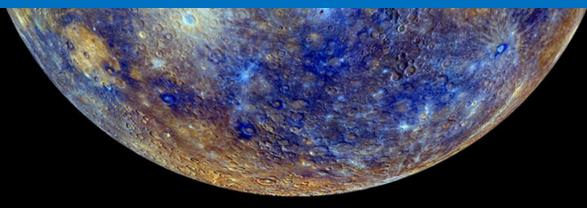


Avionics roadmap

Jean-Loup TERRAILLON – TEC-S Philippe ARMBRUSTER - TEC-E





European Space Agency

Technology Overview



Avionics Embedded Systems dossier: roadmap listing Avionics level crosssectorial activities and sectorial activities with a cross-sectorial scope

Data Systems sectorial activities with an Avionics level scope <u>defined</u> in AES dossier (D)	Data Systems sectorial activities with an Avionics level scope <u>defined</u> in AES dossier (C)	On-Board Software sectorial activities with an Avionics level scope <u>defined</u> in AES dossier (S)	
Data Systems	Control Systems	Software Systems	
On-board Computers and Data Systems dossier - refers to (D) for Avionics level activities Payload Data Processing Dossier - idem Microelectronics Dossier - idem	AOCS Sensors and Actuators dossier refers to (C) for Avionics level activities	On-board Software dossier refers to (S) for Avionics level activities	

Basic functions implemented by the Avionics Embedded Systems :

- Mission and Vehicle Management;
- Command & Control;
- Fault Detection Isolation and Recovery (FDIR);
- Attitude and Orbit Control / Guidance Navigation & Control;
- Thermal control processing;
- Power control processing;
- Telemetry & telecommand handling;
- Data processing, storage and transmission;
- Data handling;
- Payload control.

Technology Overview - Key issues

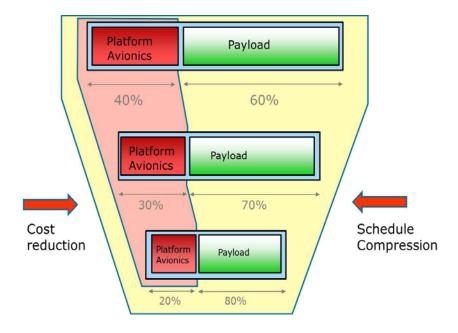


HIGH DEMANDING MISSIONS

- OBSOLESCENCE and evolution of technologies
- "BIG-DATA" challenge starts on-board
- DETERMINISTIC PROTOCOLS multiplexed with asynchronous ones

SPACE LAWS

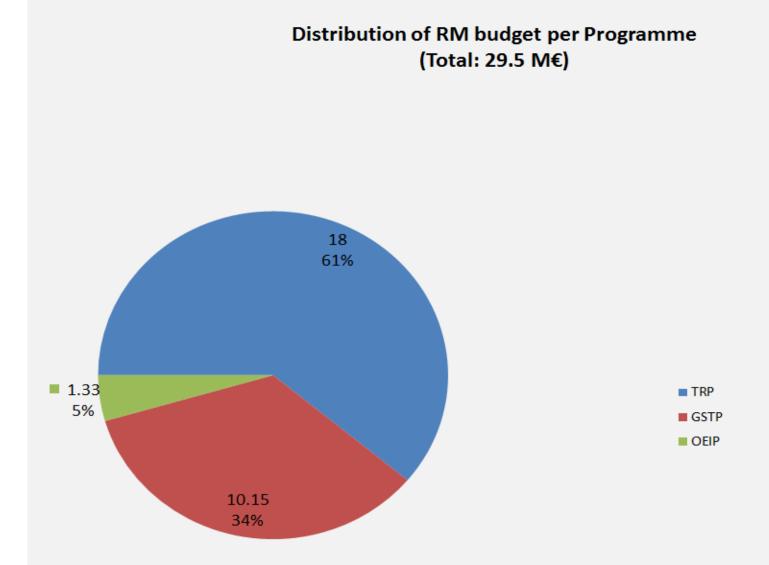
collision avoidance reliability and safe disposal.



