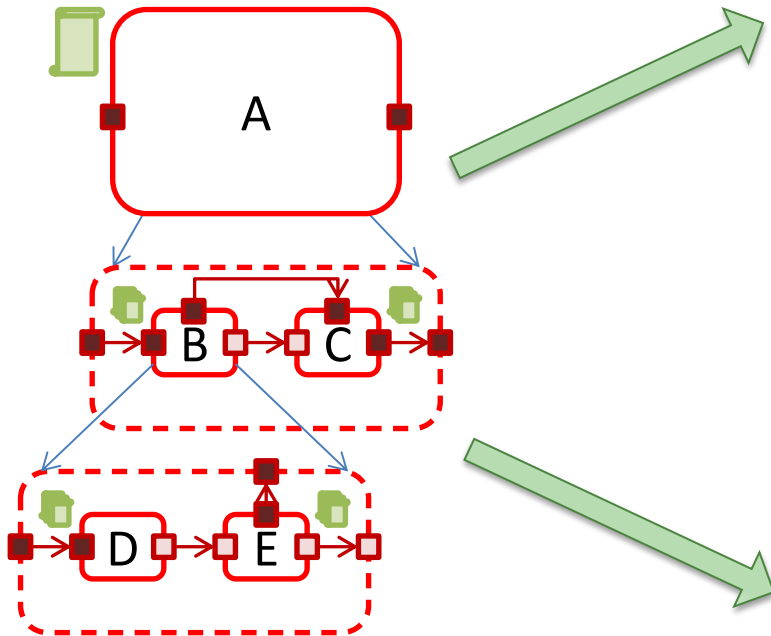
Verification goals

- Compositional verification
 - ◆ Prove that global properties are correctly refined by local properties
 - ◆ Efficient reasoning
 - ◆ Delegate proof of application components to the provider
 - ◆ Focus on the verification of the architecture
 - ◆ Formalize assumptions of system and components
- Cover different types of requirements:
 - ◆ Functional
 - ◆ Real-time
 - ◆ Safety
 - ◆ Security
- Efficient verification, effectively mixing
 - ◆ SMT-based symbolic model checking
 - ◆ Inductive reasoning
 - ◆ Automated abstraction refinement

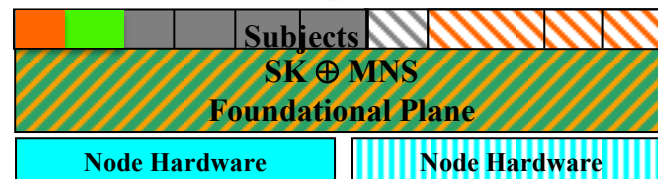
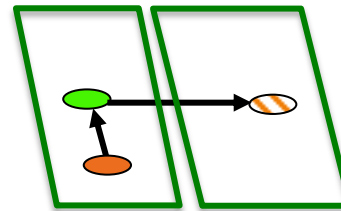
Contract-Based Design



MILS and CBD



$$\frac{\frac{D \models P_D, E \models P_E}{\gamma_B(D, E) \models \gamma_B(P_D, P_E)} \quad \gamma_B(P_D, P_E) \models P_B \quad C \models P_C}{\frac{B \models P_B}{\gamma_A(B, C) \models \gamma_A(P_B, P_C)} \quad \gamma_A(P_1, P_2) \models P} A \models P$$



AADL annotated with OCRA contracts

system Sys

features

cmd: in event data port int;

switch_to_high: in event port;

switch_to_low: in event port;

return: out event data port int;

outL: out data port int;

{ OCRA: CONTRACT secure

assume: always (

 ({cmd} implies then ({return} releases (not ({cmd or switch_to_high or switch_to_low}))))

 and (((not {switch_to_high}) since {switch_to_low}) implies (not {is_high(last_data(cmd))}))

 and ({is_high(0)} = false));

guarantee: always (({is_high(outL)}=false));

