

Final Presentation

VERICOCOS STUDY

VERIFICATION OF COMPUTER- CONTROLLED SYSTEMS

7th December 2016

Speakers:

- **Elena Alaña (GMV)**
- **Richard Melvin (SCISYS)**

CONTENTS

- ❑ Introduction and objectives
- ❑ Study activities:
 - Space user needs
 - Survey of modelling languages and tools
 - Tool development framework
 - Training material
- ❑ Conclusions and future work

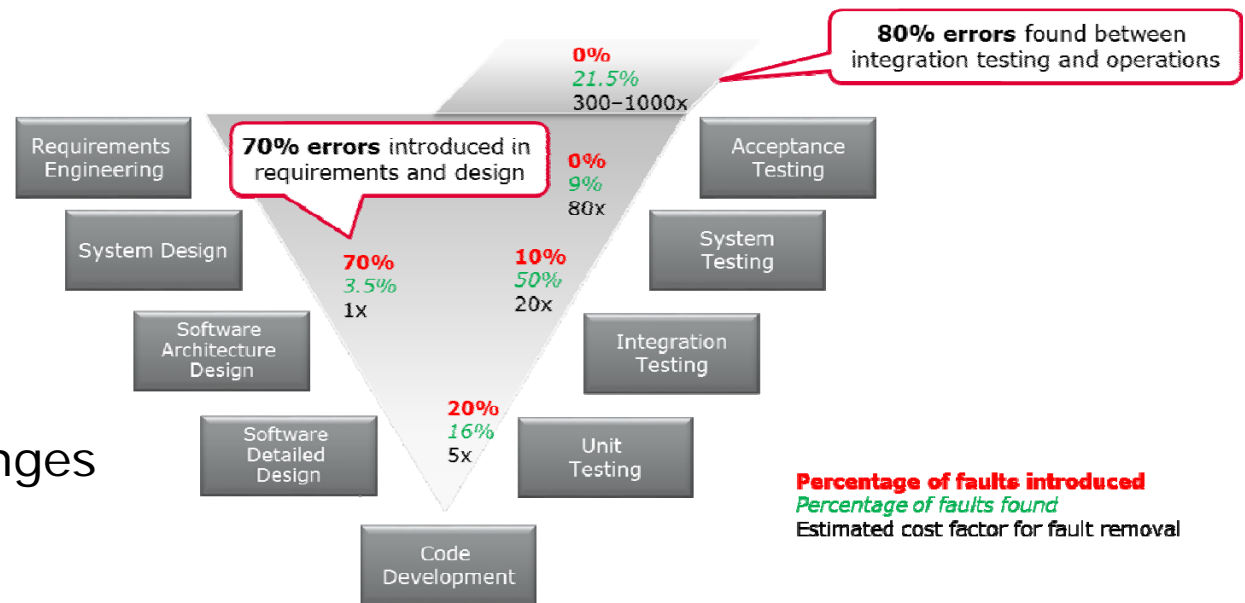
VERICOCOS - Final Presentation

INTRODUCTION AND OBJECTIVES



MOTIVATION BEHIND VERICOCOS

- ❑ Where are faults introduced?
 - Most errors are introduced during requirements and design phases
- ❑ Source of Requirements errors:
 - Bad requirements quality
 - Ambiguous
 - Incomplete
 - Incoherent
 - Inconsistent
 - Erroneous
 - Requirements changes
 - Design errors



MOTIVATION BEHIND VERICOCOS

- ❑ Good requirements management key factor for spacecraft development
- ❑ The most problematic sources of errors can be avoided or partially solved by improving the quality of the input specifications
- ❑ Requirements formats:
 - Textual requirements
 - Pseudo-code
 - Sequence diagrams
 - State machines

Behavioural modelling provides a more complete specification of requirements

VERICOCOS GOALS

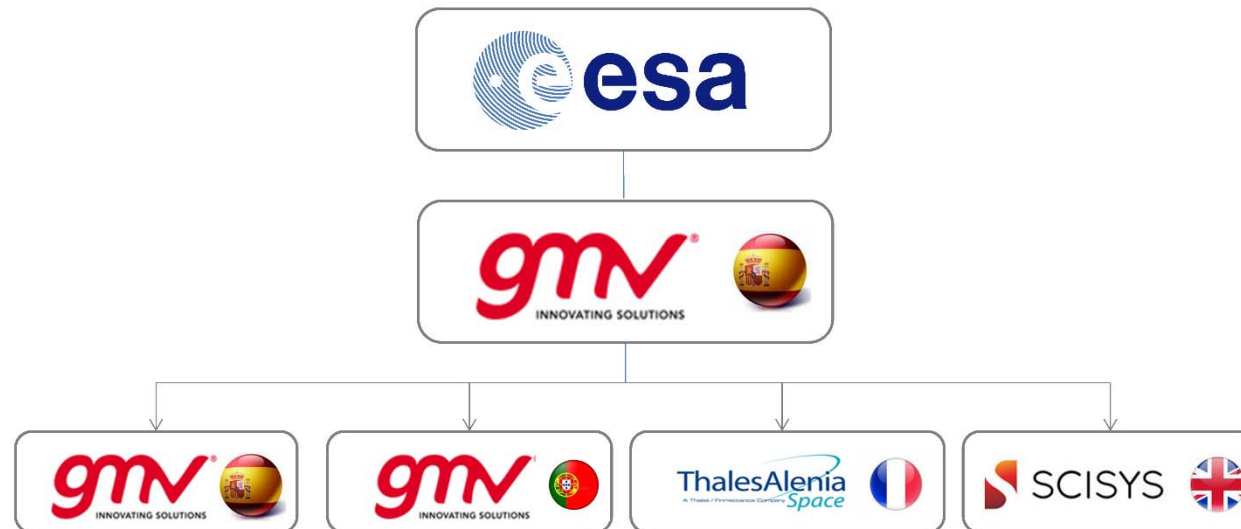
1. Confirm the applicability and subsequently open the door to the generalized use of **state machines** to the specification, design, verification and implementation of on-board software
2. Apply tools on a **space-representative case study**, and extend the tools if necessary to fit existing processes
3. Further develop and test behavioural and data modelling tools to support the implementation of **electronic data sheets**
4. Provide **training material** with the result of the study to disseminate the acquired knowledge and know-how on the topic of behavioural modelling

CONSORTIUM

❑ ESA TO: Maxime Perrotin

❑ Consortium:

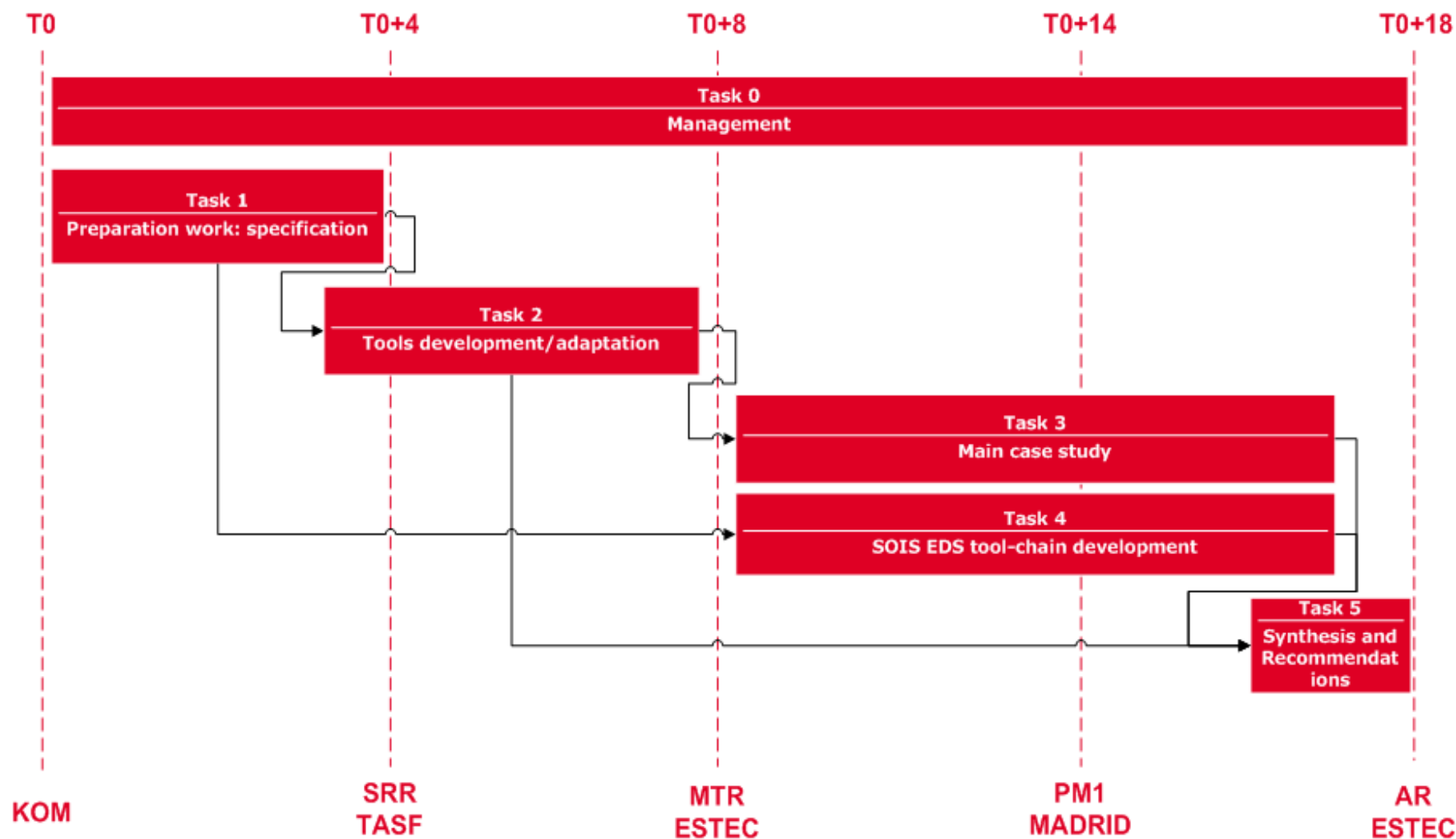
- GMV Aerospace and Defence, S.A.U. (Prime Contractor)
- GMV Skysoft S.A. Portugal
- Thales Alenia Space – France
- SCISYS UK Ltd



TECHNICAL SHARING

COMPANY	TECHNICAL RESPONSIBILITIES
GMV-ESP	<ul style="list-style-type: none"> ▪ Project management ▪ Technical coordination and responsible for: <ul style="list-style-type: none"> ○ The design of the tool architecture ○ The implementation and analysis of the case study ○ Dissemination activities ○ Project global assessment and synthesis of the results
TASF	<ul style="list-style-type: none"> ▪ Analysis of behavioural modelling on ESA operational projects ▪ Analysis of modelling languages and tools for behavioural modelling ▪ Preliminary specification of the case study ▪ Global assessment as System Integrator
GMV-POR	<ul style="list-style-type: none"> ▪ VERICOCOS tool chain: <ul style="list-style-type: none"> ○ Tool development and integration ○ Verification ○ Generation of documentation and guidelines to use the tool in the case study
SCISYS	<ul style="list-style-type: none"> ▪ SOIS EDS tool chain: <ul style="list-style-type: none"> ○ Analysis of the ESA internal SOIS EDS study ○ Specification and extension of the ESA SOIS EDS tool chain ○ Validation of the EDS concept on a real test case

