

# Processing TLEs to facilitate re-entry prediction of spent rocket bodies from GTO

Aleksander A. Lidtke<sup>1</sup>

David J. Gondelach<sup>1</sup>, Roberto Armellin<sup>2</sup>, Camilla Colombo<sup>1</sup>

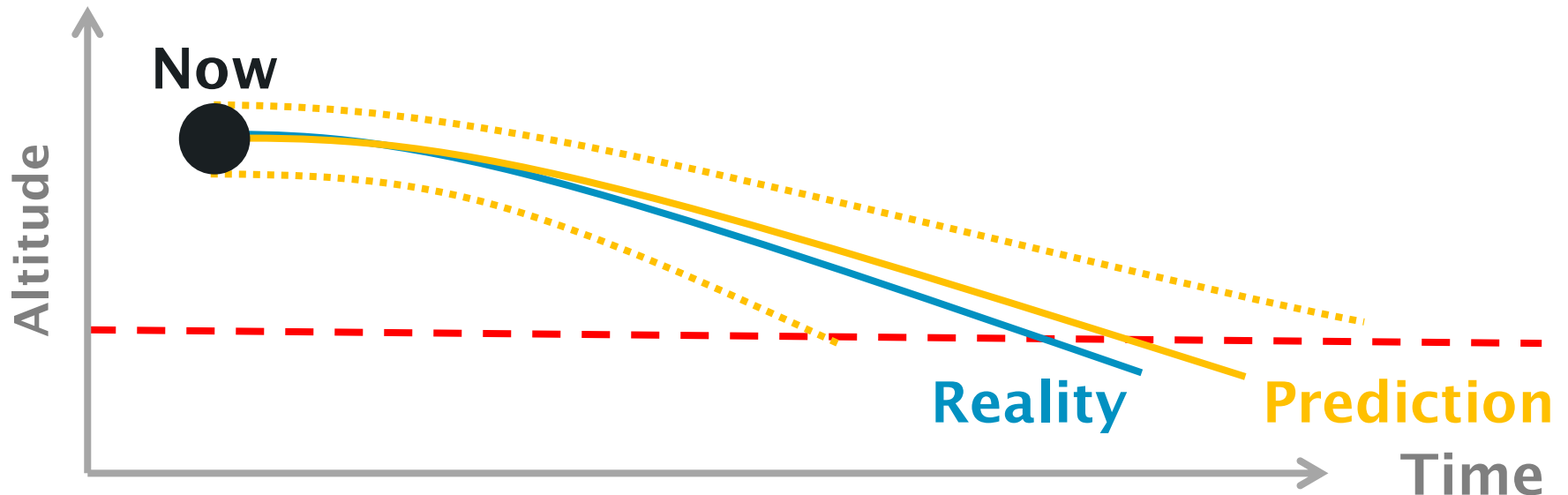
Hugh G. Lewis<sup>1</sup>, Quirin Funke<sup>3</sup>, Tim Flohrer<sup>3</sup>

1 - Astronautics Research Group, University of Southampton

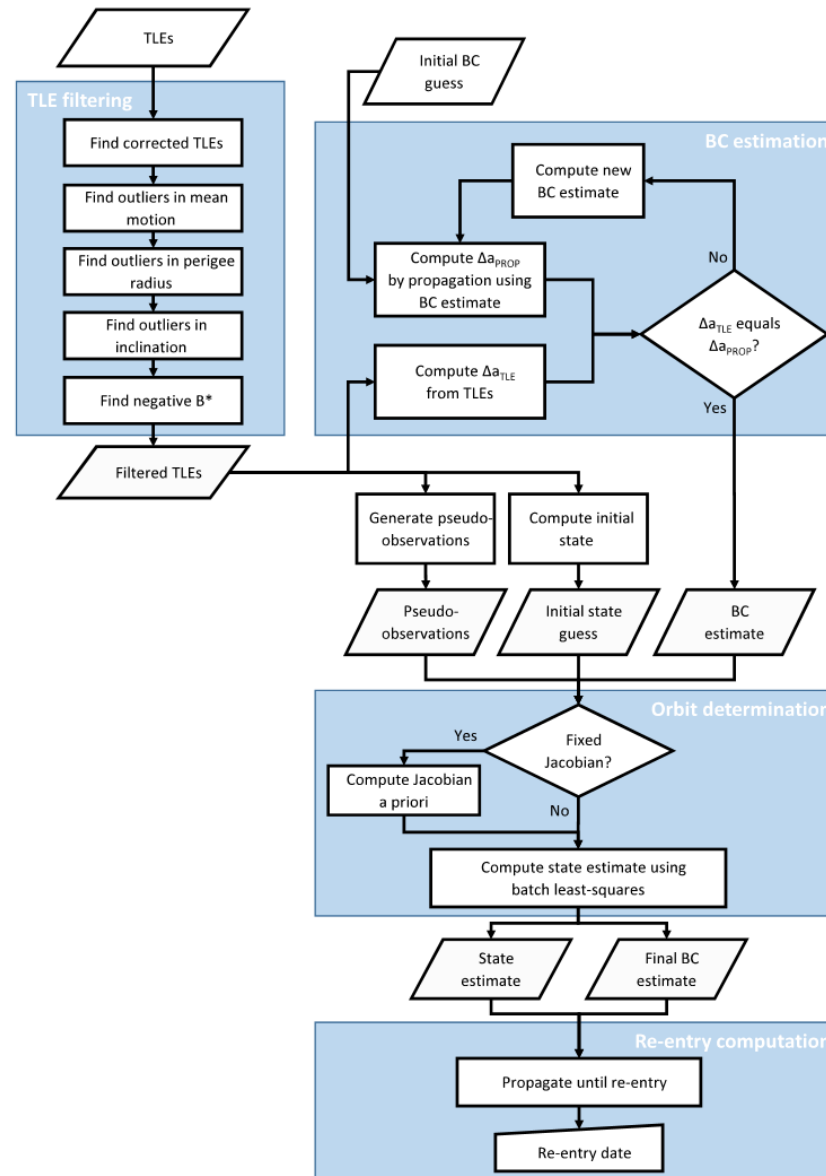
2 - Departamento de Matemáticas y Computación, Universidad de La Rioja

