The Future European Space Automation Domain



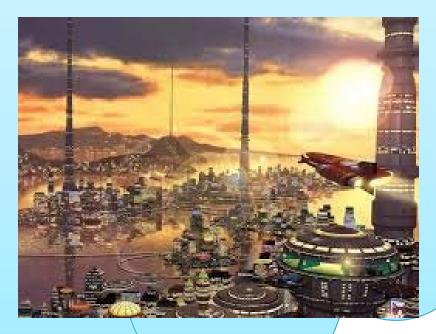




How will be the future?

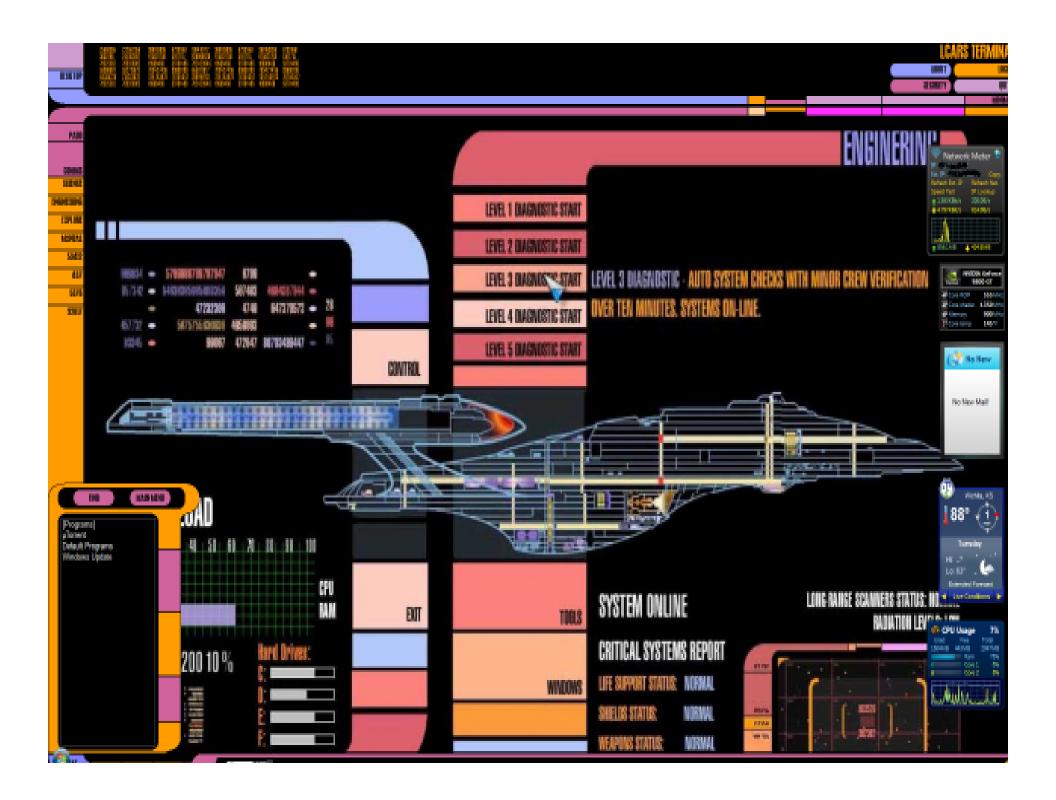
Will we live on another planet?

Cars will fly?



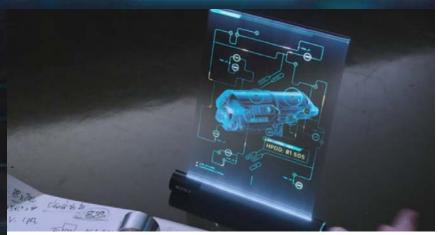
...There will be candy?

