

IOT FOR EARTH OBSERVATION USES CASES

INCL. ZOOM INTO VHR CONSTELLATION

IOT4EO STUDY TEAM 16/17 FEBRUARY 2023

IOT4EO WORKSHOP @ ESA – 16/17 FEBRUARY 2023

ОНВ

IOT4EO STUDY GOALS AND PARTNERS

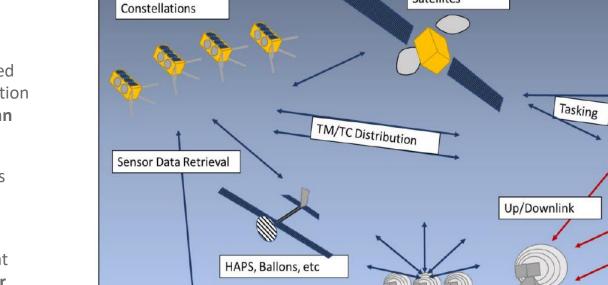
- To exploit the IoT seamless integrated networks with near instant connectivity to derive new and promising applications for Earth Observation (EO) satellite systems
- IoT nodes on-ground can be in-situ sensors, EO sensors on buoys, aboard aircrafts or HAPS and IoT Gateways
- IoT nodes in space are EO satellites, limited to LEO orbit in this study, and relay satellites in LEO, MEO and GEO
- IoT seamless communication entails simplified and low power communications systems and hence, low data rates
- EO systems can thus exploit the IoT network to send and receive urgent information, rather than as means for science data downlink and reduced latency
- IoT for Earth Observation can exploit the following four Al_on-board autonomy enablers:
 - Data processing
 - Decision making
 - Satellite cooperation
 - RF spectrum management



Industrial Team

STUDY INTRODUCTION AND UNDERSTANDING

- The first examples that arise are the fast delivery of telemetry and telecommands in case of anomalies, but also, a wide range of new end-user applications
- With on-board processing and events detection aboard the EO satellites, the IoT network could be exploited for providing end-users with key extracted information such as warnings and alarms, the location and velocity of a target, or even the triggering of an IoT actuator.
- In the definition of the EO use cases, two scenarios shall be considered:
 - <u>3 years scenario</u>: EO use cases that can be implemented with commercial IoT services that will be available in the next 3 years, with minor changes on technologies, standards and international radio regulation
 - <u>7 years scenario</u>: a more advanced and ideal case with technologies, services and standards that will be deployed in 7 years.



Users, e.g

/control centre

LEO Relay

In-Situ Sensors

GEO Relay

Satellites

IOT Ground

Gateways

TT&C Ground

Stations

EO systematic

observation

EO tasked

satellites

satellite

EO SATELLITE – PRESENT AND FUTURE



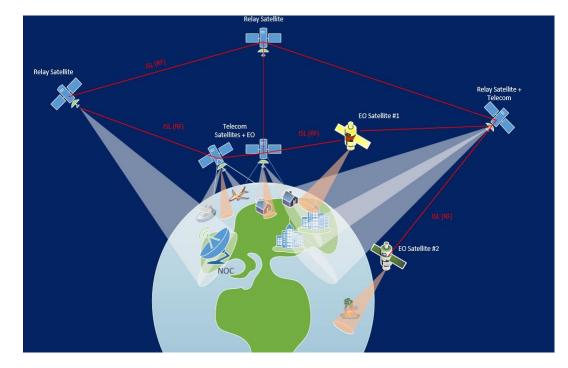
MOTIVATION FOR NEW SOLUTIONS

Current Configuration – EO satellite links



- Limited contact time
- EO Satellite working standalone
- Ad-hoc communication protocols
- High latency in transferring data
- Fixed time slots for acquisition

Future EO Satellite - Integrated Network



- EO satellite interconnected with other satellites
- Protocol /Frequencies/ to be standardized
- Low latency in transferring data
- "Near real-time" acquisition time
- Seamless network connectivity