}

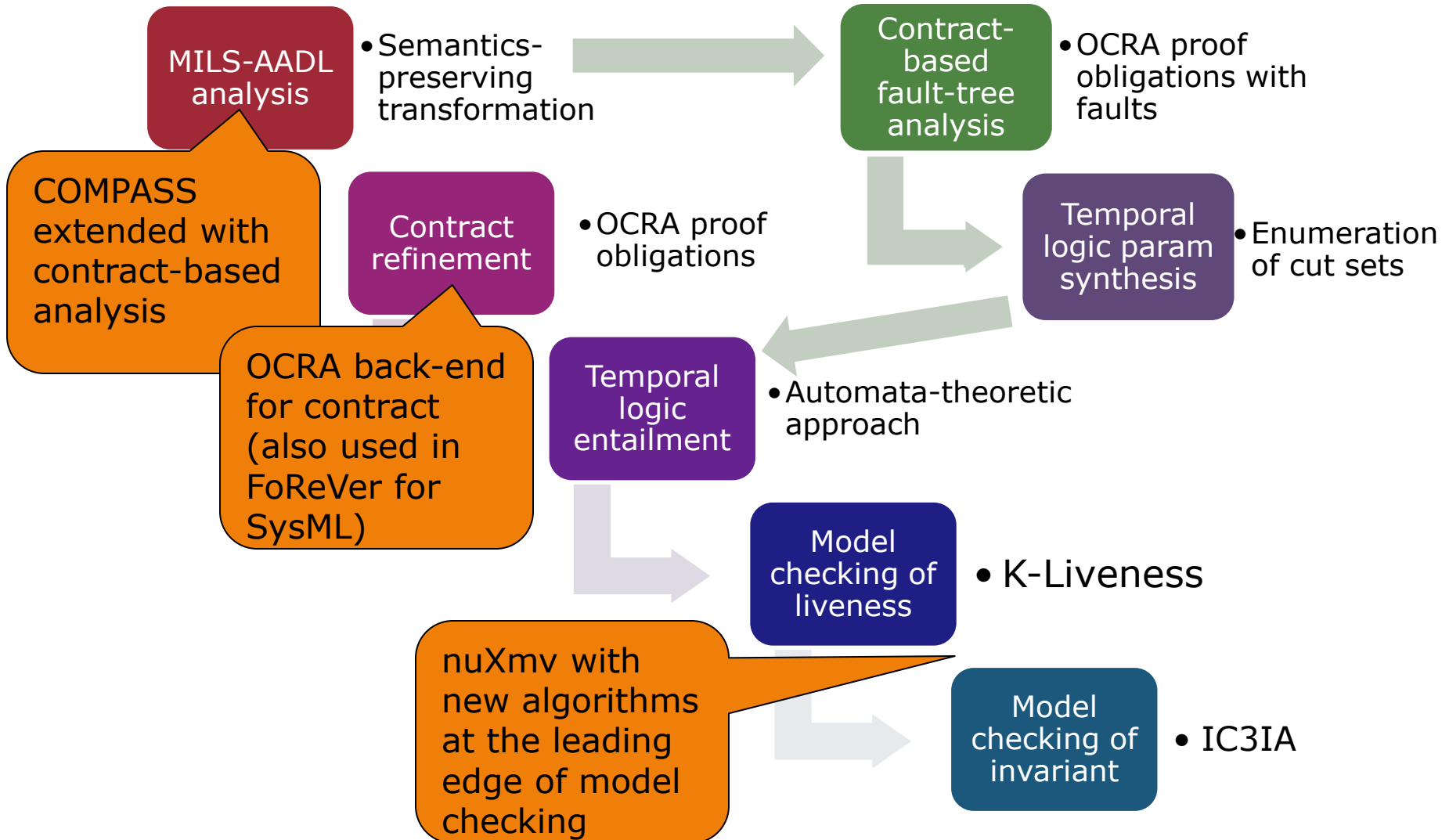
Property Specification Language

- LTL
 - ◆ **always** (**p** implies in the future **q**)
- First-order
 - ◆ **always** (**high**(**value**) iff **high**(**cmd**)) **implies**
never (**high**(**output**))
- Real-time
 - ◆ **always** (**corrupted**(**memory**) **implies**
time_until(**alarm**)<=**time_bound**)