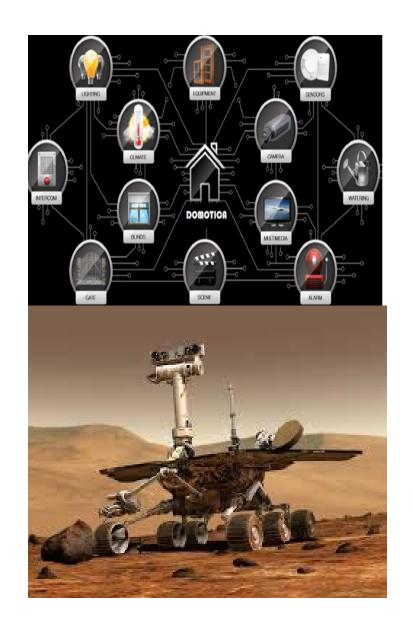














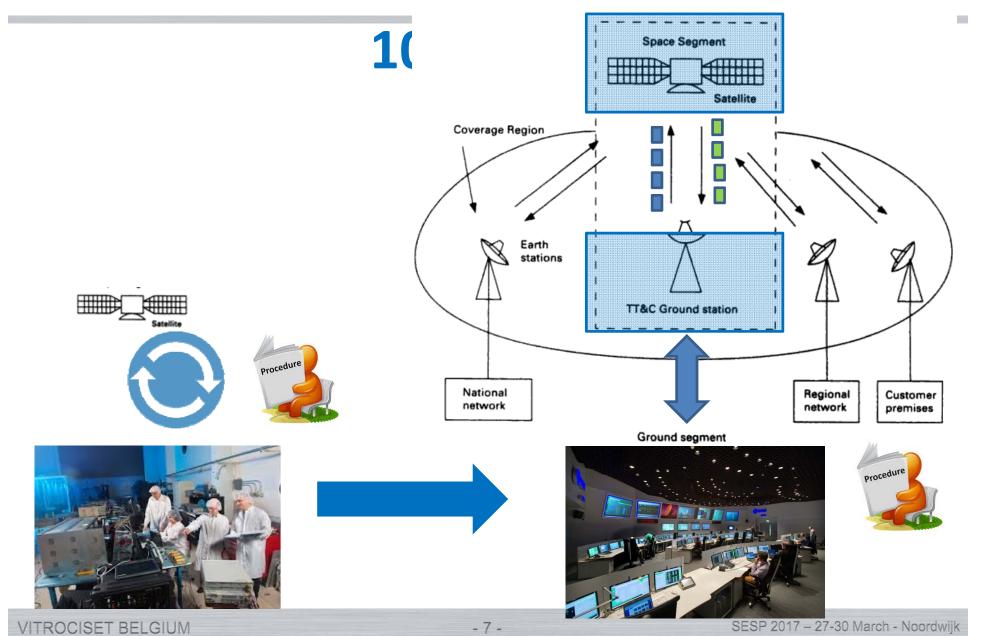


Not yet so advanced...

...but getting there.



AUTOMATION IN SPACE





AUTOMATION IN SPACE – WHAT WE

HAVE

What's there:

- Development of procedures and workflows → Prepared in AIT phases
- Describe contingency behaviors and alarm raising.
- Receive new instructions from ground segment
- The operator assess the problem based on notifications/events.
 - The operator defines a new procedure in specific format to solve the error
 - The automation system sends the procedure to the space segment by
 - Decomposing the operations in commands
 - Format the commands in the correct packet structure(s).
 - Send via uplink the info.
 - The space segment receives and perform the listed actions.
 - The space segments sends the confirmations via downlink,



AUTOMATION IN SPACE – WHAT WE

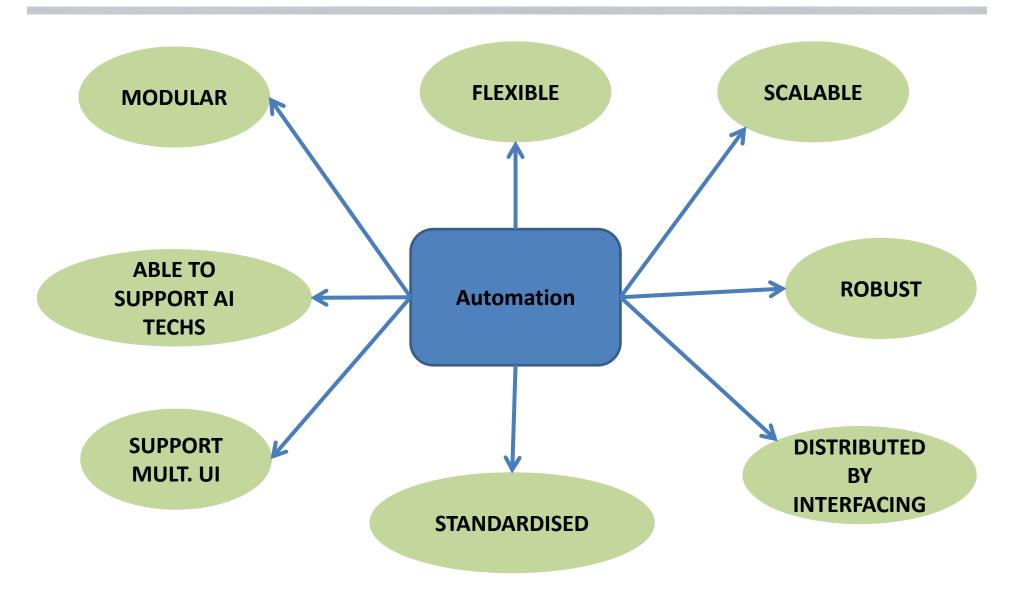
...a quantitative jump is needed...



