

# CAMELOT

## Computational-Analytical Multi-fidelity Low-thrust Optimisation Toolbox

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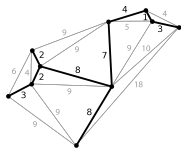
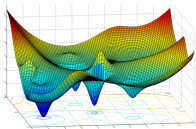
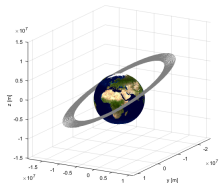
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6th International Conference on Astrodynamics Tools and Techniques  
Darmstadt, 14-17 March 2016

# Computational-Analytical Multi-fidelity Low-thrust Optimisation Toolbox (CAMELOT)

Preliminary design and optimisation of multiple-target low-thrust missions.

- ▶ **FABLE:** Fast Analytical Boundary-value Low-thrust Estimator
- ▶ **MP-AIDEA:** Multi-Population Adaptive Inflationary Differential Evolution Algorithm
- ▶ **AIDMAP:** Automatic Incremental Decision Making And Planning algorithm



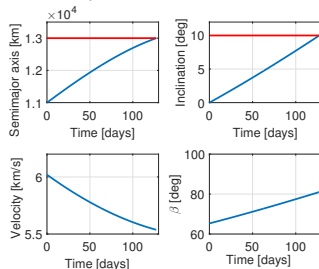
## FABLE

Cost estimation of low-thrust orbital transfer using **multi-fidelity** analytical approach and **surrogate** models.

- **Low-fidelity** fast analytical estimation of low-thrust transfer cost.  
Analytical low-thrust control law:

Transfer type	Reference
$a_0 \rightarrow a_f$	Ruggiero et al. (2011)
$(a_0, i_0) \rightarrow (a_f, i_f), e = 0$	Edelbaum (1961)
$(a_0, i_0) \rightarrow (a_f, i_f), e = 0, a < \bar{a}$	Kechichian (2010)
$(a_0, \Omega_0) \rightarrow (a_f, \Omega_f), e = 0$	Kechichian (2010)
$(a_0, e_0, \omega_0) \rightarrow (a_f, e_f, \omega_f)$	da Silva et al. (2015)
$a_0 \rightarrow a_f, e_0 = e_f$	Burt (1967)
$e_0 \rightarrow e_f$	Ruggiero et. al. (2011)
$e_0 \rightarrow e_f, a_f = a_0$	Burt (1967)
$(e_0, i_0) \rightarrow (e_f, i_f), a_f = a_0$	Pollard (2000)
$i_0 \rightarrow i_f$	Ruggiero et al. (2011)
$\omega_0 \rightarrow \omega_f$	Ruggiero et al. (2011)
	Pollard (2000)
	Petropoulos (2003)
$\Omega_0 \rightarrow \Omega_f$	Ruggiero et al. (2011)

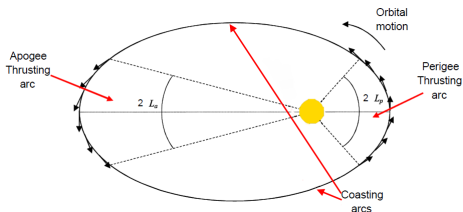
Change of semimajor axis and inclination of circular orbit (Edelbaum):



# FABLE

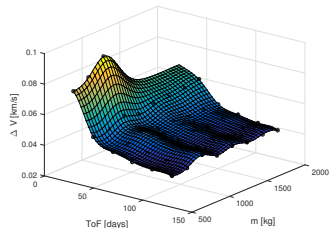
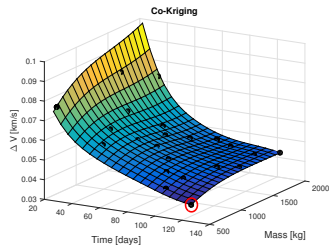
► **Higher-fidelity analytical model:**

