

#### Assessing Orbit Determination Requirement With Unscented Transformation: Case Study Of A Lunar CubeSat Mission

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## **Outline**

- Motivation
  - Effect of OD error on delta-V budget of a Lunar CubeSat Mission

#### Methods

- Monte Carlo
- Linear Covariance
- Unscented Transformation
- Simulation and Results



## **CubeQuest Challenge**

- One of NASA's Centennial Challenges
- Winning 6U CubeSats in the competition are offered a launch on the Exploration Mission (EM) 1 mission as secondary payloads



- All such CubeSats will be disposed into a high-energy trajectory that will fly by the Moon
- Most CubeSate will use some form of a low-thrust propulsion system to achieve lunar orbit
- In order to determine the OD strategy for such a mission, the OD accuracy requirement needs to be understood



## **Nominal Lunar Transfer Trajectory**

To Sun Earth L1 Burns 2	Sun-Earth L1 Burns 2					
		<b>Delta-V</b>	Duration			
	Maneuver Name	(m/s)	(days)			
	Pre-Flyby	14.2	2.3			
	Sun-Earth L1	215.9	35.0			
	Lunar Distant Retrograde Orbit (DRO)	43.2	7.0			



# Maneuver Change from OD Error

 There are many sources contributing to changes in the nominal maneuver



 In this paper, we focus on the OD error contribution to the maneuver change

 $\partial (\Delta V)_{OD Error}$  = Planned Maneuver – Nominal Maneuver



#### **Maneuver Function**

 Nonlinear function utilizing NASA GSFC's open source General Mission Analysis Tool (GMAT)



Goal is to determine the maneuver variation due to OD state estimate uncertainty

$$P_{uu} = E\left[(u - \overline{u})(u - \overline{u})^T\right]$$



## Monte Carlo (MC) Method

- Considered most accurate if large number of cases are simulated
- Perform N cases of OD simulation
- Compute the *i*-th maneuver corresponding to each OD solution
- Compute the covariance of the resulting N planned maneuvers

$$\overline{u}(i) = \frac{\sum_{j=1}^{N} u_j(i)}{N}$$
$$\frac{\sum_{j=1}^{N} (u(i) - \overline{u}(i))(u(i) - \overline{u}(i))^T}{N}$$
$$P_{uu}(i) = \frac{N}{N}$$



# Linear Covariance (LC) Method

 Linear transformation of the state estimate uncertainty into the variation in the *i*-th maneuver

$$P_{xx} \to P_{uu}(i)$$

 Requires computing the sensitivity matrix (Jacobian) of the maneuver relative to the OD state estimate

$$P_{uu}(i) = \frac{\partial(u_i)}{\partial(\hat{x})} P_{xx} \left(\frac{\partial(u_i)}{\partial(\hat{x})}\right)^T$$

The maneuver function "Black Box" is highly nonlinear with no analytic expression so numerical difference:

$$\frac{\partial(u_i)}{\partial(\hat{x})}(:,j) \cong \frac{u(i,j) - u(i)_{NOM}}{\hat{x}_j - \hat{x}_{j_{NOM}}}$$



## **Unscented Transformation (UT)**

 2L+1 sigma points are generated that statistically represent the OD estimates, where L is the number of states

$$\chi = \begin{bmatrix} \overline{x} & \overline{x} \pm \left( \sqrt{(L+\lambda)P_j} \right) \end{bmatrix} \text{ for } j = \{1, \dots, L\}$$
$$\lambda = \alpha^2 (L+\kappa) - L$$





#### **UT Maneuver Variation**

 Weights associated with the OD estimate sigma points are applied to the maneuver sigma points to form the maneuver variation

$$W_0^m = \frac{\lambda}{L+\lambda} \qquad W_0^c = \frac{\lambda}{L+\lambda} + (1-\alpha^2 + \beta) \qquad W_k^m = W_k^c = \frac{1}{2(L+\lambda)}$$

$$\overline{u}_i = \sum_{k=0}^{2L} W_k^m u_{i,k}$$
$$(P_{uu})_i = \sum_{k=0}^{2L} W_k^c \left( u_{i,k} - \overline{u}_i \right) \left( u_{i,k} - \overline{u}_i \right)^T$$



# **Pre-Flyby Orbit Determination Setup**



- 5 US ground stations
- One-way range rate measurements 15 mm/s (1 $\sigma$ )
- Range rate bias 1 km/s
- 11 hours of tracking @ 1 minute intervals
- Extended Kalman Filter solve for position, velocity, range rate bias
  - NASA GSFC's OD Tool Box (estseq function)



#### **10-Case Monte Carlo Simulation**



Actual errors e
Ensemble mean of e
Ensemble 1- to 3-std of e wrt ensemble mean



**ICATT 2016** 

0.6

#### **OD Estimate**

 Formal covariance matrix obtained from the Pre-Flyby OD

	0.4	.07	0.6	$9 \times 10^{-6}$	$3 \times 10^{-6}$	$7 \times 10^{-6}$
		0.2	-1	$-3 \times 10^{-6}$	$7 \times 10^{-6}$	$-1 \times 10^{-5}$
$P_{(1)} =$			20	$1 \times 10^{-4}$	$-4 \times 10^{-5}$	$2 \times 10^{-4}$
$I_{xx}(1) -$				$6 \times 10^{-10}$	$-1 \times 10^{-10}$	$9 \times 10^{-10}$
	•				$2 \times 10^{-10}$	$-3 \times 10^{-10}$
		•			2~10	$2 \times 10^{-9}$

• 1- $\sigma$  uncertainties

 $\delta x = [0.63 \quad 0.49 \quad 4.9]$  km  $\delta v = [25 \quad 15 \quad 47]$  mm/s



#### **Position Sigma Points & OD Estimates**



#### **Velocity Sigma Points & OD Estimates**



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## **Simulation Results**

#### Effects of Pre-Flyby OD Uncertainties on the Transfer Maneuvers

**Pre-Flyby Maneuver Variations (m/s)** 

Sun-Earth L1 Maneuver Variations (m/s)

Method	$\delta(\Delta V x)$	δ(ΔVy)	$\delta(\Delta Vz)$	$ \delta\Delta \mathbf{V} $	Method	$\delta(\Delta V x)$	δ(ΔVy)	$\delta(\Delta Vz)$	$ \delta\Delta \mathbf{V} $
MC	0.74	0.04	0.18	0.76	MC	0.36	0.94	0.68	1.22
LC	0.66	0.05	0.17	0.68	LC	0.32	0.85	0.62	1.10
UT	0.73	0.08	0.17	0.75	UT	0.36	0.93	0.68	1.21

- If there is room in the ∆V budget, a lower OD accuracy may be acceptable with a possibility of relaxing the tracking schedule or the number of ground stations to reduce operational cost
- NOTE: A similar analysis should be performed for OD done before the other transfer maneuvers



## **Conclusions**

- Three methods of determining the impact of OD accuracy on the delta-V were presented
- The Unscented Transformation method was shown to match the (10-case) Monte Carlo method better than the Linear Covariance method by about 10%
- The Unscented Transformation is an alternative to the Monte Carlo method for assessing OD requirements for a space mission
  - A larger number of Monte Carlo cases are required to really prove this out

#### Thank you!

