Space Tug Presentation for Clean Space Industrials days

Michel Frezet May 24th, 2016



Space tug concept and time for opportunity

What?

- Reusable in-orbit carrier to ferry and service satellites
- Paradigm change in access-to-space inspired from terrestrial logistics model

Why possible Now in Europe?

- Rendez-vous experience
- Electric propulsion and Power upgrade
 - Robotics progress

Why is it interesting?

- Reusability: for launcher and orbital vehicle
 - More payload or faster TTO
 - Make new orbit access possible
- Tug = ProxOps & mating = On Orbit services easy

What for ?

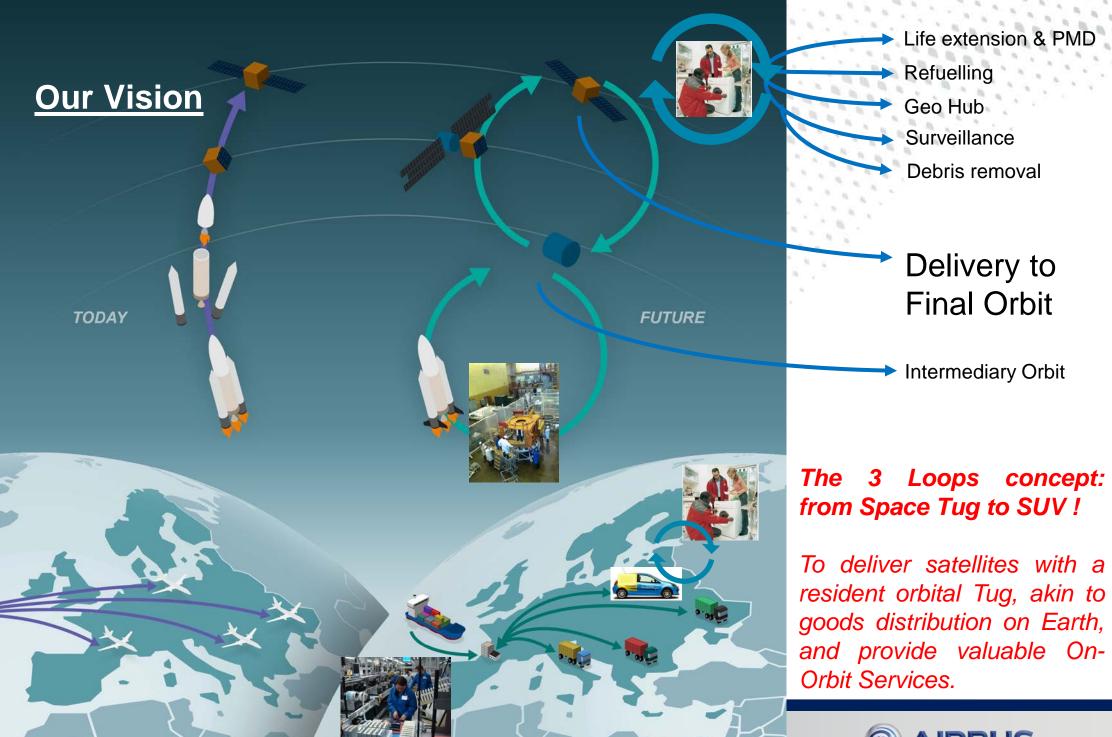
- Human exploration
- Satcom, constellations delivery
 - Satellite servicing,
 - Active Debris Removal



Why Airbus D&S?

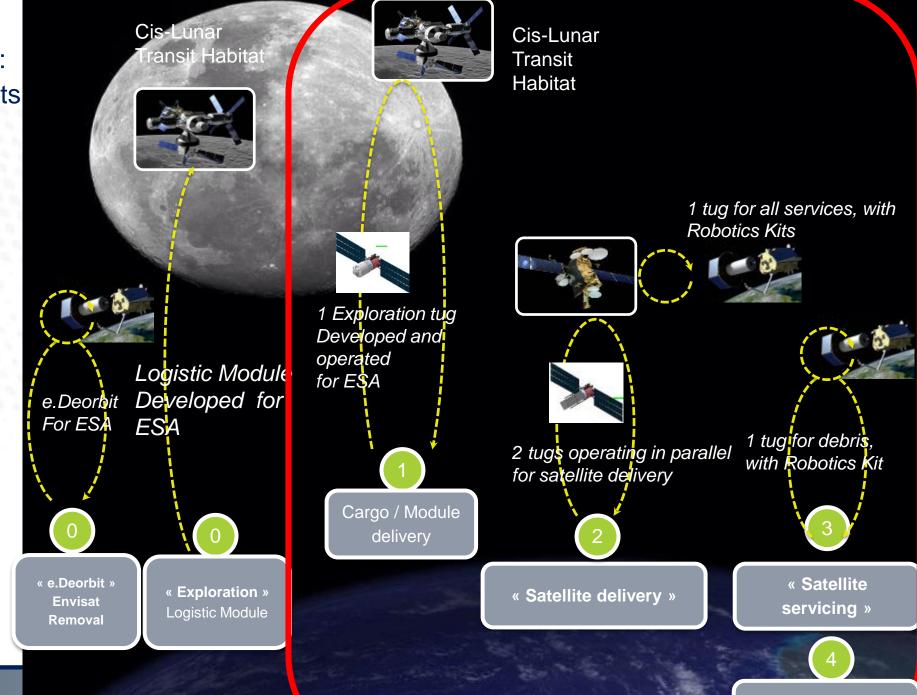
- ATV and MPCV
- Telecom EOR
- E3000 and Astrobus
 - Robotics Lab