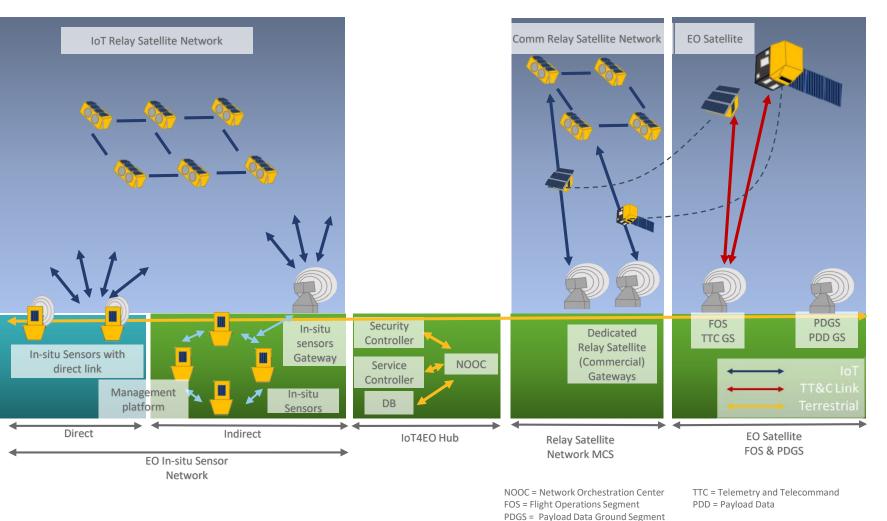
IOT4EO NETWORK ARCHITECTURE

STANDARDIZATION AND INTERCONNECTION (NETWORK OF SYSTEM)



3 years scenario

- Specific ISL transponder to be installed in new EO Satellites
- IoT Provider connected to Service Manager (NOOC) (on ground)
- NOOC as proxy between IoT provider and EO control center
- Relying on specific IoT service provider(s) (waveform and frequency)
- Limited availability of connectivity with other satellites



GS = Ground Segment

IOT4EO NETWORK ARCHITECTURE

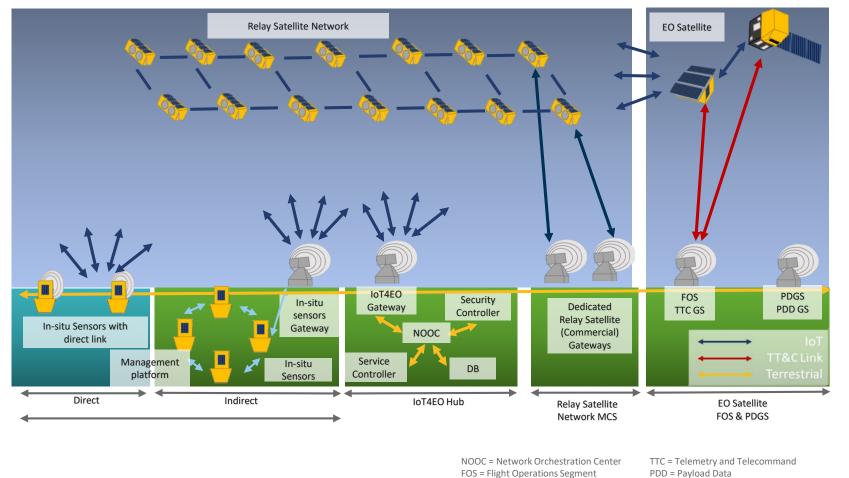


STANDARDIZATION AND INTERCONNECTION (NETWORK OF SYSTEM)

- 7 years scenario
 - a standardization is expected to be _ finalized, agreement about a standardized waveform and frequency selection
 - Connectivity to all future standardized satellites allowing EO – ISL
 - Service Manager directly interfacing either any standardized satellite or directly to the EO satellites



- **Development of dedicated standard** • transponders with low SWaP to be embarked in each EO satellite
- Standardization of IoT and data transfer . protocols (Ground to Space and Space to Space)
- Definition of available spectrum and . frequency selection