WORK FLOW



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STUDY ACTIVITIES

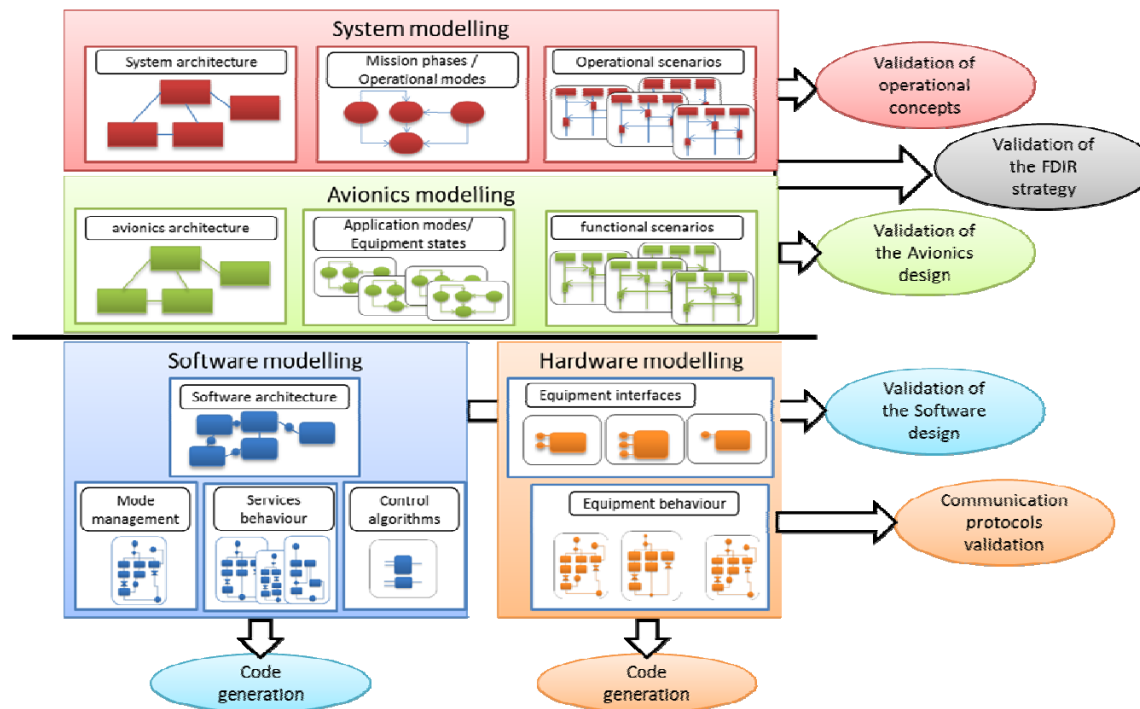


STUDY ACTIVITIES

1. Specification of **Space User Needs** for behavioural modelling
2. Survey of modelling **Languages and Tools**
3. Implementation of a **Tool Development Framework**
 - VERICOCOS Toolchain
 - SOIS EDS Toolchain
4. Elaboration of **Training Material**

SPACE USER NEEDS (1/2)

- Evaluation of state machines for developing embedded SW:
 - Improves the requirements quality (correctness, completeness, coherency)
 - Benefits are not the same at each development phase



SPACE USER NEEDS (2/2)

□ Specification of **user needs for behavioural modelling**

- Modelling levels:
 - System modelling level
 - Avionics modelling level
 - Software modelling level
 - Hardware/Equipment modelling level
- Technology agnostic
- Examples:

ID	User Need	Level
[MLR.2]	The VERICOCOS toolchain shall allow to model the system mission phases.	System
[VOR.3]	The VERICOCOS toolchain shall allow to associate a state machine to the software components (implementation) having a behaviour designed with state machine.	Software
[CGR.1]	The VERICOCOS toolchain shall allow to generate code from state machines and procedure models associated to software components in the software detailed design model.	Software

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SURVEY LANGUAGES AND TOOLS (1/2)

□ Goal:

- Find languages and tools suitable for most of the space user needs

□ Survey of **languages and tools** that can cover those needs

■ Languages:

- Focused on SDL
- Background concepts of other languages: UML, AADL, SysML, etc.
- Rated with respect to the modelling needs:
 - Compliance with respect to System/SW/HW modelling needs, aligned on a standard, non-proprietary language, graphical notation, etc.

■ Tools:

- Existing modelling tools are described such as TASTE, OpenGEODE, AAML Editor and Capella Editor
- Rated according to the tool needs:
 - Maturity level, maintainability and long-term support, user manual quality, scalability, separation of concerns, etc.

SURVEY LANGUAGES AND TOOLS (2/2)

□ Selection:

■ System and Avionics modelling:

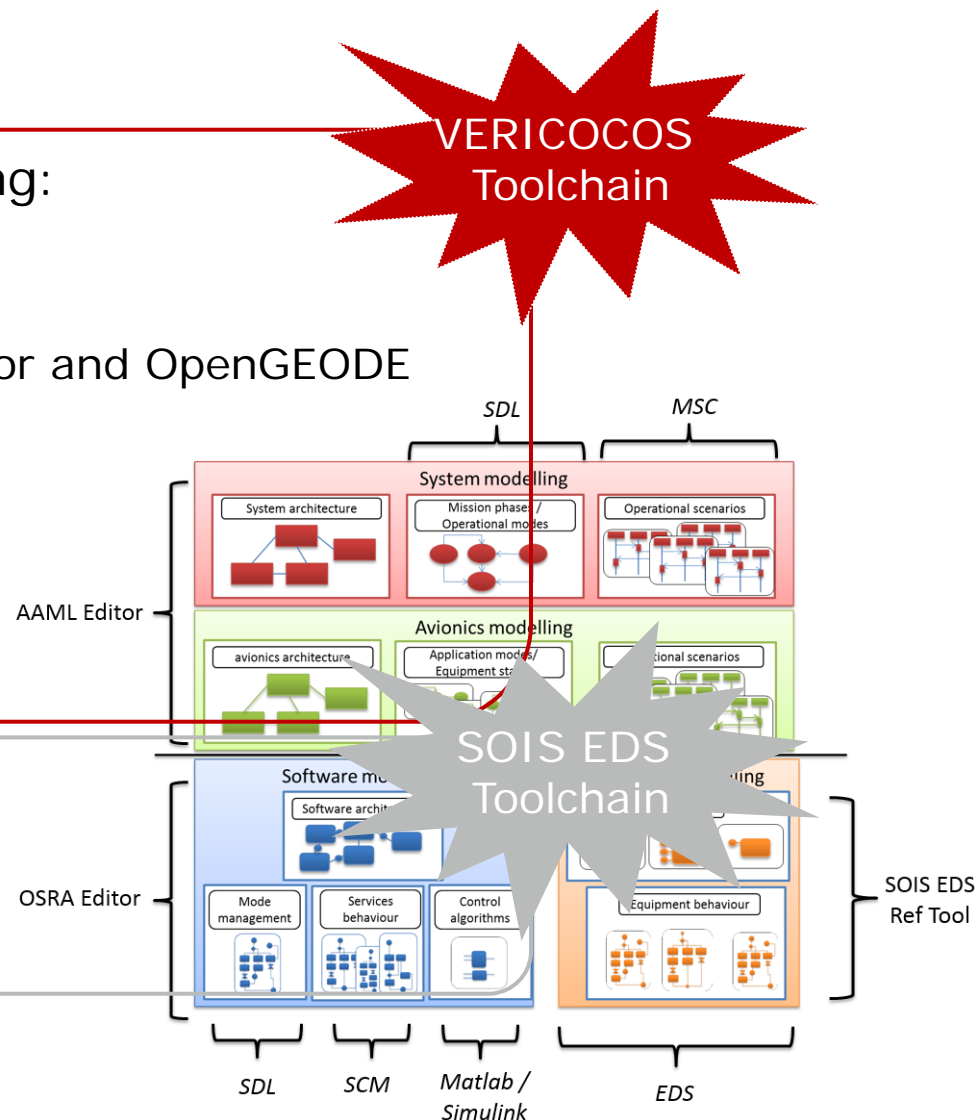
- Languages: AAML and SDL
- Tools: AAML Editor, MSC Editor and OpenGEODE

■ Software modelling:

- Languages: SCM and SDL
- Tools: OSRA Editor and OpenGEODE

■ Hardware modelling:

