

2023 Clean Space
Industry Days

19 October 2023

ESTEC, The
Netherlands

A background image showing a satellite in orbit over a view of Earth from space, with white clouds and blue oceans.

SPACE SUSTAINABILITY RATING

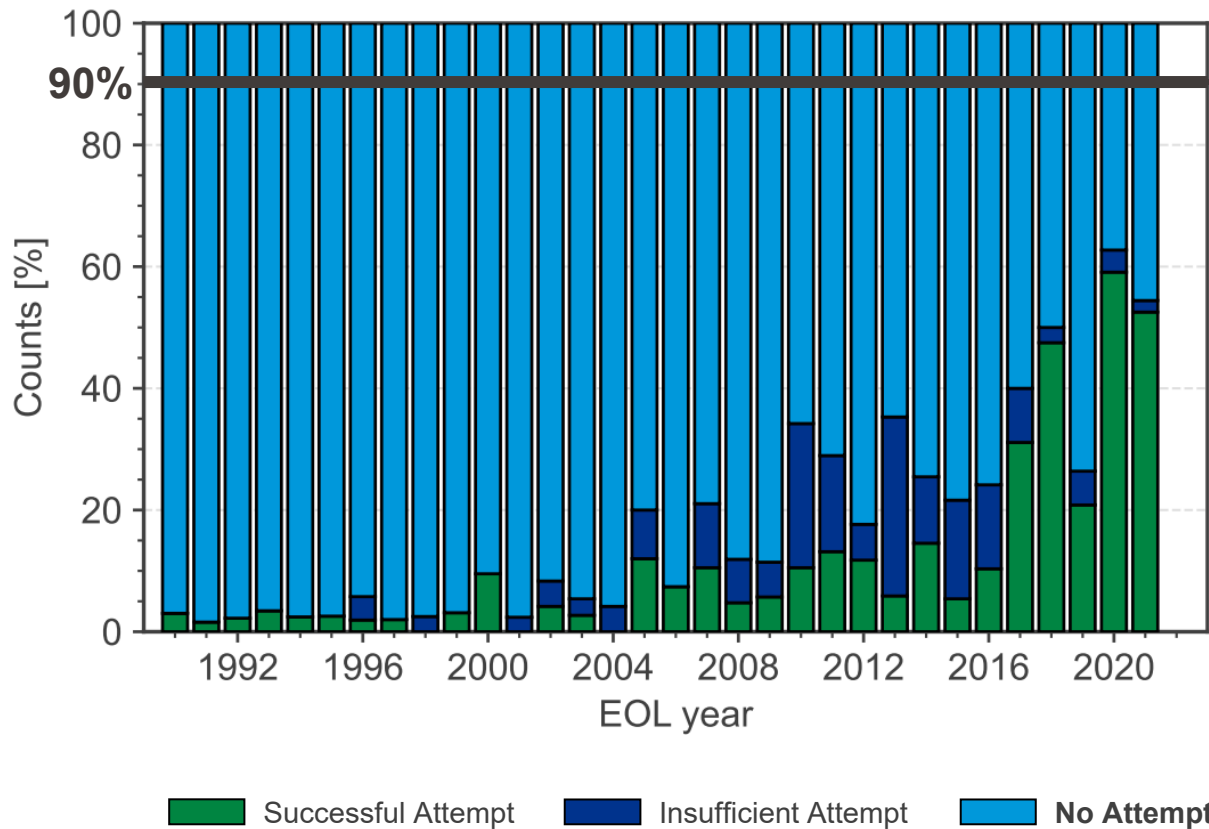
Utilization of a risk index to incentivize satellite operators to follow best practices for post mission disposal



