

AUTOCODING WORKING GROUP

Automatic Code Generation for AOCS Flight SW

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Special thanks for their valuable contribution to: Michele Pioli (trainee at ESA)
Francesco Grassini (TEC-SW) and the Extended Working Group



Outline of the presentation

- Background – Extended WG objectives
- Presentation of ESA Handbook
- Autocoding Process Definition
- Extended WG Major Comments overview
- Planning / Conclusions

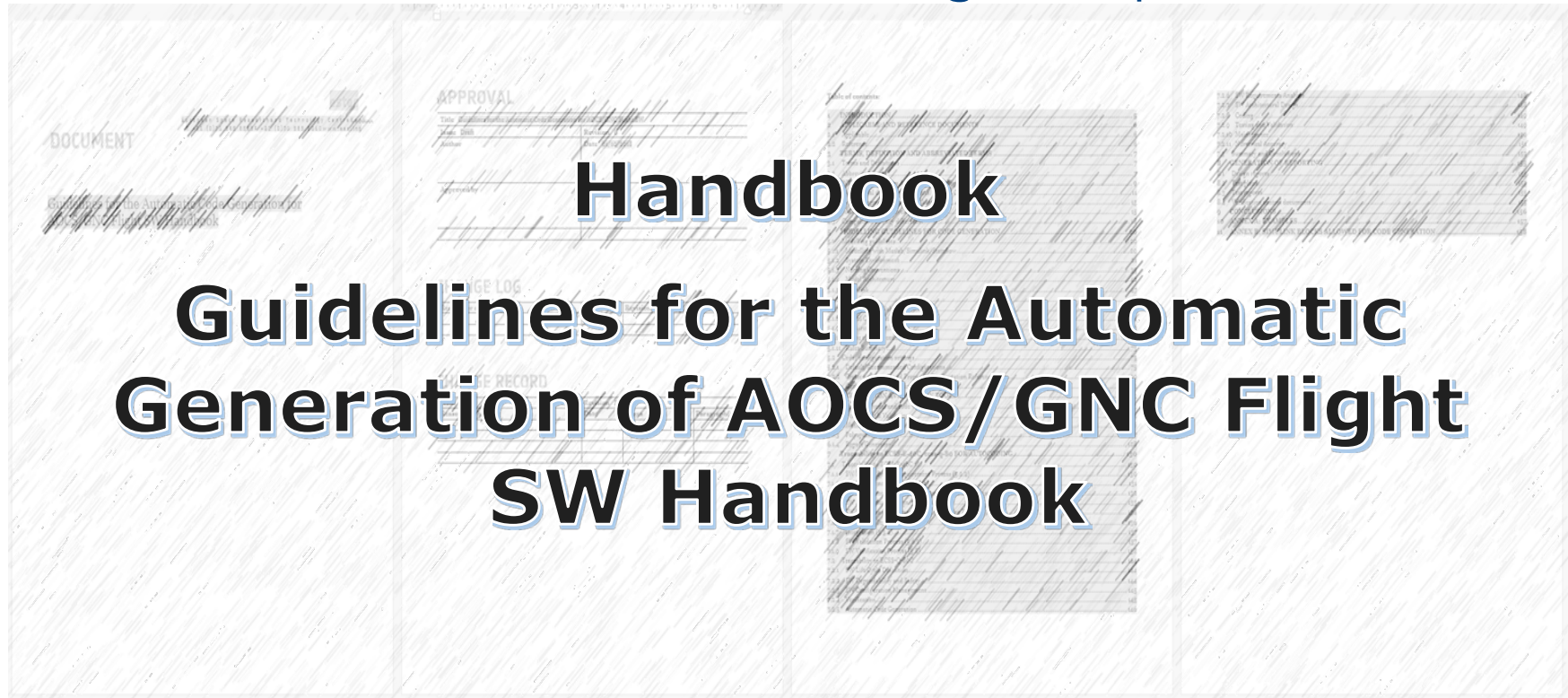




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AUTOCODE Working Group



Handbook

Guidelines for the Automatic Generation of AOCS/GNC Flight SW Handbook



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AUTOCODE Extended Working Group

The purpose of this Extended Working Group (EWG) is to **review the ESA Modeling guidelines for Autocoding Handbook** to be used as reference when creating models and generating flight code.

The Handbook shall be used as reference with the objective of ensuring generated code is correct, reliable, readable, sharable/reuse-able and maintainable.