3 - European Space Operations Center

# Re-entry prediction

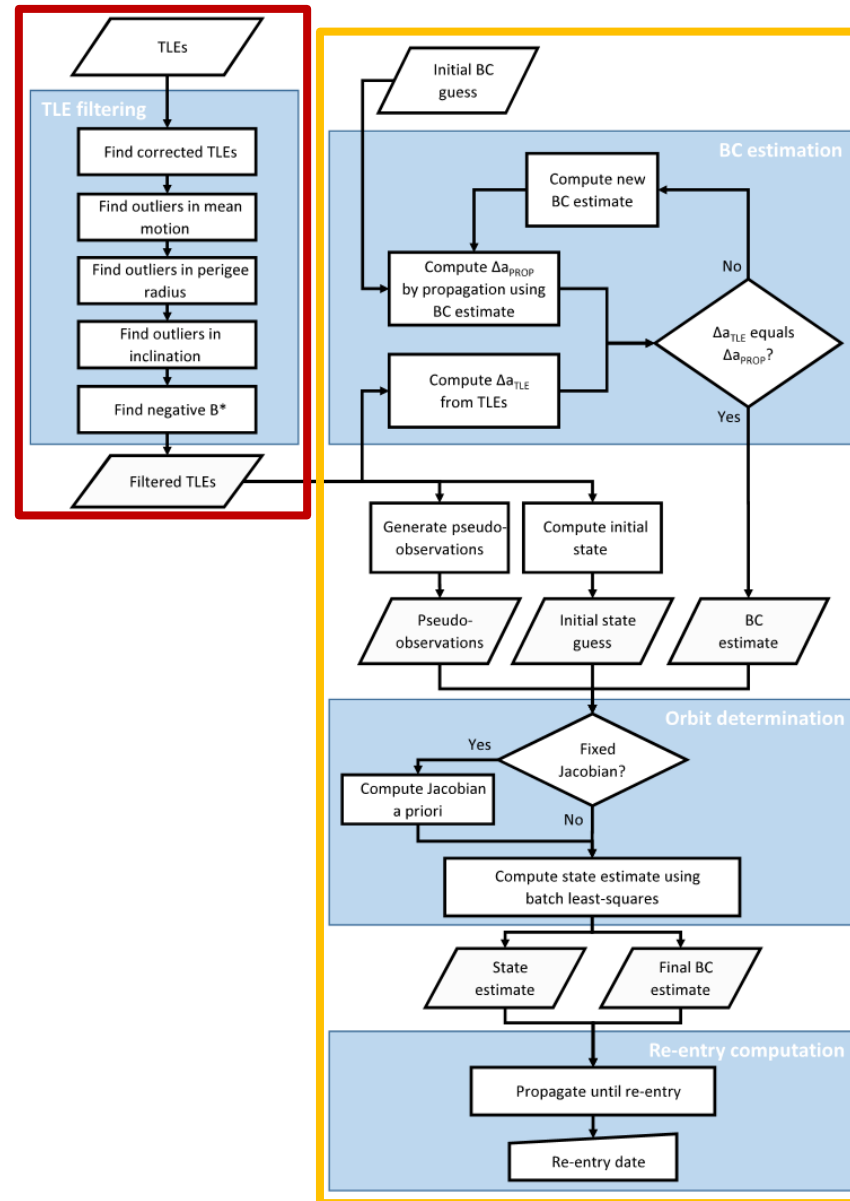


# How to improve TLE-based predictions



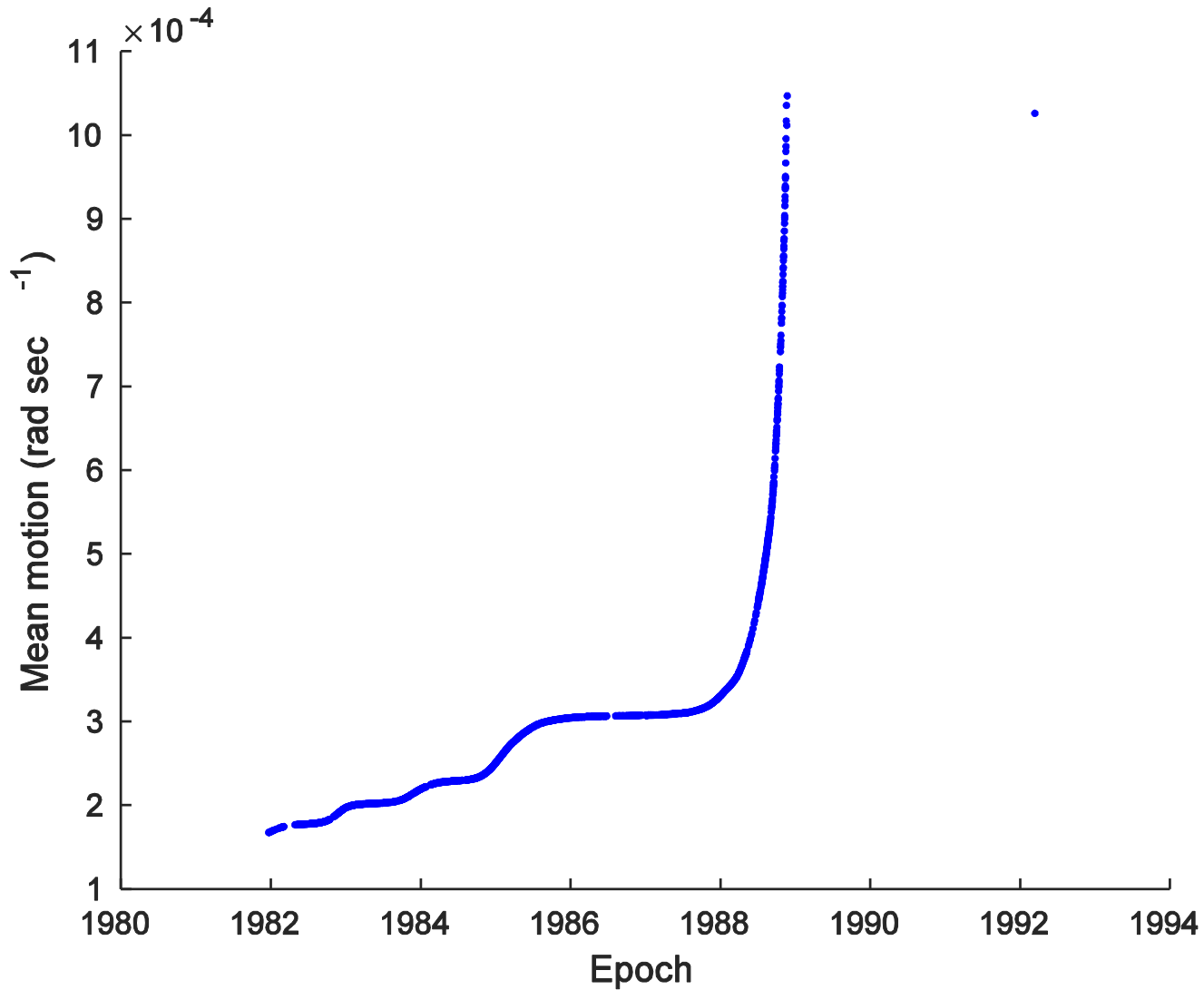
# How to improve TLE-based predictions

Today

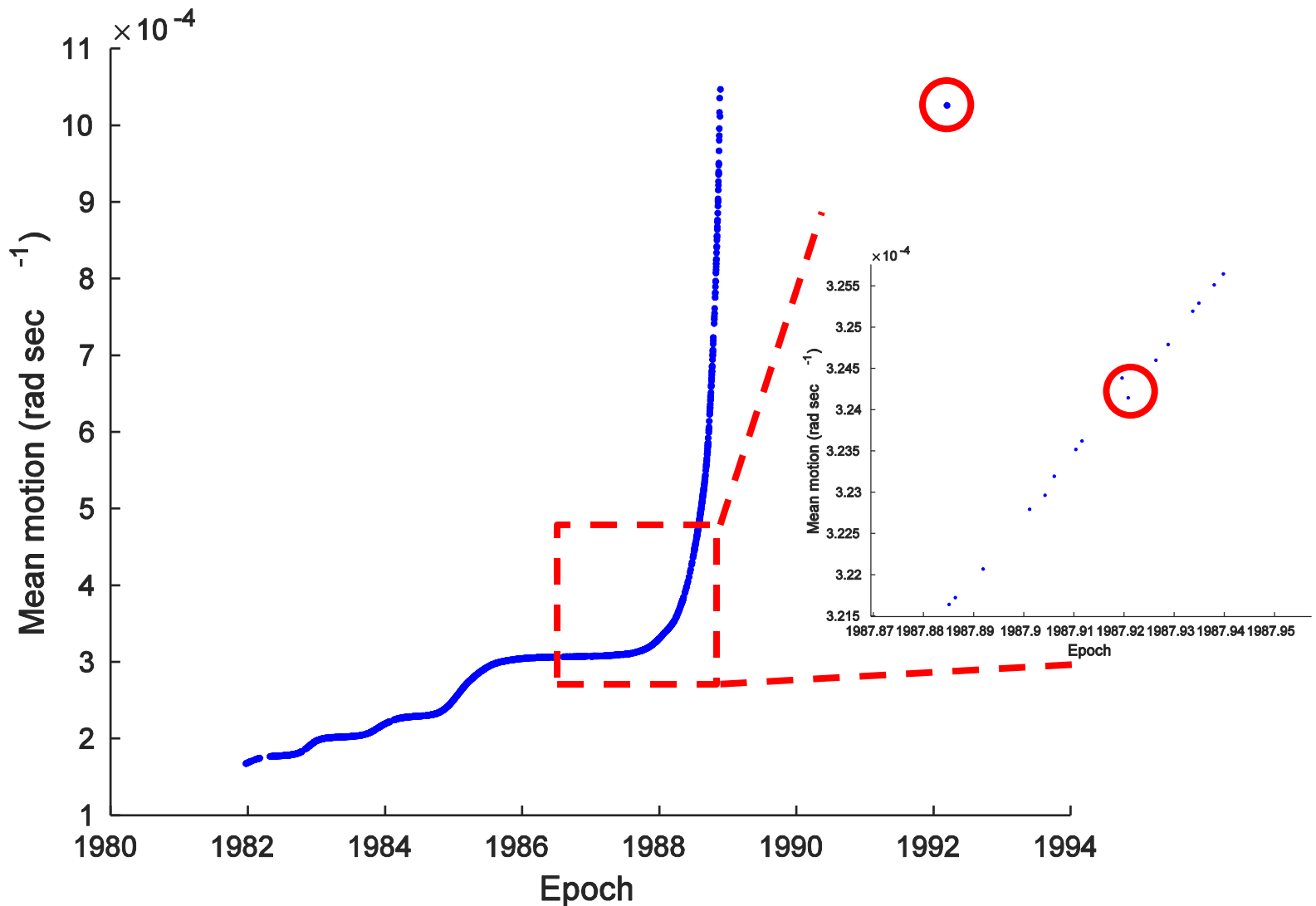


AAS 2016,  
Napa, CA

# Problems with TLEs

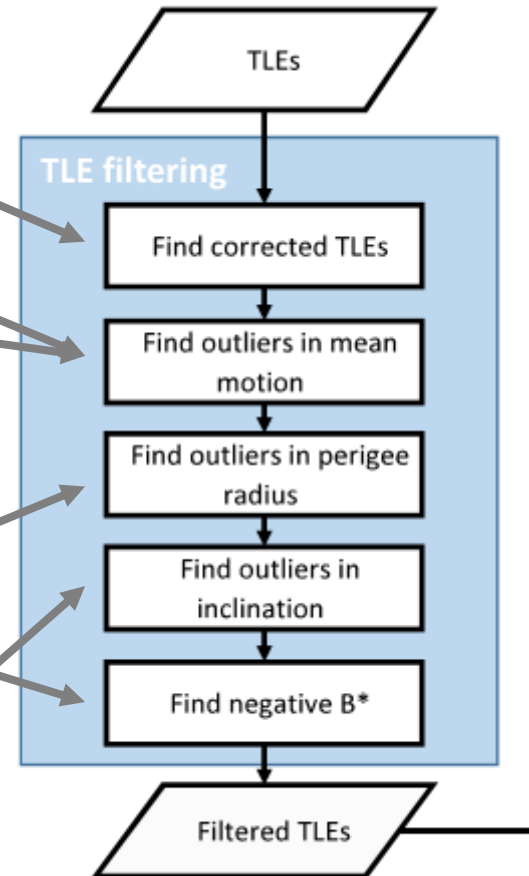


# Problems with TLEs



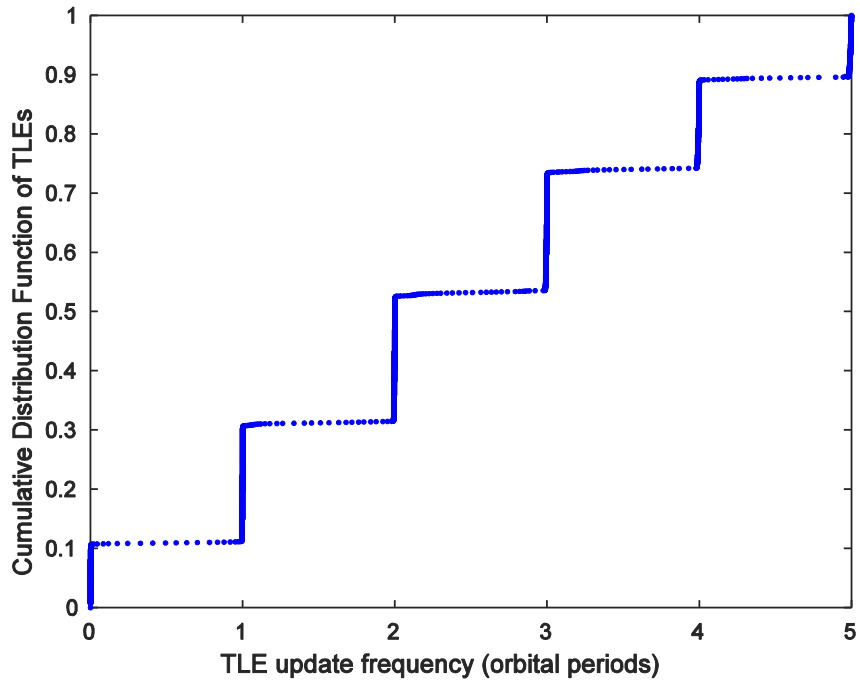
# Addressing problems with TLEs

1. Corrected TLEs
2. Time gaps
3. Outliers in mean motion and events that physically change the object
4. Outliers in eccentricity and  $B^*$  – need to estimate the ballistic coefficient
5. Outliers in inclination – need orbit determination to converge

