- ICATT 2016 - Student Session -Dynamics in the center manifold around equilibrium points in Periodically Perturbed Three-Body Problems

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March 15<sup>th</sup>, 2016



## Overview



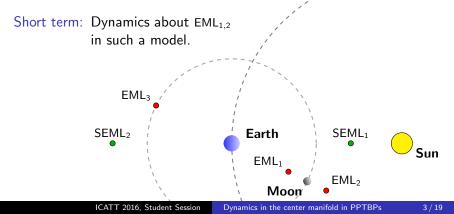
Introduction: the Sun-Earth-Moon system

- 2 The Quasi-Bicircular Problem (QBCP)
- 3 The Parameterization Method in the QCBP
- 4 The neighborhood of Earth-Moon L<sub>1,2</sub>

Objectives A hierarchy of models A variety of methods

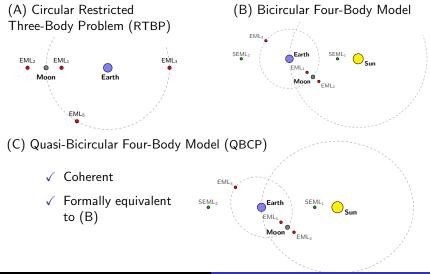
#### Framework and objectives

Long term: Near-systematic tool for the motion about & between the libration points of the **Sun-perturbed Earth-Moon** system.



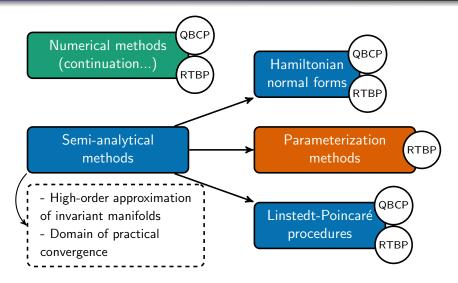
Objectives A hierarchy of models A variety of methods

# A hierarchy of models



Objectives A hierarchy of models A variety of methods

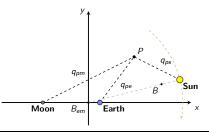
### A variety of methods in the literature



# The Quasi-Bicircular Problem (QBCP)

Periodic Hamiltonian in the Earth-Moon synodical frame

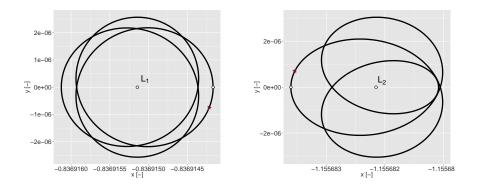
$$H(\mathbf{z},\theta) = \frac{1}{2}\alpha_1(p_x^2 + p_y^2 + p_z^2) + \alpha_2(p_x x + p_y y + p_z z) + \alpha_3(p_x y - p_y x) + \alpha_4 x + \alpha_5 y - \alpha_6 \left(\frac{1-\mu}{q_{pe}} + \frac{\mu}{q_{pm}} + \frac{m_s}{q_{ps}}\right)$$



- $\mu$  the Earth-Moon mass ratio
- *m<sub>s</sub>* the mass of the Sun
- $\alpha_k$  trigonometric functions in the variable  $\theta = \omega_s t$
- $\omega_s$  the pulsation of the Sun.

Earth-Moon  $L_{1,2}$  in the QBCP

 $2\pi$ -periodic dynamical equivalents of the Earth-Moon libration points  $L_{1,2}$ , in Earth-Moon coordinates.



Overview

Suitable form for the linearized motion Overall procedure for the center manifold Solving the invariance equation



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First step: getting an autonomous diagonal order one

•  $\exists$  2 $\pi$ -periodic symplectic change of coordinates of the form:

 $\mathbf{z} = P(\theta)\hat{\mathbf{z}} + V(\theta)$ 

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 $\mathbf{z} = P(\theta)\hat{\mathbf{z}} + V(\theta)$ 

In the new coordinates  $\hat{\mathbf{z}} = (\hat{x}_1 \ \hat{x}_2 \ \hat{x}_3 \ \hat{y}_1 \ \hat{y}_2 \ \hat{y}_3)'$ 

• Hamiltonian:

$$\hat{H}(\hat{\mathbf{z}},\theta) = \omega_1 \mathbf{i} \hat{x}_1 \hat{y}_1 + \omega_2 \hat{x}_2 \hat{y}_2 + \omega_3 \mathbf{i} \hat{x}_3 \hat{y}_3 + \sum_{k \ge 3} \hat{H}_k(\hat{\mathbf{z}},\theta)$$

• The origin becomes a fixed point.

