

# The COMPASS OBC, paving the way to a centralized avionics architecture

Jean-Luc POUPAT – Airbus Defence and Space, France

Xavier CALMET – Airbus Defence and Space, France

adcss → 10th ESA WORKSHOP



### Typical key drivers of a space system



- ☐ Mass?
- □ Volume ?
- □ Power ?
- ☐ Performances ?
- ☐ Schedule?
- ☐ Cost?





### What are the key drivers of New Space?



- Mass
- Volume
- Power
- Performances
- ☑ Schedule
- Cost

All of them!

Plus the challenges of

- ✓ Industrialisation with high volume production
- ✓ Safety/Reliability including deorbitation procedure







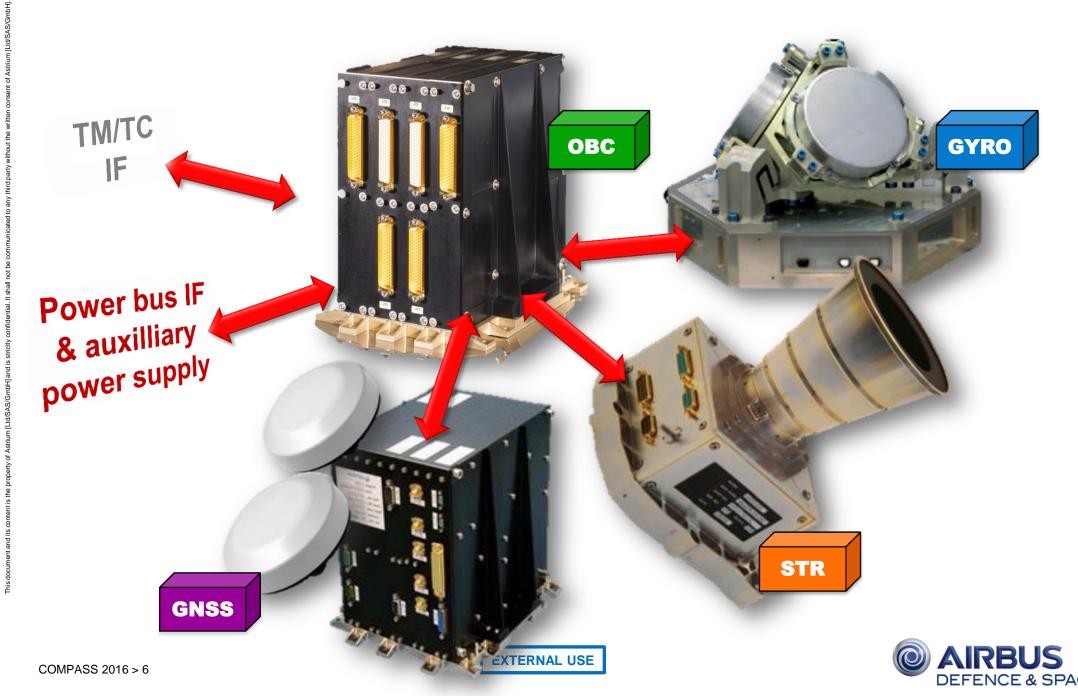
Objective 1
Push the centralized avionics concept to reality