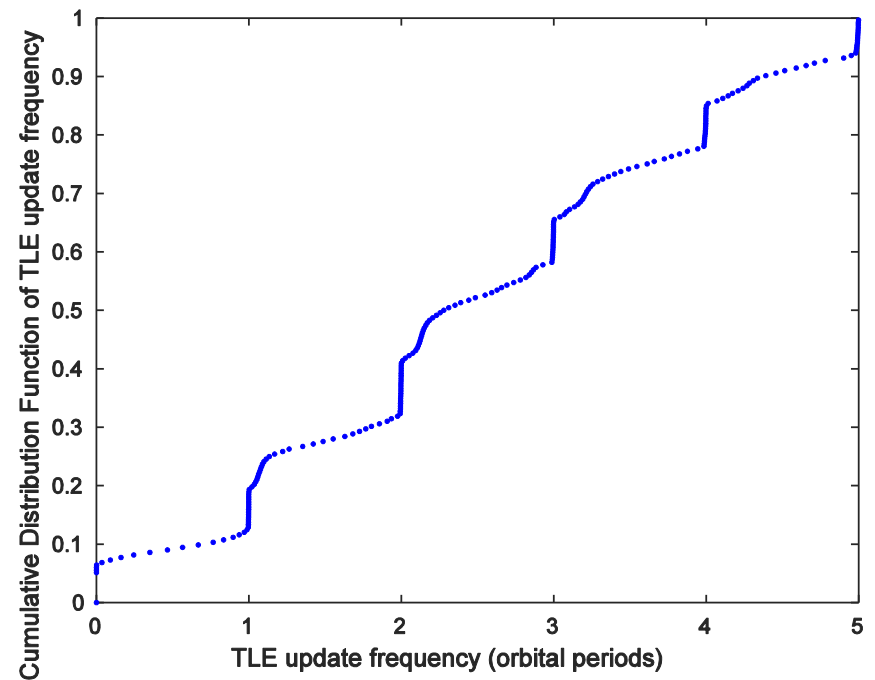


# Corrections

## Before 2011



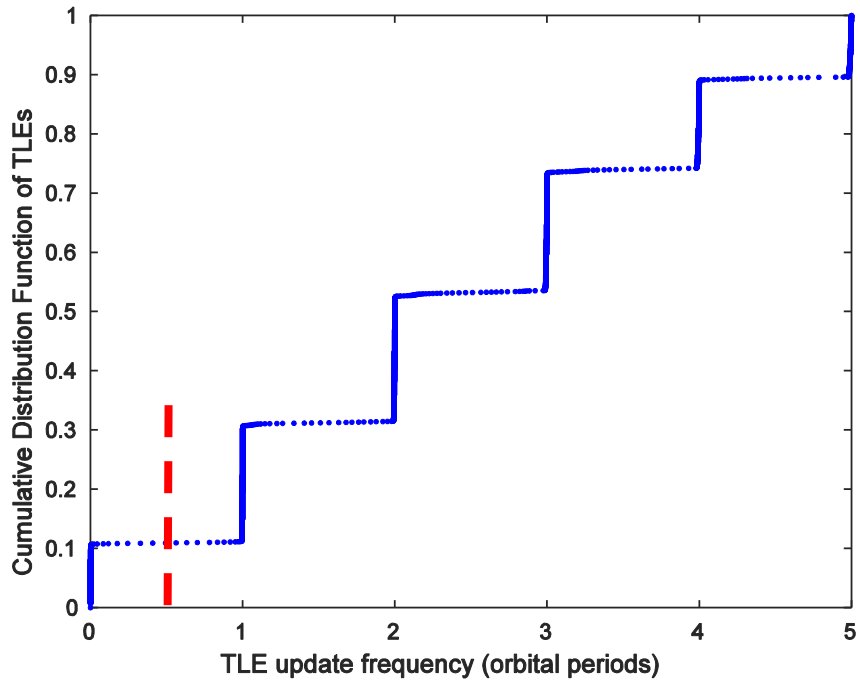
## After 2011



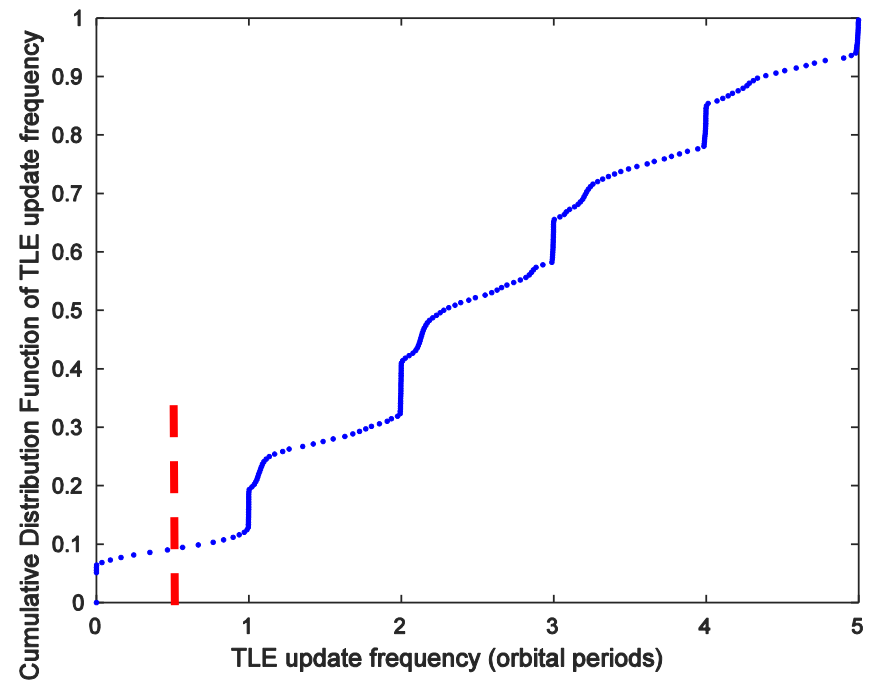


# Corrections

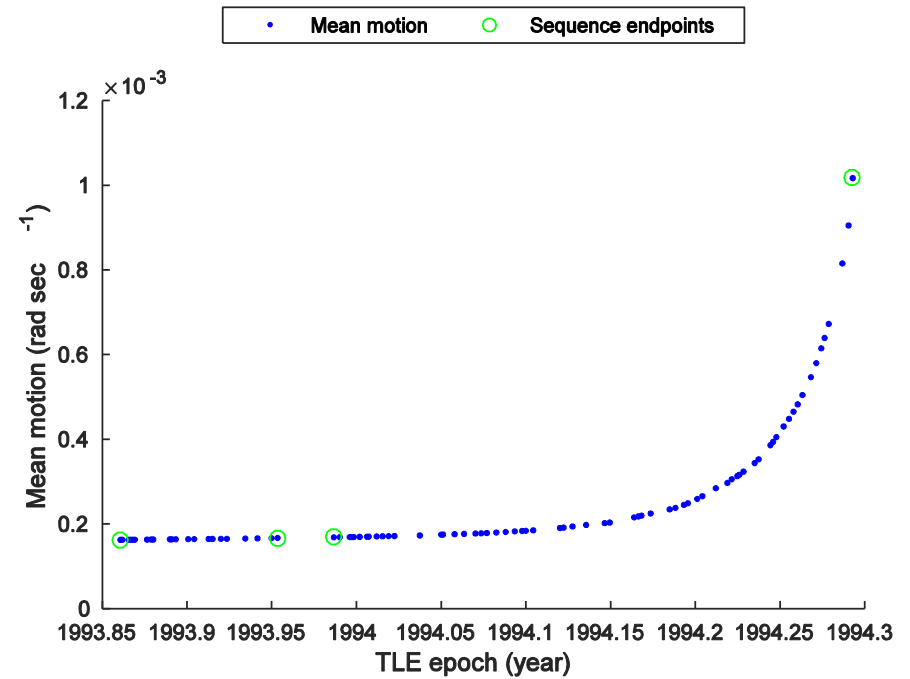
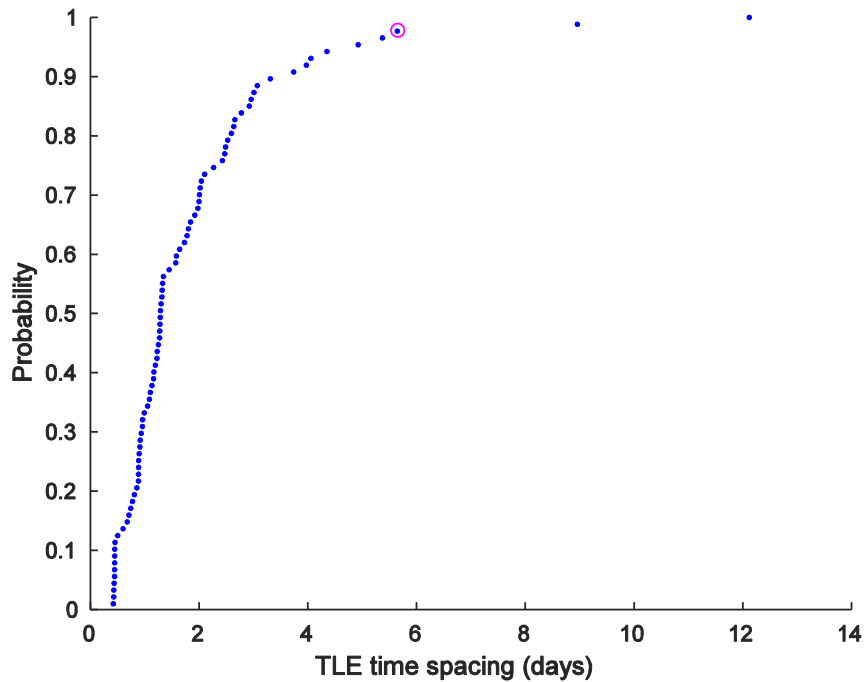
## Before 2011



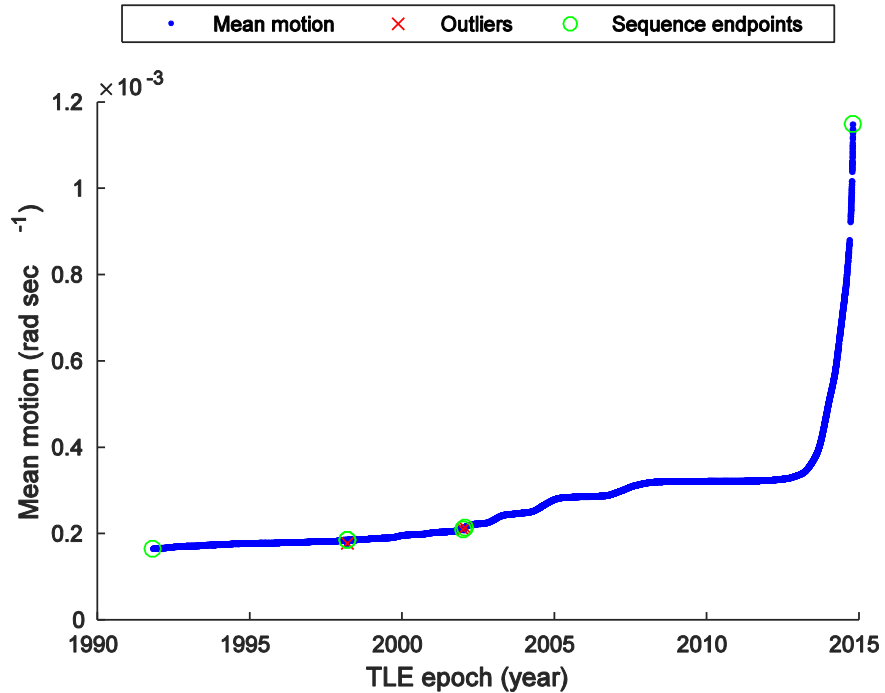
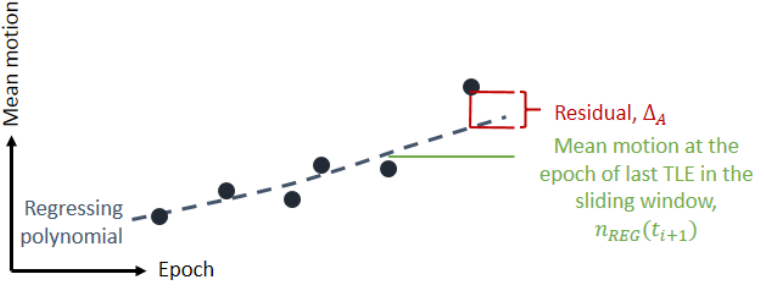
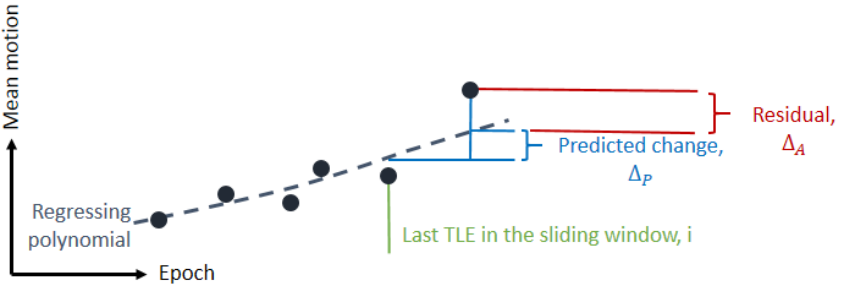
## After 2011



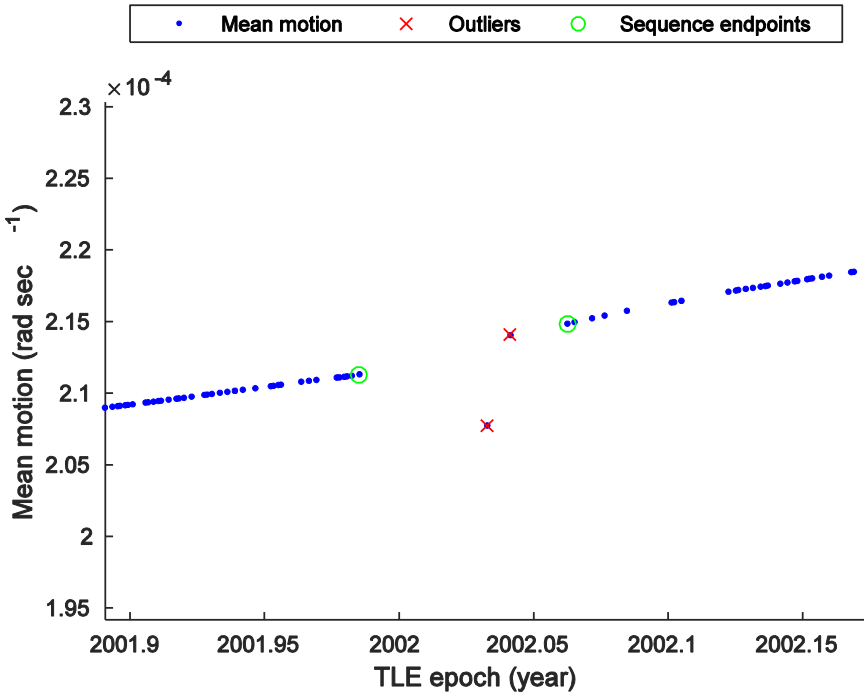
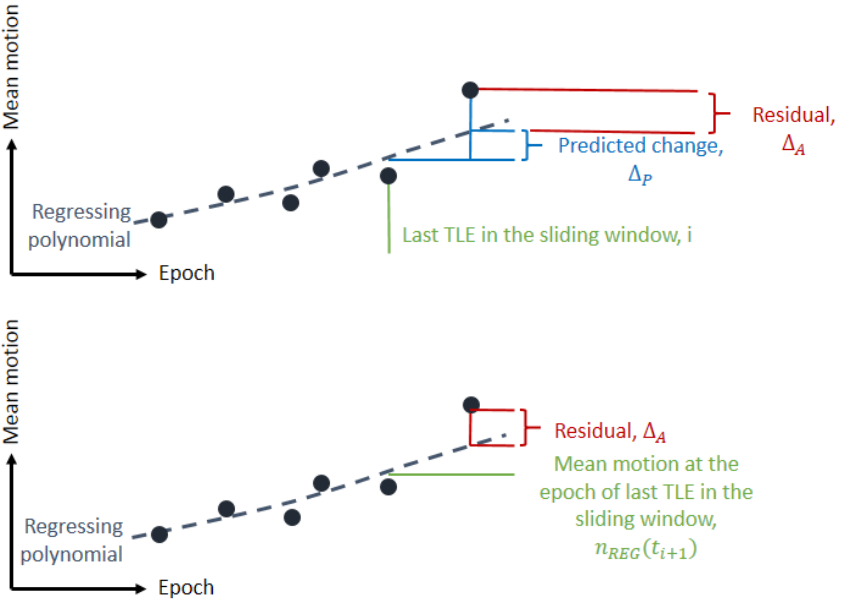
# Time gaps