...and a technological one.



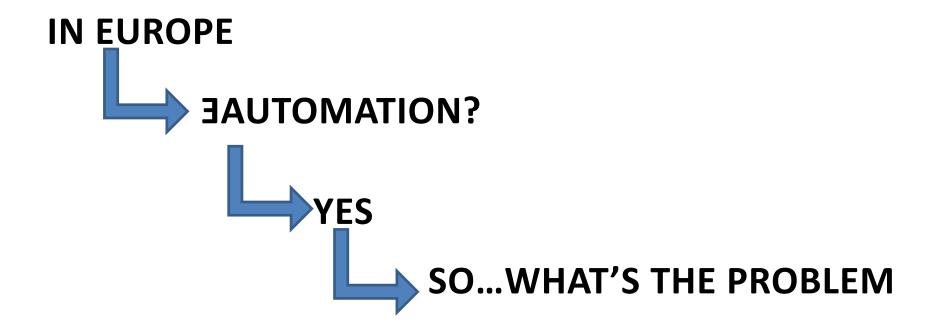
PROCESS FOR IMPROVING AUTOMATION



WHATA



STATUS OF AUTOMATION IN SPACE





Issues in Procedure Interoperability

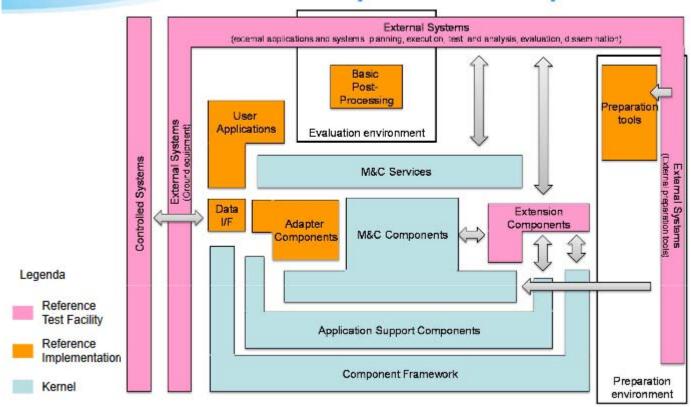




ON THE WAY TO FINDING A SOLUTION



Top Level Decomposition





ENSURING USABILITY AND FUTURE

Assessment of all user needs



Verification against applicable requirements of existing standards

Analysis of up-to-date technologies → applying criteria

Stability Amount of Usability Licensing Maintenance

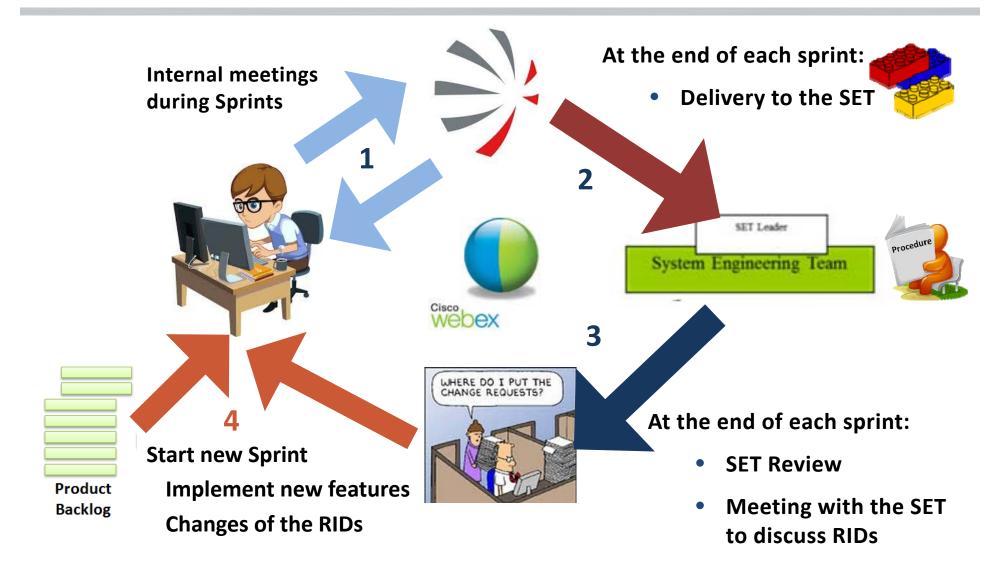
Creation of a modular architecture based on design patterns

Definition of a language and syntax for procedures





AP DEFINITION PROCESS





EGS-CC

System Engineering Team

Automation Procedure Programmer's Guide

Doc.: EGSCC-SYS-SUM-1001

Issue: 1.2

Date: 2016-12-09



Principles:

- Expose functionality of other EGS-CC components
 - Transparent to the user
 - Non-complex code
- Access to functionality shall be static to avoid instantiation
- To be scalable.