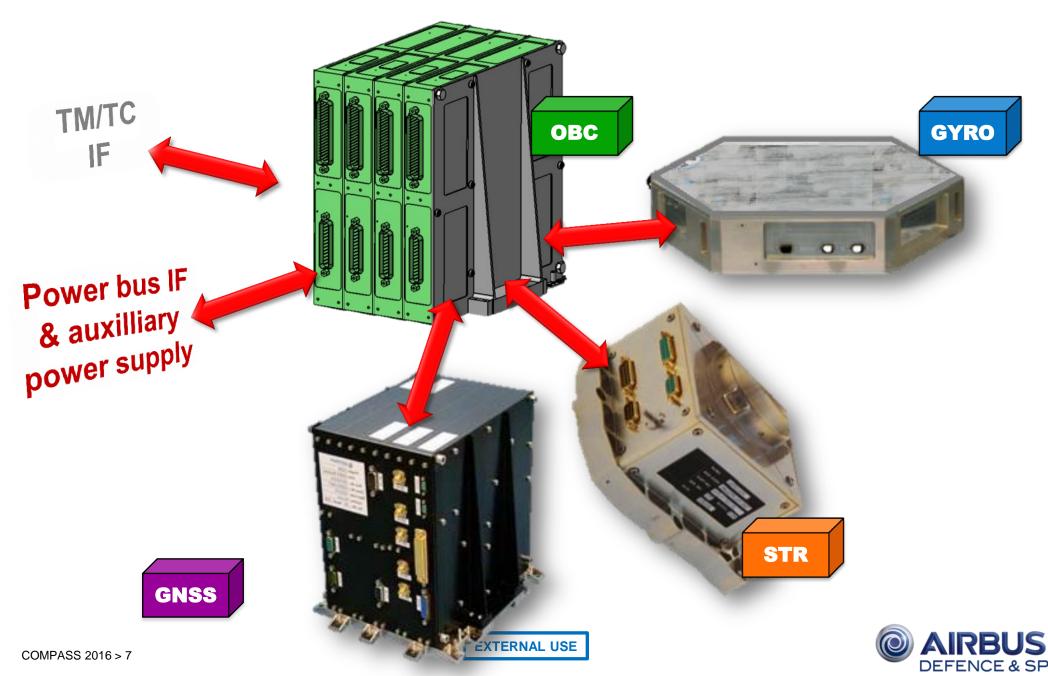
COMPASS 2016 > 5

EXTERNAL USE





#### Avionics: various units with similar Electronics

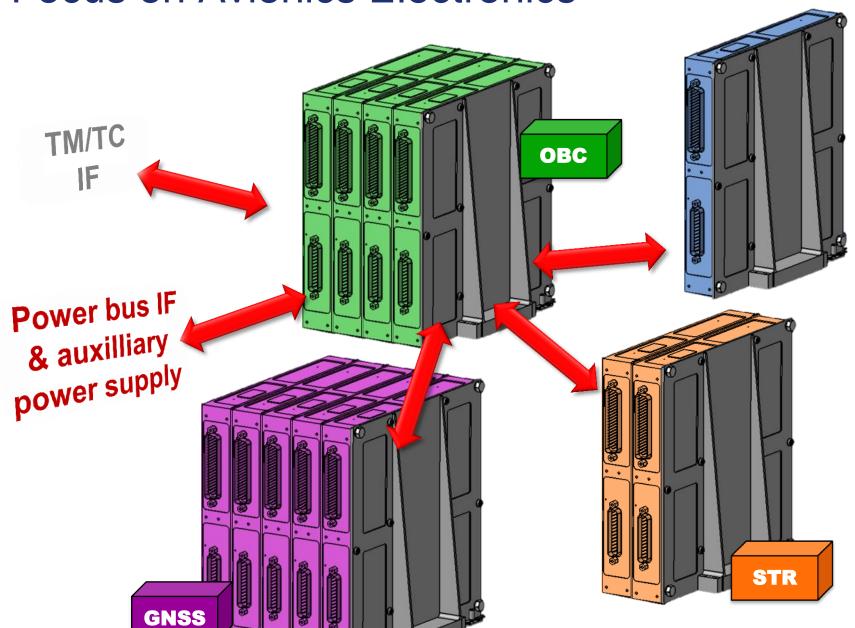


#### Focus on Avionics Electronics









**EXTERNAL USE** 





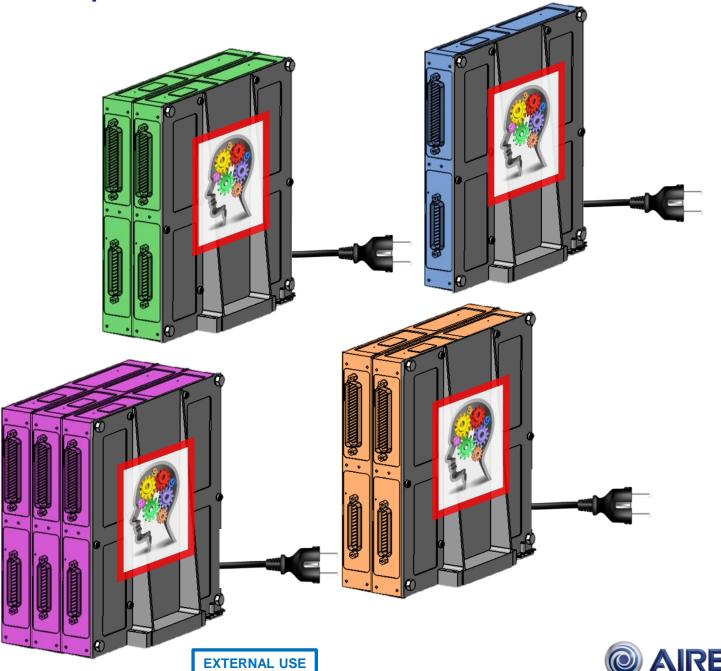
## **COMPASS** concept











# **COMPASS** concept

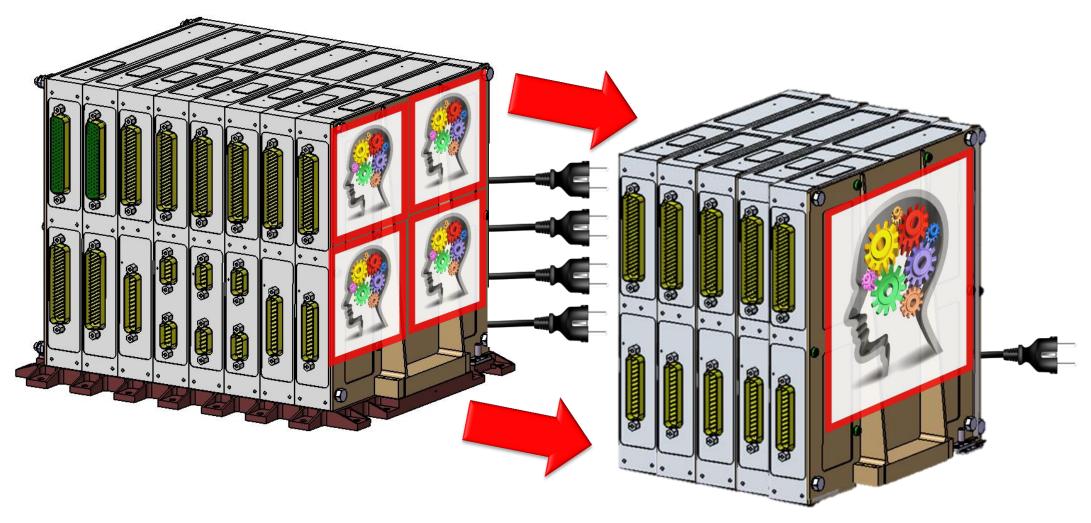








Power & Processing are common needs that can be shared by each function