- EDS with TASTE integration for code generation

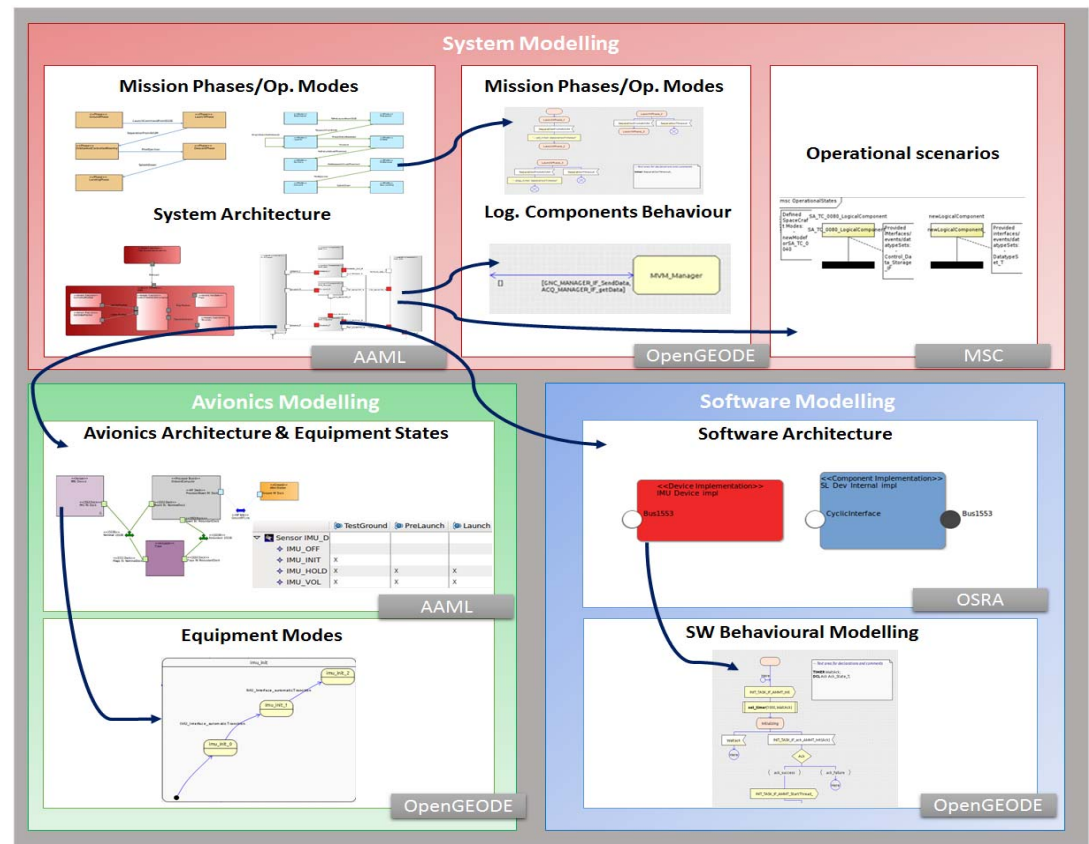


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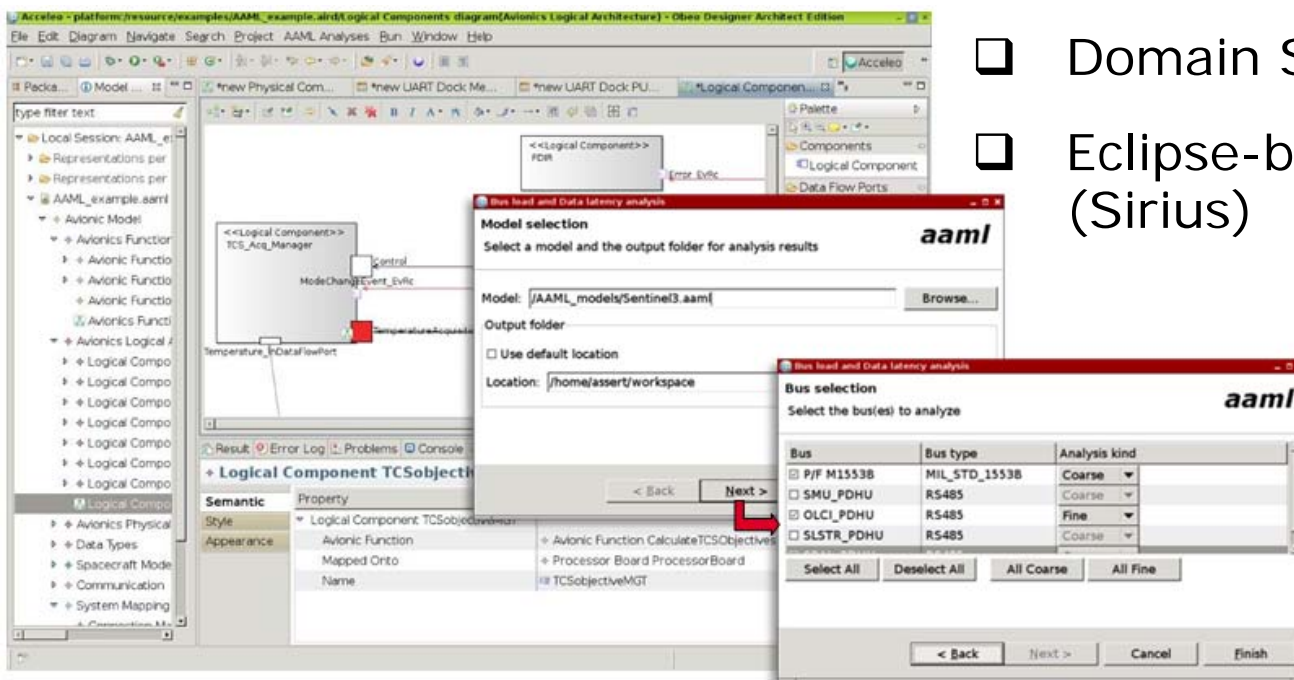
VERICOCOS TOOLCHAIN

- ❑ Modelling levels:
 - System & Avionics
 - Software
- ❑ Based on:
 - Model-Based Development
 - Modelling views



SYSTEM AND AVIONICS MODELLING

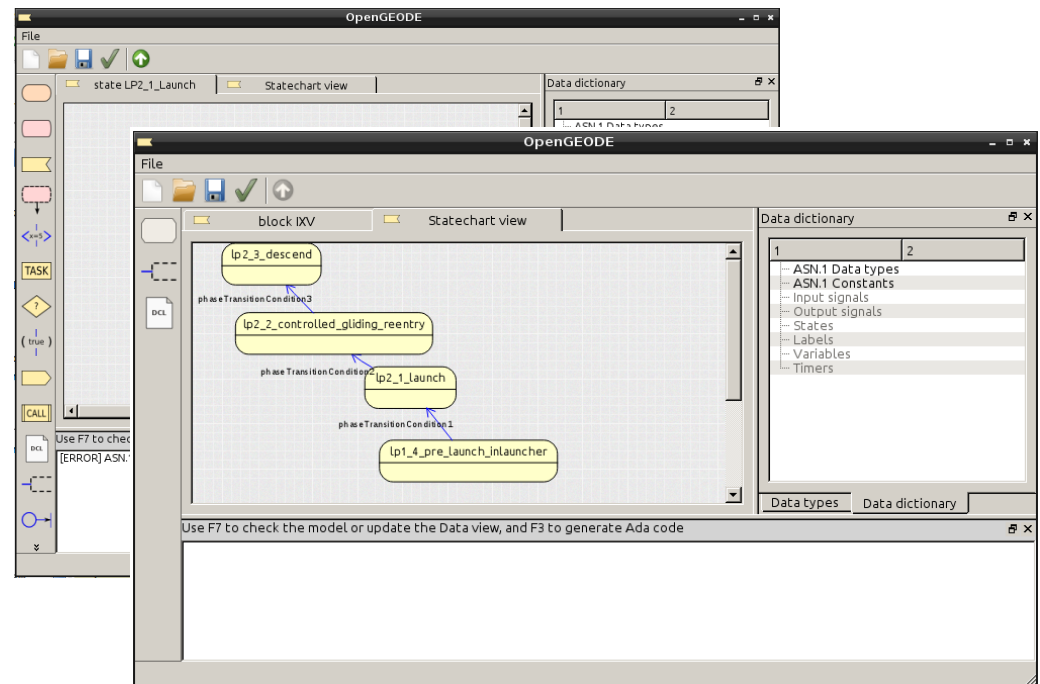
- ❑ The **AAML Toolset (Avionics Architecture Modelling Language)** aims at advancing the avionics engineering practices towards a model-based approach
- ❑ Coarse- and fine-grained specification of the avionics architecture and non-functional properties



- ❑ Domain Specific Language
- ❑ Eclipse-based toolset (Sirius)

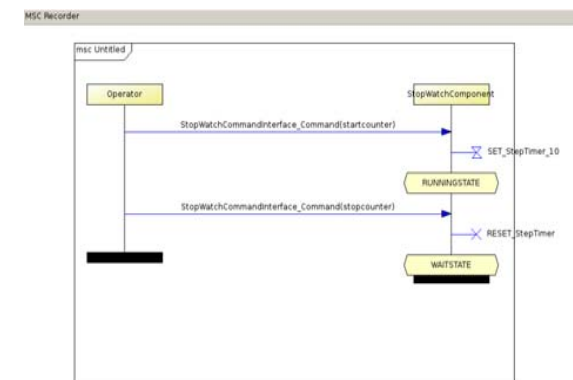
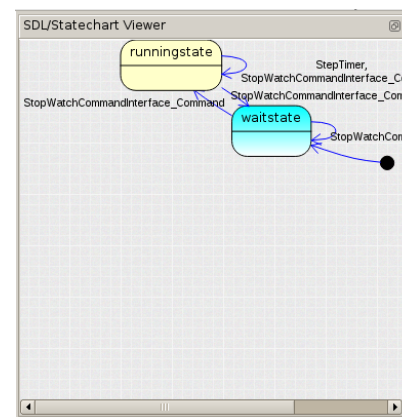
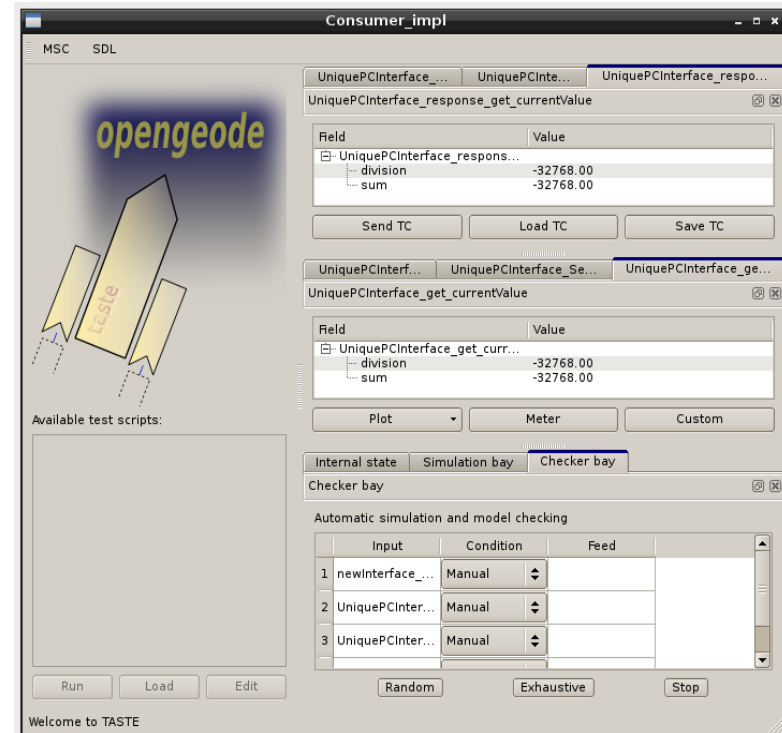
OPENGEODE TOOL

- ❑ OpenGEODE is an SDL editor (Specification and Description Language) part of ESA **TASTE (The ASSERT Set of Tools for Engineering)**
- ❑ SDL is a mature ITU standard, formal behaviour specification of complex systems through state machines
 - Behavioural modelling through rich state machines
 - Textual and graphical notations
- ❑ OpenGEODE implements a safe SDL subset for OBSW development



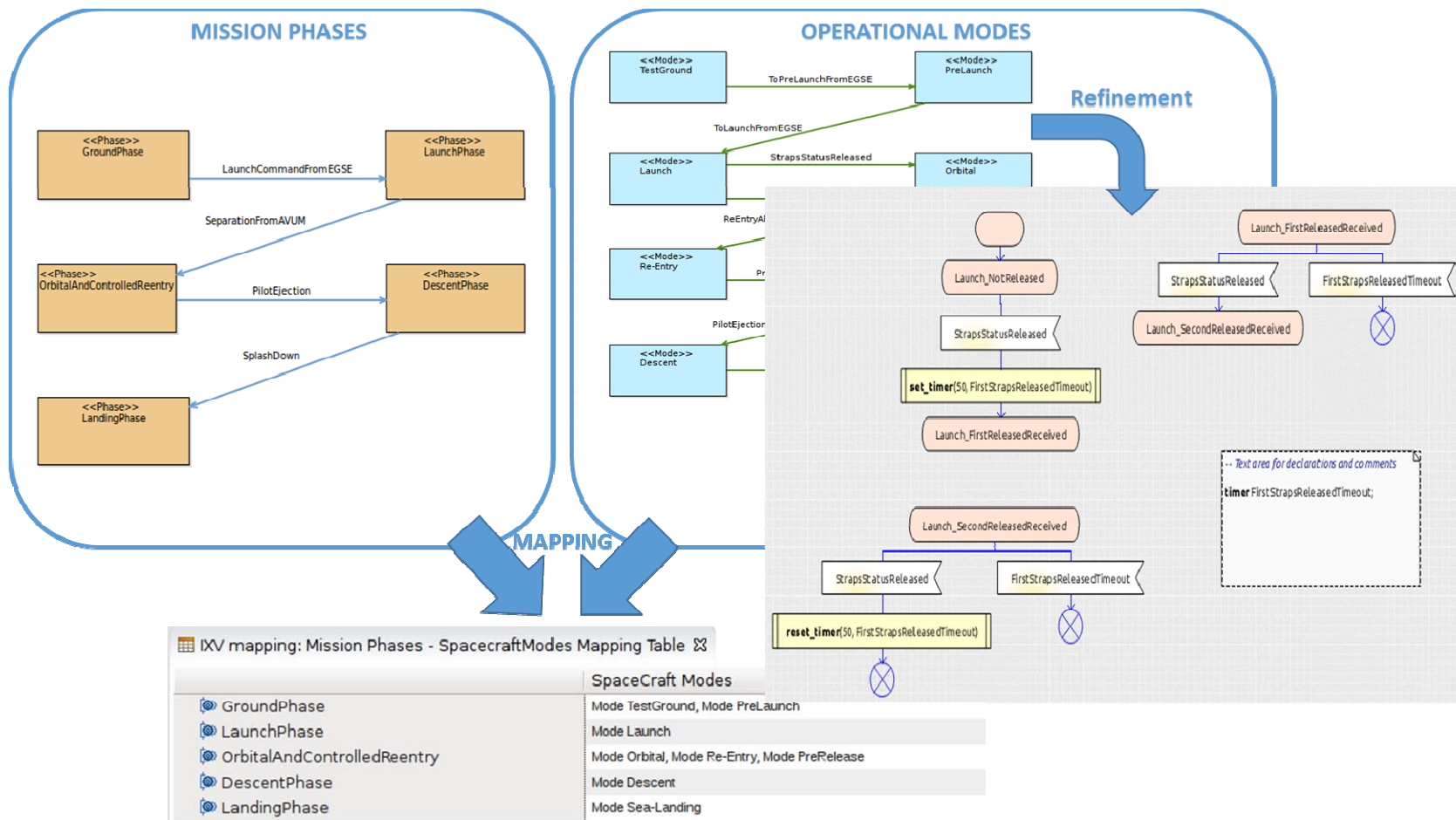
OPENGEODE FEATURES

- ❑ SDL Editor
 - State machine viewer
- ❑ SDL Checker
 - Correctness & safety checks
- ❑ Animation and simulation
 - Inject signals
 - Debugging capabilities
 - Store simulated behaviour as sequence diagram (MSC)
- ❑ Code generation
 - C and Spark Ada