- **Osculating analytical propagator** based on analytical formulas for the perturbed Keplerian motion (first order expansion in the perturbing acceleration):
  - . low-thrust acceleration
  - .  $J_2$  zonal harmonic
  - . atmospheric drag
  - . solar radiation pressure (eclipses)
- **Averaged analytical propagator**
- Different control parametrisation can be implemented



# FABLE

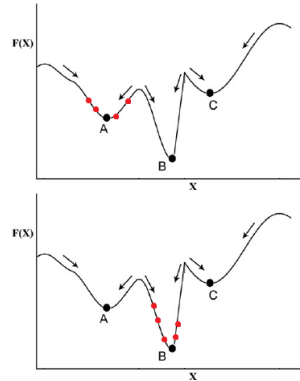
- ▶ Use of **surrogate models** to model the cost of the transfer to allow for fast evaluation of complex trajectories
- ▶ Surrogate models:
  - **Kriging**
  - **Co-Kriging** (few samples from higher-fidelity model, many samples from low-fidelity model)
  - **Tchebycheff** sparse grid
- ▶ Multi-fidelity optimisation: maximisation of **expected improvement** associated to Co-Kriging
  - Maximisation of expected improvement: point where the likelihood of achieving an improvement is maximised



# MP-AIDEA

**Multi population** single objective adaptive global optimiser based on the combination of **Differential Evolution** with **Monotonic Basin Hopping**

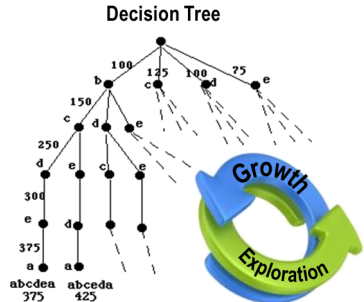
- ▶ Automatic adaptation of the parameters of Differential Evolution and Monotonic Basin Hopping
- ▶ **Local search** after Differential Evolution
- ▶ **Local restart**: transition from one local minimum to another
- ▶ Strategy to avoid multiple detection of the same local minima
  - ▶ Basin of attraction
  - ▶ **Global restart**



# AIDMAP

Single objective **incremental decision making algorithm** for the solution of complex **combinatorial optimisation problems** such as tasks planning and scheduling.

- ▶ AIDMAP decision making map based on **tree-like** topology:
  - Nodes: decisions made
  - Edges: cost associated to decision
- ▶ Tree built **incrementally with time** through **exploration** and **growth** by virtual agents
- ▶ Possible heuristics:
  - **Deterministic**: Branch-and-Cut algorithm
  - **Probabilistic**: bio-inspired Physarum algorithm



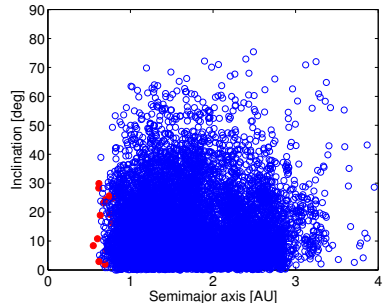
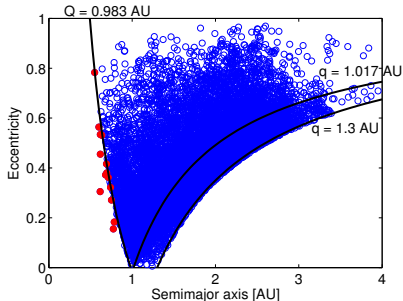
# Applications

- ▶ Multiple Atira Asteroids Fly-by Mission
- ▶ Multiple Active Debris Removal Mission



# Multiple Atira Asteroids Fly-by Mission

- ▶  $a < 1$  AU,  $Q < 0.983$  AU
- ▶ 14 known Atira asteroids - many more IEOs are expected to exist
- ▶ Observation of the inner Solar System: limitations of ground-based survey (Sun in the instrument field of view)
- ▶ Fly-by at the nodal points of the asteroids' orbit