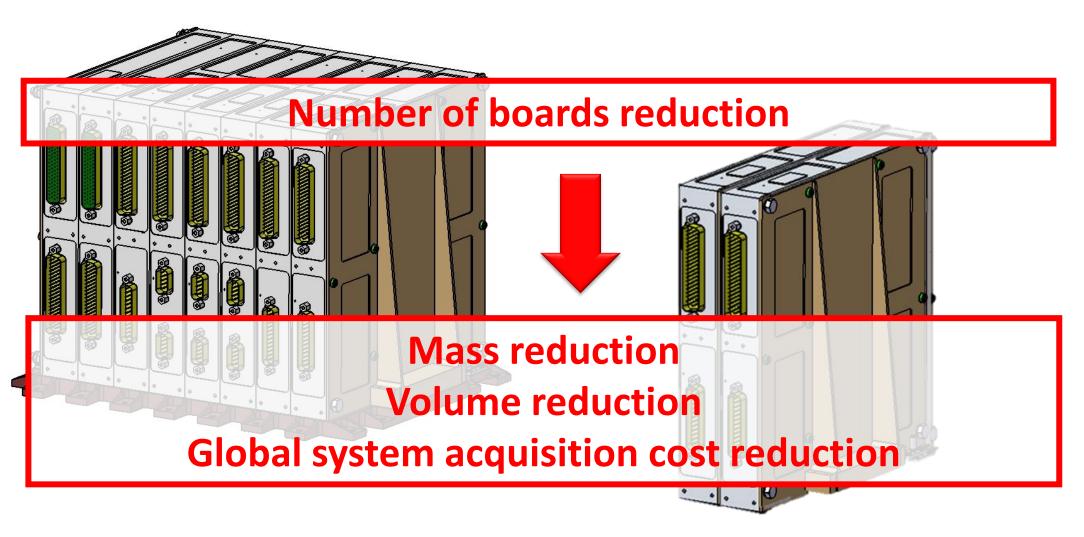
Objective 2
Drastically drop down
the avionics hardware acquisition cost



### **COMPASS** reality



Power & Processing are common needs that can be shared by each function



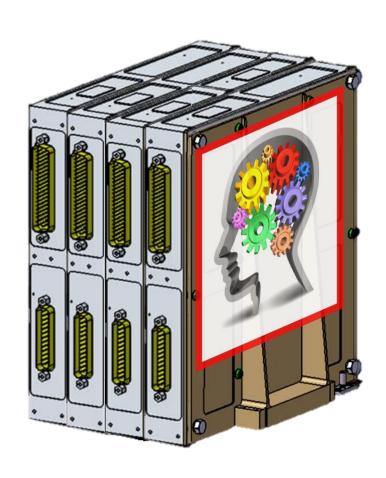




### **COMPASS** reality



Centralized avionics shall rely on a highly integrated processing system COMPASS is based on ARM core enhanced by hardening techniques