PDD = Payload Data

PDGS = Payload Data Ground Segment

GS = Ground Segment

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USE CASES – FIRST ITERATION

CURRENT TRADES

Development of dedicated standard transponders with low SWaP to be embarked in each EO satellite

For the 3 years scenario



Provider COTS Transceivers

- non-standardized
- proprietary
 Fees to the service providers
- Inter-compatibility of services

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- For the 7 years scenario
 - SDR solution
 - Standardized waveform and frequency

SDR

Dual pointing antenna (also to ground)

Definition of available spectrum and frequency selection (First iteration)

Use case #1	Use case #1	Use case #2	Use case #2
(3 years)	(7 years)	(3 years)	(7 years)
 137-138 MHz 1610-1675 MHz 1980-2025 MHz ISL: 22-24 GHz (TBC) 	 UHF (400 MHz), S-Band (2 GHz) ISL: S-band, Ka band 	 As per UC#1 ISM bands at 2.4 GHz 	As per UC#1ISM bands at 2.4 GHz

- Definition of Link Budgets and Simulations

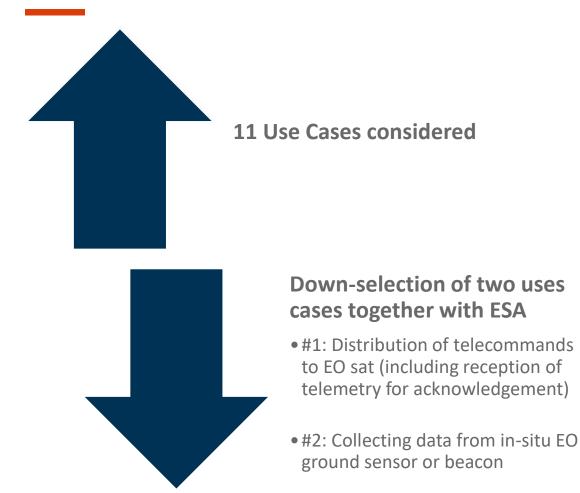




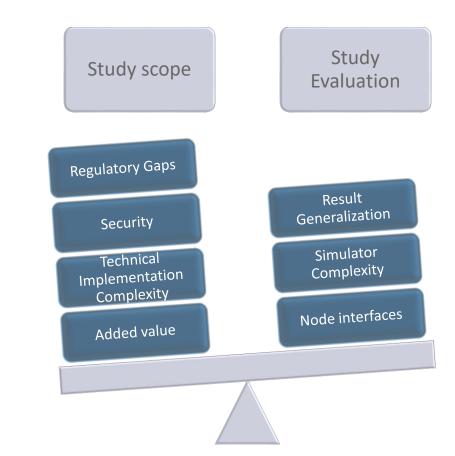
Iridium and Globalstar transceivers / Iridium and IQ Spacecom S-Band Antennas

USE CASES – TRADE OFF

DOWN-SELECTION BASED ON CRITERIA



• Trade-off criteria



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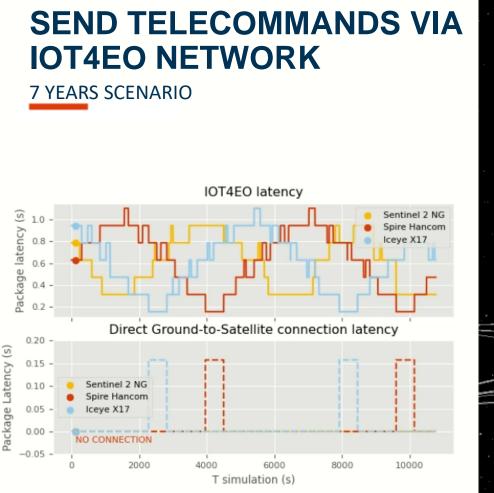
SHOWCASE SETUP OF USE CASE #1