The intended use of the guidelines are the following ones:

- Use in **support to projects** providing a harmonized ESA position across the Agency.
- Use in **R&D technology activities**.
- Promotion of the use of this type of methodology **across the phases of a development**.
- Contribution to the **assessment of the quality** of the final software product

The scope of the Handbook includes

- The **technology** (modelling guidelines, impact of the code generator, etc...)
- The **process** (GNC algorithm development process and application software process covering all the life cycle up to V&V)

General Modelling Guidelines

Approaches everything that has to do with the environment, in which the user models the system

| | |
|-------------|--|
| ID | ESA-SY-001 |
| Title | Consistent software environment |
| Priority | Mandatory |
| Description | <p>During software development, it is recommended that a consistent software environment is used across the project. Software includes, but is not limited, to:</p> <ul style="list-style-type: none"> - MATLAB - Simulink - C Compiler (for simulation) - C Compiler (for target hardware) <p>Consistent software environment implies that the same version of the software is used across the full project. The version number applies to any patches or extensions to the software used by a group.</p> |
| Rationale | If different versions are used there is no guarantee that the features will be compatible and the generated code is the same. This rule ensures the outcome is as expected. |

Simulink

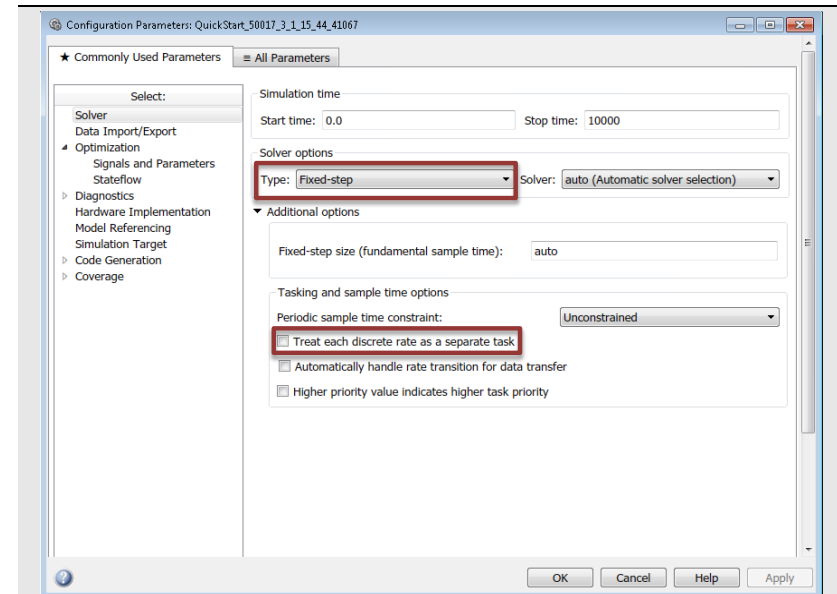
Rules regarding the Simulink blocks

| | |
|-------------|--|
| ID | ESA-SL-001 |
| Title | Blocks not recommended for C/C++ code production |
| Priority | Mandatory |
| Description | <p>The model should not have any kind of blocks that are not suitable for code production.</p> <p>The list of such blocks can be used in annex Error! Reference source not found.</p> <p>Automatic Testing: mathworks.do178.PCGSupport mathworks.maab.jm_0001 mathworks.maab.hd_0001</p> |
| Rationale | Using blocks compatible with code generation is essential for the process. |