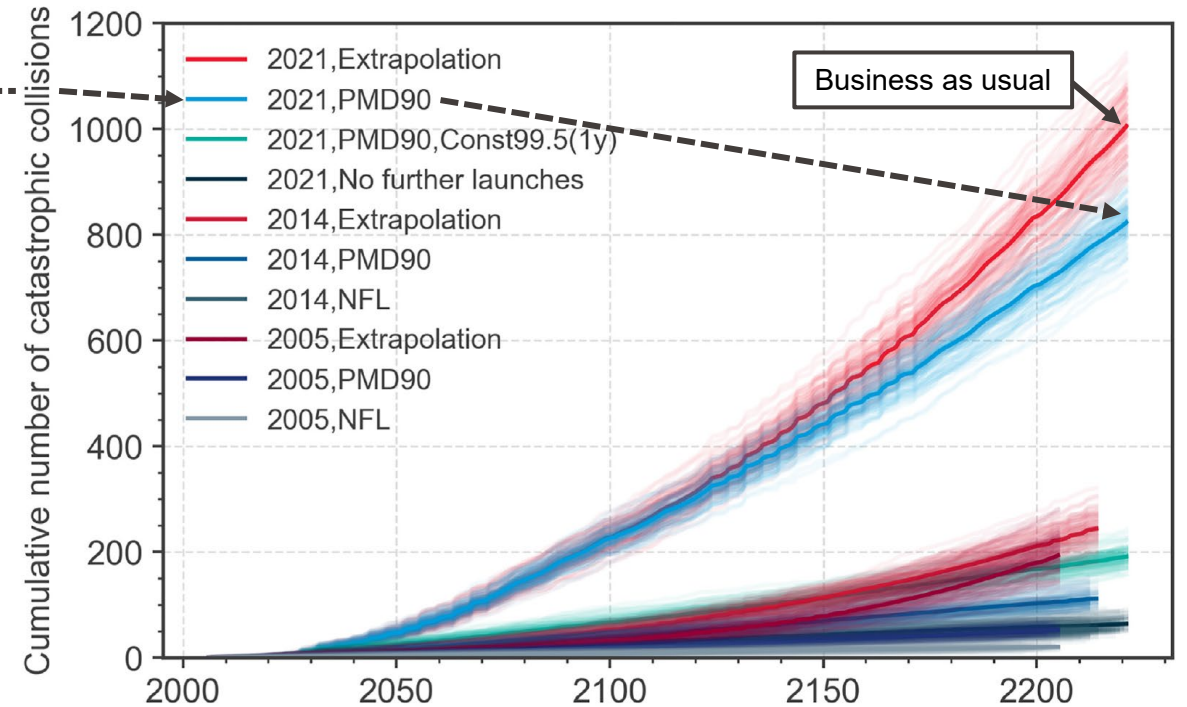
WE ARE NOT DOING ENOUGH

and doing "enough" is not enough anymore...

Payload Clearance in LEO excluding natural compliance (1)



Long-term simulation of the space environment (2)