More budget dedicated to the actual mission needs implemented by the payload, while decreasing the "infrastructure" cost of the platform.

Distribution of RM budget per program (total 29.5 M€, including running activities)





Slide 4

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Distribution of Roadmap proposed activities budget per priority (criticality): total 23.7 M€



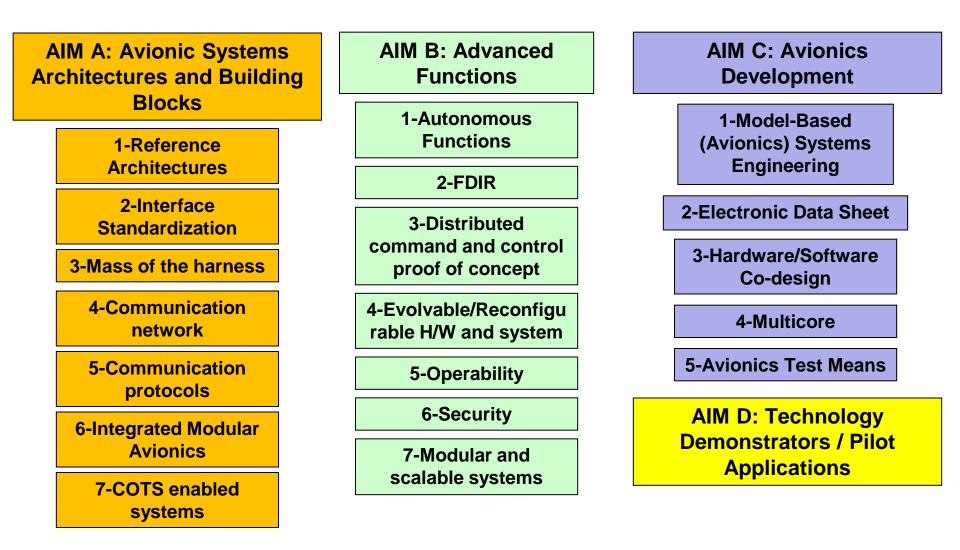
TOTAL Referen	11500	
Criticality	Budget request (k€)	Target budget (k€)
High	8600	9200
Medium	13350	11500
Low	1750	N/A
		5.75 M€ TRP 2.25 M€ GSTP

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Slide 5



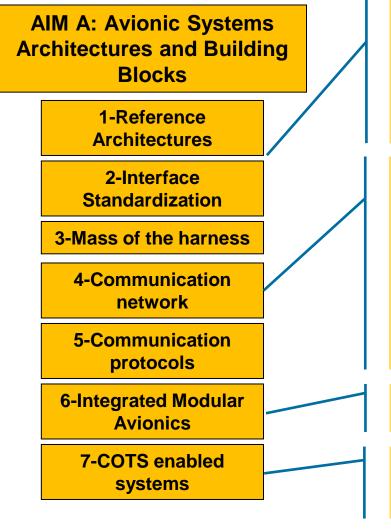
ROADMAP General Development Approach



Slide 6

ARCHITECTURE





SAVOIR: -Small missions -Payload (OSRA-P) -Other architecture



COMMUNICATION

-OSRA-NET follow on -Ethernet4Space -AOCS network, AOCS spacewire for FDIR -TTEthernet -CAN for payload

-Adaptable IMA

-COTS based OBC/Data storage, low cost, with fdir

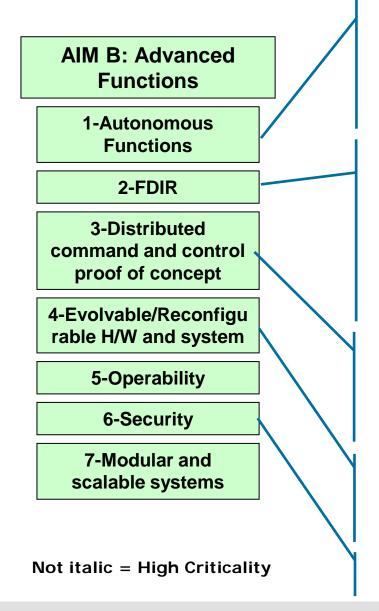
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ADVANCED FUNCTIONS