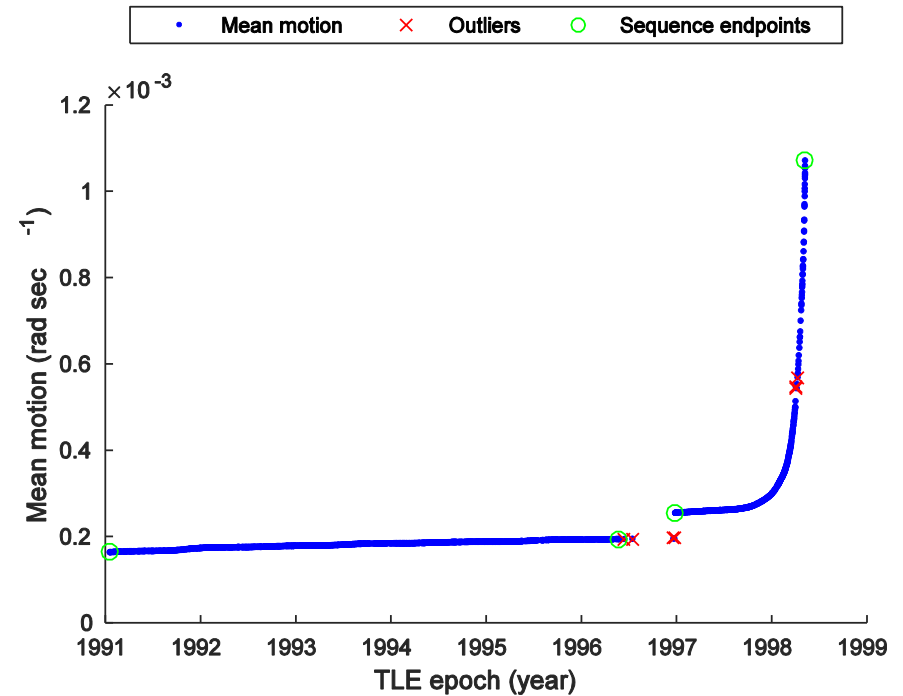
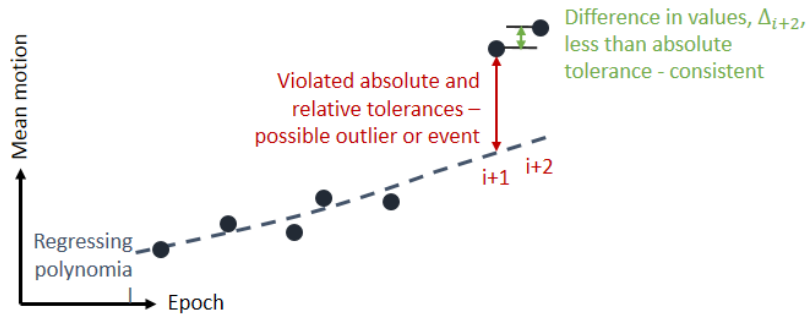
# Mean motion outliers



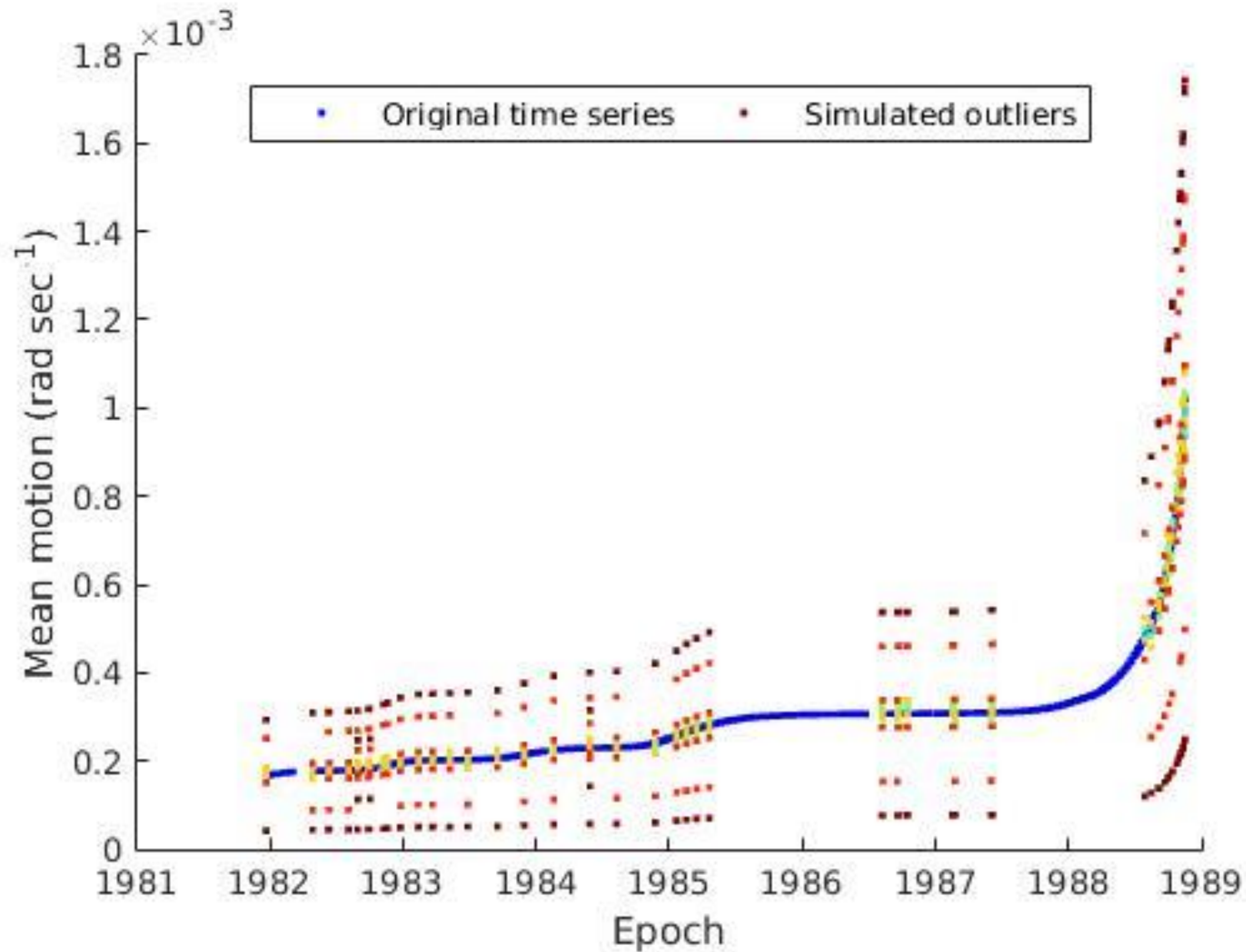
# Mean motion outliers



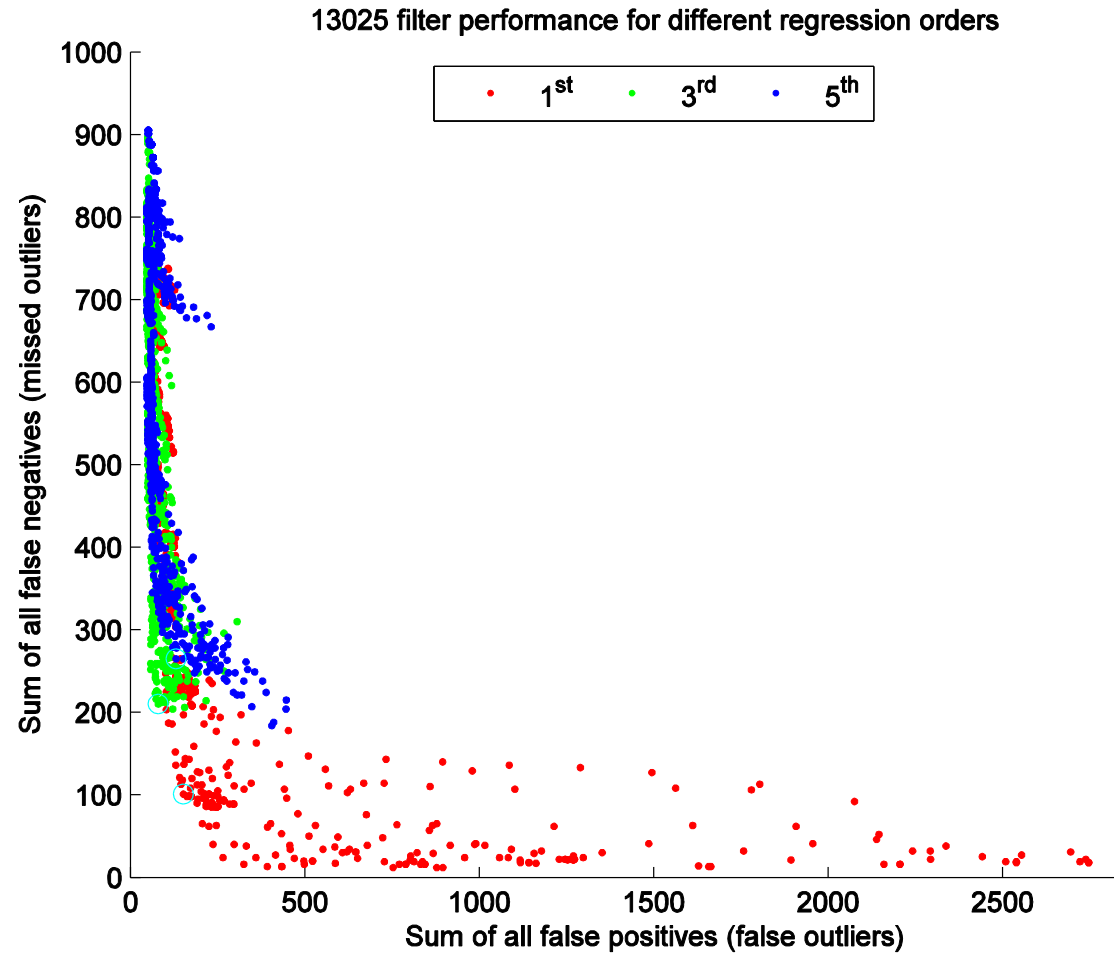
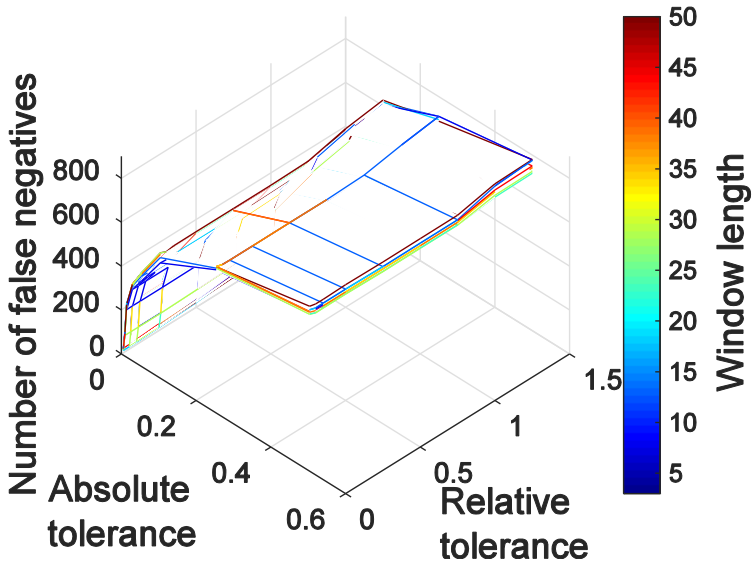
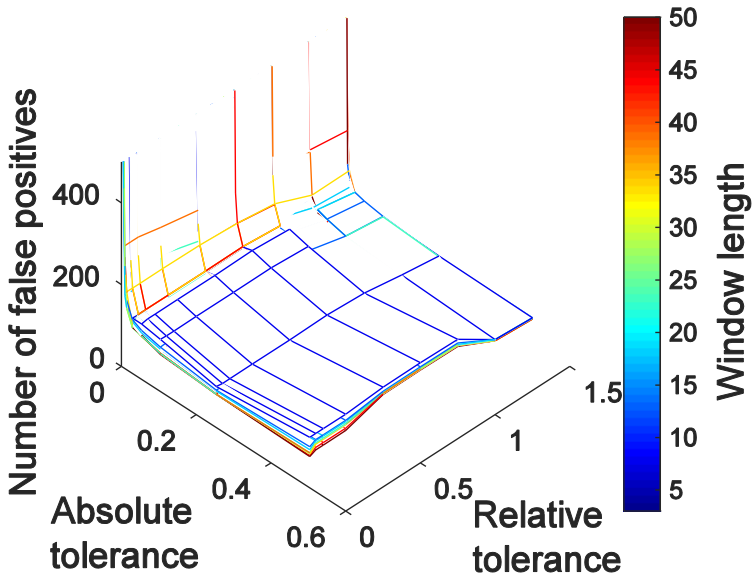
# Events – change BC and SRPC