# Multiple Atira Asteroids Fly-by Mission

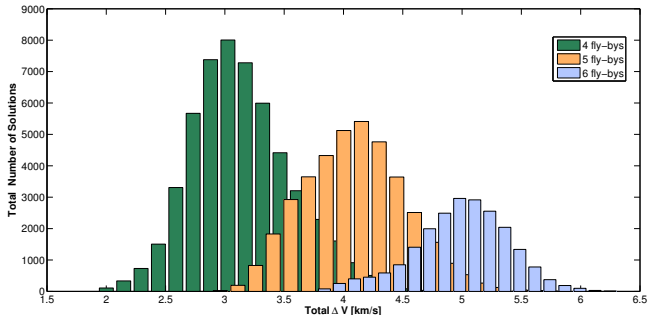
## ► AIDMAP

Identification of optimal:

- sequence of asteroids
- departure dates
- times of flight

Impulsive model: Lambert arcs with departure dates at steps of 10 days.

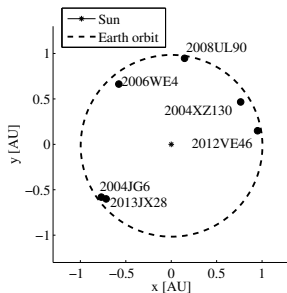
133,761 solutions identified:



# Multiple Atira Asteroids Fly-by Mission

## ► AIDMAP

Best Solution: fly-by with 6 asteroids,  $\Delta V = 3.77$  km/s



	Asteroid	Departure Date	ToF [days]	$\Delta V$ [km/s]
	2013JX28	2020/09/29	205	0.87
	2006WE4	2022/05/14	215	0.86
	2004JG6	2023/06/14	235	0.61
	2012VE46	2024/09/11	265	0.36
	2004XZ130	2026/09/15	205	0.73
	2008UL90	2028/07/31	195	0.34
TOT.				<b>3.77</b>

# Multiple Atira Asteroids Fly-by Mission

## ► MP-AIDEA

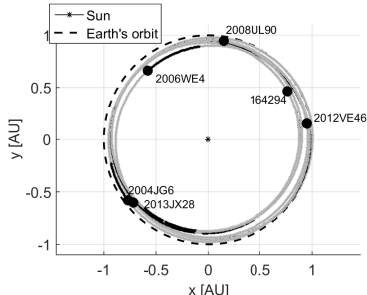
- Identification of **new departure dates leading to reduced  $\Delta V$**
- Global optimisation with search space defined allocating **time window of  $\pm 10$  days** around previously identified departure dates

	Asteroid	AIDMAP Dep. Date	<b>MP-AIDEA Departure Date</b>	AIDMAP $\Delta V$ [km/s]	<b>MP-AIDEA <math>\Delta V</math> [km/s]</b>
	2013JX28	2020/09/29	2020/09/ <b>20</b>	0.87	<b>0.95</b>
	2006WE4	2022/05/14	2022/05/ <b>24</b>	0.86	<b>0.69</b>
	2004JG6	2023/06/14	2023/06/ <b>12</b>	0.61	<b>0.61</b>
	2012VE46	2024/09/11	2024/09/ <b>05</b>	0.36	<b>0.34</b>
	2004XZ130	2026/09/15	2026/09/ <b>18</b>	0.73	<b>0.72</b>
	2008UL90	2028/07/31	2028/08/ <b>10</b>	0.34	<b>0.29</b>
<b>TOTAL</b>				<b>3.77</b>	<b>3.61</b>

# Multiple Atira Asteroids Fly-by Mission

## ► FABLE

- Direct optimisation method and multiple shooting algorithm
- Spacecraft injected into a hyperbolic escape orbit from Earth that encounters the first asteroids at its nodal point.
- Low-thrust engine:  $T = 0.07$  N,  $I_{sp} = 3000$  s