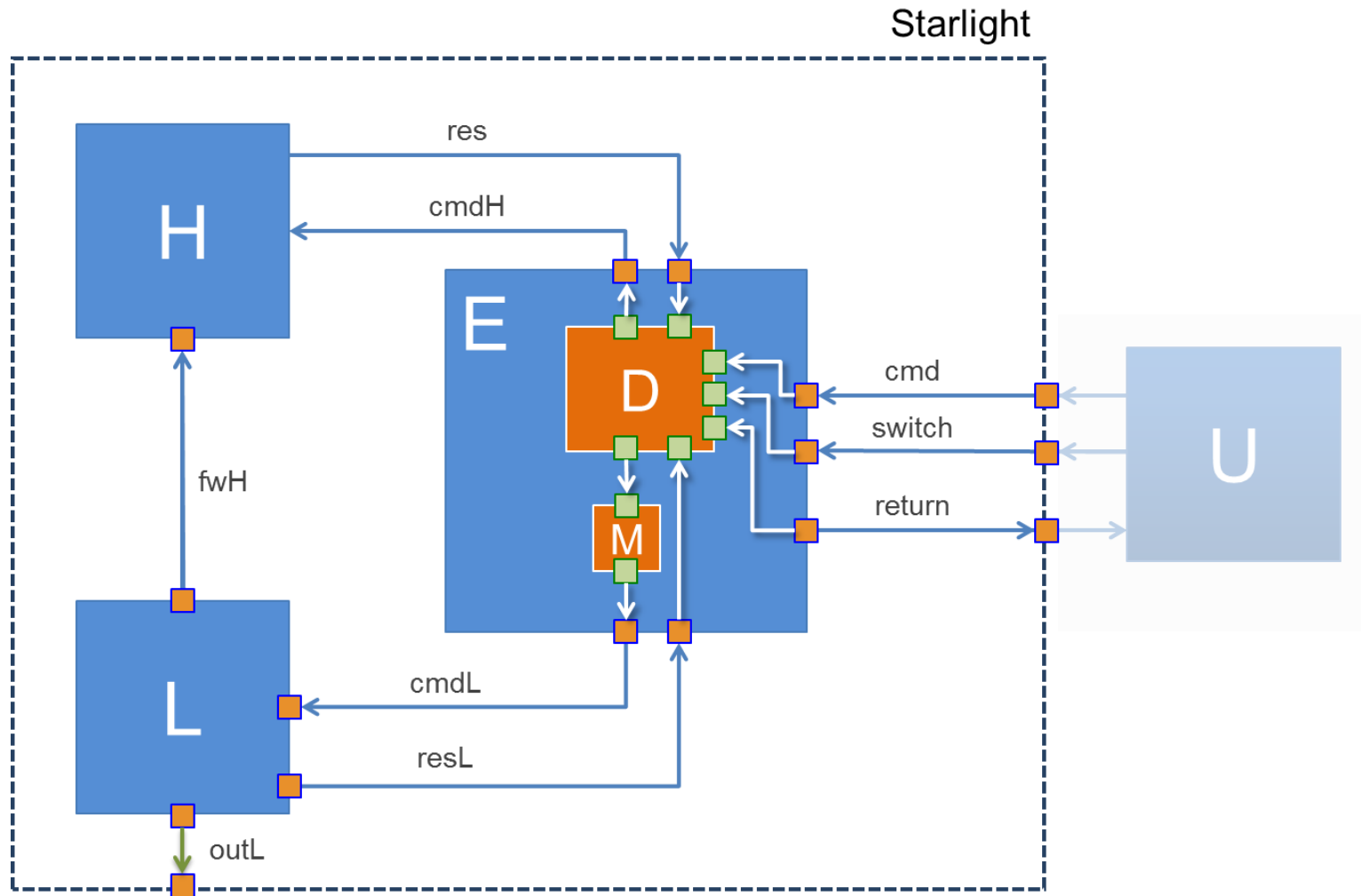
Verification Framework

- The framework consists of a collection of tools
 - ◆ COMPASS (baseline developed in ESA projects) as front-end for MILS-AADL models
 - ◆ OCRA for contract-based
 - ◆ nuXmv for model checking
 - ◆ xSAP for safety analysis (e.g. FTA)
 - ◆ secureBIP for transitive non-interference
 - ◆ RT-DFinder for invariant and deadlock checking
- Validation with
 - ◆ Simulation
 - ◆ Deadlock checking
 - ◆ Timelock checking
 - ◆ Reachability and other queries in temporal logic
- Verification of
 - ◆ Functional requirements
 - ◆ Real-time requirements
 - ◆ Security requirements
 - ◆ Safety requirements