Generated Code Structure

These rules apply to the entire model

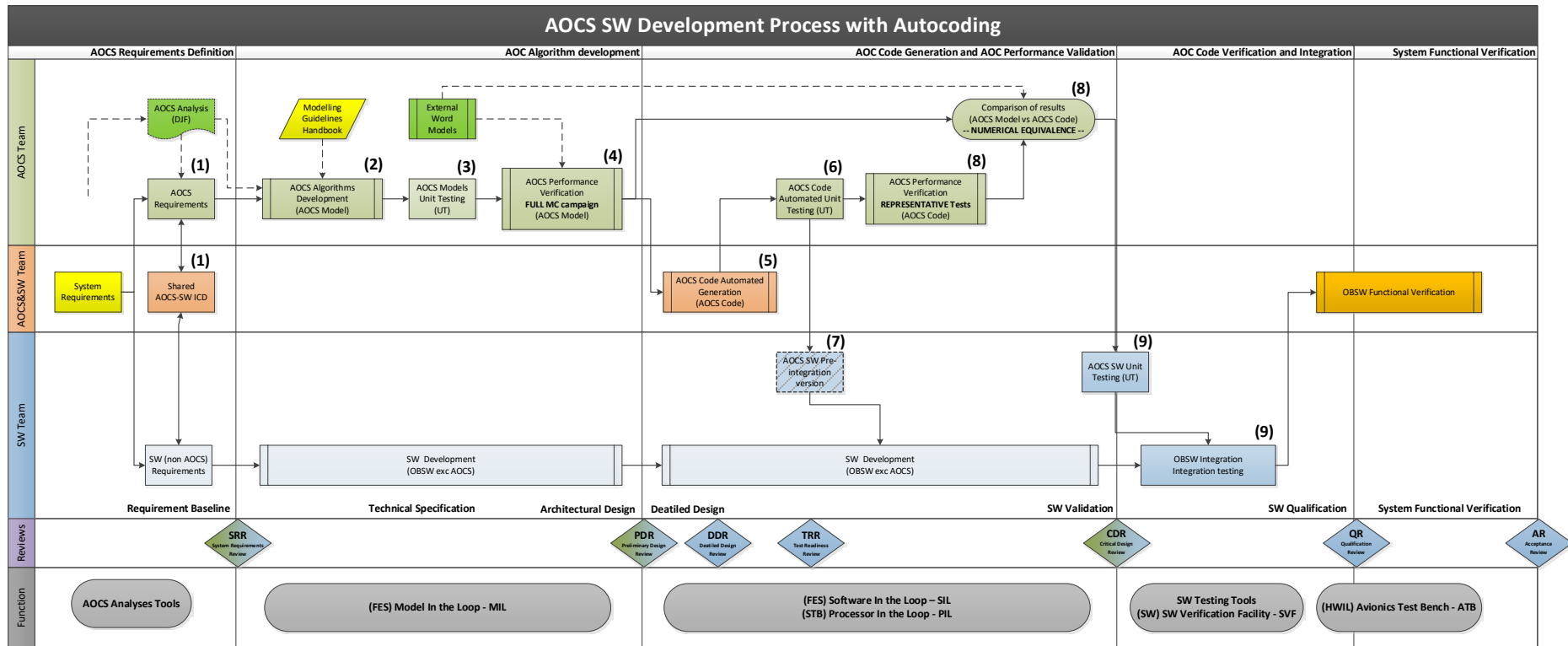
| | |
|-------------|---|
| ID | ESA |
| Title | Parameter definition |
| Priority | Highly Recommended |
| Description | <p>The parameters should be documented along with the class chosen for the parameter definition.</p> <p>It is recommended that parameters are defined either in the File Scope or in a general file containing all the OBSW parameters.</p> <p>Procedures and options on how to define parameter classes are demarcated in subsection Error! Reference source not found.</p> |
| Rationale | By defining beforehand how the parameters should be defined, it become predictable in which portion of the code the parameters will be declared and defined. |

