

Simulating the Space Environment for Hardware-inthe-Loop Testing of Space Particle Sensor Signal Chains

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Motivation

Charged particle fluxes can vary greatly in magnetosphere

- Wide-dynamic range in particle flux due to location and time
- Relative ratio of charged particle-species (background contamination)
- Anisotropic angular dependence



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Simulation Approach



enables modeling of anisotropic fluxes

Bootstrap and exponential distributions to sample amplitudes & occurrence times

Requires proper calibration of function generator compared to typical detector response

Ultimately goal is to compare reported measurements from the signal chain against particle flux spectrum used to drive the simulation

Modeling of Anisotropic Particle Fluxes

From Sullivan (1971) for a single, time independent particle species for a detector:



Make approximation to separate flux into intervals with small variations in angle dist.

 $j(E,\omega) = J(E)F(\omega | E_{\mu})$ J(E) – Energy dep. amplitude $F(\omega | E_{\nu})$ – Angular distribution $\omega - (\theta, \phi)$ spherical polar angles

Can show for anisotropic flux with limited support (in energy) that:

Diff. omni. flux at center energy E_k and interval width ΔE_k

Count rate in i'th channel $C_i \approx \sum_{k=1}^N \int_E^{E_{k+1}} J_{omni}(E) \widetilde{\Gamma}_{ik}(E) dE \quad \longleftarrow \begin{array}{c} \text{Normalized} \\ \text{gathering power} \end{array}$

where: $\widetilde{\Gamma}_{ik} = \frac{\int d\omega \int d\vec{\sigma} \cdot \hat{\mathbf{r}} \varepsilon_i(E, \vec{\sigma}, \omega) F(\omega | E_k)}{\int F(\omega | E_k) d\omega}$

Inputs: Incident flux distribution in magnetic coordinates; Euler angles between magnetic and detector coordinates

Constraints: Source is "flat" surface with constant surface normal

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Outputs: (1) Source gathering power (2) Integral of angular dist. (3) Initial momentum direction for each simulated event

$$\Gamma_{ik} = \frac{N_{ik}}{N_{sim}} \Gamma_{source}$$

GEANT class allows calculation of normalized gathering power



Example: LEO Proton Response



Pinhole type detector that only counts particles that deposit energy in detector 1 (rejects events that deposit 1 & 2)



Isotropic

Proton Energy (MeV)

90 deg from B 75 deg from B

 10^{2}

Lenchek & Singer type model¹ to include East-West effects in low-altitude trapped protons

- Pancake type pitch angle distribution
- Theta is pitch-angle relative to local mag. field; Phi is azimuthal angle
- Theta, phi are spherical polar angles in magnetic frame



1. A.M. Lenchek, S.F. Singer, "Effects of the finite gyroradii of geomagnetically trapped protons", J. Geophys. Res. 67, 4073-4075 (1962).

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Normalized Gathering Power (cm)

10⁻³L

10

AFRL

Simulated Detector & Hardware-in-Loop Simulated Detector Test Setup



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simulate detector & analog chain

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1 through 4 (Energy deposited in Det. 2 < 1.8 MeV)

Test Sequence Creation

Step 1: Sample poisson distribution to determine when events occur



λ = (Sample Interval) x(Highest Detector Rate)

Currently implemented using Matlab functions

Step 2: For each non-zero time, sample the output of Monte Carlo simulation to get peak amplitudes

Event	Det. 1 Energy dep.	Det. 2 Energy dep.	Det. 3 Energy dep.	Det. 4 Energy dep.	Det. 5 Enegy dep.
1	0.61	0.00	0.00	0.00	0.00
2	0.17	0.00	0.00	0.00	0.00
3	0.18	0.00	0.00	0.00	0.00
4	0.17	0.00	0.00	0.00	0.00
5	0.16	0.22	0.85	0.00	0.00
6	0.55	0.00	0.00	0.00	0.00
7	0.14	0.00	0.00	0.00	0.00
8	0.15	0.65	1.03	0.00	0.00
9	0.14	0.00	0.00	0.00	0.00
10	0.43	0.67	0.46	0.00	0.00
11	0.35	0.72	0.00	0.00	0.00
12	0.17	0.00	0.00	0.00	0.00
13	0.45	0.00	0.00	0.00	0.00
14	0.17	0.00	0.00	0.00	0.00
15	0.24	0.00	0.00	0.00	0.00
16	0.14	0.64	0.00	0.00	0.00
17	0.16	0.54	0.00	0.00	0.00
18	0.00	0.70	0.33	0.00	0.00

Use uniform (or appropriate) distribution to select particular event with replacement (bootstrap method

Step 3: Create pulses for event and add to existing sequence



Requires that calibration exists to convert from MeV to DAC input

Process is repeated until all events have been created



Examples of Sequences

A 3 MeV electron beam was used to illuminate the sensor:



(~ 1297 kHz)



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Multiple time-scales for 1400 kHz example



Initial Results





- Although approximately 50% of H1 events being dropped at 1.3 MHz more than 70% of coincidence events still being processed
- Note the build-up of the shoulder representative of pile-up in the count spectrum



Conclusions

Methods to investigate misbehavior of the sensor due to anisotropy & high count rates have been proposed

- Often hard to simulate using particle sources on the ground
- Simulating and modeling of anisotropic fluxes on response
- Creating simulated test sequences to investigate dead-time, pile-up, and signal processing artifacts for hardware-in-the loop testing

Questions?