





MACHINE LEARNING-BASED ON-BOARD REAL-TIME CLOUD DETECTION FOR THE CHIME MISSION

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COPERNICUS HYPERSPECTRAL IMAGING MISSION FOR THE ENVIRONMENT (CHIME) Radiance Levels (W/sr/m2/micron)



/// Future Space mission To complement COPERNICUS "Sentinels"

- Hyperspectral instrument with 220 spectral bands in VNIR and SWIR (400 – 2500nm) domains
- Spatial sampling of 30 m SWATH > 100 km
 Continuous acquisitions over the land and coastal
- Continuous acquisitions over the land and coastal areas

I HIGH VOLUME OF DATA => ON-BOARD COMPRESSION APPEARS MANDATORY





/// Clouds statistically cover more than 50% of the Earth surface

=> POSSIBILITY TO REDUCE ON-BOARD DATA VOLUME AND DOWNLINK DATA RATE WITH A SELECTIVE COMPRESSION APPLIED ON OPAQUE CLOUDS

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SELECTIVE CLOUD COMPRESSION

/// General compression scheme



Pre-quantization

Original



Adaptation of CCSDS standard Selective error settings Residual to Zero





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See OBPDC paper 2020 : On-board cloud detection and selective spatial/spectral compression based on CCSDS 123.0-B-2 for hyperspectral missions, Lebedeff et al for more details

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ON-BOARD CLOUD DETECTION

- /// Machine learning based cloud detection Support Vector Machine approach has been selected
- I SEPARATE PIXELS IN 2 CLASSES (CLOUD OR CLEAR) IN N-DIMENSION SPACE
 - Learning stage with cloud data base to find the optimal hyperplane between the 2 classes

MACHINE LEARNING FOR SVM PARAMETERS DETERMINATION FROM TAS EXISTING TOOL

- Machine learning inputs :
 - Useful bands for features discrimination
 - Specific indexes (i.e. band combinations) to help high reflective rejection (e.g. snow)
 - Worked on existing Cloud multi spectral Data Base (LandSat)
- Machine learning Outputs
 - Generic parameters are considered (no distinction on type of ground)
- Existing tool in the framework French sensor / Thales Alenia Space Export Programs

LANDSAT data inputs for pre-developments



X

SVM parameters uploaded on board

ON ground Machine Learning : Hyper Spectral pixel -> vector estimated

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X2



ON-BOARD CLOUD DETECTION

/// Performances assessed on SPARCS Landsat 8 data base https://landsat.usgs.gov/cloud-validation/sparcs/l8cloudmasks.zip

I 80 SCENES, SIZE 1000 X 1000 X 10 SPECTRAL BANDS WITH CLOUD MASK

I HALF OF SCENES FOR TRAINING / HALF FOR PERFORMANCE ASSESSMENT





Example of Landsat data base with mask (right)



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ON-BOARD CLOUD DETECTION

/// Globally good detection for all type of landscapes

FALSE POSITIVE*: 0.60% IN AVERAGE

I ONE CRITICAL CASE (FALSE POSITIVE>10%) OVER DESERT AREA

 Such landscape was not part of the limited training set (< 40 images) => should be removed with complete training set

- /// On hyperspectral images with SVM trained on Landsat data base
- **I** VISUALLY GOOD DETECTION, FALSE POSITIVE SEEMS LOW
- **I NO DETECTION ON IMAGE WITHOUT CLOUD** => ROBUST SOLUTION
- I POTENTIAL IMPROVEMENT WITH ADDITIONAL BANDS AND HYPERSPECTRAL IMAGES TO BE COLLECTED DURING THE PROGRAM





AVIRIS
677 x 1800
224 bands [365-2500nm]
Clouds 35.7%

710 x 5501 224 bands [365-2500nm] Clouds 38.6%



AVIRIS

*False Positive: Proportion of clear pixels incorrectly detected as cloud

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DEMONSTRATOR PHYSICAL IMPLEMENTATION



/// FTDI UMFT601X-B mezzanine

- USB 3.0 to FIFO interface bridge
- Max 2,13344Gbps

/// Xilinx KCU105 board

- FPGA: Xilinx Kintex Ultrascale, XCKU040
- External Memory: 16 Gb DDR4
- Monitoring & Control interface: UART
- Data Input and output interfaces: FMC connector with mezzanine
- USB JTAG to program the FPGA



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DEMONSTRATOR TEST SET-UP



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VALIDATION PLAN

Conformity Tests

Compliance with the models: DPM and CCSDS 123 B2 standard By VHDL simulations in workstation (Mentor Graphics Questa Sim tool) Outputs: text files coming from the simulations

Demonstrator tests

On hardware validation VHDL code synthesized, place&route performed into Xilinx FPGA Outputs: text files generated by the Tester SW in the M&C PC



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TESTS RESULTS: SUCCESS CRITERIA MET

/// SUCCESS CRITERION 1: Limited quantization error between VHDL and DPM

Matlab model (maximum 2%).

OKIII

/// SUCCESS CRITERION 2: For the Cloud Mask a maximum of 1% of False Positives admitted between implementation and model.

QK!!! With threshold adaptation

/// SUCCESS CRITERION 3: The CCSDS 123.0-B2 compressed image bit to bit comparable to the data obtained from the CNES software.

OKIII

/// SUCCESS CRITERION 4: Data rate comparable with real data rate in Chime (up to 2 Gbps, 16 bits sample at 125MHz).

Cloud Mask Validation: Threshold adapted for 0 False Positives Threshold = -81.06652800000005Number of Total Errors: 560 0.058% (100% = 965941) Number of False Positives: 0 0.000% (100% = 965941) Number of No Detected Clouds: 560 0.058% (100% = 965941)



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CONCLUSION

/// Pre-development Demonstration has been established into a Xilinx KU040 FPGA including:

- The Cloud Detection and Processing algorithms
- The CCSDS 123.0-B-2 compression modules (Predictor and Encoder)

/// Cloud compression scheme has been defined for on-board implementation

- Support vector machine for on-board cloud detection
- Spatial / spectral selective compression scheme based on CCSDS standard with potential evolutions
- Data rate reduction between 20 and 35% for images with around 40% of clouds
- /// Machine learning allows Potential improvement with additional bands And hyperspectral images to be collected during the mission
 - Cloud data base can be built / consolidated during commissioning phase
 - SVM parameters can be updated and uploaded on-board

d LANDSAT data inputs for pre-developments Hyperspectral real data collected during the CHIME program









Parameters uploaded on board to DPU

ON ground Machine Learning : Hyper Spectral pixel -> vector estimated



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