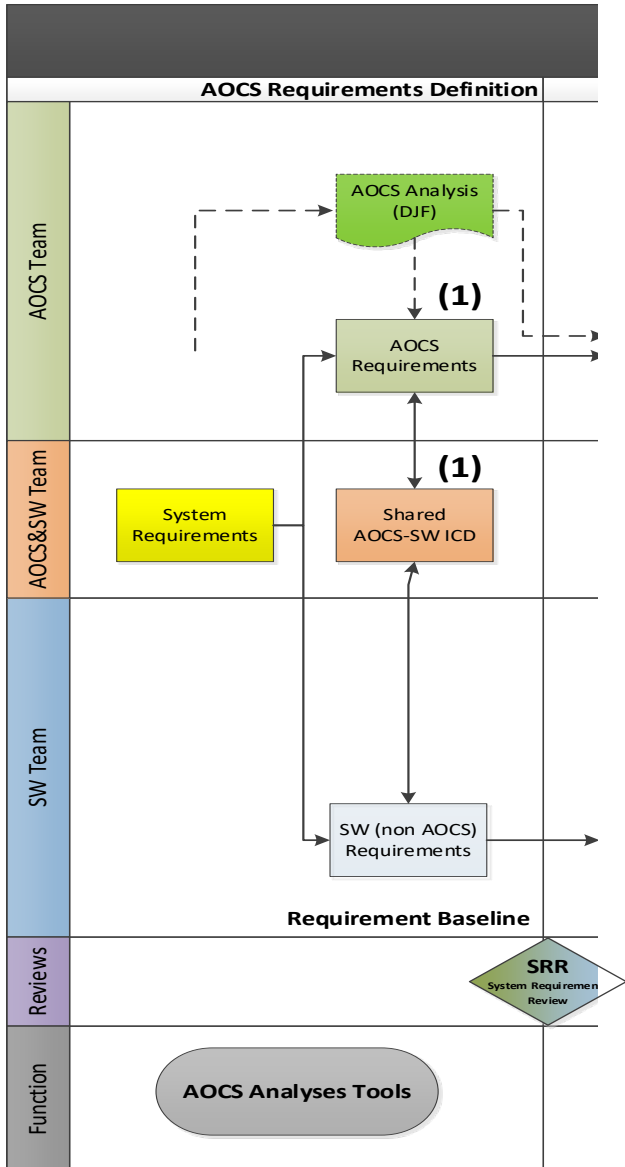


| Parameter | Value | Description |
|---|------------|--|
| Type: | Fixed-step | Required for code generation |
| Treat each discrete rate as a separate task | Unselected | Makes sure only one sample time (interruption in generated code) is generated. |

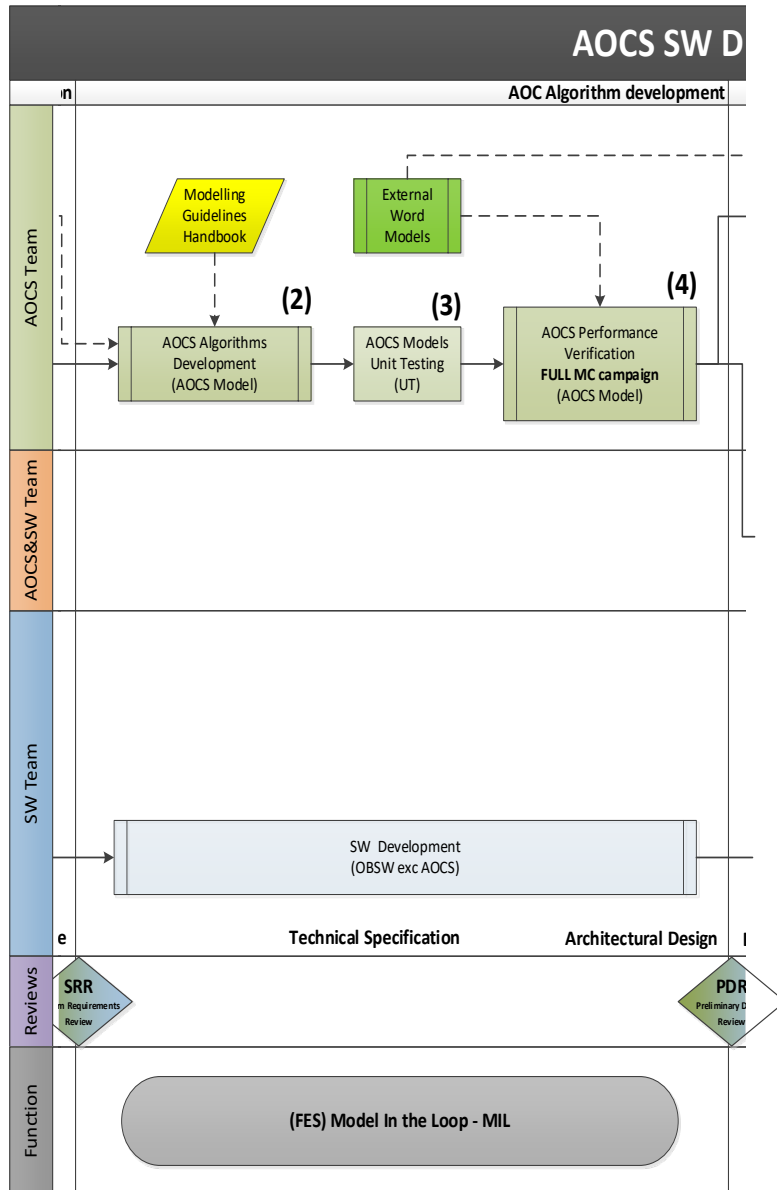
| Clause | Description | Compliance |
|---------|--|---|
| 5.3.2.4 | <p>Automatic code generation</p> <p>a. The autocode input models shall be reviewed together with the rest of the software specification, architecture and design.</p> <p>NOTE The autocode input models are integral part of the software specification, architecture and design. EXPECTED OUTPUT: Autocode input model review [MGT, SDP; SRR, PDR].</p> <p>b. In the case of coexisting autocoded and manually written parts, the software development plan shall include the definition of a clear interface definition and resource allocation (memory, CPU) at PDR. EXPECTED OUTPUT: Autocode interface definition and resource allocation [MGT, SDP; SRR, PDR].</p> <p>c. The input model management, the code generation process and supporting tools shall be documented in the SDP. EXPECTED OUTPUT: Automatic code generation development process and tools [MGT, SDP; SRR, PDR].</p> <p>d. The supplier shall define in the SDP the verification and validation strategy for automatic code generation as a result of the trade off between the qualification of the code generation toolchain and the end to end validation strategy of the software item, or any combination thereof, in relation with ECSS-Q-ST-80 clause 6.2.8. EXPECTED OUTPUT: Automatic code generation verification and validation strategy [MGT, SDP; SRR, PDR].</p> <p>e. The configuration management of the automatic code generation related elements shall be defined in the SCMP. EXPECTED OUTPUT: Automatic code generation configuration management [MGT, SCMP; SRR, PDR].</p> | <p>a. Proposed in this HB: the model is part of the PDR, DDR reviewed by joint GNC/SW teams</p> <p>b. As proposed in this HB. In particular a SW/SW ICD between manual SW/GNC models and autocoded SW shall exist and be submitted to PDR</p> <p>c. This HB provided useful inputs for such Software Development Plan</p> <p>d. Qualification of the code generator is complex. Instead, this HB provide inputs for producing automated "qualifiable" code</p> <p>e. The approach to configuration management of model options, model toolchain shall be described in the SW Configuration Management Plan.</p> |