The Space Tug: market segments and operational scenario



Debris removal

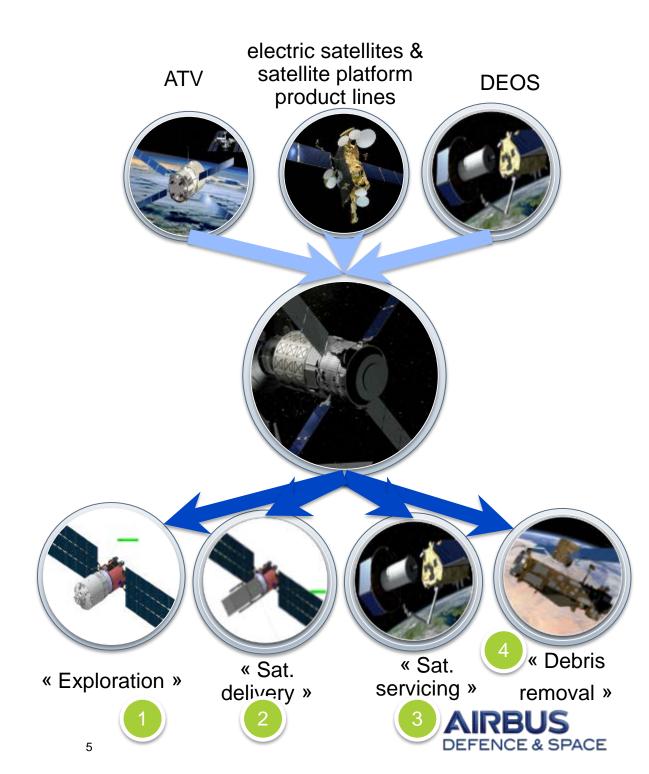
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Product Line approach

Heritage

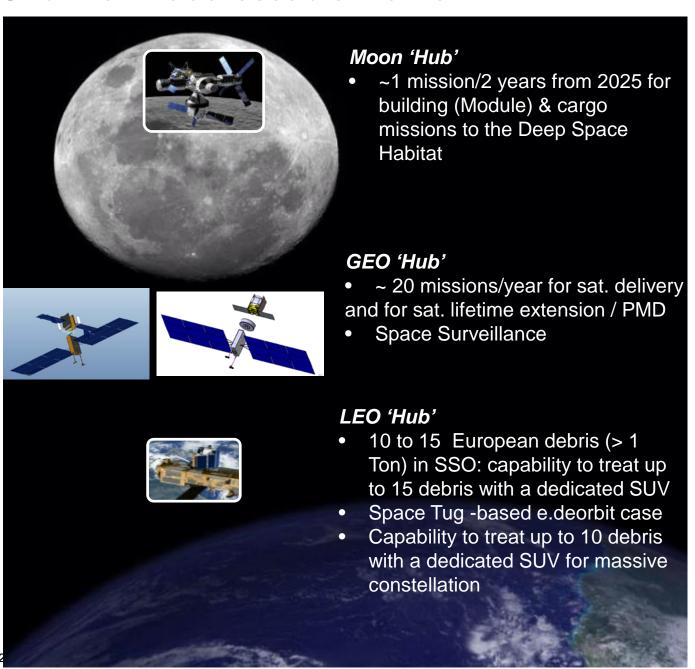
Generic platform and common technologies (e.g. high thrust electric propulsion, Power management, solar arrays, radiation, Rendez-vous, robotics)