Current Functionality

- Packets, Monitoring Checks,
 Calibrations, Global Variables.
- Log and File Support
- Date management
- Encoding/Decoding
- Report Handling



AUTOMATE IN ISOLATION?



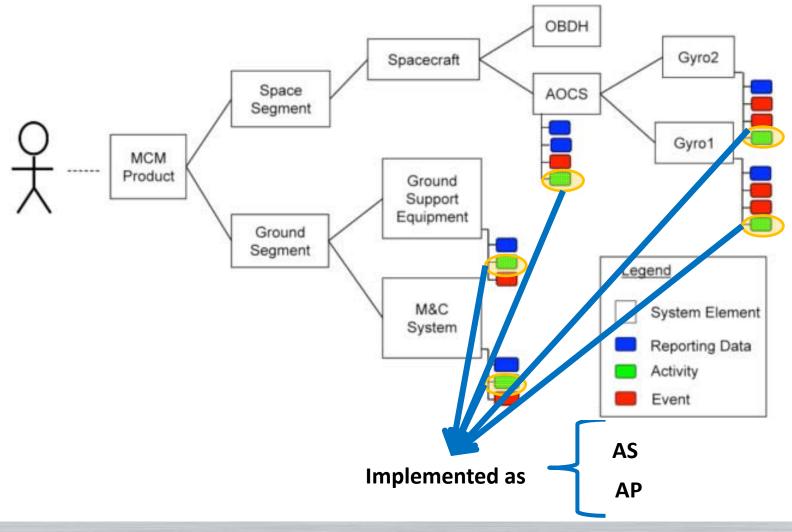


MONITORING CONTROL MODEL

Functional core of the EGS-CC kernel



abstraction layer for M&C operations





AUTOMATION IS FORCED TO BE SOCIAL PLAYER

File Management

Logging Handling

Information Monitoring

Calibrations

Parameter Injection

Time Handling

automation ocess

Packetization

3rd Party Script Library