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First step: getting an autonomous diagonal order one

•  $\exists$  2 $\pi$ -periodic symplectic change of coordinates of the form:

 $\mathbf{z} = P(\theta)\hat{\mathbf{z}} + V(\theta)$  Precision bottleneck

In the new coordinates  $\hat{\mathbf{z}} = (\hat{x}_1 \ \hat{x}_2 \ \hat{x}_3 \ \hat{y}_1 \ \hat{y}_2 \ \hat{y}_3)^T$ 

• Hamiltonian:

$$\hat{H}(\hat{\mathbf{z}},\theta) = \omega_1 \mathbf{i} \hat{x}_1 \hat{y}_1 + \omega_2 \hat{x}_2 \hat{y}_2 + \omega_3 \mathbf{i} \hat{x}_3 \hat{y}_3 + \sum_{k \ge 3} \hat{H}_k(\hat{\mathbf{z}},\theta)$$

• The origin becomes a fixed point.

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### Parameterization of the center manifold (1)

- Linearized vector field:  $D\hat{F}(0) = \text{diag}(i\omega_1, \omega_2, i\omega_3, -i\omega_1, -\omega_2, -i\omega_3).$
- Isolating the center part:

$$L = \begin{pmatrix} i\omega_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & i\omega_3 & 0 & 0 \\ 0 & 0 & -i\omega_1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -i\omega_3 \end{pmatrix}$$

L spans the 4-dimensional subspace  $V^L \subset \mathbb{C}^6$  tangent to the center manifold  $\mathcal{W}_c$  about the origin.

• Goal: compute

$$egin{array}{rcl} \hat{\mathcal{W}} & : & \mathbb{C}^4 imes \mathbb{R} & o & \mathbb{C}^6 \ (\mathbf{s}, heta) & \mapsto & \hat{\mathcal{W}}(\mathbf{s}, heta) \end{array}$$

**High-order parameterization** of  $\mathcal{W}_c$ , starting with  $\hat{\mathcal{W}}_0(\mathbf{s}, \theta) = 0$ ,  $\hat{\mathcal{W}}_1(\mathbf{s}, \theta) = L\mathbf{s}$ .

Suitable form for the linearized motion Overall procedure for the center manifold Solving the invariance equation

## Parameterization of the center manifold (2)

• Parameterization form: Fourier-Taylor (FT) series.

$$\hat{W}^1(\mathbf{s},\theta) = \sum_{k \ge 1} \hat{W}^1_k(\mathbf{s},\theta) = \sum_{k \ge 1} \sum_{r_1 + \dots + r_4 = k} \underbrace{w^1_r(\theta)}_{\text{Fourier series}} s_1^{r_1} \dots s_4^{r_4}$$

• Dynamics on the manifold:  $\dot{\mathbf{s}} = f(\mathbf{s}, \theta), f(0) = 0.$ 

#### Parameterization method: an iterative procedure

•  $(\hat{W}, f)$  satisfy the invariance equation:

$$\hat{F}(\hat{W}(\mathbf{s},\theta),\theta) = D_{\mathbf{s}}\hat{W}(\mathbf{s},\theta)f(\mathbf{s},\theta) + \frac{\partial\hat{W}}{\partial t}(\mathbf{s},\theta)$$
(1)

• At order k: substitute  $(\hat{W}_{k-1}, f_{k-1})$  in (1) and find the k-homogeneous terms that solve  $(1)_k$ .

Suitable form for the linearized motion Overall procedure for the center manifold Solving the invariance equation

# Solving the invariance equation

Computing  $(\hat{W}_k, f_k)$  in different *styles* (Haro, 2008):

**Graph style:**  $\hat{W}_k$  as simple as possible.

- ✓ Limit the number of small divisors.
- ✓ Easy projection  $\mathbf{s} = \hat{W}_k^{-1}(\hat{\mathbf{z}})$ .
- **X**  $f(\mathbf{s}, \theta)$  is a full Fourier-Taylor series.

**Normal form style:**  $f_k$  as simple as possible.

- ✓ Possible autonomous f up to a medium order.
- ✗ Numerous small divisors ⇒ divergence rate increased.

Poincaré maps EML<sub>1</sub> case EML<sub>2</sub> case

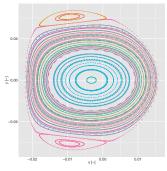
# Overview

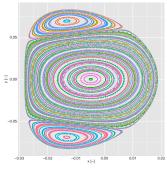
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# Poincaré maps: basic principle (autonomous case)

- Intersection with a lower-dimensional subspace: z = 0,  $p_z > 0$ .
- In practice: z(t) is regularly projected on the center manifold.
- In the autonomous case: energy slices.  $\delta H_0 = H(\mathbf{z}) H(L_1) = cst$



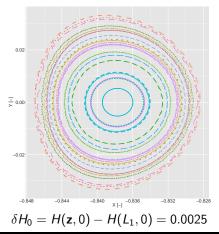


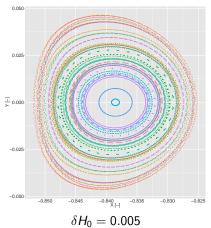
CRTBP, EML<sub>1</sub>,  $\delta H_0 = 0.01$ 

Poincaré maps EML<sub>1</sub> case EML<sub>2</sub> case

#### QBCP $EML_1$ case

- Graph style is used.
- Energy no longer constant but bounded.