Product Line with Customised vehicle by application



May 26, 2016

Short-term addressable market





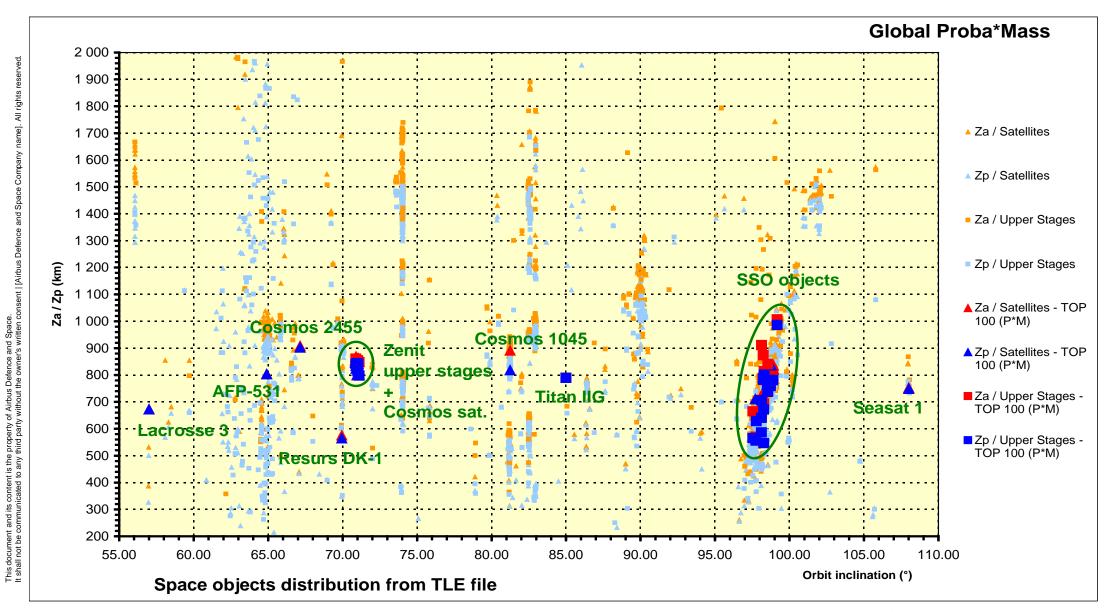
Zoom on Active Debris Removal

- Rendez-vous approach common: compatible with product line, including e.deorbit
 - ☐ cooperative (or designed for) / uncooperative
 - Quiet debris with on-purpose handling system
 - Quiet debris with accessible launcher interface
 - Quiet debris with no accessible handling
 - Tumbling debris: fly-around, capture (i.e. specific propulsion and capture kit)
 - ☐ Capture with arm or with alternative methods (net, harpoon,...) & « tethered » motion
 - □Natural demise or controlled re-entry
 - o Transfert and leave at 400 km / 500 km tbc
 - o Transfert and boost with the debris or leave with deorbit kit



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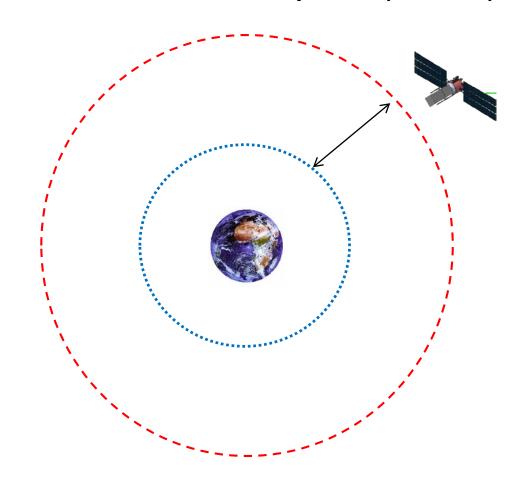
TOP 30 satellites on 2012 TU-Braunswick list





Reaching SSO Debris challenge: tackling Orbit Plan change

Different altitude **loitering** orbit on given **duration** for **RAAN natural drift** adaptation (J2 effect)



Assumptions:

- Stand-alone Tug
- Change plan with natural RAAN drift when different circular altitude
- S/C deorbitation assumption: Tugging to 400 km / 500 km orbit for natural erosion (natural demise)
- Alternative: deorbit kit when necessary



SSO Debris Removal mission with a Space Tug Delta-V analysis preliminary conclusions

- European '1st/2nd Priority' debris from Proba-Mass figure of merit are not randomly distributed in terms of RAAN
- Addressing '1st/2nd Priority' debris in a same mission is very interesting in terms of delta-V
- In those conditions, stand-alone SUV typical debris removal capability is as follows:
 - Up to 15 Major European debris capturable for one Tug
 - One Debris transported to 400 km / 500 km (for natural reentry) every 3 months
 - Interesting cost rough order of magnitude per debris



Massive constellation: the heterogeneous case with the SUV

Using a (several) resident multi-mission "Space Tug" chaser(s)

- Target S/C spin assumed controlled
- Dead S/C capture is performed with Space
 Tug robotic Arm (on serviced S/C launch interface or specific grappling feature)
- S/C tugged to a ~400 km / 500 km orbit destination. Uncontrolled de-orbitation with full natural demise
- Homogeneous constellation orbital planes & homogeneous failed target distribution is assumed
- Orbital plane transfer capability with altitude

Typical sizing and performances

- 30 kW prop power with 4,5t propellant
- Scenario 1 with one Space Tug
 - o On-demand service from a waiting orbital plane
 - o Can change 180° RAAN within 12 to 16 months
 - o 8 up to 20 missions
- Scenario 2 with 4 Space Tugs
 - Systematic visit of each plane once a year
 - 1 Tug can visit 1 plane every ~2-3 months
 - All planes can be serviced at 12 months period with a fleet of 4 Space Tugs



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