Analysis Tool Chain



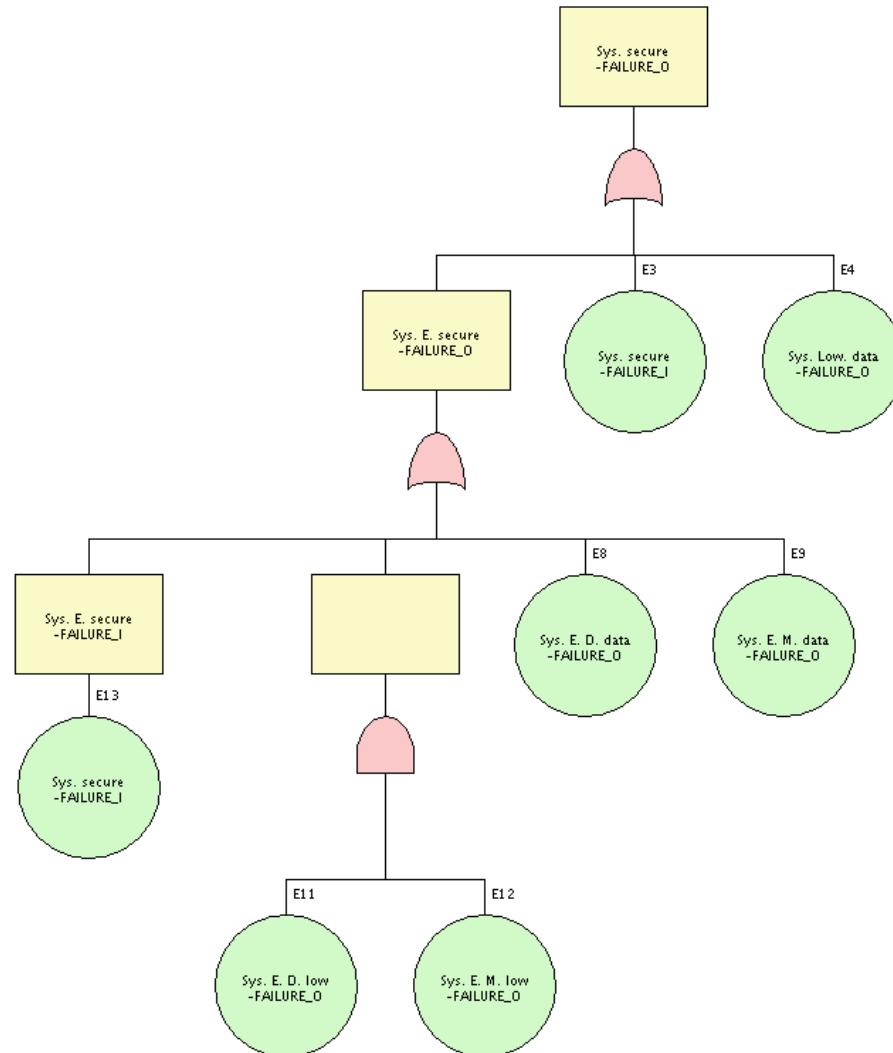
Starlight Architecture



Starlight reqs formalization

- Req-Sys-secure: No high-level data shall be sent by L to the external world.
 - ◆ Formal-Sys-secure: never $\text{is_high}(\text{last_data}(\text{outL}))$
- Req-User-secure: The user shall switch the dispatcher to high before entering high-level data.
 - ◆ Formal-User-secure: always $((\text{is_high}(\text{last_data}(\text{cmd}))) \text{ implies } ((\text{not } \text{switch_to_low}) \text{ since } \text{switch_to_high}))$
- Proved system guarantess Formal-Sys-secure assuming Formal-User-secure.
- Req-Sys-safe: No single failure shall cause a loss of Req-Sys-secure.