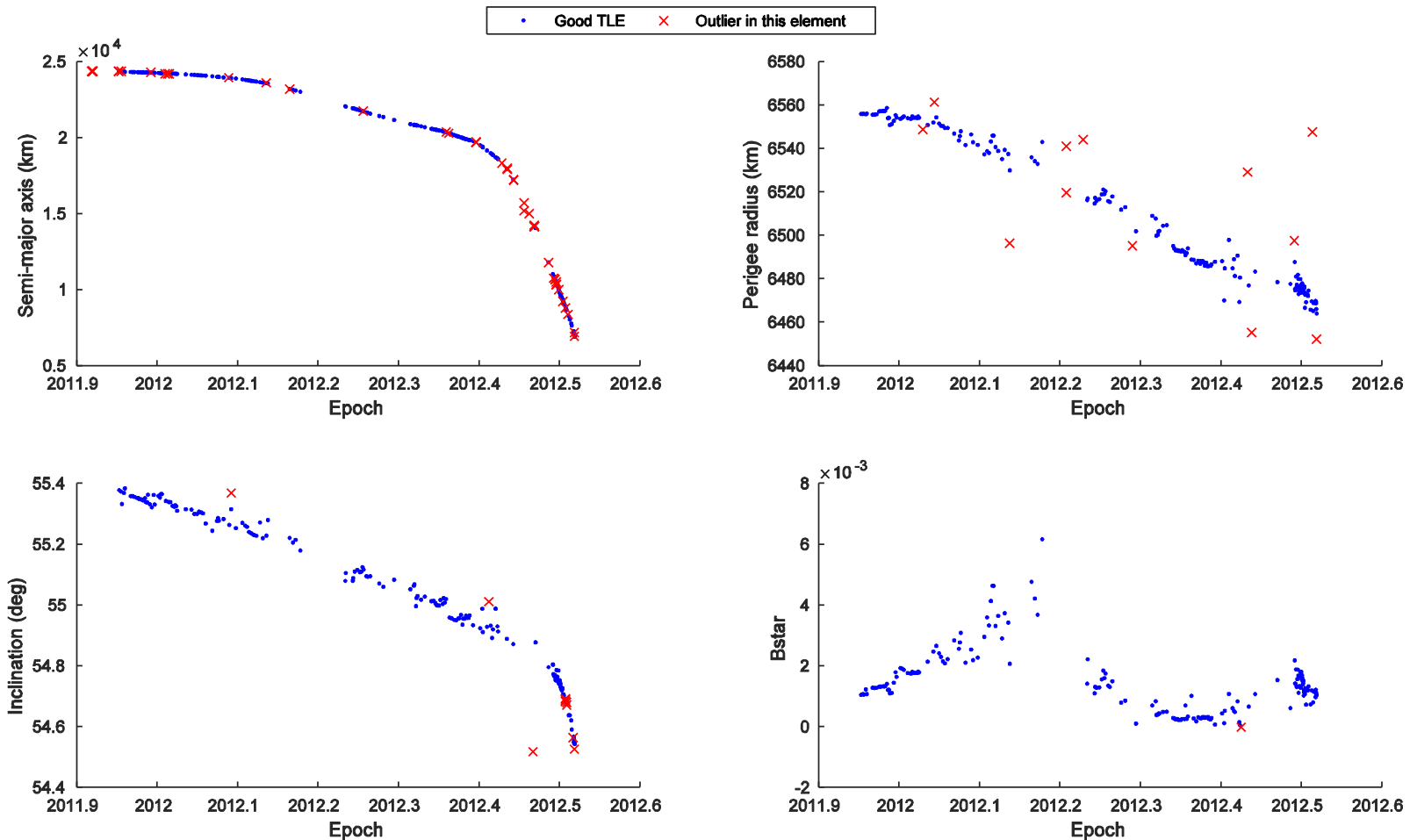
# Mean motion filter tuning



# Mean motion filter tuning

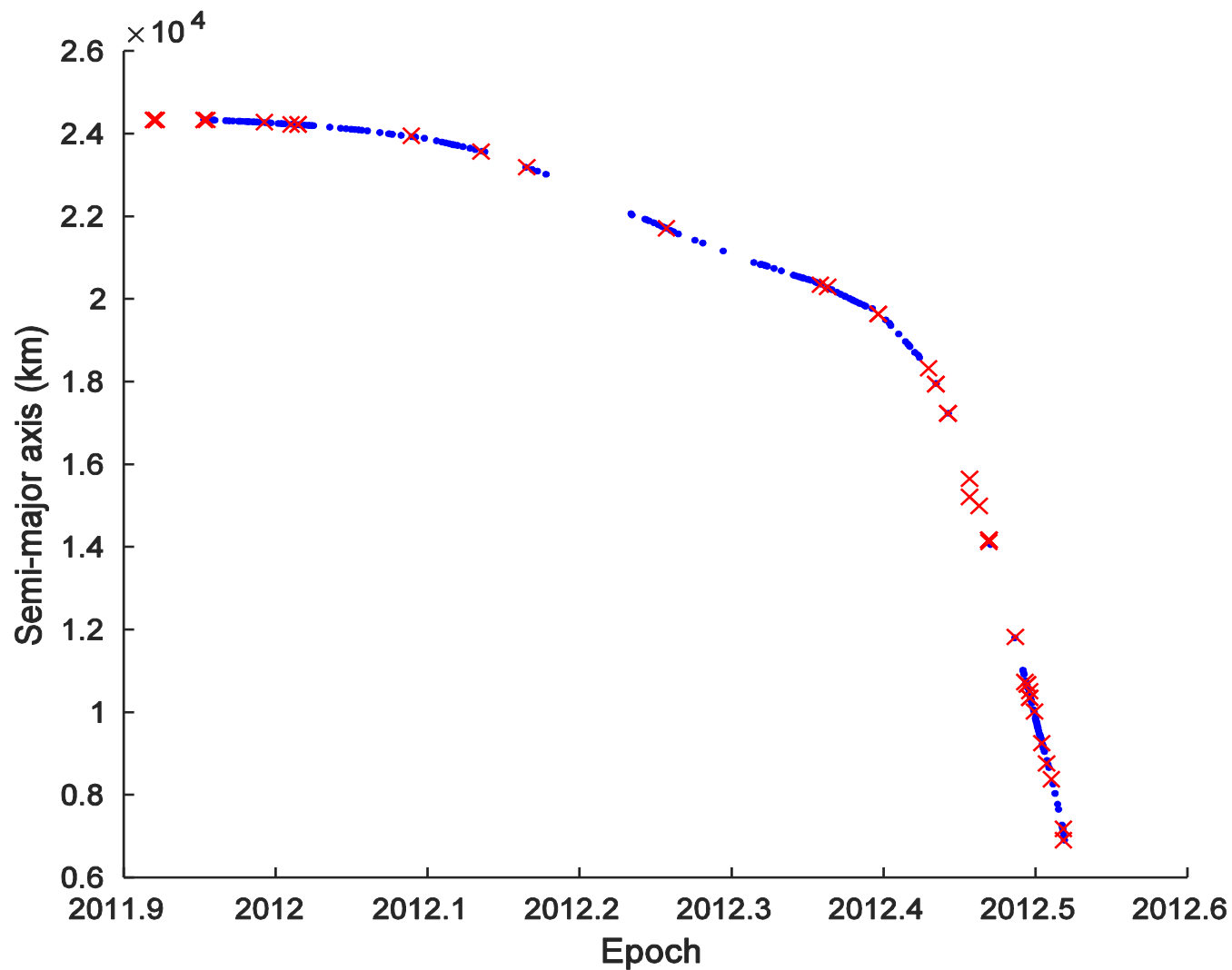


# Outliers in $n$ , $e$ , $i$ , and $B^*$

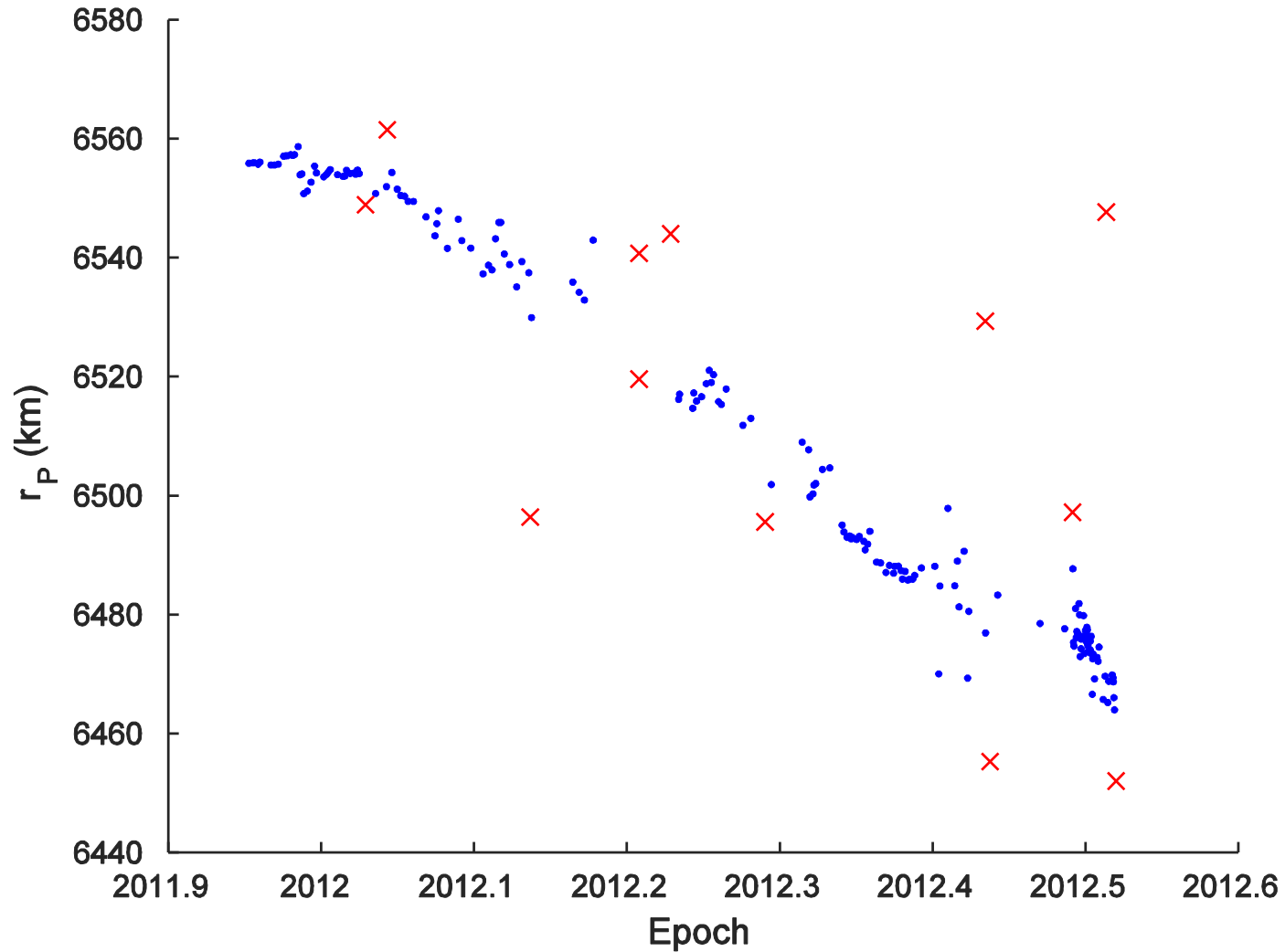