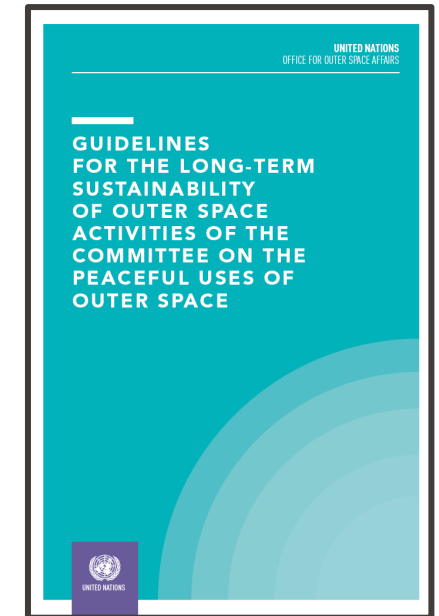
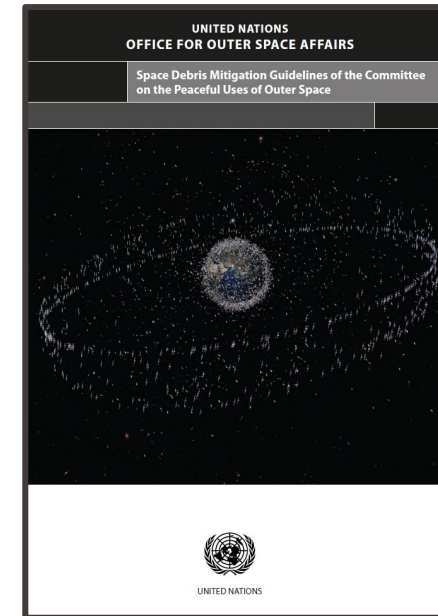
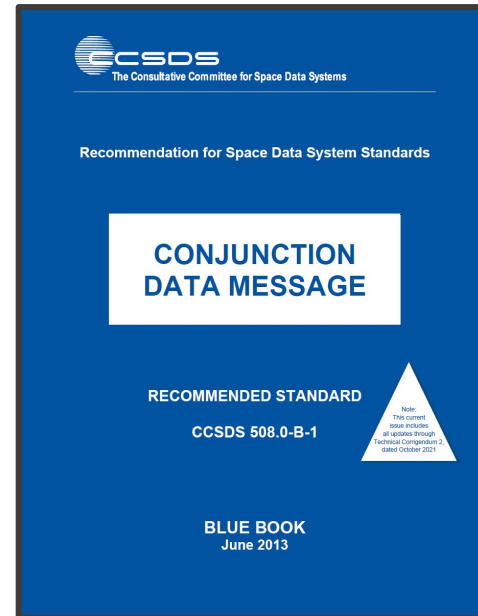
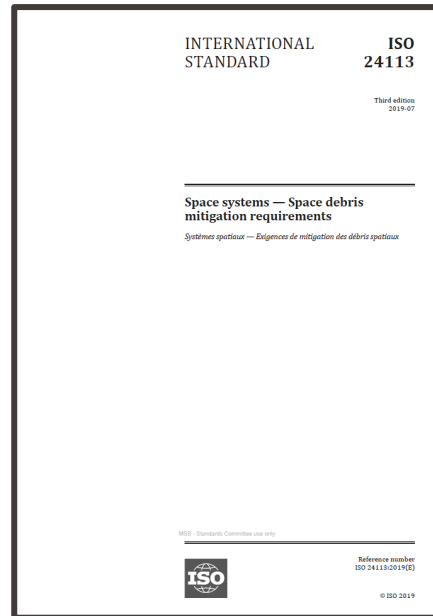
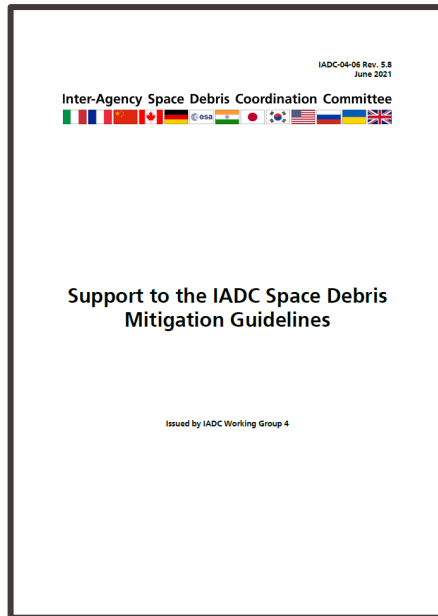


*“The extrapolation of the current behaviour to the future results in an unstable environment, with **collision rates increasing exponentially**”*



A NEED TO INCENTIVIZE FURTHER ADOPTION OF BEST PRACTISES

There are no legally binding space debris mitigation instruments (at international level)





THE SSR AS AN INCENTIVE TOOL

Encouraging space actors to design & implement sustainable & responsible space missions for the long-term sustainability of the space environment



