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Active Debris Removal by Shape Memory Polymer Composite Devices Loredana Santo¹, Fabrizio Quadrini¹, Malgorzata Holynska², Ana Cipriano² ¹ Department of Industrial Engineering, University of Rome Tor Vergata, Italy ² ESTEC – European Space Research & Technology Centre, ESA, The Netherlands



ESA's Clean Space Industry Days (2021 CSID)



Outline

- Background and introduction on Shape Memory Polymer Composites (SMPC)
- ✓ Experiments in Space
- ✓ Design and modelling of smart composite structures
- ✓ The ESA project e-SpaDeS (Space Debris Suppression)
- ✓ Functional and performance requirements
- ✓ Analysis of debris distribution, properties and Space environment
- ✓ Conclusion

Background and potential of SMPC

Contributions per year

- Scientific Literature (Agencies)
- Internal Research

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- Available Data from Market
- "Space debris" AND "Removal" AND "Shape memory polymer composites", only
 - 1. Conceptual design of an experiment for the international space station about shape memory composite in space environment, ASME 2017 12th MSEC).
 - 2. Design and testing of self-deployable structures for advanced space applications, 69th IAC 2018.

Proceedings of AVT-257 NATO Specialists Meeting on "*Best Practices for Risk Reduction for Overall Space Systems*", 26-29 September 2016, Avila, Spain)

(SMPC) devices may play an important role for small debris removal with undefined shape, mainly in the optic of inspace manufacturing of cleaning satellites.







Background

SMPC can freeze a non-equilibrium shape (open) and recover the equilibrium shape (closed) by heating. Heaters and sensors can be integrated in the SMPC structure during manufacturing.





Shape Memory Polymers and Composites

Ability to fix and recover a given deformation by cooling below and heating above Tg (thermo-mechanical cycle)



Self-deployable structures, actuators, biomedical devices

Advantages over shape memory alloys, resulting potential substitutes (lightness, low cost, high shape recovery, easy to process)



Grabbing systems



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Cubic configuration







Deploying systems





Experiments in microgravity conditions

I-FOAM (Shuttle Mission STS 134, May 2011)

Clamping device
Configuration

Compression

Compression

Bending

Torsion

t = 50 min

Ribes_Foam2 BION-M1 MissionSoyuz-2 launch vehicle April 20, 2013



F. Quadrini, L. Santo, E.A. Squeo, "Shape memory epoxy foams for space applications", Materials Letters, 69 (2012) 20-23.

L. Santo, F. Quadrini, E.A. Squeo, F. Dolce, G. Mascetti, D. Bertolotto, W. Villadei, P-L. Ganga, V. Zolesi, "Behavior of Shape Memory Epoxy Foams in Microgravity: Experimental Results of STS-134 Mission", Microgravity Science and Technology, 24 (2012) 287-296. **L. Santo , F. Quadrini , W. Villadei , G. Mascetti , V. Zolesi**, Shape memory epoxy foams and composites: ribes_foam2 experiment on spacecraft "bion-m1" and future perspective, Procedia Engineering 104 (2015) 50 – 56

Santo L., Quadrini F., Ganga P., Zolesi V., "*Mission BION M1: Results of Ribes/Foam2 experiment on shape memory polymer foams and composites*", Aerospace Science and Technology, 40 (2015) 109-114.

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Experiments outside the ISS

The effect of the Space environment on the Shape Memory Polymer Composite (SMPC) behavior has been investigated thanks to experiments on the MISSE platform. The Materials International Space Station Experiment (MISSE) is a NASA exposing platform mounted externally on the International Space Station (ISS) which investigates the effects of long-term exposure of materials to the harsh space environment. Small SMPC samples have been mounted in the MISSE-9, MISSE-10, MISSE-12, and MISSE-13 experiment in collaboration with Kim de Groh of NASA Glenn Research Center.



