Active Debris Removal : a possible solution for mega constellations

CleanSpace Industrial days

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Collision risk Increase of 1 failure SC

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On-going ESA Phase 0 Study managed by Robin Biesbroek





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Objective

- Mega constellations operators have to address problem of removal failed satellite
- Compliance to Space Debris Mitigation requirement have to consider Collision risk & snow ball effect
- Solutions to trade
 - 🛰 Reliability increase
 - SIn-orbit servicing
 - 🛰 Removal

Solution Solution Solution Solution

ADR for debris issue linked to Mega constellations





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Study Logic

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Study cases



Mega-1000

1080 sat / 200 kg / 1 m2 eff cross section
1100 km/ 85° - 20 planes with 54 SC

•Electric propulsion – 7y lifetime



Mega-200

•200 sat / 1000 kg / 4 m2 eff cross section

- •1100 km/ 85° 10 planes with 20 SC
- Chemical propulsion 10y lifetime



Tas-3200

3200 sat / 380 kg / 2.6 m2 eff cross section
780 km/53° & 820 km / 53.8°
Chemical propulsion – 5y lifetime



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Tas-100

- •108 sat / 1200 kg / 1.8 m2 eff cross section
- •1400 km/ 90° 6 planes
- Electric populsion 10y lifetime



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Mitigation method



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Collision risk

- Sebris environment is strongly dependent from the altitude
 - Sk evaluation of losing the satellites caused by an impact above the catastrophic threshold (40J/kg)
 - Smaller impacts possibly deactivating permanently a critical unit





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Collision risk

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Collision risk analysis

- Risk of collision for the single satellite (during nominal mission) with an untracked debris
- Risk of collision for a satellite inactive or with impaired Collision Avoidance Manoeuver (CAM) function with tracked debris

Sebris generations through collisions









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Ref.:

End Of Life operations analysis

- Scenarios defined by:
 - ADR Constraints
 - Constellation Data
 - Regulations
 - ADR Needs
 - Added value from the ADR service
 - ADR Architecture
 - Strategies

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- Architecture Components and **Functions**
- **Mission Analysis and Performances**
- Space Segment Technologies



Operational Analysis (functions, collision risk, delta-V, LOS Constraints, ...)

Technologies

(mapped to functions, with

on the overall system)

Reference Scenarios

(mapped to functions, with relevant characteristics and parameters for trade-off)



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EOL operations analysis



Stechnologies associated to this activities and related variability relevant for trade-off (e.g. IR or optical cameras not relevant, use of chemical or electrical propulsion is relevant)

 $cost_{TOT} = cost_{constellation} + cost_{ADR}$ $cost_{ADR} = N_{removers} \cdot cost_{remover} + N_{launchers} \cdot cost_{launcher} + cost_{GS}$



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EOL operations analysis

 $N_{removers} = \left[\frac{N_{failed \ satellites}(p_R) + N_{collisions}(p_{collision})}{N_{satellites/remover}}\right]$

- Number of satellites removed by each remover is one of the main factor for the overall evaluation
- Cone-shot or small size removers are not expected to be in larger constellations (impact on costs)



$$cost_{TOT} = cost_{constellation} + cost_{ADR} | cost_{ADR} = N_{removers} \cdot cost_{remover} + N_{launchers} \cdot cost_{launcher} + cost_{GS} + cost_{CS} + cost_{CS$$



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EOL operations analysis

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Simplification at first glance



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Conclusion

Solution to highlight function of constellation

🛰 Failure case will happen

Collision risk not neglectible

SADR solution to be challenged

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Susiness model will drive orientation



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