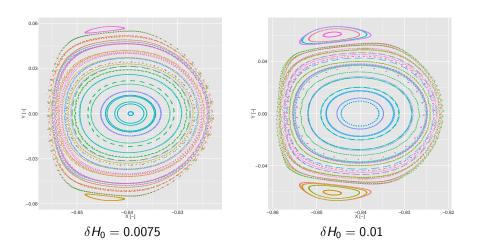




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Poincaré maps EML<sub>1</sub> case EML<sub>2</sub> case

#### QBCP $EML_1$ case



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Poincaré maps EML<sub>1</sub> case EML<sub>2</sub> case

#### QBCP EML<sub>2</sub> case

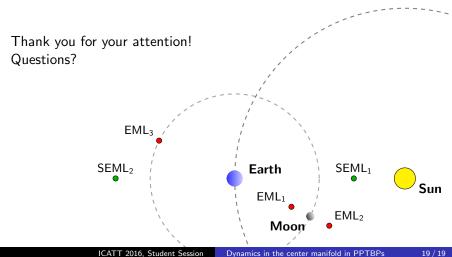
- Low energy: easily obtained up to  $\delta H_0 \sim 0.008$ .
- Higher energy: apparent precision decay. Who is to blame?
  More
  - Low-order resonances. more
  - Inherent properties.

# Conclusion

Poincaré maps EML<sub>1</sub> case EML<sub>2</sub> case

- Example of parameterization of invariant manifolds in the Sun-Earth-Moon system.
  - Flexibility of the method (*styles*).
  - Work in lower dimension (4) than usual normal form procedures (6).
  - Numerically challenging in the non-autonomous case.
- Compact tool for the description of the neighborhood of EML<sub>2</sub> and extended neighborhood of EML<sub>1</sub>.
- Works very well in the SEML case (smaller perturbation).

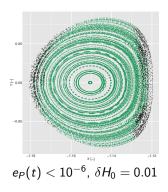
## Questions

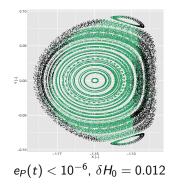


EML<sub>2</sub> case

#### QBCP EML<sub>2</sub> case

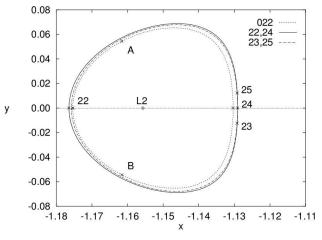
- Low energy: easily obtained up to  $\delta H_0 \sim 0.008$ .
- Higher energy: apparent precision decay  $(e_P(t) = |\mathbf{z}(t) \mathbf{z}_P(t)|).$





 $\begin{tabular}{l} \mathsf{EML}_2 & \mathsf{case} \\ \end{tabular} \end{tabular} Low-order \ resonances \end{tabular}$ 

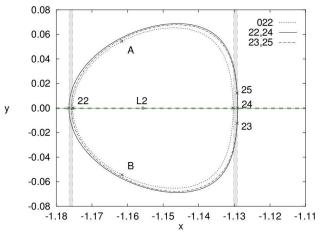
#### Resonances about EML<sub>2</sub> in the QBCP



 $2\omega_s$ -resonant orbits around EML<sub>2</sub>. From Andreu, 1998.

 $\begin{tabular}{l} \mathsf{EML}_2 & \mathsf{case} \\ \end{tabular} \end{tabular} Low-order \ resonances \end{tabular}$ 

#### Resonances about $EML_2$ in the QBCP

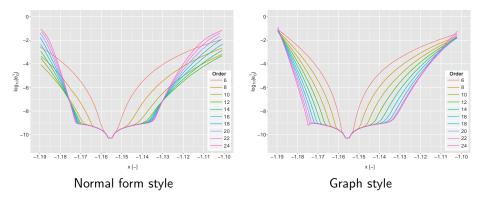


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 $\begin{tabular}{l} \mathsf{EML}_2 & \mathsf{case} \\ \end{tabular} \end{tabular} Low-order \ resonances \end{tabular}$ 

### Accuracy about EML<sub>2</sub> in the QBCP

• Orbital error:  $e_O(t, \mathbf{s}_0) = |W(\mathbf{s}(t)) - \mathbf{z}(t)|_{\infty}$ .



• There is no miracle!