Data Definitions

Runtime Monitoring Control

Event Injection

Archiving

Messaging

Uls

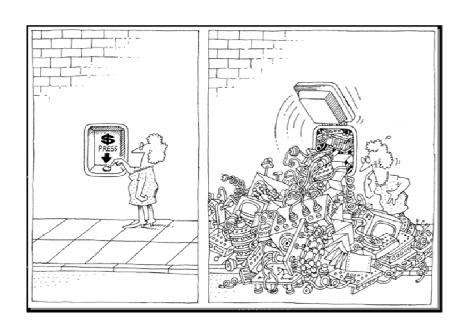


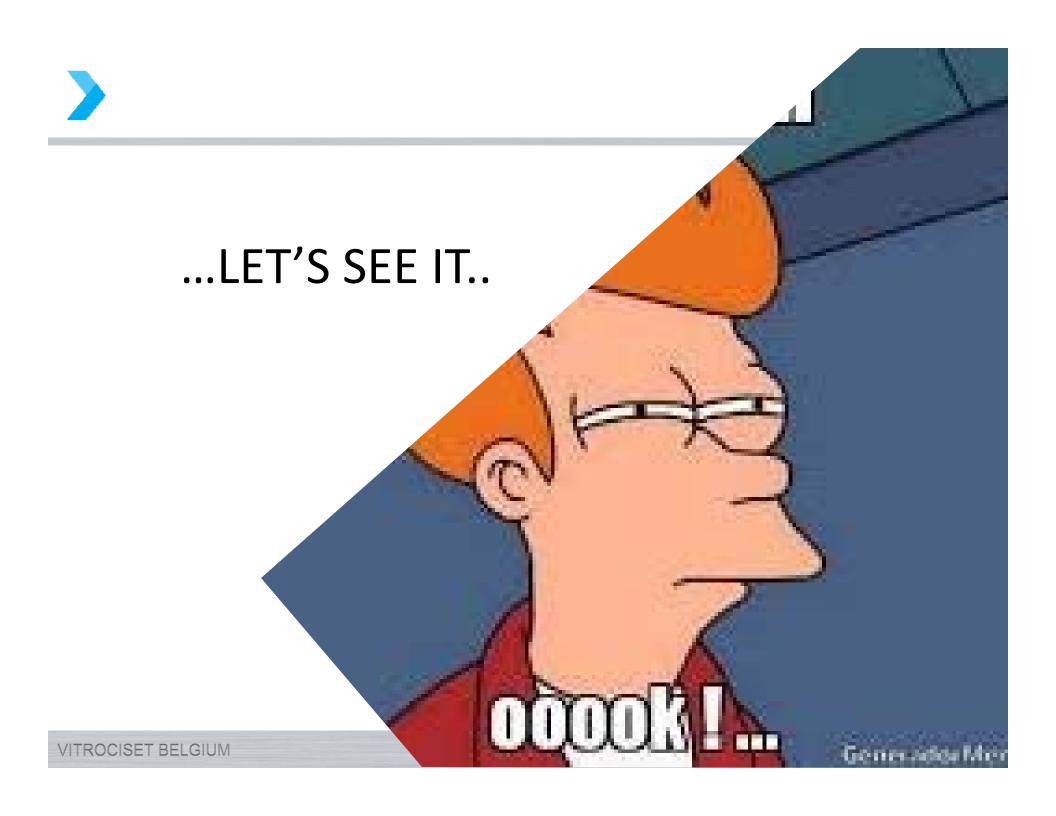
➤ MONITORING CONTROL MODEL — AP STYLE

- 1. Users will not navigate or use pure programming code for accessing information.
- 2. Ensure consistency of the data at compile time.
- 3. Provide most common functionalities of other components
- 4. Hide complexity to the users



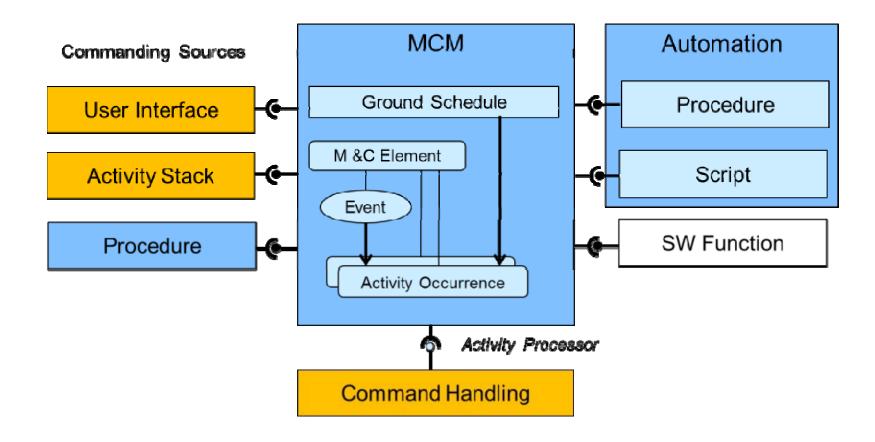
Generation of wrapping API for the **MCM**