AUTONOMY

-Autonomy development process -PMOPS follow on -On-line energy management

FDIR

-SAVOIR Handbook -FDIR Metrics -Model based FDIR (combine COMPASS and AAML) -Industrialization of COMPASS

OPERABILITY -Distributed C&C -Impact of large constellation on avionics

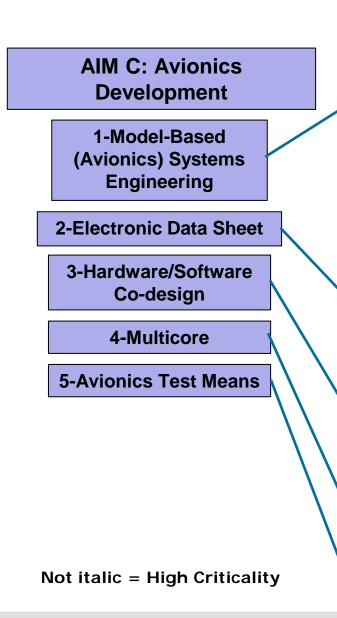
-Reconfigurable FPGA methodology (BRAVE) (follow on CORAx3)

-Secured CFDP, security & FDIR

Slide 8

AVIONICS DEVELOPMENT





-Model Based Avionics trade-off
-Model based RAMS data handling + AOCS
-Data modelling
-Library of Components and tools for System-Software Co-simulation and trade-offs
-From system to avionics model based engin.
-Formal verification for system engineering
-Multidisciplinary design optimization
-Use case maps

-SEDS update -EDS device simulator -Automatic test generation from EDS

-Non symmetric, not shared memory hw/sw architecture -HW/SW co-design

-Probabilistic analysis of shared memory multicore

-Avionics V&V

Slide 9

DEMONSTRATORS





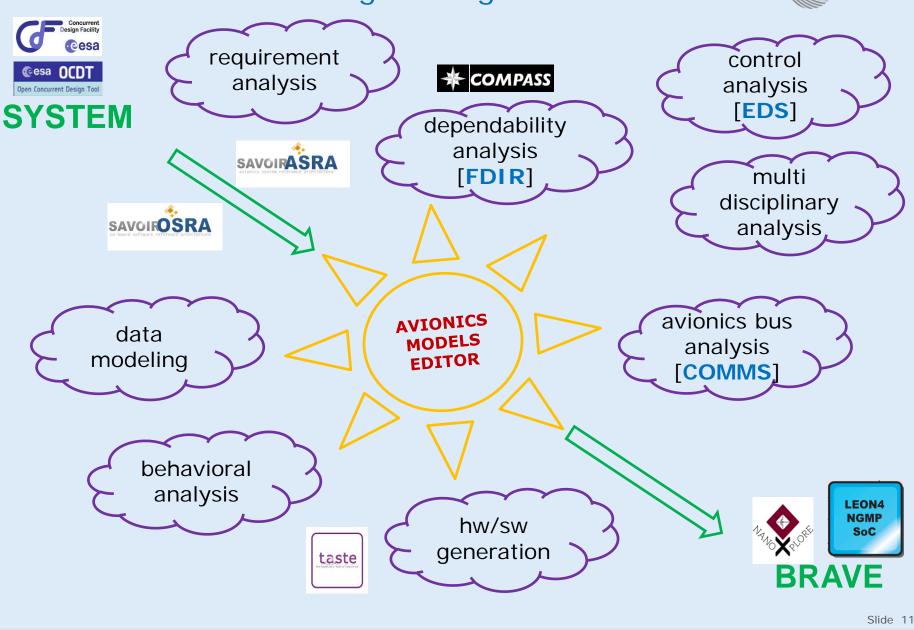
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Model Based Avionics Engineering



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