Misse-9

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Misse-12



Misse-13



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Designing smart composite hand

Smart

- Prototyping of smart hinges
- Testing smart hinges

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Measuring recovery loads







Designing smart composite hand

- Structure modelling
- Prepreg cutting

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- Laminate molding
- Structure assembly

Automotive prepreg





Ly556_rGO 90° Hexply prepreg Ly556_rGO 90° Ly556_rGO 90° Ly556_rGO 90° Ly556_rGO 90° Hexply prepreg





"This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No760779".



Designing smart composite hand

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Depart

Manufacturing Technology

Research Group

- Structure testing
- Memory-recovery cycles





Modelling

- Modelling shape memory behavior
- Applying to the SMPC finger
- Simulating SMPC actuation

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• Development of FE models





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Modelling

- ٠
- Modelling the SMPC triggering •
- SM interlayer damping •

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12

10

8

6

4

2

0

Uz (mm)

•







The ESA project e-SpaDeS (Space Debris Suppression) has the goal to design SMPC devices for space debris grabbing.

SMPC devices apply low grabbing forces and high damping during debris capture approach, thus minimizing possible fragmentation and issues due to debris spin.

Moreover, SMPC devices are light structures with manufacturing procedures compatible with the additive logic, therefore in the line of the concepts for in-space manufacturing.

The project aims to define, for the first time, the optimal SMPC geometry for debris capture.

Functional and performance requirements

- 1-10 cm: 1, 3, 5 cm (with the same architecture)
- 10x10, 30x30, and 50x50 with I, I/2, and I/4 shape ratio
- Altitude of 800 km

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- Possibility of different weights
- Rotational speed
- From large debris fragmentation







L x L 3L x 3L

5L x 5L Area

L 3L/2 5L/4 Depth



Analysis of debris distribution and properties

Data from ESA

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- Existing Space object catalogues are typically limited to objects larger than 5 - 10 cm at low altitudes (LEO)
- Focus of large debris
- ENVISAT spin < 1 rpm





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Analysis of Space environment

Data from ISS

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- MISSE 9, 10, 12, 13 with NASA Glenn
- Complex environment
 - Vacuum: outgassing
 - Atomic oxygen
 - Ultraviolet radiation
 - Particulate or ionizing radiation
 - Plasma
 - Temperature extremes and thermal cycling: -120°C to 120°C
 - Micrometeoroid and orbital debris impact: from 10 to 60 km/s









Conclusion

- Possible target: 1, 3, 5 cm in size, different shape and shape ratio, spin of 10 rpm, variable mass;
- This debris size is compatible with a low-cost low-size expendable cleaning satellite, above all in the optic of Space manufacturing;
- As a first requirement, the size of the SMPC grabbing device will be confined
- in 1U;

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- Moreover, the same device will be able to capture 3 objects with different size in the selected range.
- Next steps

		M1	M2	M3	M4	M5	M6	M7	M8	M9	M10	M11	M12
WP1	Device working conditions (M1-M6)												
T1.1.	Background and potential of SpaDeS												
T1.2.	Analysis of debris distribution and properties												
T1.3.	Analysis of Space environment												
T1.4.	Conceptual design of the grabbing mechanism												
T1.5.	Example of a cleaning mission												
T1.6.	Intermediate review meeting.												
WP2	Design and modelling (M4-M9)												
T2.1.	Definition of the grabbing geometry												
T2.2.	Definition of the manufacturing procedure												
T2.3.	Design of the SMPC device												
T2.4.	Modelling the behaviour of the SMPC device.												
WP3 - Validation (M7-M12)													
T3.1.	Manufacturing SMPC samples												
T3.2.	Sample characterisation												
T3.3.	Manufacturing SMPC devices												
T3.4.	Testing SMPC device functionalities												
T3.5.	Validating numerical models												
T3.6.	Final review meeting and related deliverables												
			Review Meeting						Final meeting				
	01-apr-2	21											
	30-sep-	21											
	01-apr-2	22											

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