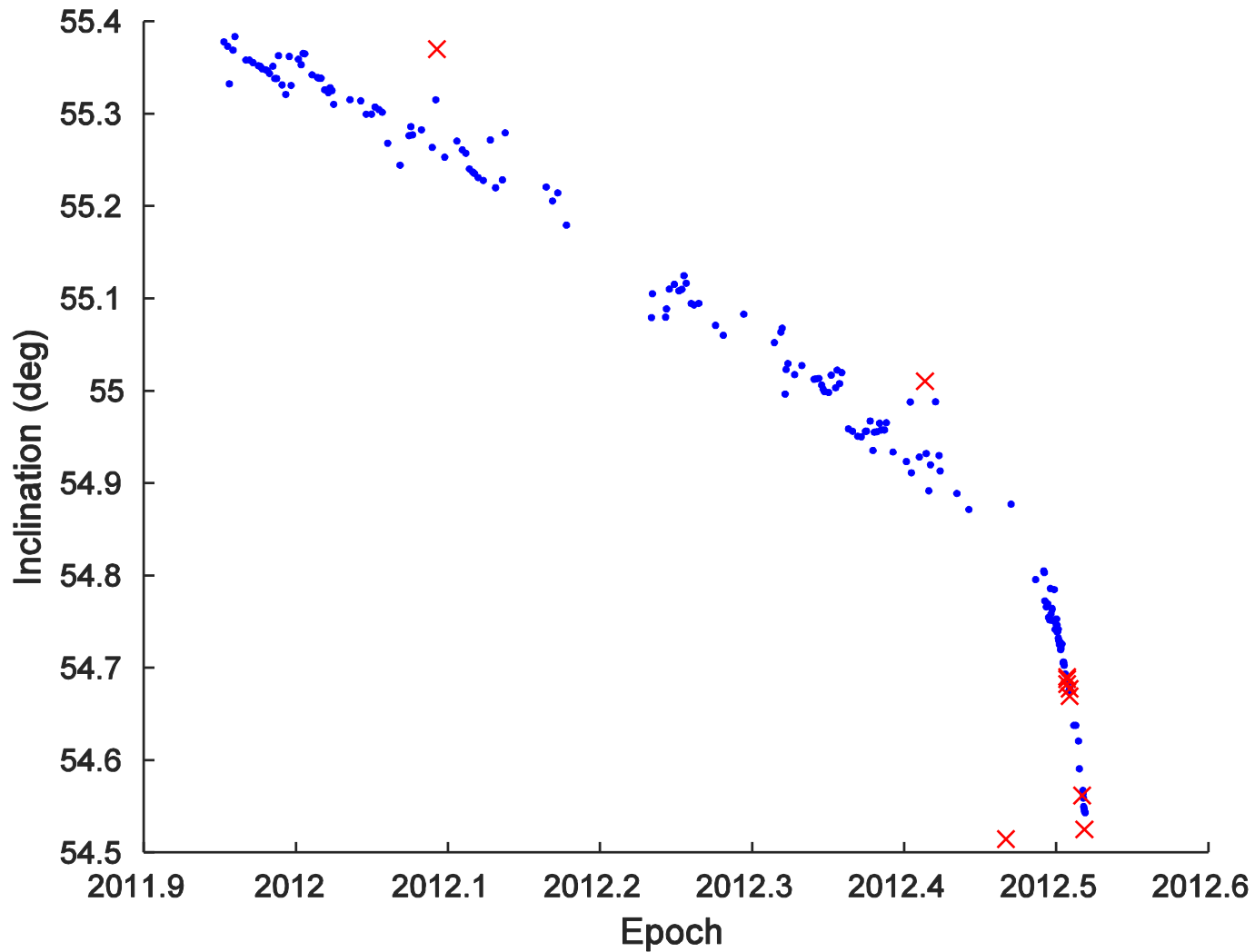
# Outliers in $n$



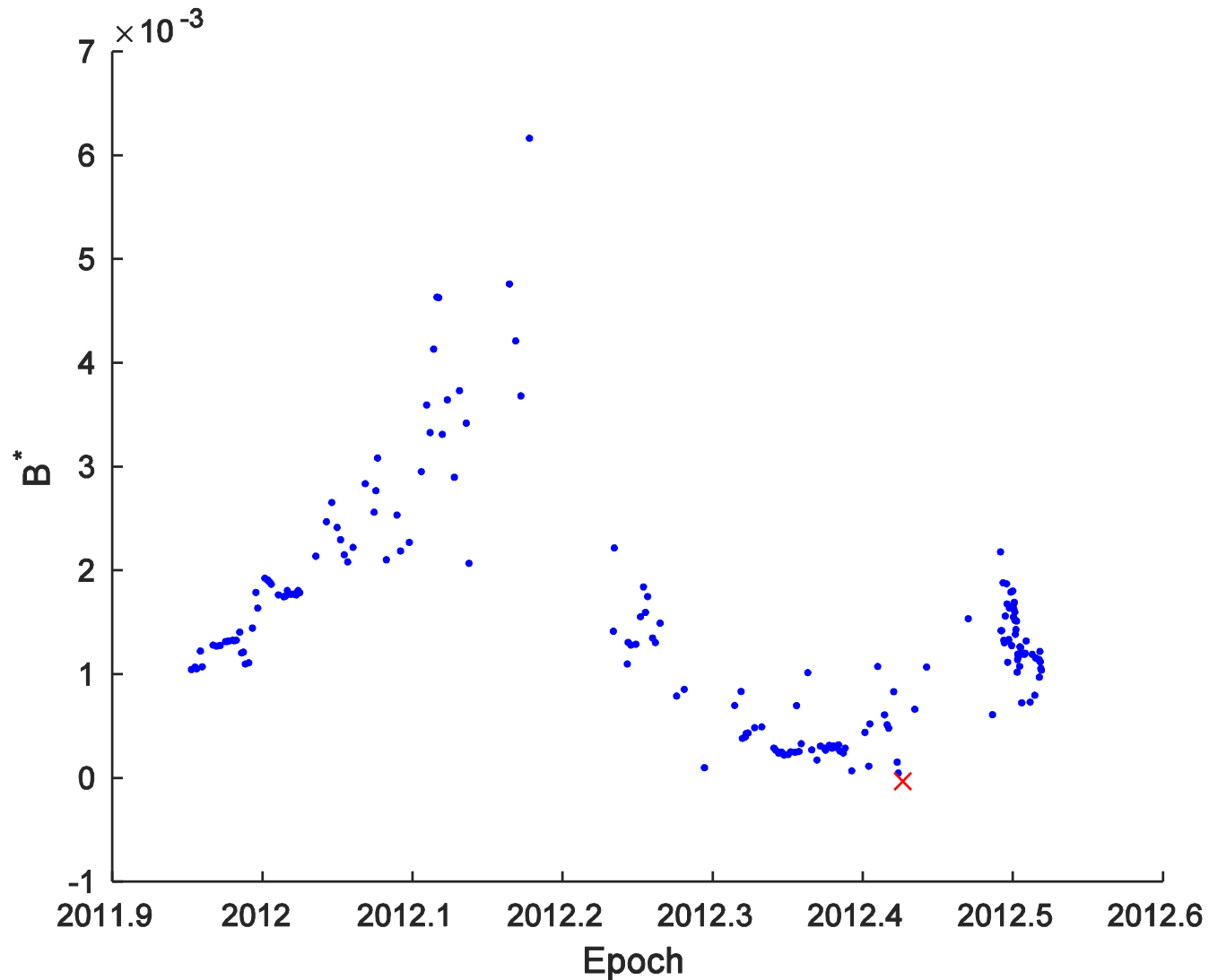
# Outliers in $e$



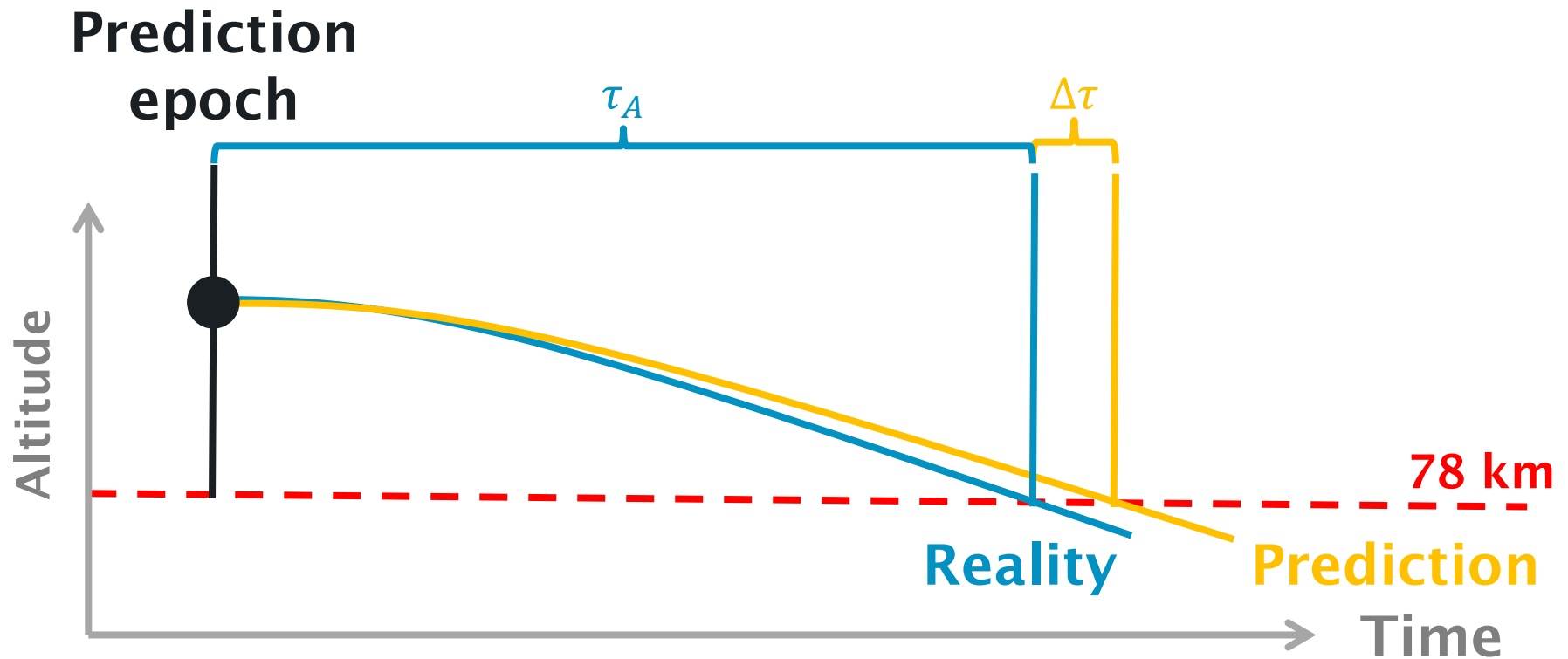
# Outliers in $i$



# Outliers in $B^*$

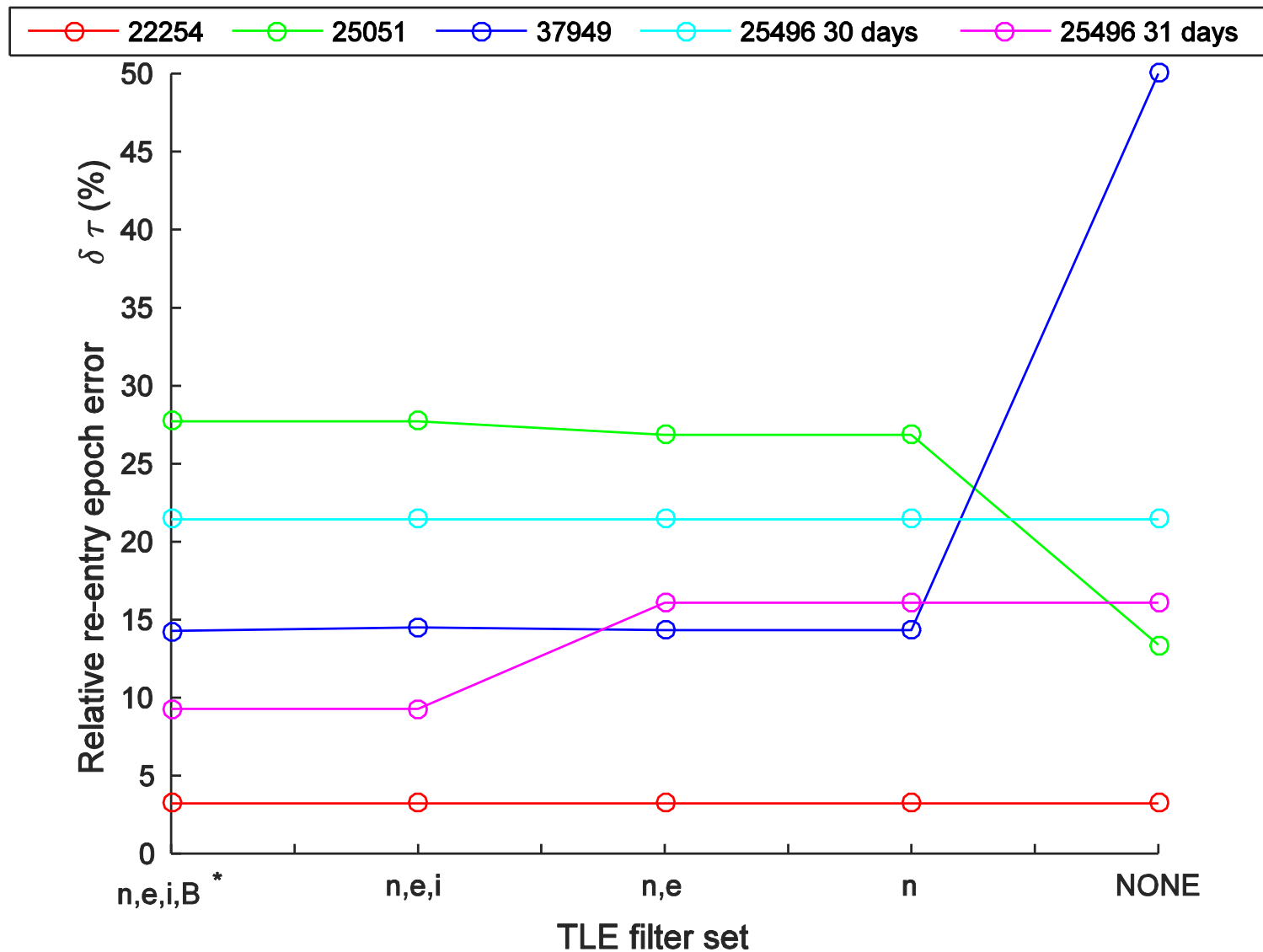