UPDATES AT SYSTEM & AVIONICS LEVEL

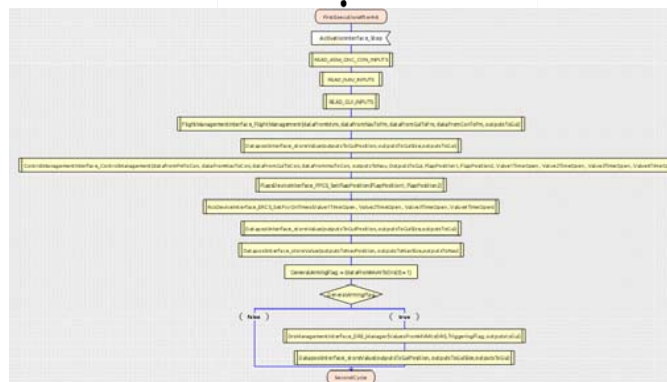
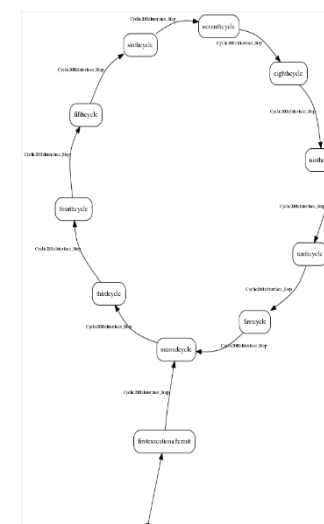
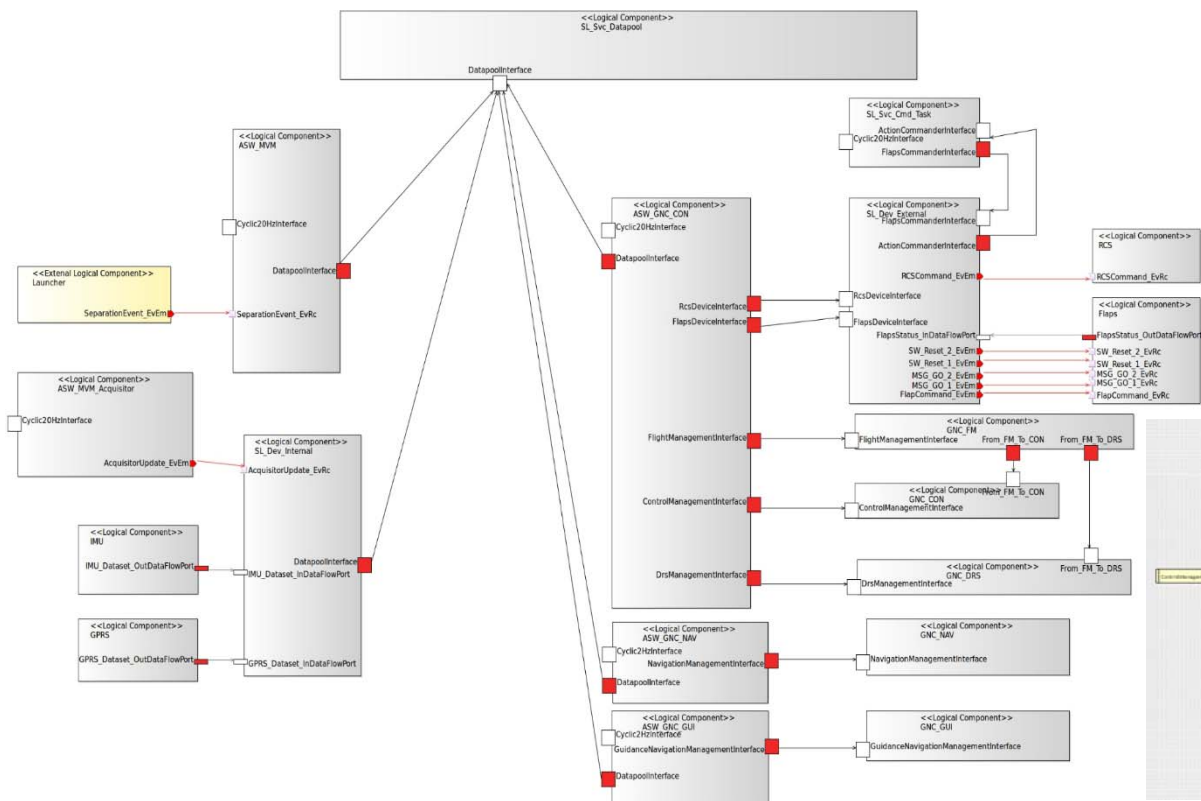
Formalization of **mission phases** and **operational modes**:



UPDATES AT SYSTEM & AVIONICS LEVEL

Logical architecture

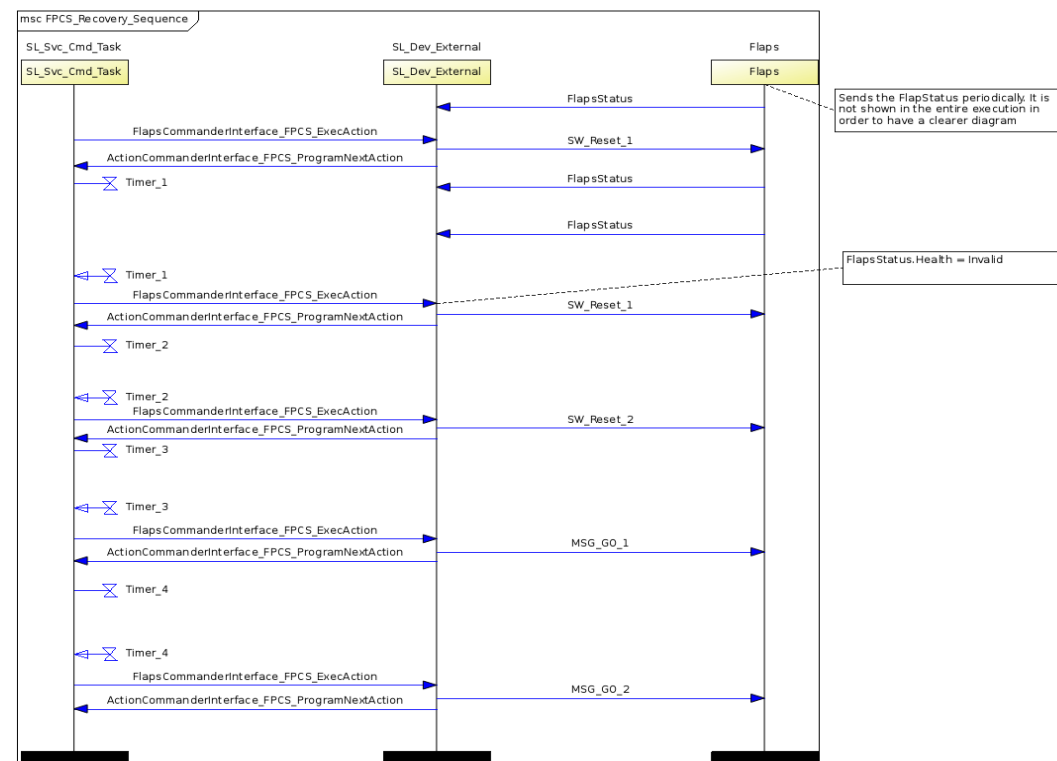
- Dynamic behaviour of logical components (OpenGEODE)
 - Functionality subset used in the mission



UPDATES AT SYSTEM & AVIONICS LEVEL

□ Logical architecture

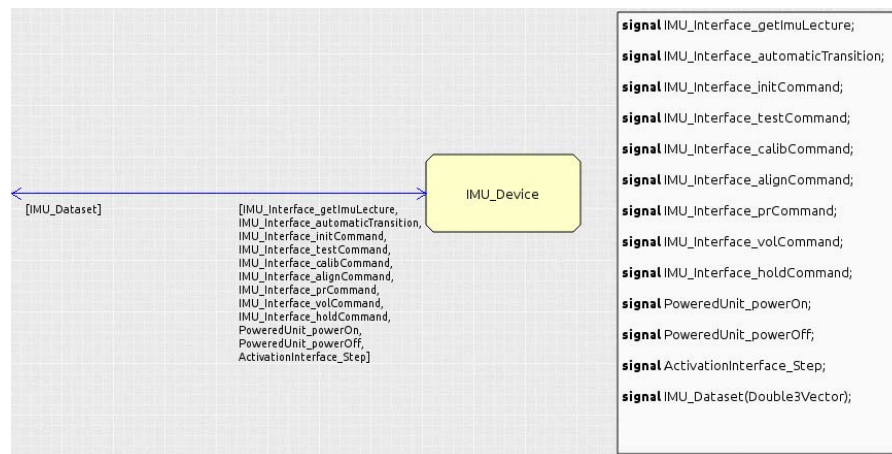
- Inter-component scenarios (MSC Editor):
 - Operational scenarios (nominal mission sequences)
 - FDIR scenarios (fault detection and recovery sequences)



UPDATES AT SYSTEM & AVIONICS LEVEL

Physical architecture:

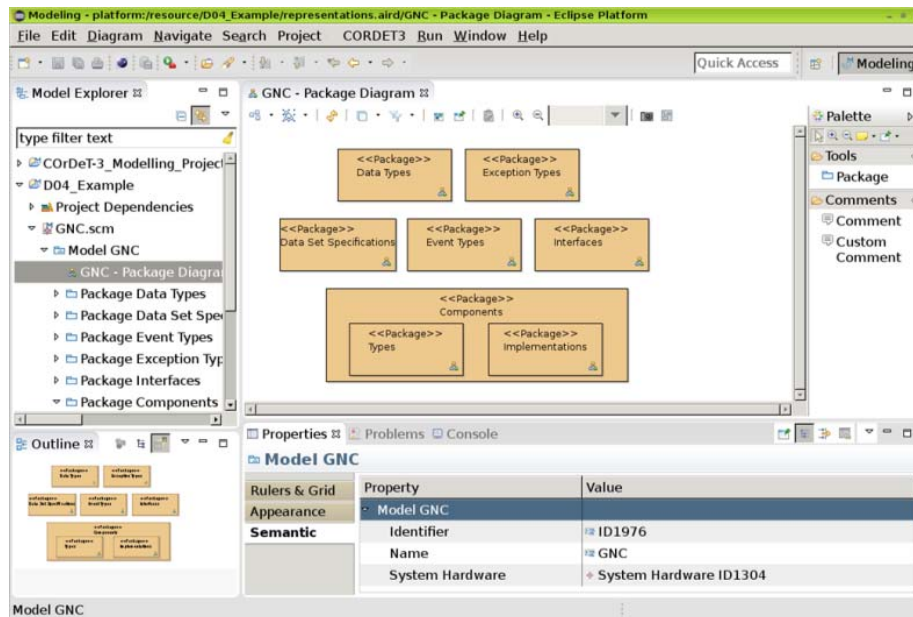
- Behaviour of physical devices
 - Complete dynamic aspects of the device
- Definition configuration
 - Definition of device states
 - Can be mapped to operational modes