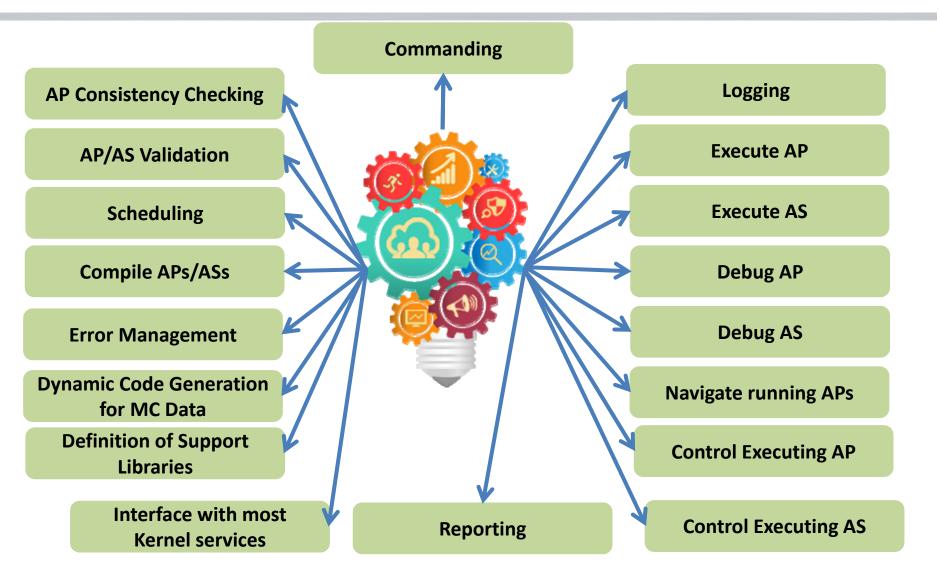


AUTOMATION PLACE IN THE SYSTEM



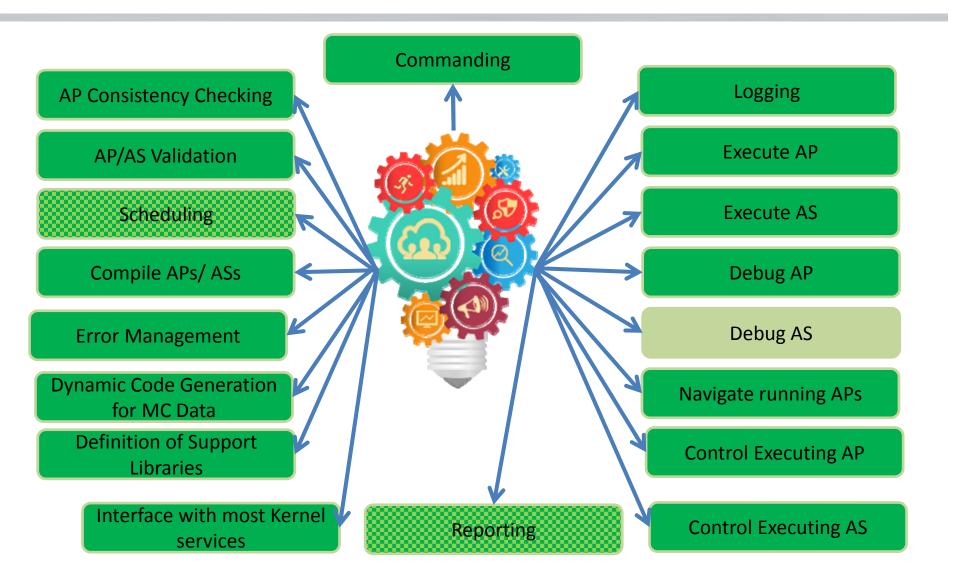


AUTOMATION FEATURES



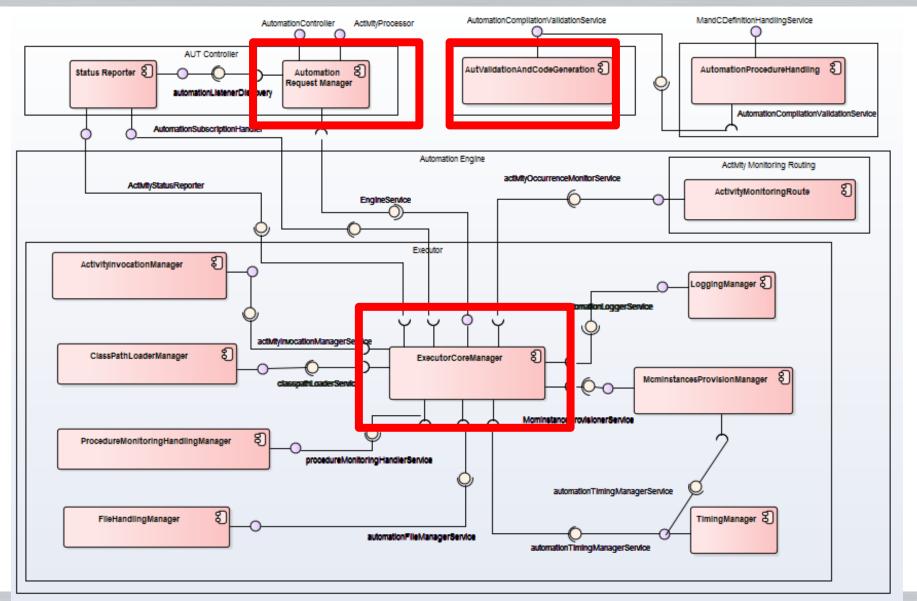


AUTOMATION FEATURES



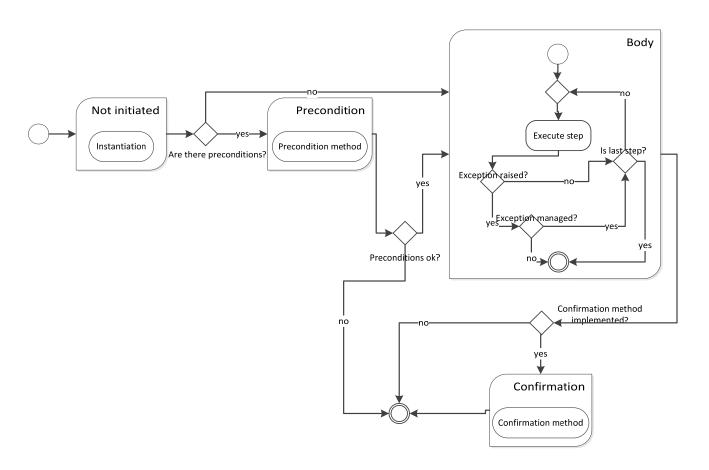