SPACE SUSTAINABILITY RATING



BRONZE



SILVER



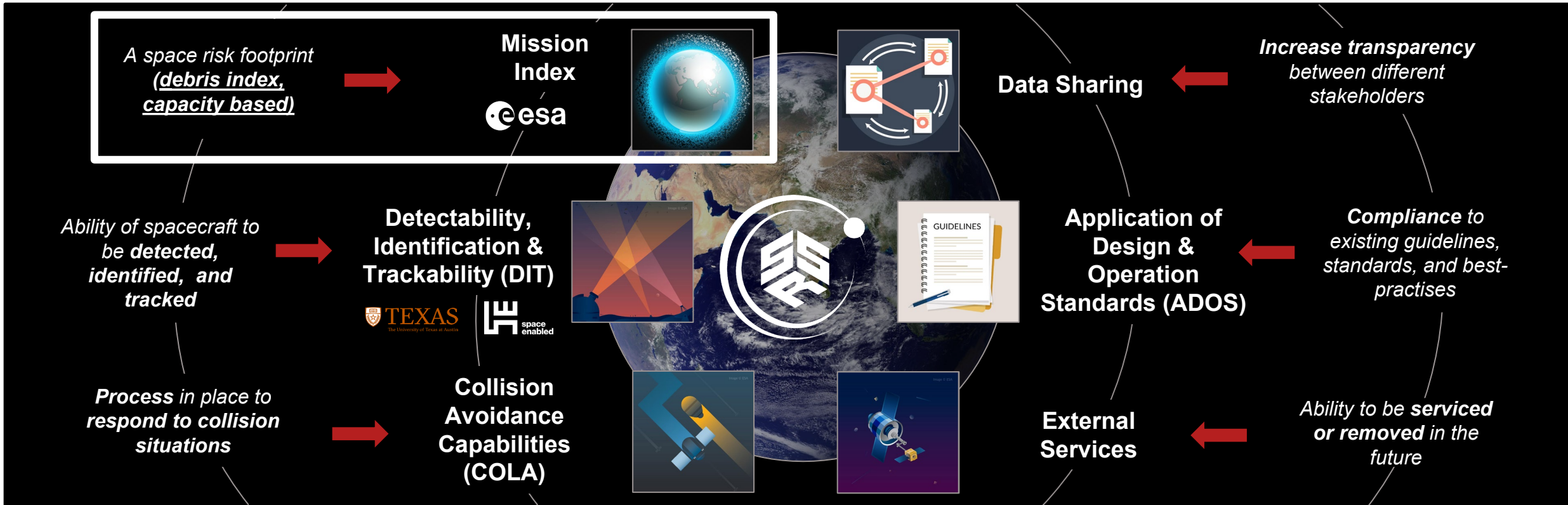
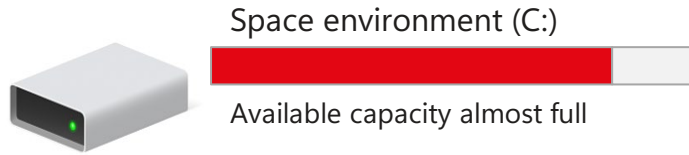
GOLD



PLATINUM



SSR MODULES IN A NUTSHELL



ACKNOWLEDGEMENT

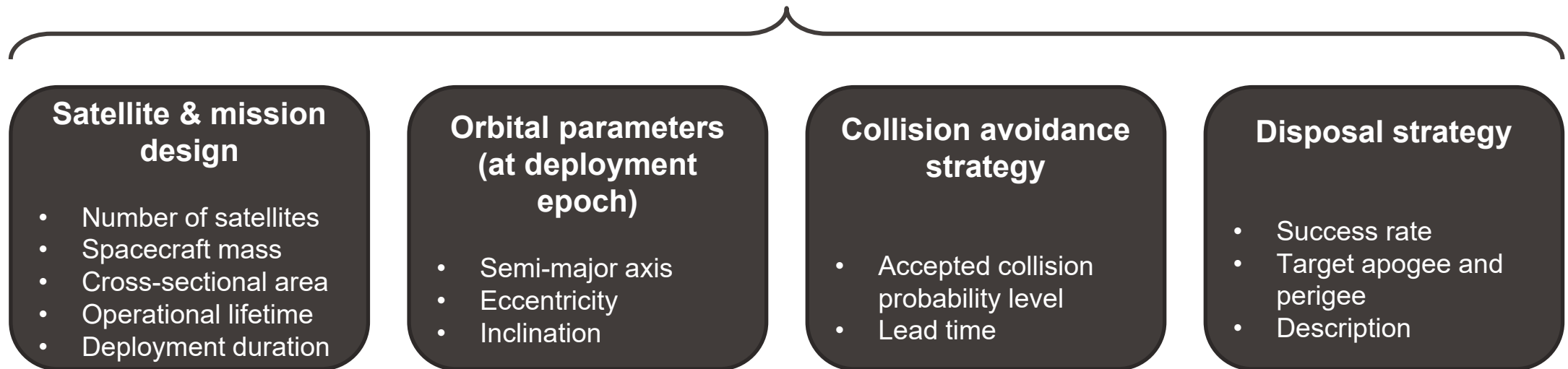
The Mission index module methodology of the Space Sustainability Rating heavily relies on research that have been performed in the past years by several entities such as ESA Space Debris Office and Politecnico di Milano.