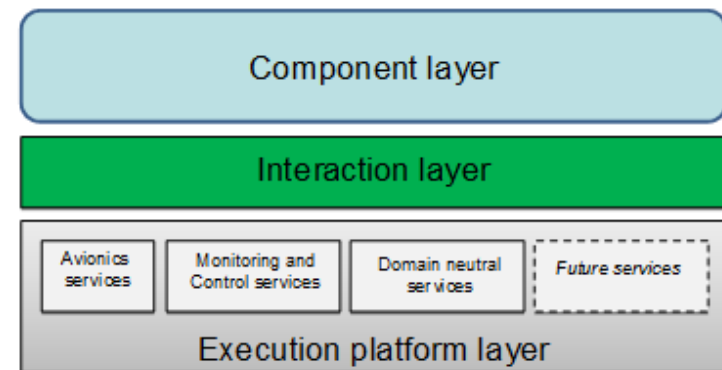
	TestGround	PreLaunch	Launch	Orbital	Re-Entry	PreRelease	Descent	Sea-Landing
▼ Sensor IMU_Device								
◆ IMU_INIT		X	X					
◆ IMU_HOLD		X	X					
◆ IMU_ALIGN		X	X					
◆ IMU_OFF	X							
◆ IMU_VOL				X	X	X	X	
◆ IMU_CALIB								
◆ IMU_PR								
◆ IMU_TEST	X							
▼ Actuator Flaps								
◆ ON		X	X	X	X	X	X	
◆ OFF	X							
◆ FAILED				X	X	X	X	

SOFTWARE MODELLING

- ❑ The ESA **OSRA Editor (On-board Software Reference Architecture)** assists the software architect and suppliers to design, develop, integrate, and generate the final executable
- ❑ Methodological approach for developing Space Applications (See OSRA Specification and Rational for further details)

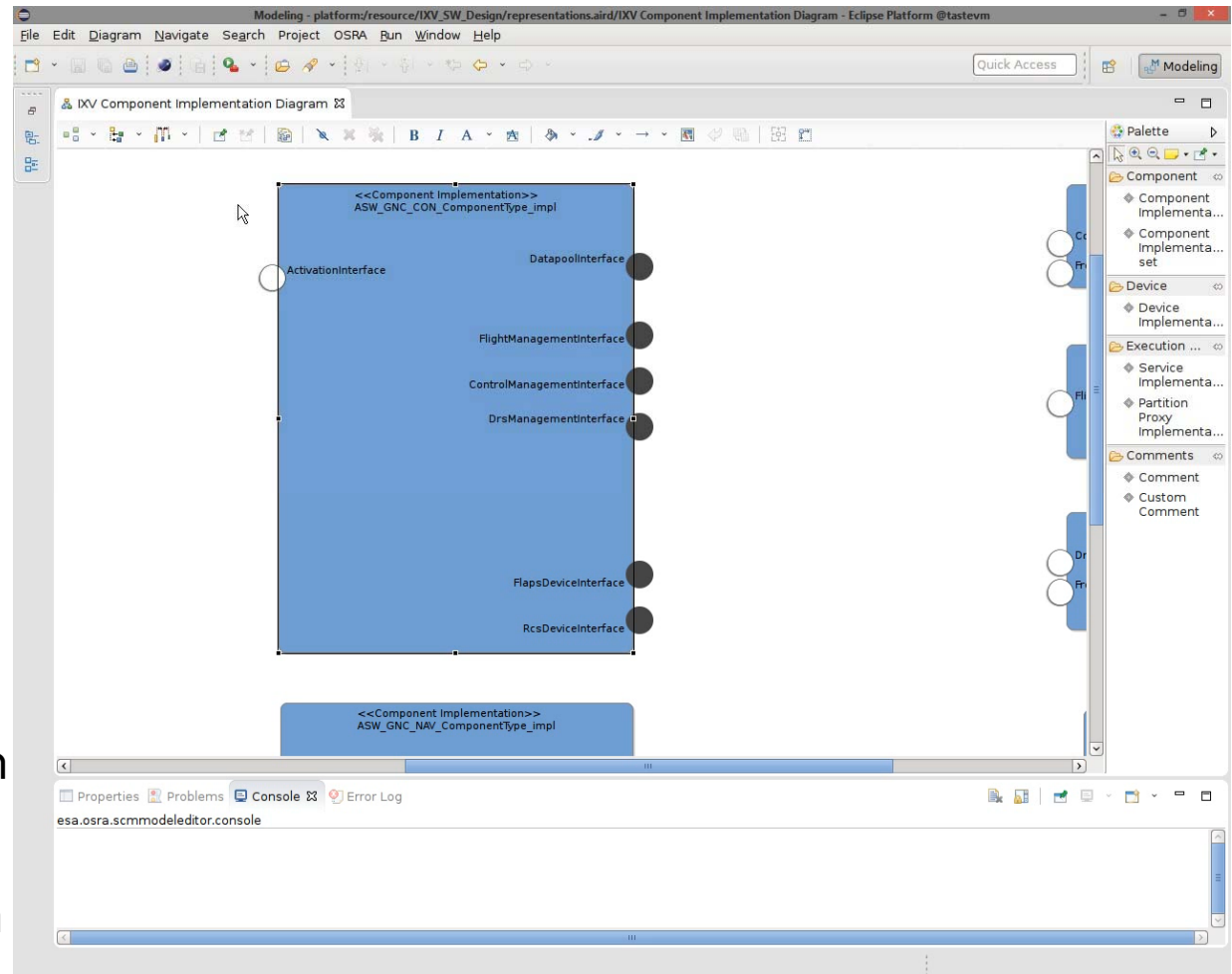


- ❑ Domain Specific Language (Space Component Model)
- ❑ Eclipse-based toolset (Sirius)

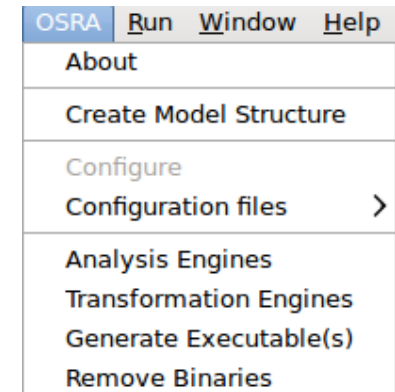


UPDATES AT SOFTWARE LEVEL

- ❑ Specification of the behaviour of component implementations
 - SDL language
 - OpenGEODE tool
- ❑ All communication entities defined in OSRA for the component, are available in the SDL diagram
- ❑ Datatypes translated into ASN.1 notation
- ❑ Code generation from SDL state machines
- ❑ Document generation



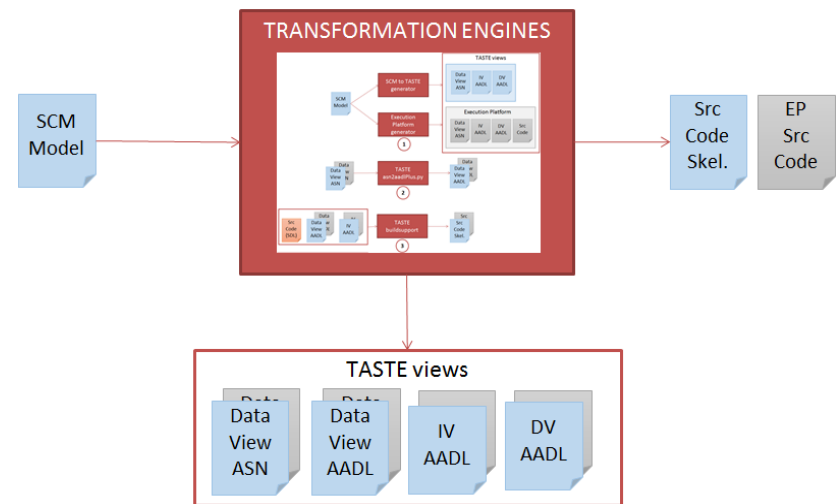
CODE GENERATION



- ❑ Code generation from the OSRA menu
 - Transformation Engines”: generates the source code skeletons of the OBSW
 - “Generate Executables” produces the OBSW binary(ies)

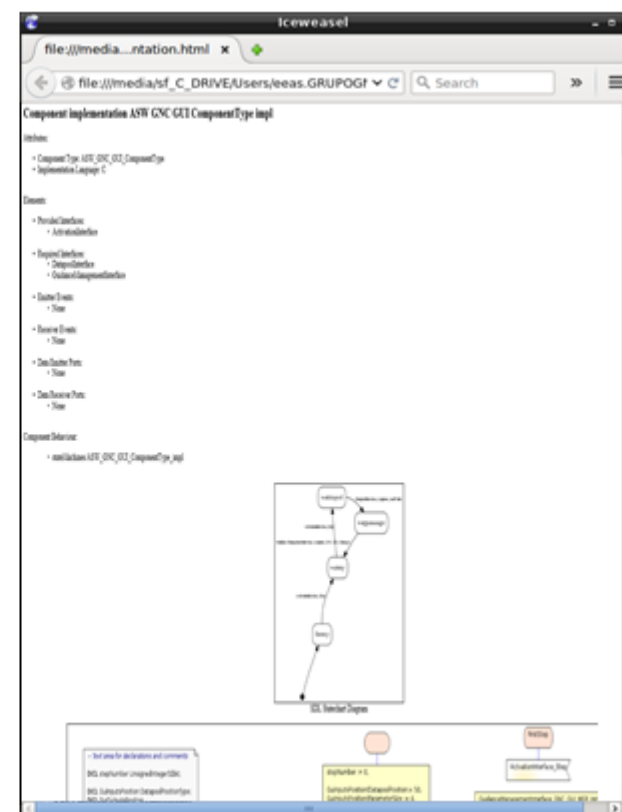
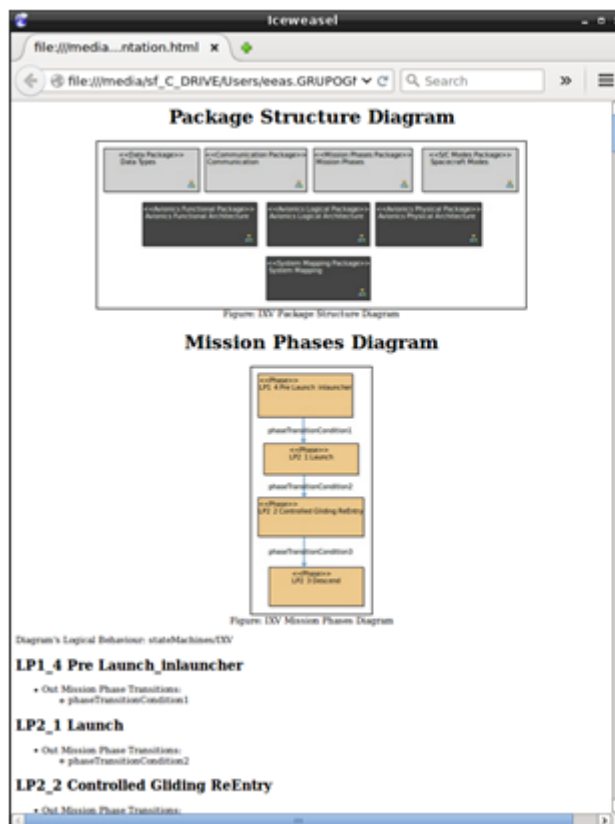
❑ The programming language is specified in the Components Implementation:

