Rate and collision probability of tethers and sails against debris or spacecraft

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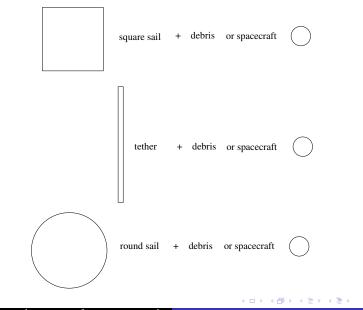
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- Contrary to the sphere-sphere case, attitude matters.

Introduction

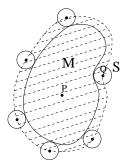


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Rate and Collision Probability

Introduction

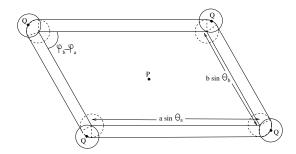
 ρ is the projection on the $b\mbox{-plane}$ of the pdf of the relative position.



probability of collision =
$$\int_{M \oplus (-S)} d^2 r \rho(\vec{r})$$

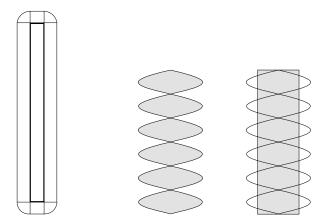
$$\text{rate of collision} = \frac{\bar{\rho} \ \mathrm{A}(M \oplus (-S))}{\text{time between encounters}} \to \phi \mathrm{A}(M \oplus (-S))$$

prob. of *n* collisions during a time $t = e^{-\phi A(M \oplus (-S))t} \frac{(\phi A(M \oplus (-S)))^n}{n!}$



 $A(M \oplus (-S)) = A(M \oplus S) = A(M) + per(M)R + \pi R^2$

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 $A(M \oplus (-S)) =$

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$$A(M \oplus (-S)) =$$

$ab\sqrt{-\cos(\theta_a+\theta_b)\cos(\theta_a-\theta_b)}+2(a\sin\theta_a+b\sin\theta_b)R+\pi R^2$

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 $2(R+r)L\cos\alpha$

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$2(R+r)L\cos\alpha$

$$2\Big(\frac{w}{\pi}+R\Big)L\cos\alpha$$

$$\pi R_{sail}^2 \cos \theta_M + 4 R_{sail} E(\sin^2 \theta_M) R + \pi R^2$$

$\overline{\mathrm{A}(M\oplus(-S))} =$

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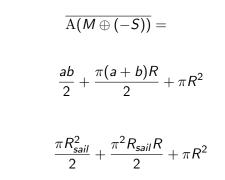
$$\overline{\mathcal{A}(M \oplus (-S))} =$$
$$\frac{ab}{2} + \frac{\pi(a+b)R}{2} + \pi R^2$$

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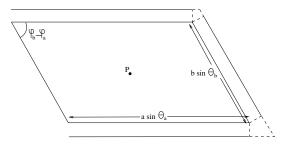


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Collision probability Rectangle

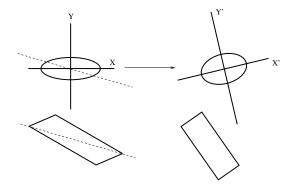
$$\int_{M\oplus(-S)} d^2 r \
ho(ec{r}) \leq \int_{ ext{parallelogram}} d^2 r \
ho(ec{r})$$



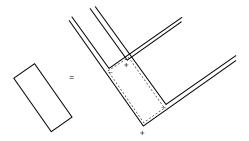
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The affine transformation of a parallelogram into a rectangle transforms the Gaussian into another Gaussian.



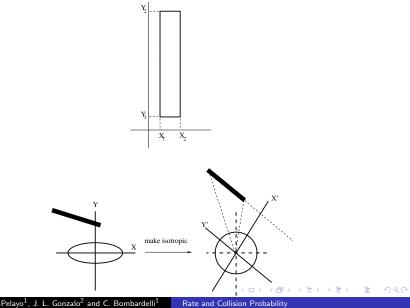
This allows the use of Genz's algorithm.



http://sdg.aero.upm.es/index.php/online-apps/
gaussian-over-parallelogram

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Collision probability Tether



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Collision probability Tether

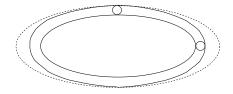
$$\frac{1}{4} \left\{ \operatorname{erf} \left[\frac{D^2 L/2 + x \sigma_y^2 \cos \Lambda + y \sigma_x^2 \sin \Lambda}{\sqrt{2} D \sigma_x \sigma_y} \right] + \operatorname{erf} \left[\frac{D^2 L/2 - x \sigma_y^2 \cos \Lambda - y \sigma_x^2 \sin \Lambda}{\sqrt{2} D \sigma_x \sigma_y} \right] \right\}$$

$$\left\{ \operatorname{erf}\left[\frac{\Delta/2 + |y\cos\Lambda - x\sin\Lambda|}{\sqrt{2}D}\right] + \operatorname{erf}\left[\frac{\Delta/2 - |y\cos\Lambda - x\sin\Lambda|}{\sqrt{2}D}\right] \right\},\$$

where:

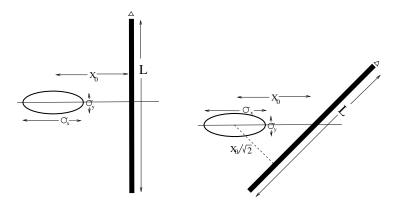
$$D \equiv \sqrt{\sigma_x^2 \sin^2 \Lambda + \sigma_y^2 \cos^2 \Lambda}.$$

Collision probability Round sail





 $\Lambda=45^{\rm o}$ and 90°; L=2000 m; $\Delta=7$ cm, 30 cm, 2 m, and 8 m. $x,y,\sigma_x,\sigma_y.$



Numerics Tether

$\Lambda=\pi/2,~\Delta=0.07~{\rm m}$		$\sigma_x \setminus p$		10 ⁻³	10^{-4}	10 ⁻⁵	
		2		4.6	6.3		7.6
		8		12.6	21.3		27.4
		n 32		0	66.6		95.7
		128 512		0	160	318	
				0	0	943	
		2048		0	0	1	613
		$\sigma_x \setminus p$		10^{-3}	10 ⁻⁴		10 ⁻⁵
$\Lambda=\pi/2,~\Delta=8$ m	2		10.2		11.4		12.6
	8		29		34		38.1
	32		97		119		138
	128		325		425		506
	512		482		1200		1837
	2048		1929		4800		6508

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The contribution to the overall probability of collision of the end masses is almost always negligible compared to the contribution of the tether. The reason is that the perimeter of the tether, p_t , is about 1,000 longer than the perimeter of any of the end masses, p_m .

Conclusions

• For a tether of length 2R and diameter d the area of its average projection is $\pi dR/2$, while the area of the projection of the circumscribing sphere is πR^2 . For a disk of radius R and its circumscribing sphere the average projected areas are, respectively, $\pi R^2/2$ and πR^2 .

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- Thus for these two cases the ratios of the area of the average projection to the area of the projection of the circumscribing sphere are d/(2R) (in reality less than 0.01) and 1/2, respectively.
- No additional computational cost, since the formulae are all analytical except for the case of the collision probability of a rectangle, for which a very fast algorithm, available as an app, is provided.

In general one may decompose a complex aircraft in various pieces, and separately compute the probability of collision for each. When one of the pieces is a solar panel then the formulae for the rectangle can be used.