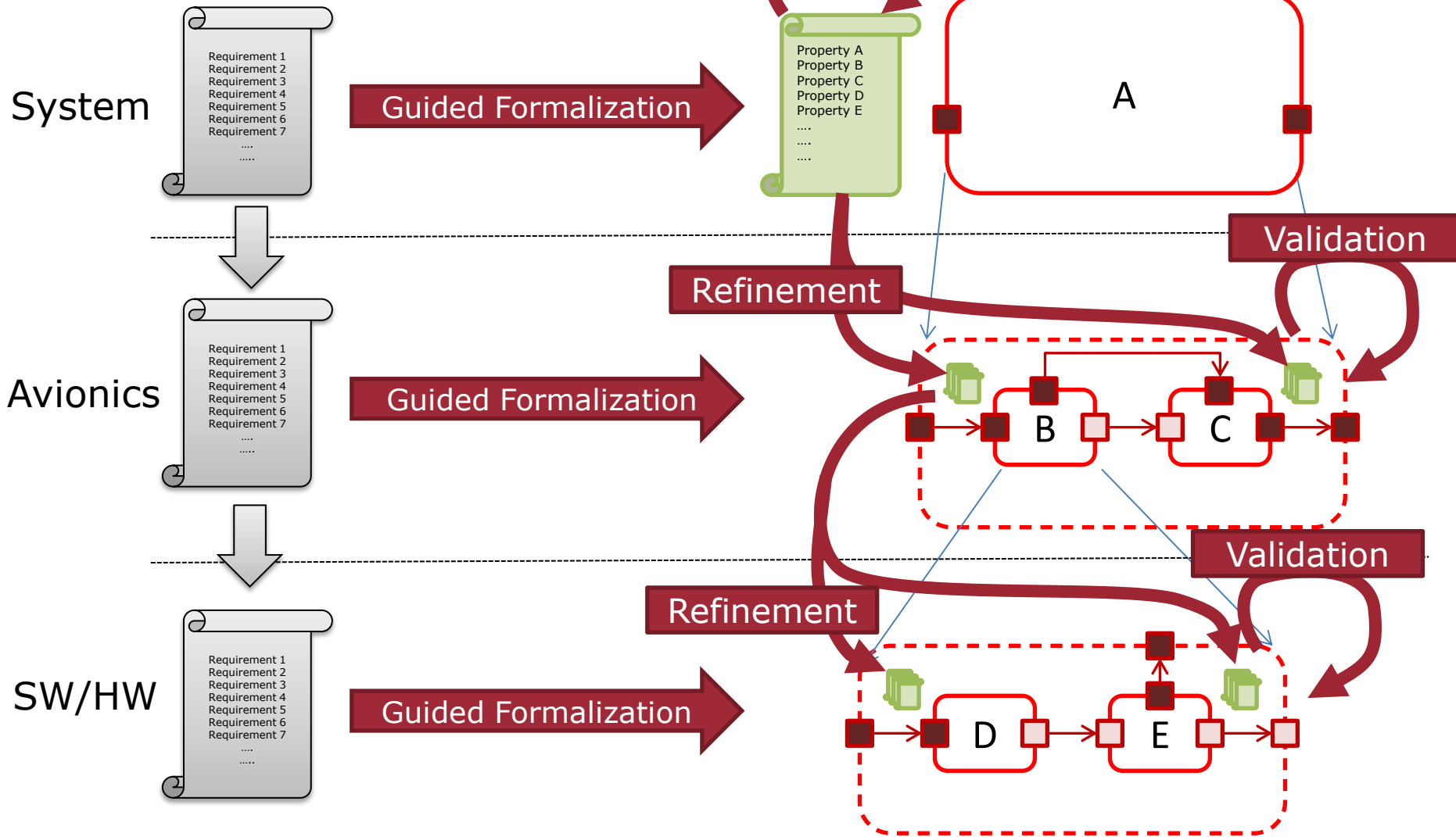
Starlight fault tree for secure req



Conclusions

- COMPASS used in a non-ESA project
- MILS-AADL (a variant of SLIM) models annotated with OCRA contracts
- Efficient analysis tool chain for scalable verification on very expressive logic
- Verification applied to both safety and security requirements.

Next in CATSY



Next in CATSY

- Guided formalization based on CSSP
 - ◆ Taxonomy of requirements and
 - ◆ Formal property patterns
 - ◆ Specific patterns for low-level properties (deadline, monitoring frequency, threshold, ...)
- Validation of the formalization with
 - ◆ Queries to test the formalization
 - ◆ Traces to show possible executions
 - ◆ Explanation/debugging of the refinement
- Language tailored to property and contract specification
 - ◆ Abstract components
 - No required implementation
 - No required hw bindings
 - ◆ Mode transitions only for component configuration (behaviors only in the leaf components)
 - ◆ Simpler semantics of interaction
- Paving the way to higher TRL
 - ◆ New code repository management
 - ◆ Improve testing framework