- Ada
- C
- SDL
 - Ada language skeletons
 - Skeletons automatically filled in with the source code of the associated state machines following this process



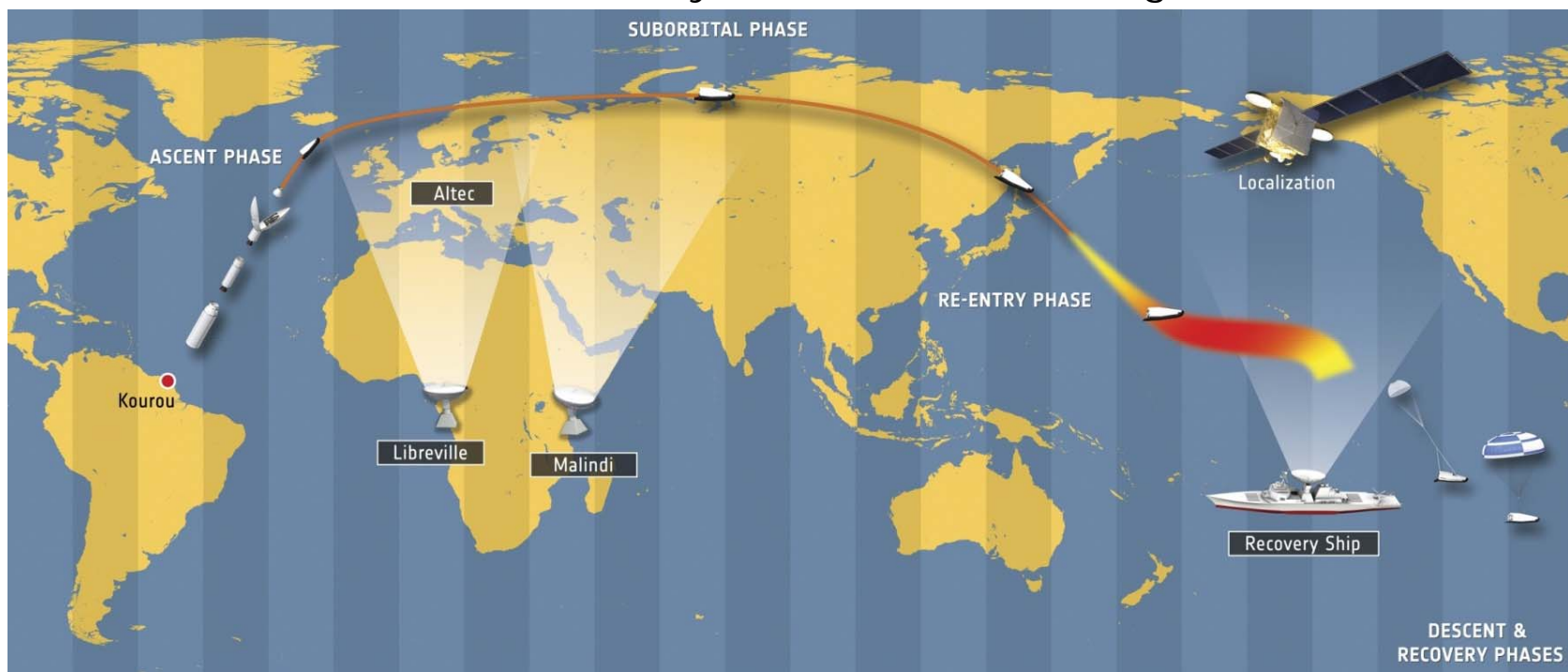
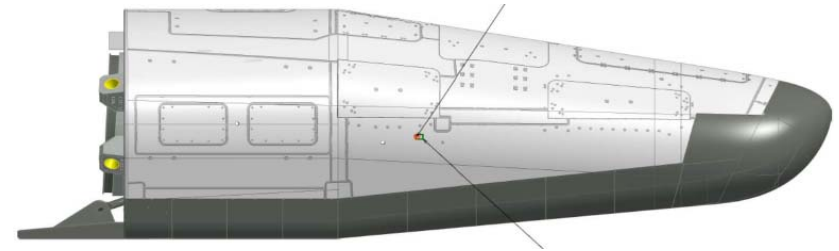
DOCUMENT GENERATION

- ❑ Proof-of-concept
- ❑ AAML and OSRA generates HTML, with all diagrams and tables
- ❑ To be tailored to specific documentation needs



INTERMEDIATE EXPERIMENTAL VEHICLE

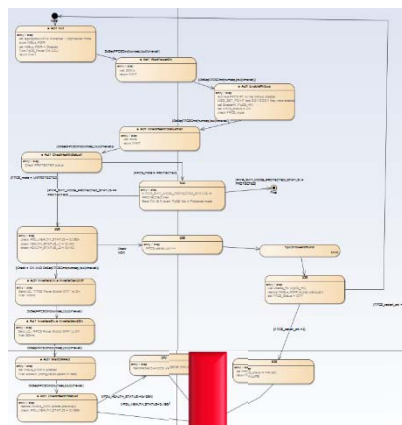
- ❑ Space vehicle to experiment on **atmospheric re-entry**
- ❑ Duration: around 100 min
- ❑ Fully-automated sub-orbital flight
- ❑ No pilot, passengers, nor TC
- ❑ TM monitored from ground, and recorded in vehicle
- ❑ Phases: Ascent, Orbital, Re-entry, Descent, Sea-landing



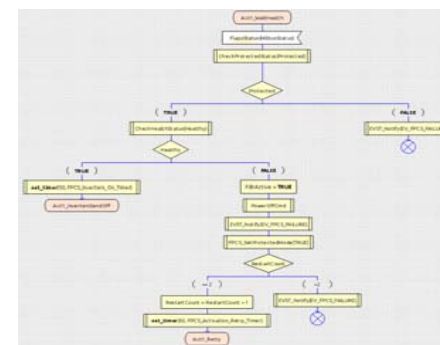
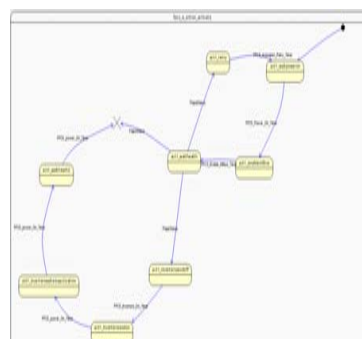
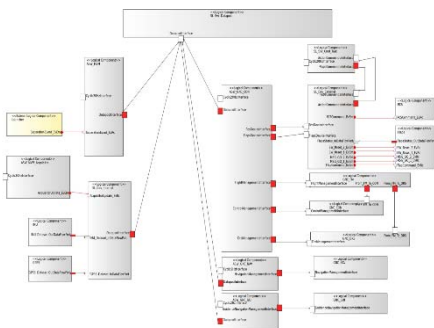
IXV CASE STUDY

IXV DATA

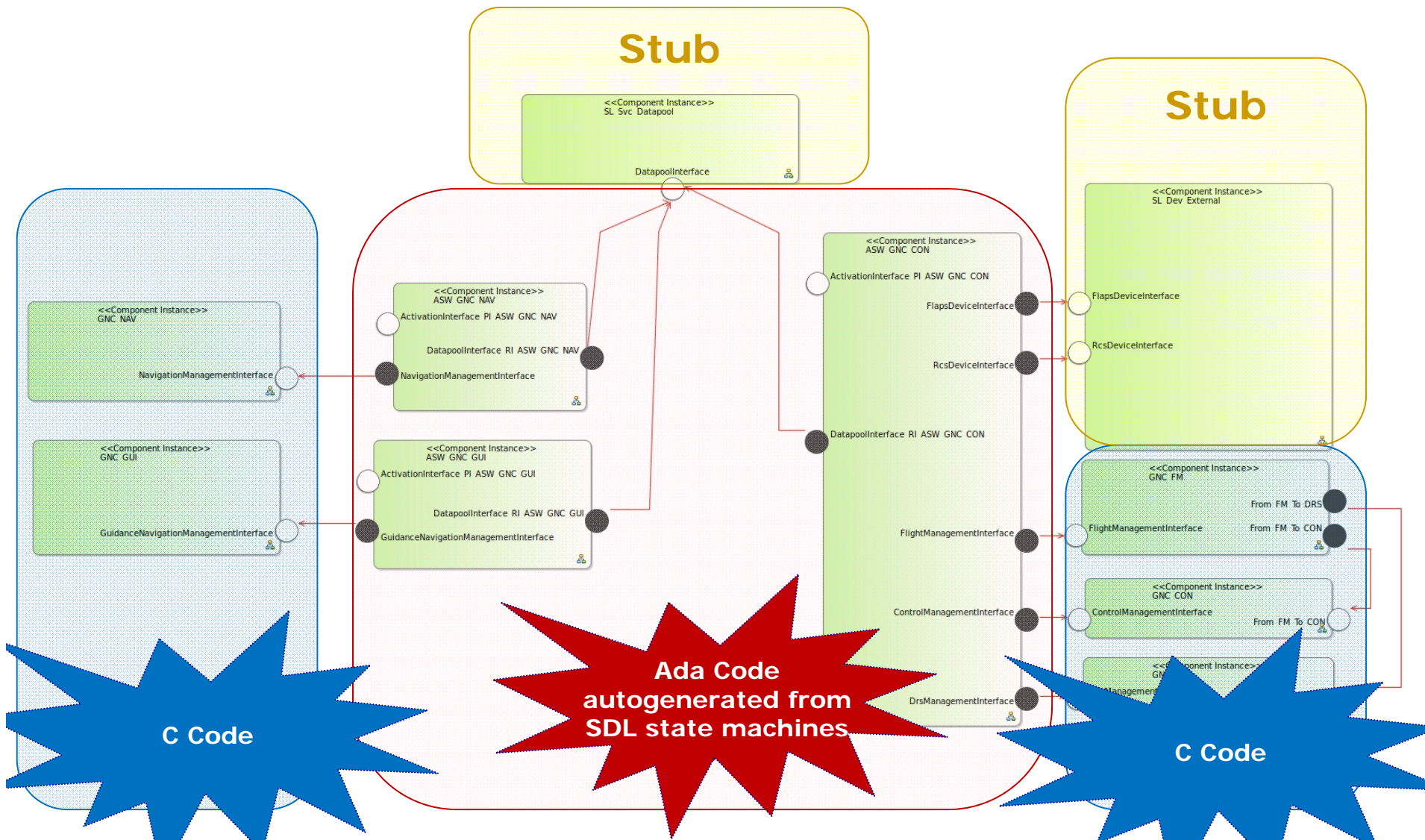
Phase	Task	Start	End	Status
Phase 1	Task 1.1	2011-01-01	2011-03-31	Completed
	Task 1.2	2011-04-01	2011-06-30	In Progress
	Task 1.3	2011-07-01	2011-09-30	Planned
Phase 2	Task 2.1	2011-10-01	2011-12-31	Completed
	Task 2.2	2012-01-01	2012-03-31	In Progress
	Task 2.3	2012-04-01	2012-06-30	Planned