Automatic Code Generation approach of AOCS FSW



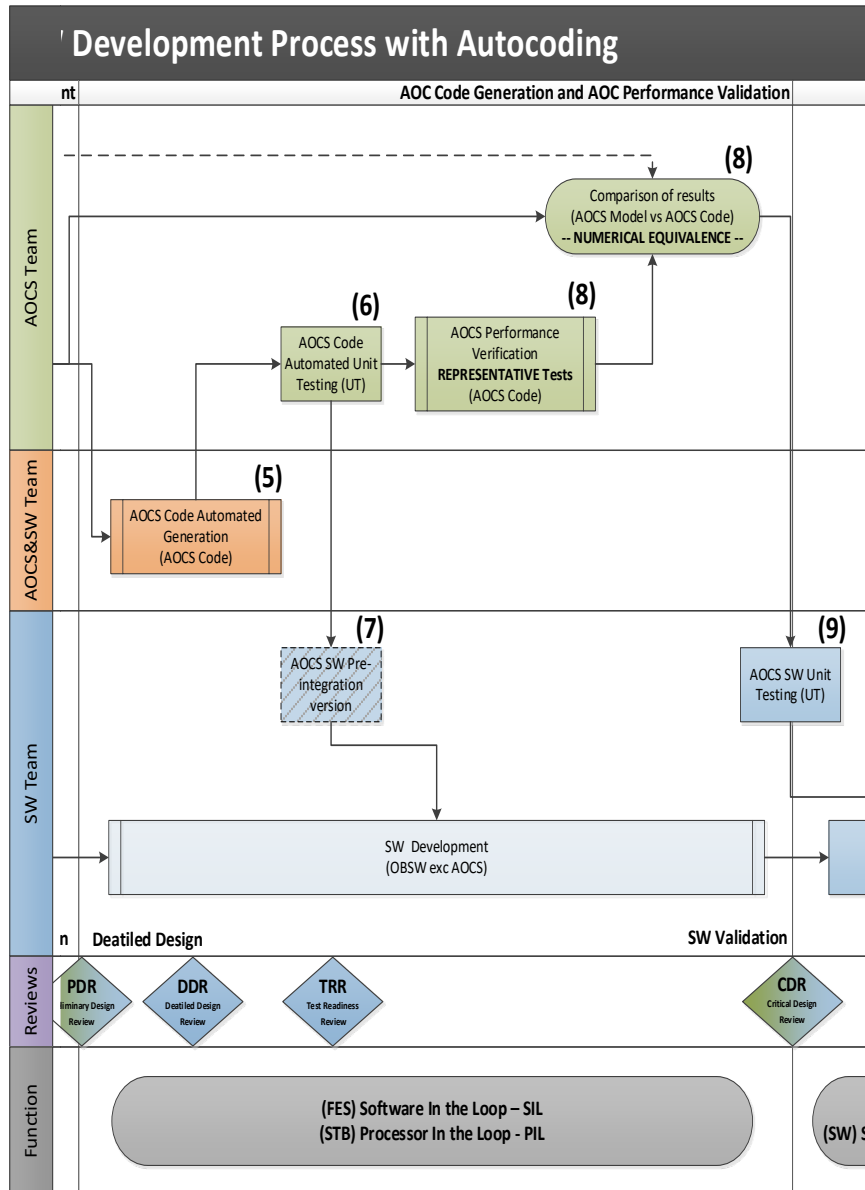


| N | Name | Description | Facilities |
|-----|------------------------------|---|----------------|
| (1) | AOCS Requirements Definition | Derivation/apportionment of AOCS requirements from System requirements. AOCS/SW ICD shall be developed together by AOCS and SW team | Analyses tools |