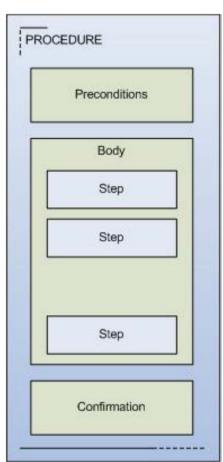
Simple Automation Architecture





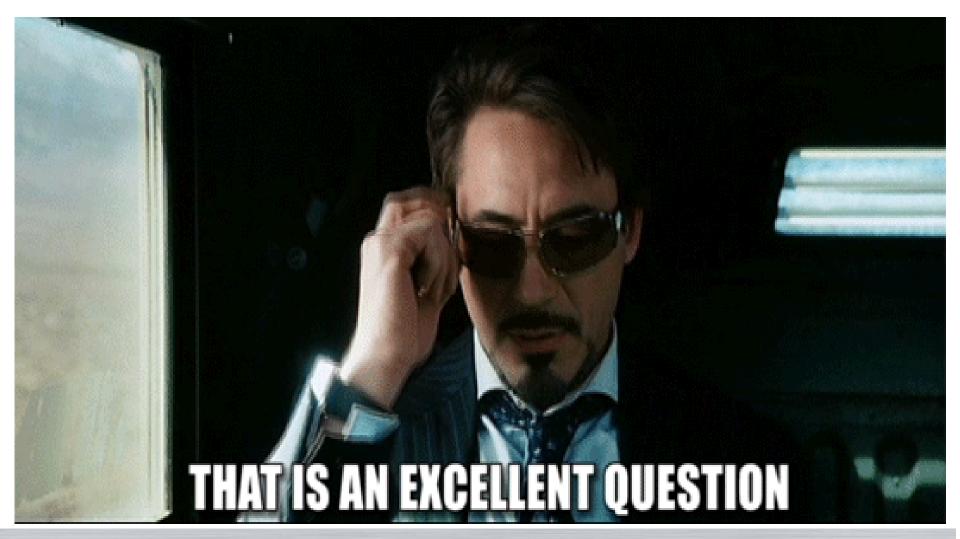
Procedure Execution Flow





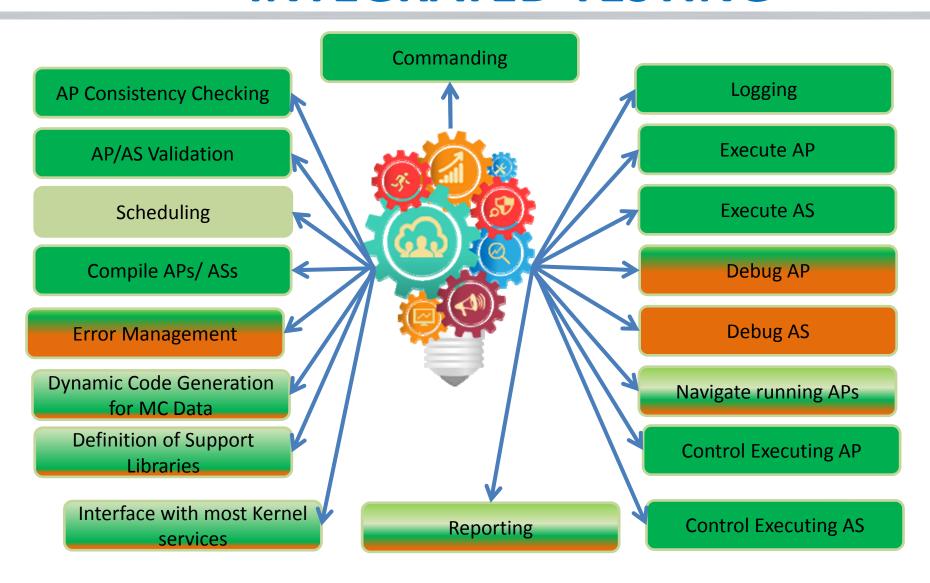


IS IT WORKING?