VERICOCOS MODEL

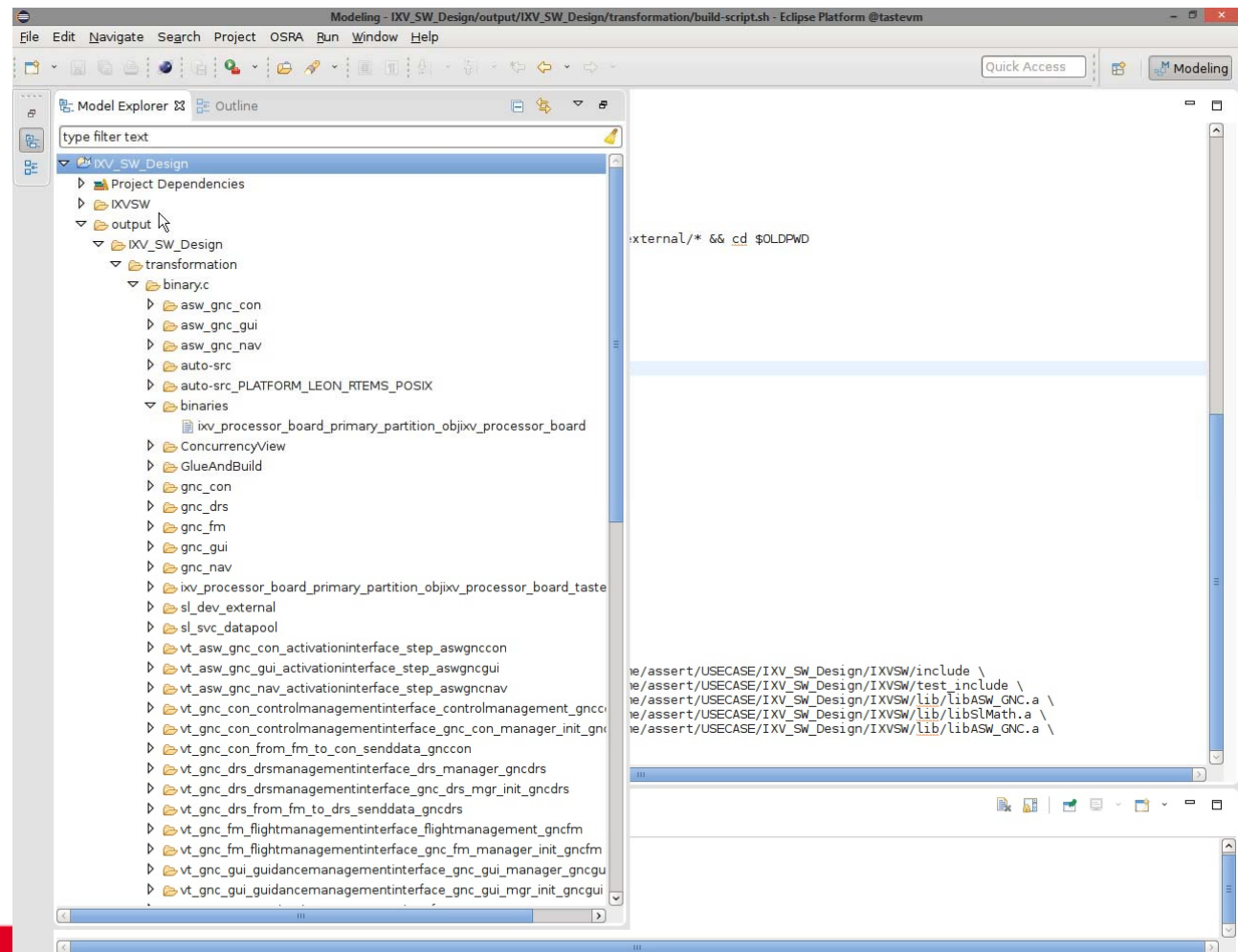


INTEGRATION WITH REAL CODE



GENERATION OF EXECUTABLE

- ❑ Configuration of the TASTE Processor:
 - IXV_Processor_Board : PROCESSOR ocarina_processors_leon::leon.rtems_posix;
- ❑ TASTE used for:
 - Code skeletons generation
 - Executable generation



RESULTS

- ❑ **Unambiguous and precise semantics** due to formal languages ✓
 - Early error detection when creating SW from scratch
 - Designer is forced to think about all cases, including error sequences
- ❑ Design maintained at **model level**, including dynamic behaviour ✓
 - Mappings ensure consistency
 - Document and code generation
- ❑ **Early verification and validation** at design phase ✓
 - Static correctness checks
 - Animate state machines
 - Possibility to improve analysis engines with behavioural information not explored in the case study
- ❑ **Process in line with life cycle of space projects** ✓
- ❑ Tools must evolve to be applicable to other space projects ⚠

STUDY ACTIVITIES

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 - SOIS EDS Toolchain
4. Elaboration of **Training Material**

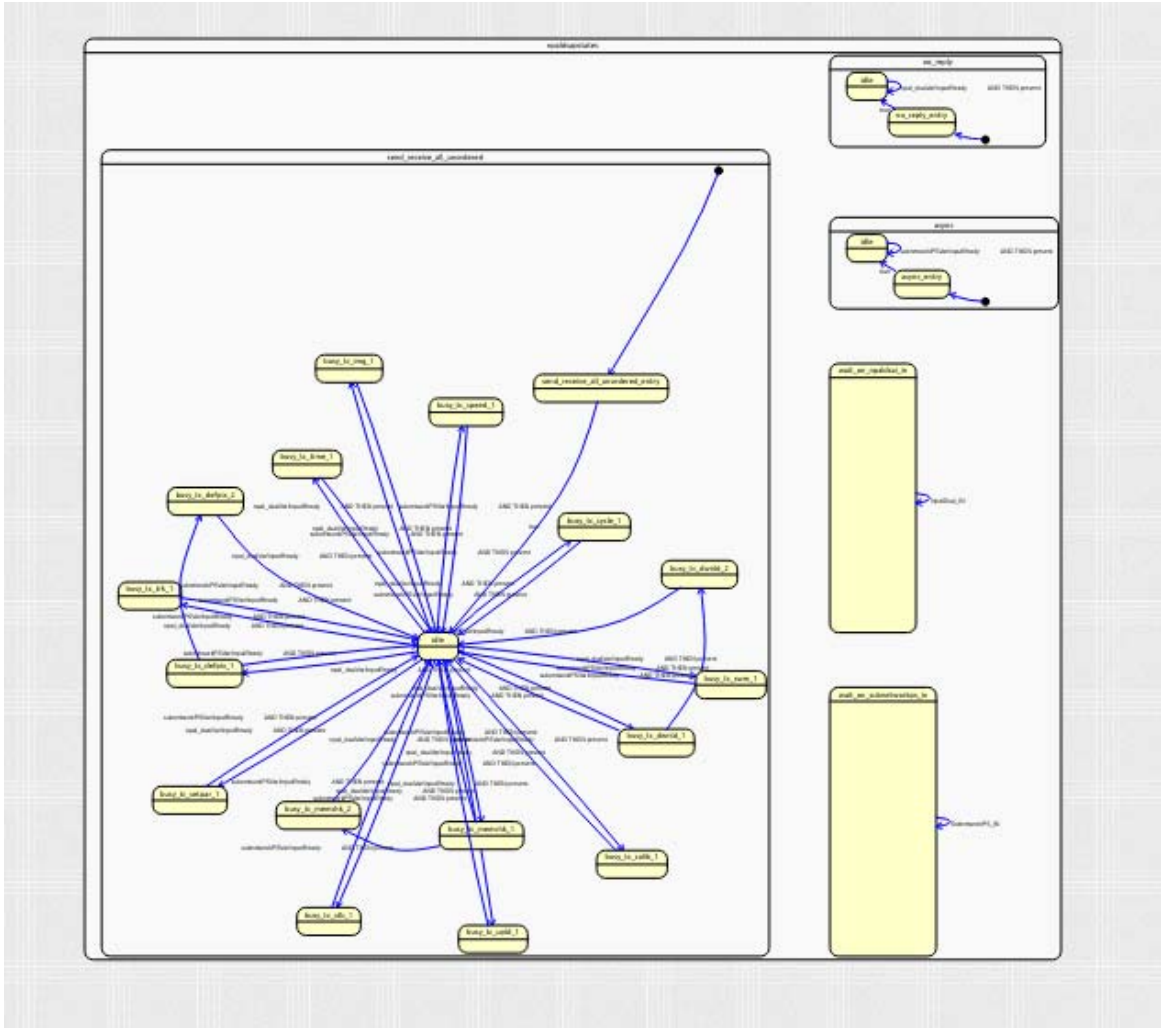
SOIS EDS TOOLCHAIN (1)

Presenter:

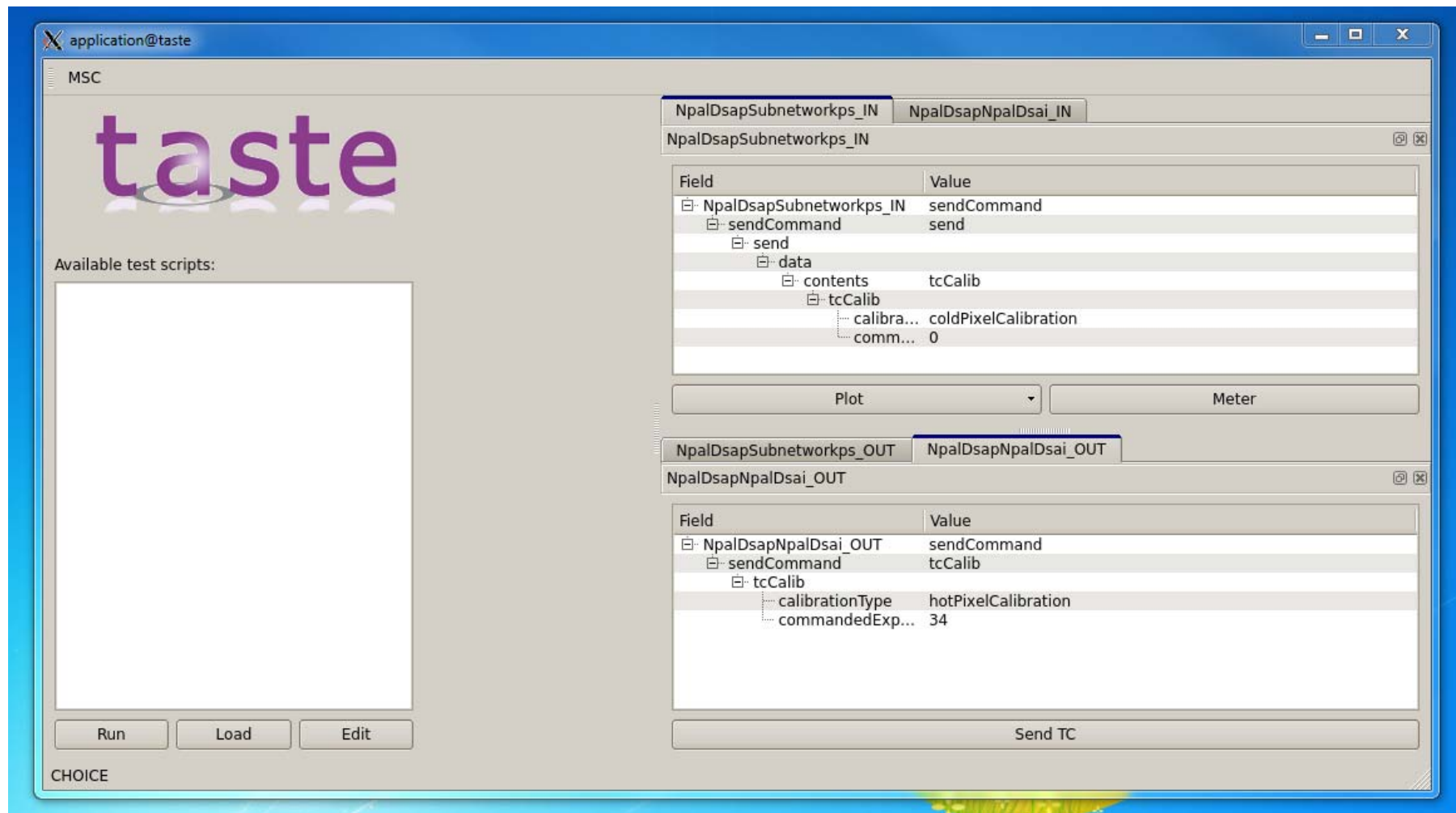


- USE of EDS as an input to behavioural modelling
 - Typical case: hardware exists, you want to monitor and control it
 - Other direction not currently addressed
 - ESA's TASTE used as behavioural modelling tool
 - Automatic generation of TASTE model from an EDS
 - ASN.1/ACN data types
 - SDL/PR behavioural model
 - AADL system structure (for a testbench)

TRANSLATED EDS IN OPENGEODE



TASTE TEST BENCH FROM AN EDS



The screenshot shows the TASTE test bench interface. On the left, there is a section titled "Available test scripts:" with a large empty box. Below this are buttons for "Run", "Load", and "Edit". The word "CHOICE" is visible at the bottom left of the interface.