| N | Name | Description | Facilities |
|-----|---|---|---|
| (2) | AOCS Algorithms Development (AOCS Models) | Development and modelling of the AOCS algorithms (following the modelling guidelines) <u>Note:</u> in parallel the models for external world (DKE, Sensors, Actuators, Environment) shall be developed and made available for the performance tests | Modelling tools (e.g. Matlab, Simulink) |
| (3) | AOCS Models Unit Tests (AOCS Models) | The developed algorithms are subjected to Unit Testing where they are checked against modelling standard guidelines (generation of C-code) and open loop tests performed to be used as reference cases. Coverage tests are also performed to ensure sufficient model coverage with selected test harness | Modelling tools (e.g. Matlab, Simulink) |
| (4) | AOCS Performance verification (AOCS Models) | AOCS team runs performance verification campaign (normally Monte Carlo) to verify the compliance with performance requirements | Modelling tools (e.g. Matlab, Simulink) |

Automatic Code Generation approach of AOCS FSW



| N | Name | Description | Facilities |
|-----|--|---|--|
| (5) | AOCS Code Generation (AOCS Models to AOCS SW) | Automatic Generation of the AOC SW Code | Coder tools (e.g. Simulink Coder) |
| (6) | AOCS Code Test (AOCS SW) | The (auto)generated code is subjected to several tests to verify the correctness of code generation process. This consists of code generation guidelines compliance testings and coverage testing to ensure sufficient code coverage with selected test harness | Modelling tools (e.g. Matlab, Simulink) |
| (7) | AOCS Code preliminary integration (AOCS SW not verified) | The generated AOCS Code is delivered to SW team for pre-integration tests with the other On board SW modules. The feedback from pre-integration test is sent back to AOCS team to be implemented in the Model before final delivery (derisk of integration issues after final delivery) | SW Testing Environment (SIL, PIL) |
| (8) | Proof of Equivalence test (AOCS Model & AOCS SW) | The Proof of Equivalence test is aimed to verify that the generated code behaves as the Model at numerical precision level. The test compares results from representative (sufficient coverage shall be granted together with sufficient excitation of functionalities) set of reference tests cases run on the same test environment (e.g. Matlab MIL and SIL) using AOCS Models and AOCS SW. <i>Note:</i> in case the test is not succesful (i.e. some differences cannot be explained) or as an alternative the AOCS Generated Code shall be submitted to full AOCS Performance campaign (e.g. Monte Carlo) on the SIL to verify the compliance with AOCS performance requirements. | Test Environment MIL and SIL (e.g. Matlab, Simulink) |
| (9) | AOCS Code Verification and Integration (AOCS SW) | The generated and verified Code is delivered to the SW team to undergo the SW Unit Tests as per standard SW development plan and the integrated in the On Board SW (OBSW) for their qualification and acceptance testing before final delivery to system for functional verification (as per standard process) | SW Testing Environment (SVF, PIL, HWIL) |





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AUTOCODE Extended Working Group *Major comments overview*



Collection of comments and observations to the HB draft
TAS, ADS, OHB, GMV, CNES, DLR
Mathworks has been also involved focused on details about the toolboxes

ESA-SE-050: Library Blocks Defined as Atomic

All the library blocks (e.g. mathematical, guidance, navigation, control models, etc.) shall be set as atomic subsystem with explicitly specified interfaces for data type and dimension.

Model reference is the only way to ensure deterministic, reusable C code. Reusable functions shall be defined as **reference model** to ensure that same code is generated and strong definition of I/O ports to ensure the consistency.

ESA-SE-010: Consistent Software Environment

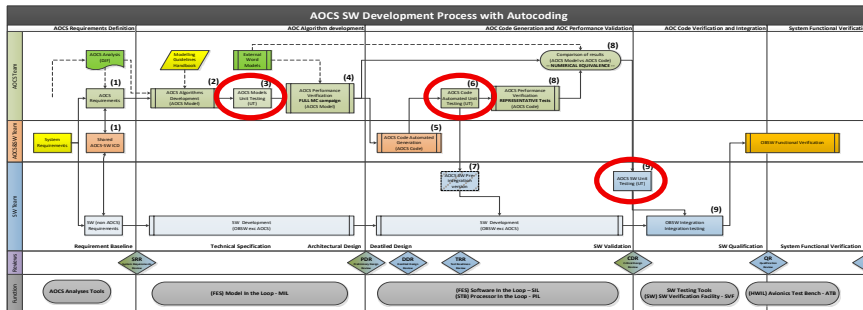
During software development, it is recommended that a consistent software environment is used across the project. Consistent software environment implies that the same version of the software is used across the full project

It will be clarified that the freezing of the development environment release (e.g. Matlab version) shall be in place at the proof of equivalence step, just before the code generation process.