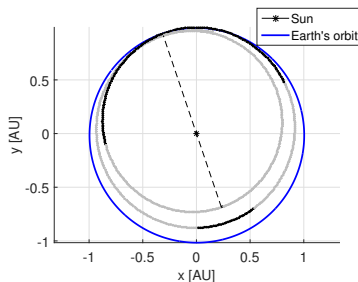


Asteroid	$m_0$ [kg]	$m_f$ [kg]	$\Delta V$ [km/s]
2013JX28	<b>700</b>	700	-
2006WE4	700	673.45	1.12
2004JG6	673.45	642.07	1.37
2012VE46	642.07	633.47	0.39
2004XZ130	633.47	600.89	1.51
2008UL90	600.89	<b>594.17</b>	0.30
<b>TOT.</b>			<b>4.69</b>

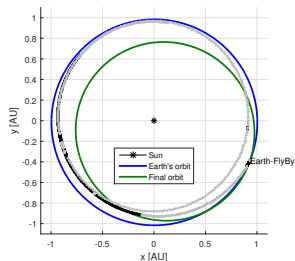
# Multiple Atira Asteroids Fly-by Mission

## ► FABLE

- Transfer to a **reduced perihelion orbit (0.725 AU)** for observation of asteroids of the inner Solar System
- Transfer: low-thrust propulsion or Earth gravity-assist
- $T_0 / T_{\oplus} = 0.88$
- $T_f / T_{\oplus} = 0.78$



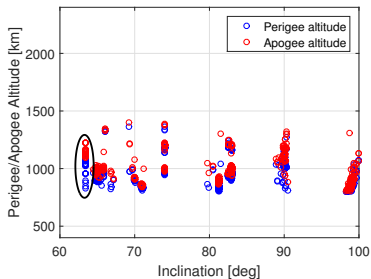
$\Delta V$ [km/s]	ToF [days]
1.79	422



$\Delta V$ [km/s]	ToF [days]
1.31	565

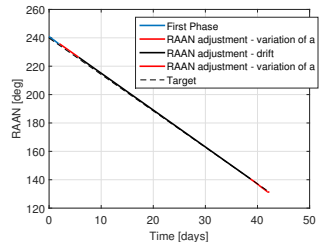
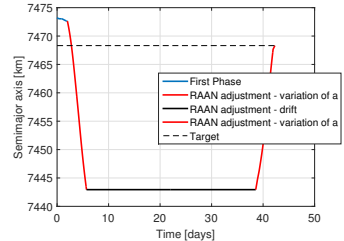
## Multiple Active Debris Removal Mission

- ▶ Deorbiting of **large satellites from LEO** (800 - 1400 km) using a **low-thrust servicing spacecraft** ( $T = 0.1$  N,  $I_{sp} = 1600$  s,  $m = 1000$  kg)
- ▶ Two possible strategies:
  - multi-target delivery of **de-orbiting kits** (100 kg) to perform a controlled re-entry;
  - low-thrust **fetch and deorbit** using the single servicing spacecraft.
- ▶ Selected targets: 25 objects with high Criticality of Spacecraft Index and low inclination (J2 drift to change  $\Omega$ )



# Multiple Active Debris Removal Mission

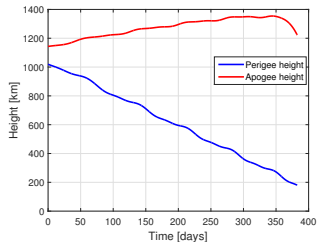
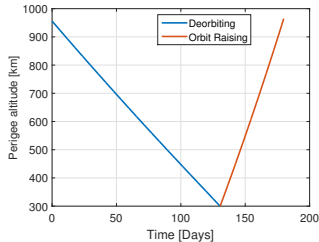
- ▶ FABLE: transfer between two satellites (multi-target delivery of deorbiting kit)