INTEGRATED TESTING





EXAMPLES OF PROCEDURES

```
nublic vaid body() throws EGGCCEvention S
private void embeddedLogic() throws EGSCCException
   LogUtil.info("Started step embeddedLogic");
   LogUtil.info("Element Antenna" + this.antenna);
   ActivityInvocation act1 = this.antenna.p007 Activity()
                                                                                                             □ Θ<sub>0</sub> P007
            .directives(new Directive("The first directive", "The first directive value"),
                       new Directive("The second directive", 42),
                       new Directive("The third directive", true));
                                                                                                                  antenna: P007Anten
   for(Directive directive : act1.getDirectives())
                                                                                                                    body(): void
       LogUtil.info("The directive name : " + directive.getName() + " - the directive value : " + directi
                                                                                                                    embeddedLogic() : vo
   LogUtil.info("Returned activity " + act1);
    try
       if (act1 != null)
           // we trigger the execution synchrounously
           ActivityOccurrence occur = act1.invokeAndConfirm();
           LogUtil.info("FINISH TO FIRST INVOCATION");
           LogUtil.info("Invoke And Confirm Confirmation Status " + occur.getConfirmationStatus().toStrir
           // this should be completed with success
           LogUtil.info("Invoke And Confirm Execution Status " + occur.getExecutionStatus().toString());
           ActivityP007_SecondActivityInvocation act2 = this.antenna.p007_SecondActivity();
```



EGS-CC AUTOMATION HANDICAPS

JAVA is a programming language



All stakeholders are NOT programmers

People want to reuse legacy procedures



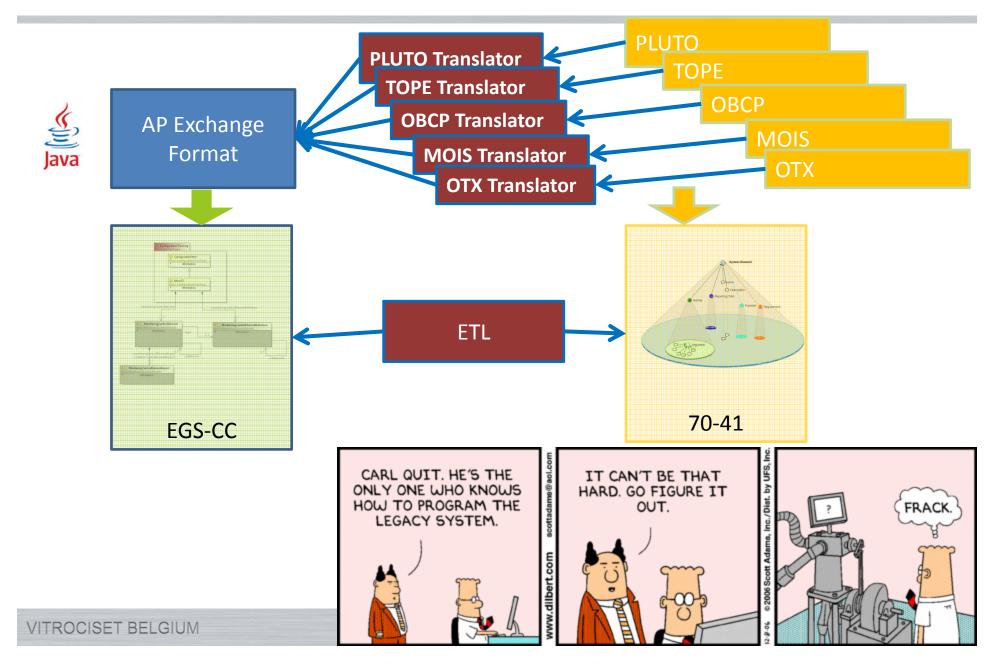
System needs to be extended



Create Scalable Modules On Top

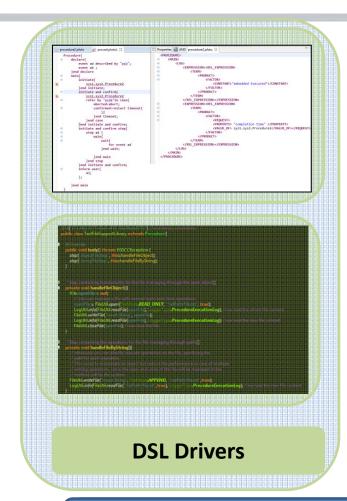


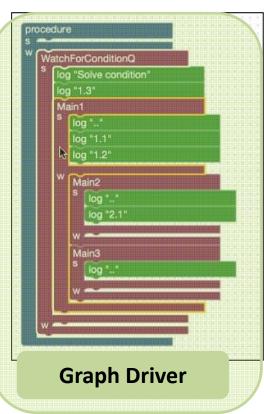
LEGACY HANDLING

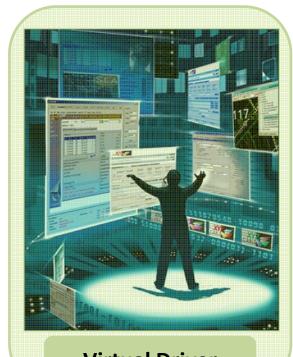




AP CUSTOM DEFINITION







Virtual Driver

AP Exchange Format

EGS-CC AUT COMPONENT



"We get to the peak together, or we don't get there at all"