Autocoding Process: Unit Testing on Model, Code and generated SW *Why Unit testing at different levels are necessary?*

| | | | |
|-----|--------------------------------------|--|---|
| (3) | AOCS Models Unit Tests (AOCS Models) | The developed algorithms are subjected to Unit Testing where they are checked against modelling standard guidelines (generation of C-code) and open loop tests performed to be used as reference cases. Coverage tests are also performed to ensure sufficient model coverage with selected test harness | Modelling tools (e.g. Matlab, Simulink) |
|-----|--------------------------------------|--|---|

| | | | |
|-----|--------------------------|---|---|
| (6) | AOCS Code Test (AOCS SW) | The (auto)generated code is subjected to several tests to verify the correctness of code generation process. This consists of code generation guidelines compliance testings and coverage testing to ensure sufficient code coverage with selected test harness | Modelling tools (e.g. Matlab, Simulink) |
|-----|--------------------------|---|---|



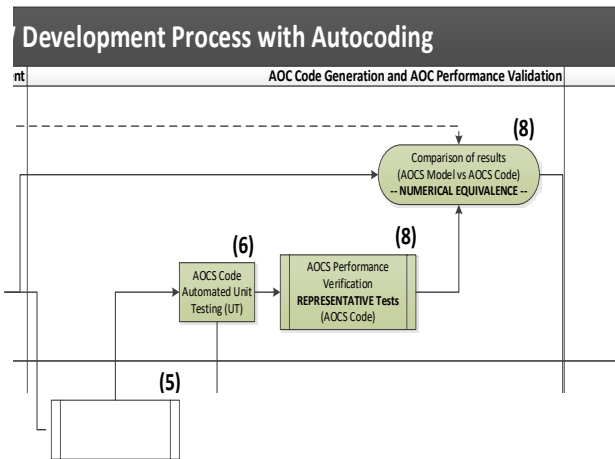
| | | | |
|-----|--|--|---|
| (9) | AOCS Code Verification and Integration (AOCS SW) | The generated and verified Code is delivered to the SW team to undergo the SW Unit Tests as per standard SW development plan and the integrated in the On Board SW (OBSW) for further qualification and acceptance testing before final delivery to system for functional verification (as per standard process) | SW Testing Environment (SVF, PIL, HWIL) |
|-----|--|--|---|

The Model Unit Tests are different in scope and execution from SW Unit Tests and therefore they cannot be skipped.

SW unit tests are considered complementary tests aiming to achieve compliance with ECSS E-40 requirement 5.5.3.2 clause c (currently reported in a note in section 7.1.6)

Autocoding Process: MC campaign on MIL & 'Proof of Equivalence' test SIL == MIL

What about running the MC campaign with the final SW (=SIL and not prototyped)?



| | | | |
|-----|--|--|--|
| (8) | Proof of Equivalence test (AOCS Model & AOCS SW) | <p>The Proof of Equivalence test is aimed to verify that the generated code behaves as the Model at numerical precision level. The test compares results from representative (sufficient coverage shall be granted together with sufficient excitation of functionalities) set of reference tests cases run on the same test environment (e.g. Matlab MIL and SIL) using AOCS Models and AOCS SW.</p> <p><u>Note:</u> in case the test is not succesful (i.e. some differences cannot be explained) or as an alternative the AOCS Generated Code shall be submitted to full AOCS Performance campaign (e.g. Monte Carlo) on the SIL to verify the compliance with AOCS performance requirements.</p> | Test Environment MIL and SIL (e.g. Matlab, Simulink) |
|-----|--|--|--|

Despite it is considered against one of the advantages of the autocoding process, alternative verification approach where performance are verified in SIL will be included in the HB.

Even with such alternative approach any change needed from test results shall be implemented at model level.