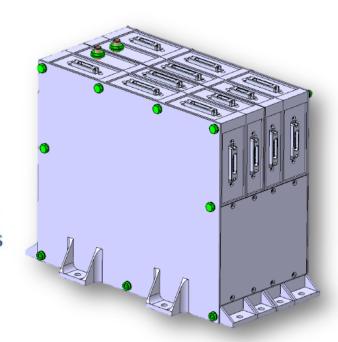
#### **COMPASS Performance Summary**

# $11 \times 24 \times 17 \text{ cm}^3$

Assembly volume including boards leads



Complete assembly weight Including 20% contingencies



20 W

Consumption of the whole OBC

# above 200 DMIPS

Processing performance of one OBC side





#### Cost oriented approach



COTS topic is in fashion, but for space applications, we shall not forget that they can easily jeopardize the full unit reliability

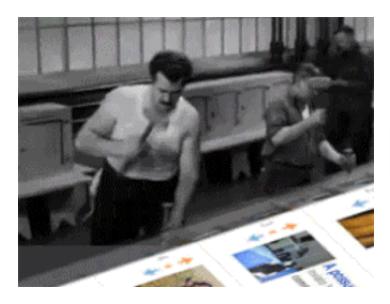
So COTS shall be combined with appropriate hardened mechanisms and with robust architecture choices based on strong heritage

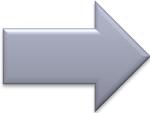


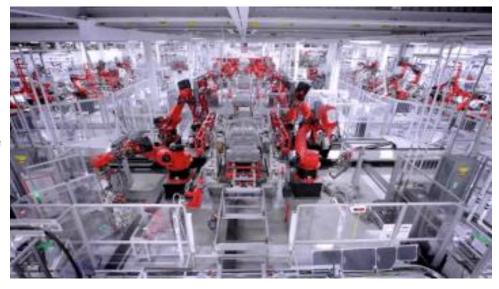


#### Cost oriented approach through industrialization

- High volume production baseline
- Full automatic process (fabrication and test)
- Dedicated assembly line
- Quality indicator on assembly line to detect any process divergence













Objective 3
Design with uncompromising reliability and radiation tolerance



#### **COMPASS Hardware**

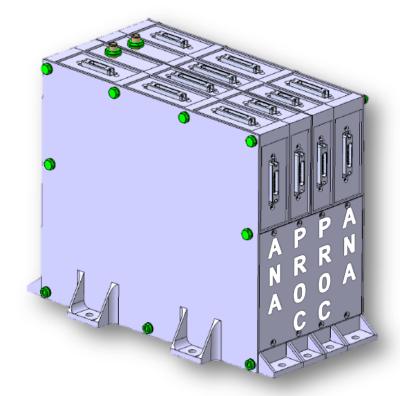
The full COMPASS OBC unit is composed of 4 boards for its 2 rad tolerant sides

One OBC side is constituted by two boards:

- 1 PROC board for processing & digital functions
- 1 ANA board for power management & analog functions

#### The functions performed by the OBC are:

- Power bus interface
- Auxiliary power supply
- Processing based on an ARM core
- Reconfiguration unit
- On board time
- TM/TC interface
- Digital I/O
- Analog I/O
- GPS interface



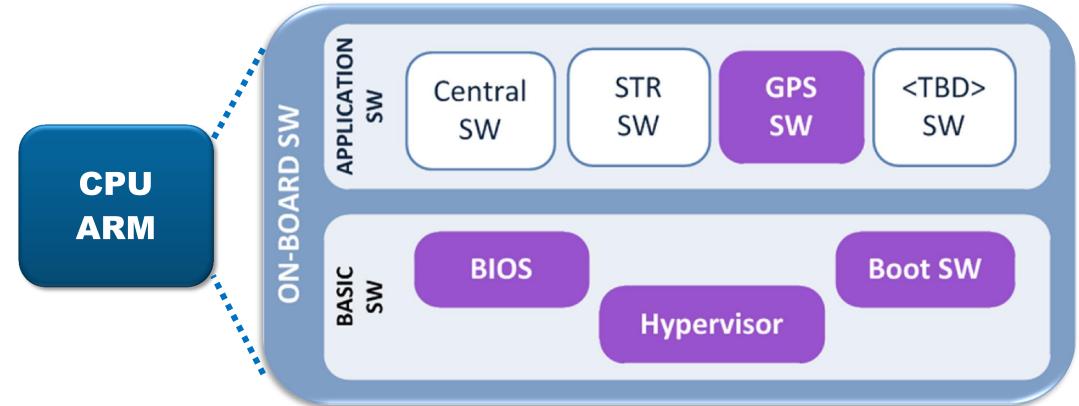




#### **COMPASS Software**

Associated to an ARM-based HW, COMPASS is delivered with a complete SW environment:

- The Boot software
- The BIOS
- The Hypervisor providing the TSP environment.
- The GPS software









Conclusion



#### **COMPASS** key achievements

- 1. Pushing the centralized avionics concept to reality
- 2. Drastically dropping down the avionics hardware acquisition cost
- 3. ARM-based equipment with TSP
- 4. Uncompromising reliability and radiation tolerance