KEY ASSUMPTIONS

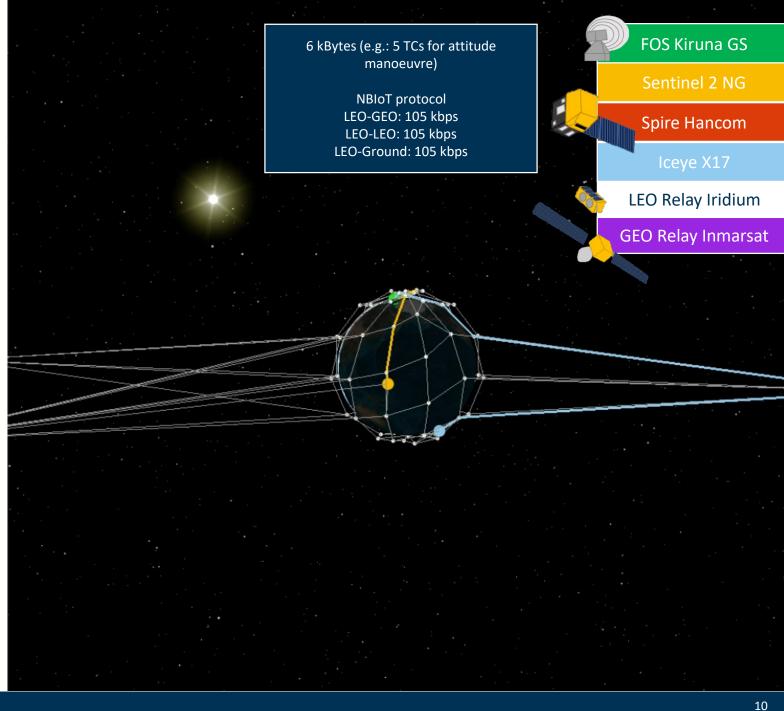
OHE

- 7 years scenario
 - Standardized IoT4EO network where EO Satellites, Relay
 Satellites and Ground nodes can all communicate between them
- Iot4EO use case
 - FOS sends 6 KBytes TC to EO Satellite via IoT4EO network
 - Sentinel-2 NG
 - Iceye
 - Spire
 - IoT4EO network with
 - LEO relay satellites (Iridium constellation)
 - GEO relay satellites (Inmarsat)
- NBIoT Protocol, with 105 kpbs data rate capability
 - LEO LEO
 - LEO GEO
 - LEO Ground

Object	Properties in simulation	
FOS Ground Station	Kiruna Ground Station	
GEO Relay Constellation	Inmarsat 4-F1, 4-F2 and 4-F3	
LEO Relay Constellation	66 Satellites Delta constellation 6 orbit planes 785km at 90° inclination Inter and intra plane ISL	
EO Sentinel 2 NG	SSO 631km at 10:30 LTDN	
EO Spire	SSO 500km	
EO Iceye	SSO 500km	



- Communication availability with EO satellite >99% •
- Intersatellite Link (ISL) between different satellites/constellations





VHR CONSTELLATION STUDY

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VHR CONSTELLATION STUDY

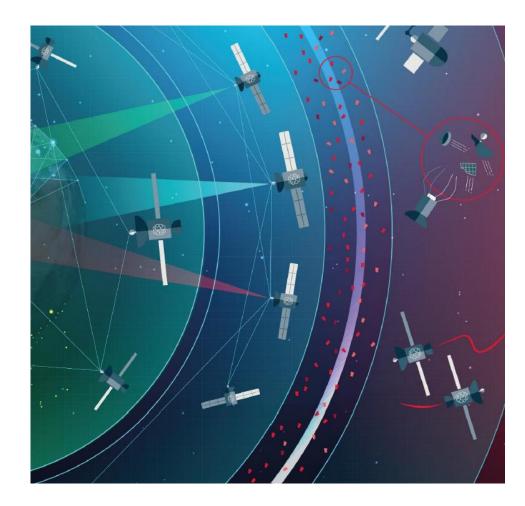
GOALS AND PARTNERS



- For the global mapping component
- For the on demand and rapid response component
- The system should complement the current and evolving Copernicus data set and support downstream services
- The system should complement Sentinel-2 NG
- The system should provide non-systematic sub-metric image acquisitions in a rapid response and agile manner
- The activity is not only covering technical aspects but also programmatic, business and legal related aspects (e.g. PPP schemes)
- Maximum reuse of European technologies and heritage