V&V philosophy for Autocoding: Qualification of the tool-chain (ECSS E40 5.3.2.4.d)

Why the final product qualification cannot be achieved by qualification of the Autocoding generation tool-chain?

| Clause | Description | Compliance |
|---------|---|--|
| 5.3.2.4 | <p>Automatic code generation</p> <p>d. The supplier shall define in the SDP the verification and validation strategy for automatic code generation as a result of the trade off between the qualification of the code generation toolchain and the end to end validation strategy of the software item, or any combination thereof, in relation with ECSS-Q-ST-80 clause 6.2.8.</p> <p>EXPECTED OUTPUT: Automatic code generation verification and validation strategy [MGT, SDP; SRR, PDR].</p> | <p>d. Qualification of the code generator is complex. Instead, this HB provide inputs for producing automated “qualifiable” code</p> |

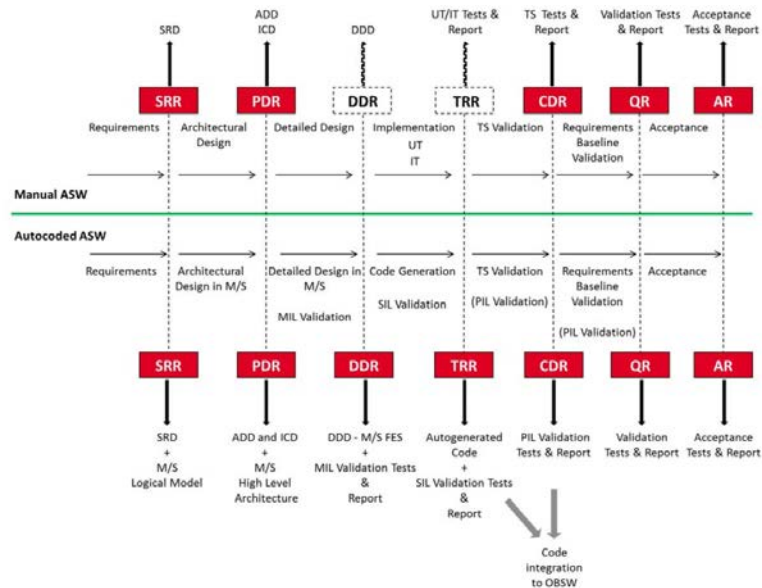
It is not intended to qualify the tool chain.

There are different reasons, the main one linked to the feasibility of this qualification considering the (quick) evolution of the tools, their complexity (all functions would need qualification) and the accessibility to the source code.

Anyway the compiler would not be qualified and the recommended approach has always been to qualify the final product.

V&V philosophy for Autocoding: deliverables, “...implies that the GNC Model shall be delivered as part of the GNC code release note”

Why the Model is a deliverable if it has been proved that the HB modelling guidelines are respected?



With the Autocoding the GNC Models became the TS for the SW generation and as such they have to be delivered to customer, to check verification, despite it is an automated process.

The maintainability of the code modifying the Simulink model (no manual change of flight code) is possible only if the model has been developed following the guidelines.

Generic process defined by industry might differ on some specific points despite is generally closed to the HB process.

The HB will define the process (shared within the extended working group) that, if followed, will avoid many iterations within specific project reviews.

Any proposed deviation will be discussed.

The Extended Working Group iterations aim to clarify the needs and harmonize understandings, with the scope to minimize specific discussions

The Handbook today covers only AOCS Flight SW

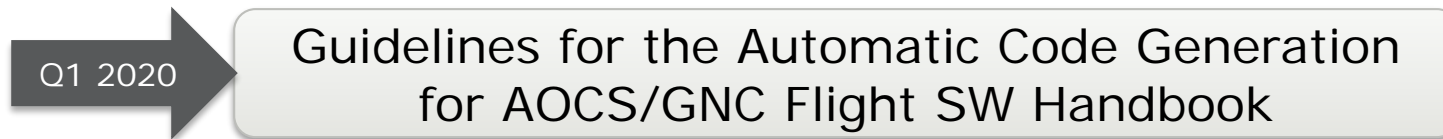
When the working group has been established within SAVOIR cappella, the scope was to define the guidelines and the process for the AOCS Flight SW Autocoding, being recognized as the most suitable considering the use of specific environments and tools for development.

In a second phase it has been agreed to look forward to extend the concept to other OBSW elements

Planning

The following schedule is in place (target dates – number of meetings is TBC):

- 11/2019 **Replies to comments** distributed back to authors
- 12/2019 Invitation to meetings (Skype):
 - 01 2020 Meeting#1 – individual review meetings
 - 02 2020 Meeting#2 – group review meeting(s)
- 02/2020 **Wrap Up** finalization of the Handbook
- March 2020 **Final issue 1**



TO BE CONTINUED