# Re-entry prediction error

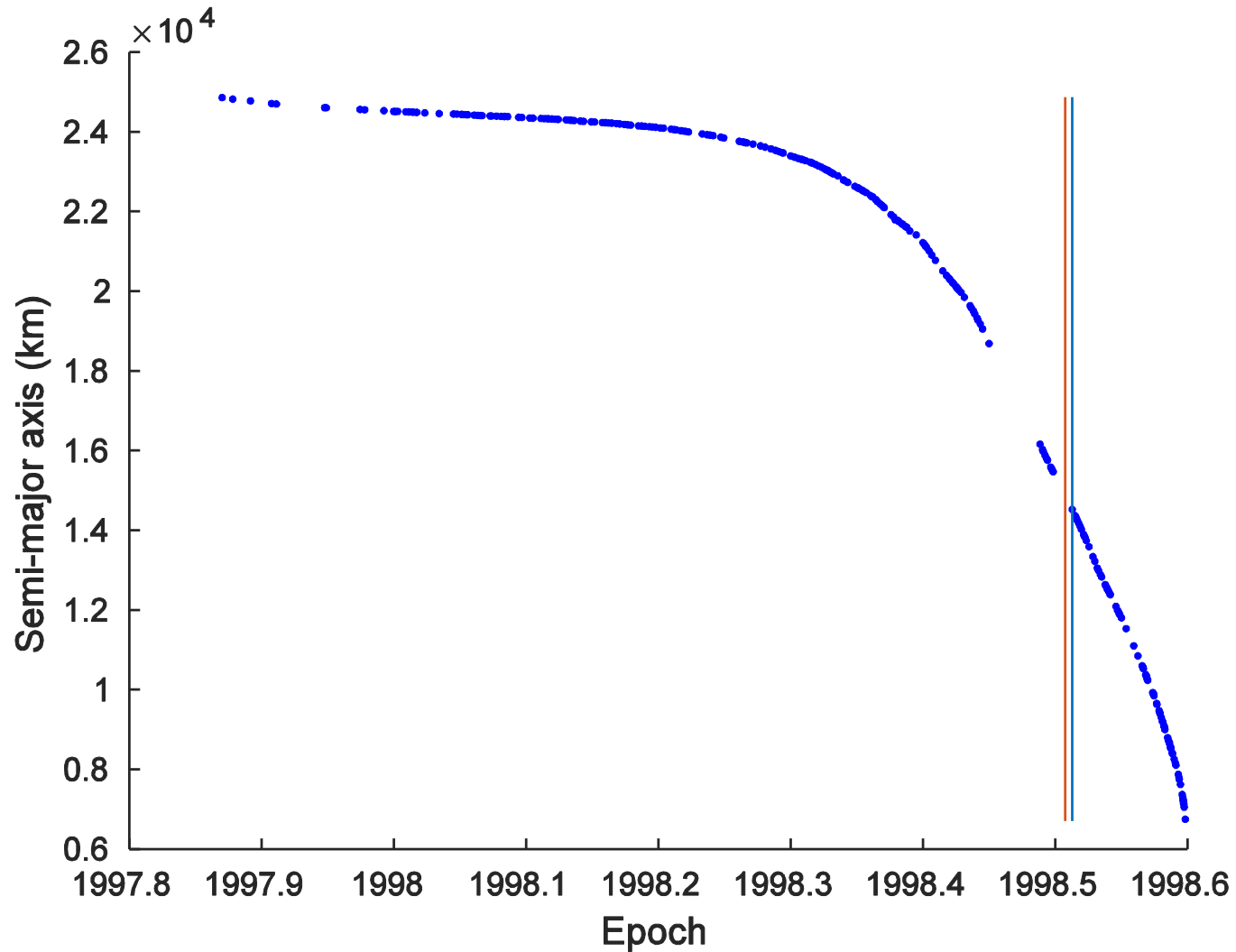


$$\text{Relative error: } \delta\tau = \frac{\Delta\tau}{\tau_A}$$

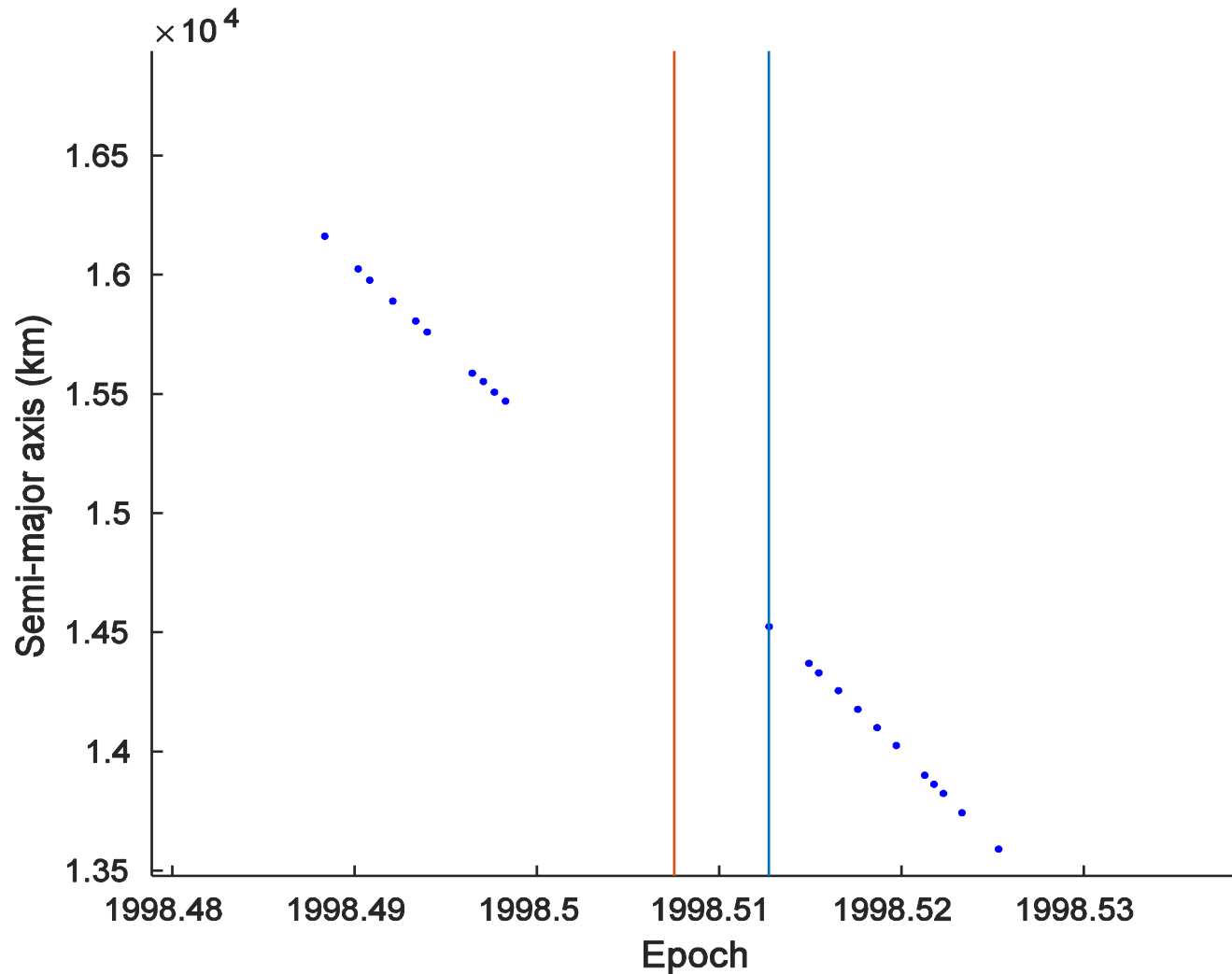
# Effects of filtering on prediction accuracy