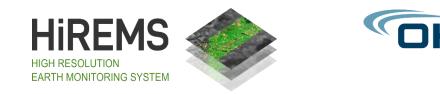
MAIN MISSION REQUIREMENTS

TWO MISSION TYPES

- Constellation A Systematic Carpet Mapping
 - RGB + PAN
 - GSD (Goal): 2 m; PAN: 1 m
 - Effective coverage: cloud free acquisitions
 - Images with max. 10% cloud coverage
 - Map of global landmasses + coastlines: 60 days
 - Co-registration with S2-NG
 - Coverage Europe: tbd



Large constellation of High Resolution microsatellites



- Constellation B Agile Targeted VHR Image Acquisition
 - RGB + PAN + Video
 - GSD (Goal): 0.6 m; PAN 0.3 m; Video 0.5 m
 - Video duration: 1,5 2 min
 - Maximum access time: < 3 hrs (Goal) 24 hrs (Threshold)
 - Coverage requirement: 100.000 km² per day
 - Geolocation accuracy < 1 SSD with GCP



Small constellation of Very High Resolution satellites

MAIN MISSION REQUIREMENTS

VIDEO REQUIREMENTS FROM EC/SECURITY DOMAIN





EMSA use cases

- Support to search and rescue
- Monitor ship transfer
- Monitor dark/suspicious vessels
- Monitor sensitive areas of interest, where there shouldn't be vessels
- Monitor small vessels that don't reflect on SAR and that are fast

SATCEN, use cases



- Evacuation plans
- Critical infrastructure (e.g. analyse if an activity is ongoing on a critical infrastructure)
- Smuggling
- Monitor migration
- Moving vehicles, people, ships
- FRONTEX, use cases

FRONTSX

- Maritime: Detection of moving vessels, small speed boats
- Terrestrial: trans-border movements; movements close to borders

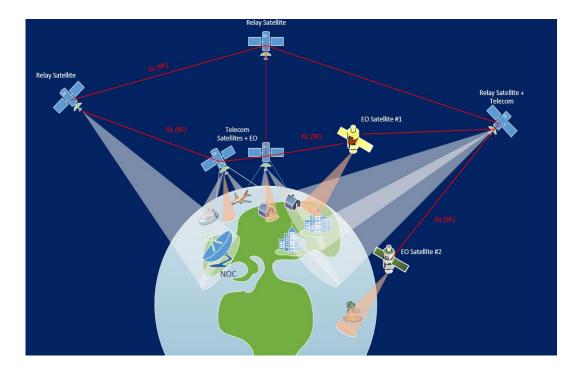


- Video duration: from 20 seconds to 2 minutes
- **Required resolution:** less than 1 meter (ideally less than or equal to 0.5 m)
- Frame rate: larger than 5 (ideally in the range 15-30 fps)
- Frequency: on-demand, with the possibility of more than 1 capture per day
- Latency (from sensing to product availability):
 < 15 minutes
- Tasking Lead Time (from User request to sensing): < 2 hours
- Revisit time: < 2 hours

ADVANTAGES IN THE AVAILABILITY OF AN IOT4EO SYSTEM SOME EXAMPLES

Achieving low system latency by faster distribution of tasking commands

- IoT sensors on ground automatically trigger imaging modes (e.g. calibration)
- Triggering of other satellites to acquire new observations in specific areas (-> interoperability)
- Support to on-board autonomy in constellations
- Download of on-board processed data (-> actionable information) directly to the ground
- → Vision: (Near) Real-time EO satellite Data-as-a-Service



- EO satellite interconnected with other satellites
- Protocol /Frequencies/ to be standardized
- Low latency in transferring data
- "Near real-time" acquisition time
- Seamless network connectivity





THANK YOU!

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