On the right, there are two data tables. The top table is for "NpalDsapSubnetworkkps_IN" and the bottom table is for "NpalDsapNpalDsai_OUT". Both tables have columns for "Field" and "Value".

Field	Value
NpalDsapSubnetworkkps_IN	sendCommand
sendCommand	send
send	
data	
contents	tcCalib
tcCalib	
calibra...	coldPixelCalibration
comm...	0

Field	Value
NpalDsapNpalDsai_OUT	sendCommand
sendCommand	tcCalib
tcCalib	
calibrationType	hotPixelCalibration
commandedExp...	34

Below the tables, there are controls for "Plot" (a dropdown menu) and "Meter". At the bottom right, there is a "Send TC" button.

SOIS EDS TOOLCHAIN (2)

- ❑ Interoperability Test Data Set for EDS Reference Tooling
 - Necessary step in CCSDS standardisation process
 - All-Pairs generation of artificial test data from schema
 - 20,000 lines of xml
- ❑ Update Reference Tooling to fully handle this test data set
- ❑ Feed ITDS into TASTE translator
 - TASTE was improved as a result of this activity

STUDY ACTIVITIES

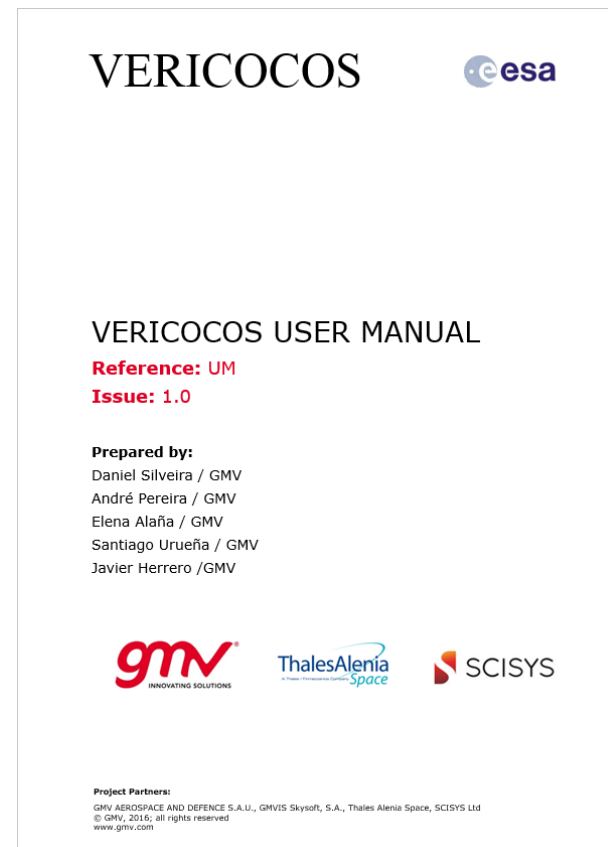
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TRAINING MATERIAL

- ❑ Supports the dissemination of the project results and, ultimately, foster the use of state machines and behavioural modelling in on-board software specification, design, development and validation

- **VERICOCOS User Manual**

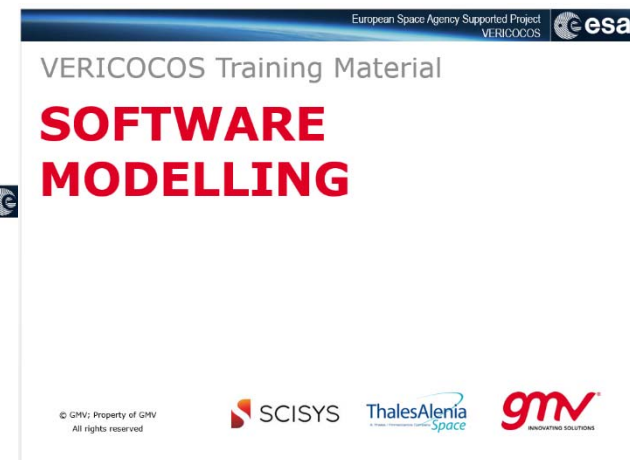
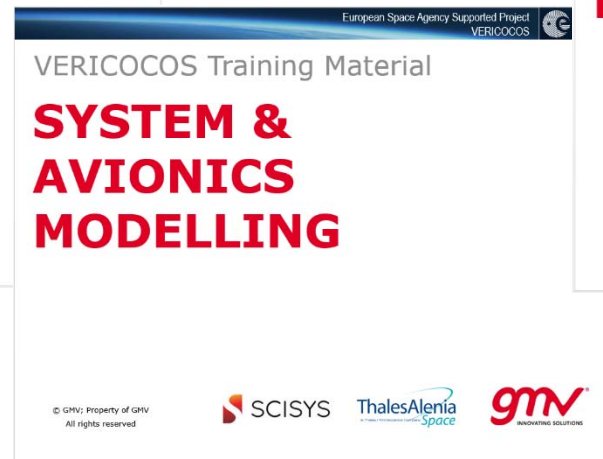
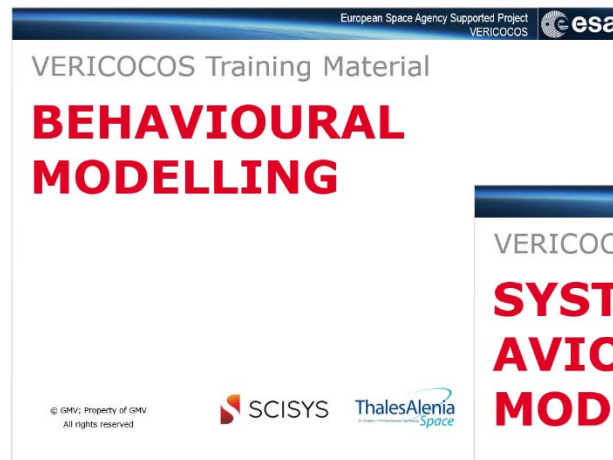
- Integrated User manual for System, Avionics & Software levels
- Step-by-Step descriptions



TRAINING MATERIAL

■ Presentations

Title	Audience	Duration	Comments
Behavioural Modelling Overview	Managers/Engineers	30 min.	Technology independent
System & Avionics Modelling	Engineers	2 hours	Self-training (AAML/OpenGEODE)
Software Modelling	Engineers	2 hours	Self-training (OSRA/OpenGEODE)



TRAINING MATERIAL

■ Website

<http://vericocos.gmv.com/>

- Public information only
- Private documentation shall be requested to Maxime Perrotin
- The website will be updated with new publications

The screenshot shows the VERICOCOS website with the following content:

- Navigation:** PROJECT, RESULTS, CONSORTIUM, RESOURCES, CONTACT
- Project Description:** "The VERICOCOS study (contract 4000113294/15/NL/FE) aims at fostering the use of behavioural modelling for the development of computer-controlled systems using dedicated languages and tools."
- Objectives:**
 - Confirm the applicability and subsequently open the door to the generalized use of **state machines and sequence diagrams** for the specification, design, verification and implementation of on-board software. Behavioural modelling brings many advantages to the development process, avoiding ambiguities in the system specification through clear semantics, enabling early V&V before starting the implementation phase, and ensuring the source code and design are aligned even in the presence of evolving requirements.
 - Produce a tool development framework.** On the one hand, AAML and OSRA Editors are selected to design the architecture at System, Avionics and Software levels, relying on ESA TASTE's OpenGEODE and MSC Editor for behavioural modelling. On the other hand, SOIS EDS toolchain is selected for Equipment modelling, through the use of Electronic Data Sheets (EDS).
- Diagram:** A hierarchical diagram showing the toolchain structure:
 - System modelling:** System architecture, Mission plans / Operational modes, Operational scenarios.
 - Avionics modelling:** Avionics architecture, Equipment status, Functional semantics.
 - Software modelling:** Software architecture, Models, Services, Control algorithms.
 - Hardware modelling:** Equipment structure, Equipment behaviour.
 - Editors:** AAML Editor (System, Avionics, Software), OSRA Editor (Software, Hardware).
 - Toolchain:** SOIS EDS Ref Tool (EDS).
 - Standards:** eSW, eRA, Modelib /
- Calendar:** November 2016 with dates 1-4 highlighted.
- Agenda:**
 - 8 June, 2015 – VERICOCOS KOM
 - 30 September, 2015 – VERICOCOS RRR
 - 9 March, 2016 – VERICOCOS MTR
 - 21 July, 2016 – VERICOCOS PM1
 - 2:00 pm – 2:45 pm, 7 December, 2016 – VERICOCOS Final Presentation
- Quick links:** AAML Editor, OSRA Editor, SCM, TASTE, OpenGEODE

VERICOCOS - Final Presentation

CONCLUSIONS AND FUTURE WORK



BENEFITS

Model Simulation

Model Checking

Information interchange

Abstraction

Avoid ambiguities

Document generation

Code generation

SVF

System tests

ASSESSMENT

☐ Achievements:

- VERICOCOS outcomes matches the expectation of the VERICOCOS project
- The study demonstrates the benefits of behavioural modelling

☐ Improvements:

- The adoption of this new approach requires money and time
- It does not only depend on the technical quality of the toolchain but also on the project management decisions

☐ Recommendations:

- Dissemination, evolutions of VERICOCOS toolchain, consolidation of EDS process, etc.

FUTURE LINES OF WORK

- ❑ Dissemination of the VERICOCOS results
- ❑ Evolutions of the VERICOCOS Tool Framework
 - Potential evolutions have been identified:
 - **ID**: Identifier of the open point/future work
 - **Item**: Element (e.g. tool) involved in the open issue
 - **Description**: Brief summary of the capability to be implemented
 - **Priority**: Low/Medium/High
 - **Work-plan** (effort needed): short-term, mid-term or long-term activity

❑ Example:

ID	Item	Description	Priority	Work-plan
1.	MSC Editor	There is no check in charge of verifying if the operations are used between the correct components.	High	Mid-term



Thank you

VERICOCOS consortium
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INNOVATING SOLUTIONS