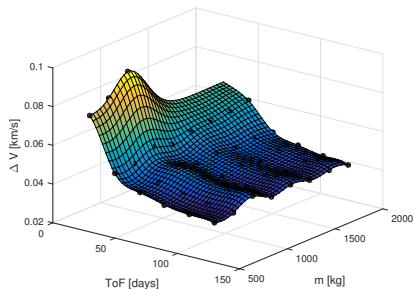
# Multiple Active Debris Removal Mission

- ▶ FABLE: transfer between two satellites (multi-target delivery of deorbiting kit)
- ▶ FABLE: deorbiting of objects (fetch and de-orbit)
  - Spiral with negative tangential acceleration:  $\gamma = 0$  deg
  - Increase of eccentricity (negative thrust at apogee and positive thrust at perigee):  $\gamma = 1.5$  deg



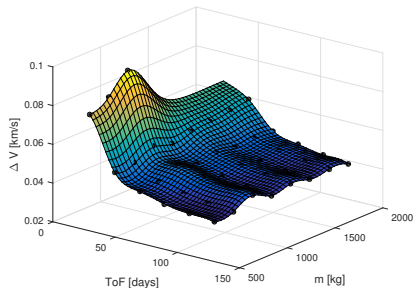
# Multiple Active Debris Removal Mission

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- ▶ FABLE: surrogate model of the cost of the transfer for different possible initial mass of the spacecraft and time of flight of the transfer



# Multiple Active Debris Removal Mission

- ▶ FABLE: transfer between two satellites (multi-target delivery of deorbiting kit)
- ▶ FABLE: deorbiting of objects (fetch and de-orbit)
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  - Increase of eccentricity (negative thrust at apogee and positive thrust at perigee):  $\gamma = 1.5$  deg
- ▶ FABLE: surrogate model of the cost of the transfer for different possible initial mass of the spacecraft and time of flight of the transfer
- ▶ AIDMAP: identification of the optimal sequence of targets to be removed using surrogate model



# Multiple Active Debris Removal Mission

Multi-target delivery of de-orbiting kits:

	Departure Object	Arrival Object	$\Delta V$ [km/s]	$ToF$ [days]	$m_0$ [kg]	$m_f$ [kg]
1	39015	40343	0.0628	30.43	1900.00	1892.40
2	40343	40340	0.1128	65.75	1792.40	1779.55
3	40340	39016	0.0595	33.14	1679.55	1673.19
4	39016	40342	0.0429	29.73	1573.19	1568.89
5	40342	40338	0.0339	42.28	1468.89	1465.72
6	40338	40339	0.0013	7.05	1365.72	1365.60
7	40339	39011	0.1116	44.55	1265.60	1256.63
8	39011	39012	0.0035	14.19	1156.63	1156.37
9	39012	39013	0.0448	28.04	1056.37	1053.34
<b>Total</b>	-	-	<b>0.4731</b>	<b>294.17</b>	-	-

Fetch and deorbit:

	Departure Object	Arrival Object	$\Delta V$ [km/s]	$ToF$ [days]	$m_0$ [kg]	$m_f$ [kg]
1	39244	36413	1.1307	159.91	3000.00	890.11
2	36413	39011	0.9811	182.32	2890.11	802.79
<b>Total</b>	-	-	<b>2.1118</b>	<b>373.23</b>	-	-

# Conclusions

CAMELOT, toolbox for the preliminary design of multi-target low-thrust missions:

- ▶ FABLE: low-thrust transfer estimator
- ▶ MP-AIDEA: single objective multi population adaptive global optimiser
- ▶ AIDMAP: single objective combinatorial optimiser

Applications:

- ▶ Multiple Atira Asteroids Fly-By Mission
  - Six asteroids fly-by in less than 10 years
  - Limited propellant consumption
- ▶ Multiple Active Debris Removal Mission
  - De-orbiting kits: 10 objects removed from LEO in less than 1 year
  - Fetch and deorbit: 3 objects removed from LEO

Thank you.  
Questions?