# When we filter too many TLEs

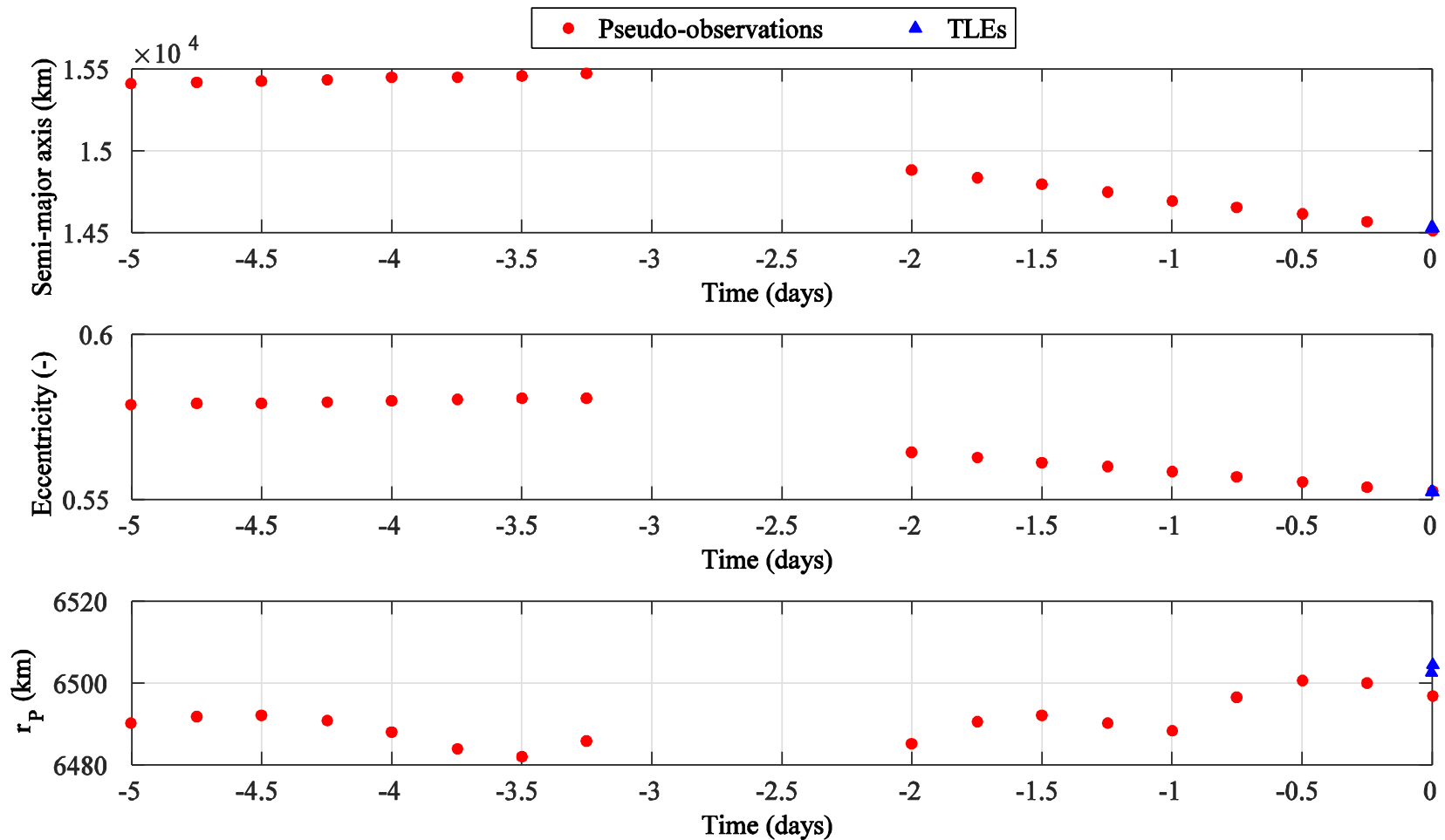


# When we filter too many TLEs

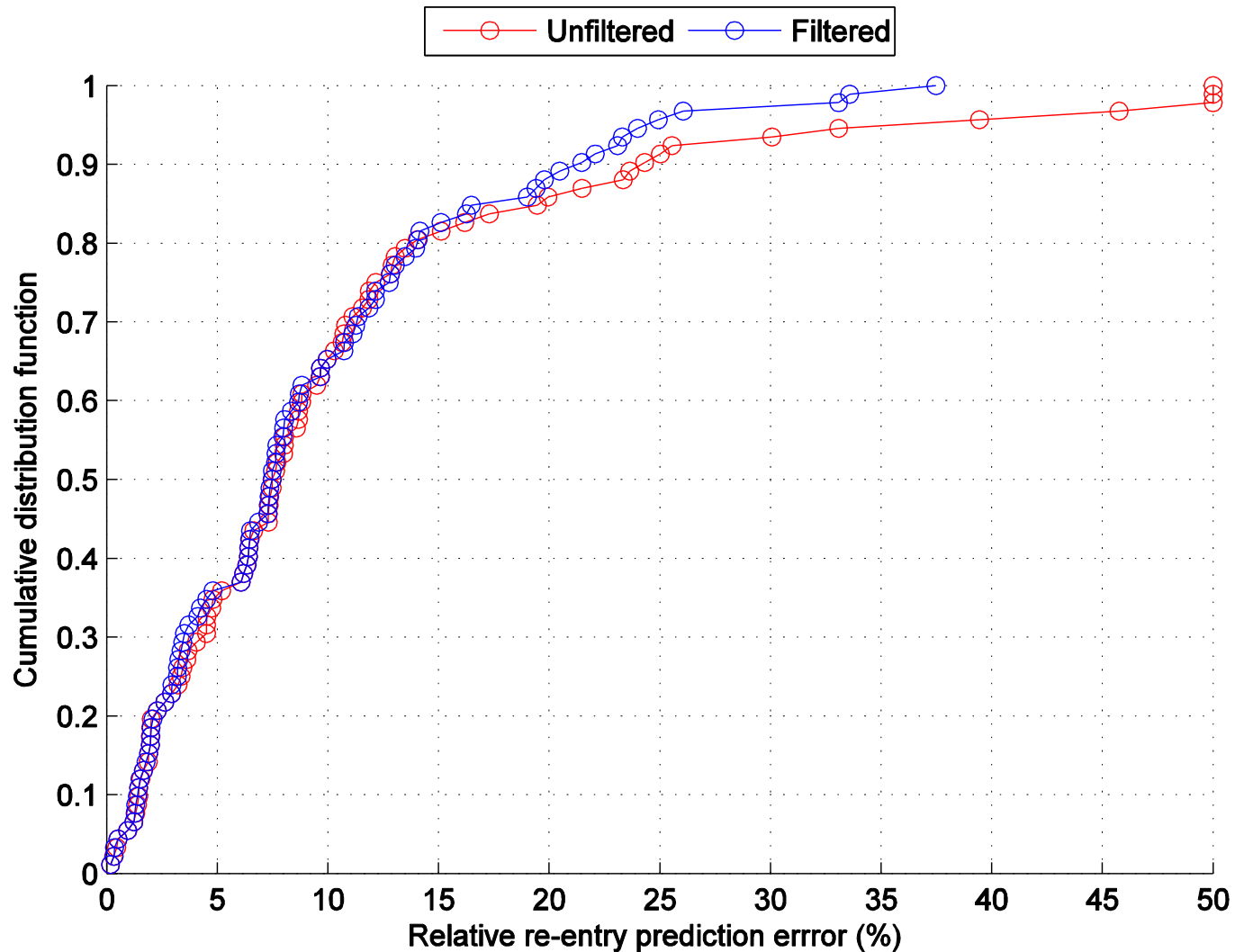




# When we DO NOT filter TLEs



# Importance of filtering



# Conclusions and recommendations

- Filtering of the TLEs is key to get good predictions, however it isn't always necessary
- Filter in all orbital elements you're using
- Be wary that the TLEs change with time (2011, 2013...)
- Outliers => robust statistics

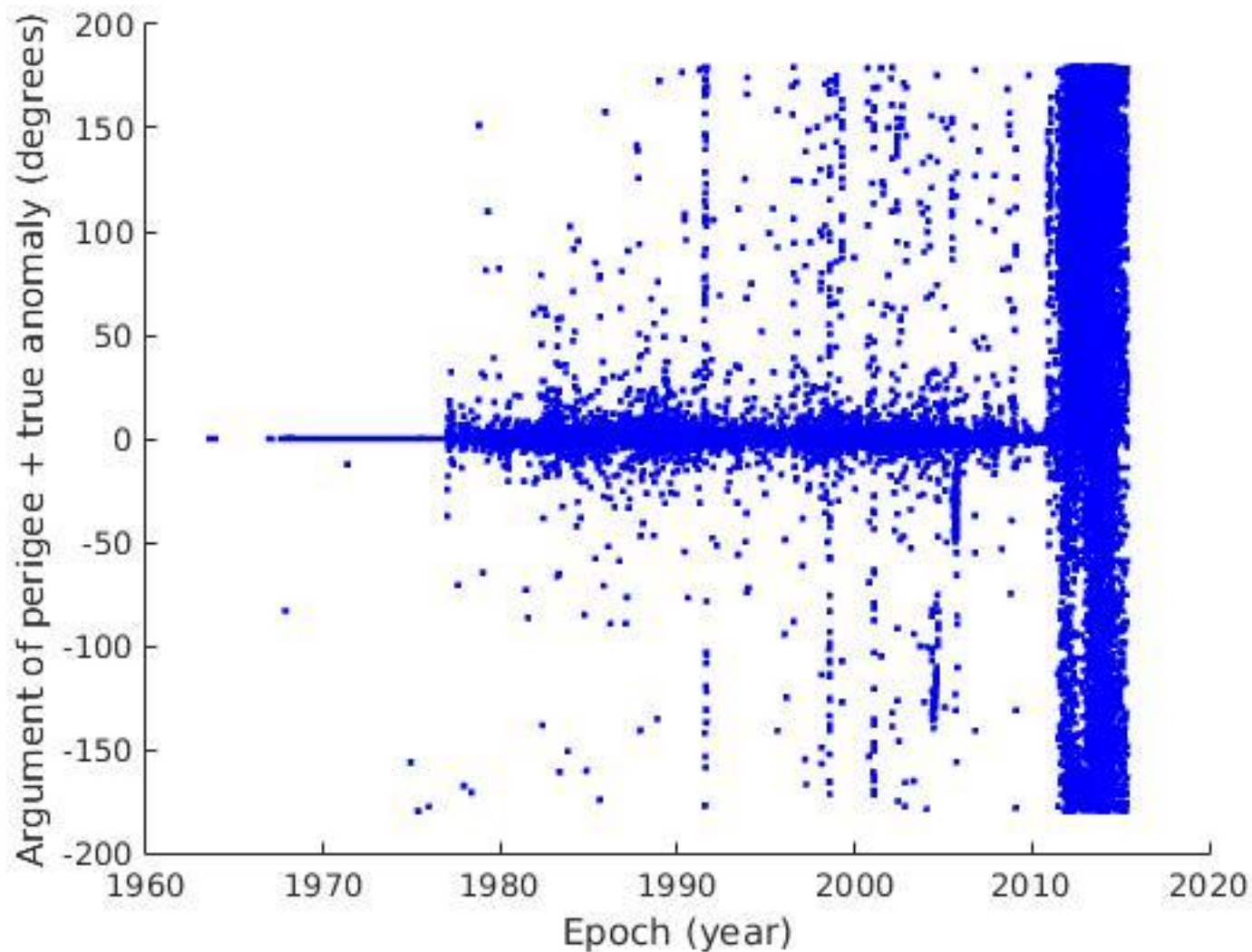
# Contact:

Aleksander Lidtke  
Astronautics Research Group  
Faculty of Engineering and the Environment  
University of Southampton  
Southampton SO17 1BJ  
United Kingdom

: [al11g09@soton.ac.uk](mailto:al11g09@soton.ac.uk)

: [www.aleksanderlidtke.com](http://www.aleksanderlidtke.com)

# Changes in TLE generation process



# Why do we care



16 Mar 2016

6<sup>th</sup>

nd

30

Image credit: NASA

# We don't know the re-entry epoch too well



24 hours lead time.

# We don't know the re-entry epoch too well



48 hours lead time.



# We don't know the re-entry epoch too well



74 hours lead time.