MISSION INDEX - INPUTS

A *space risk footprint*

- Quantifies the **collision risk** using an index metric;
- Evaluates the risk contribution of a mission to the debris environment **compared to a capacity target**;
- Uses **high level parameters** that can be obtained early in the mission development;





MISSION INDEX - FORMULATION

Index formulation for one object, at a given epoch

Probability of collision p_c

$$I = p_c \cdot e_c$$

Severity of collision e_c

High $I \Leftrightarrow$ High risk \Leftrightarrow Low Score

I depends on orbital parameters and spacecraft physical properties

Environment simulated with



Cumulative collision probability

$$p_c = 1 - e^{-\rho \cdot \Delta V \cdot A \cdot \Delta t}$$

- ρ the density of object large enough to trigger a catastrophic collision (1)
- ΔV the relative impact velocity
- A the cross-sectional area
- Δt the timestep increment value

Collision severity (2)

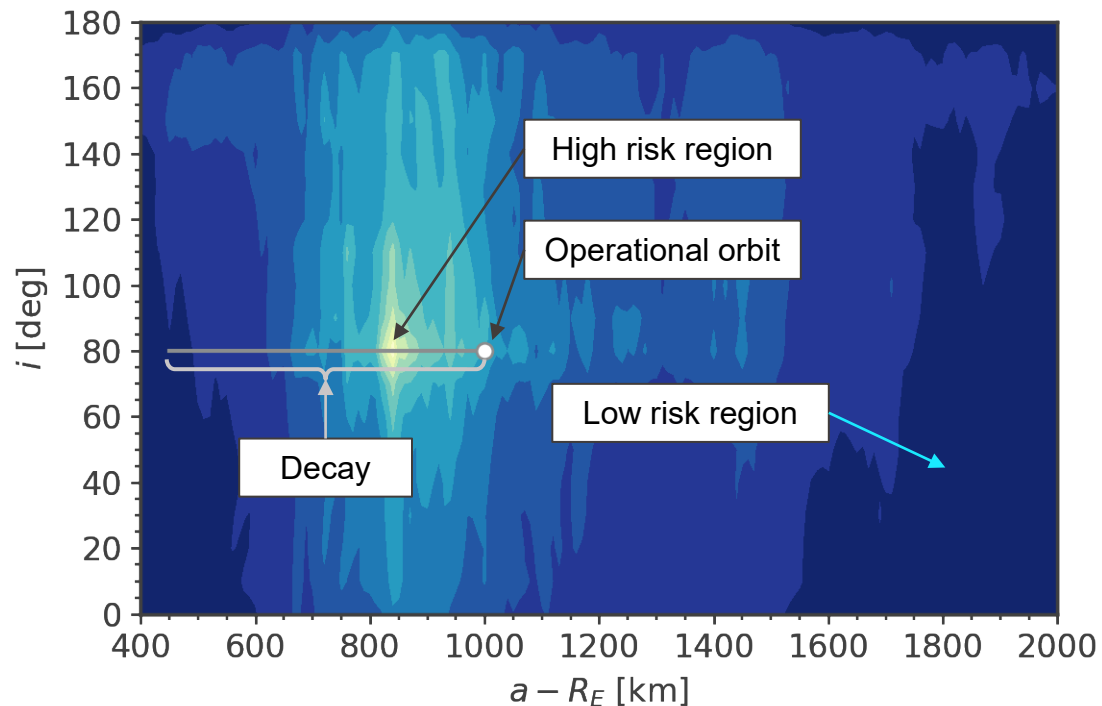
- Synthetic fragmentation triggered and modelled (reformulated NASA breakup model)
- Propagation of the debris cloud (phase space density)
- Quantification of the **increased probability of collision for a set of representative objects**





MISSION INDEX – INDEX MAPS

Index value heatmap (LEO region)



The index value is discretized, and integrated over the object's lifetime

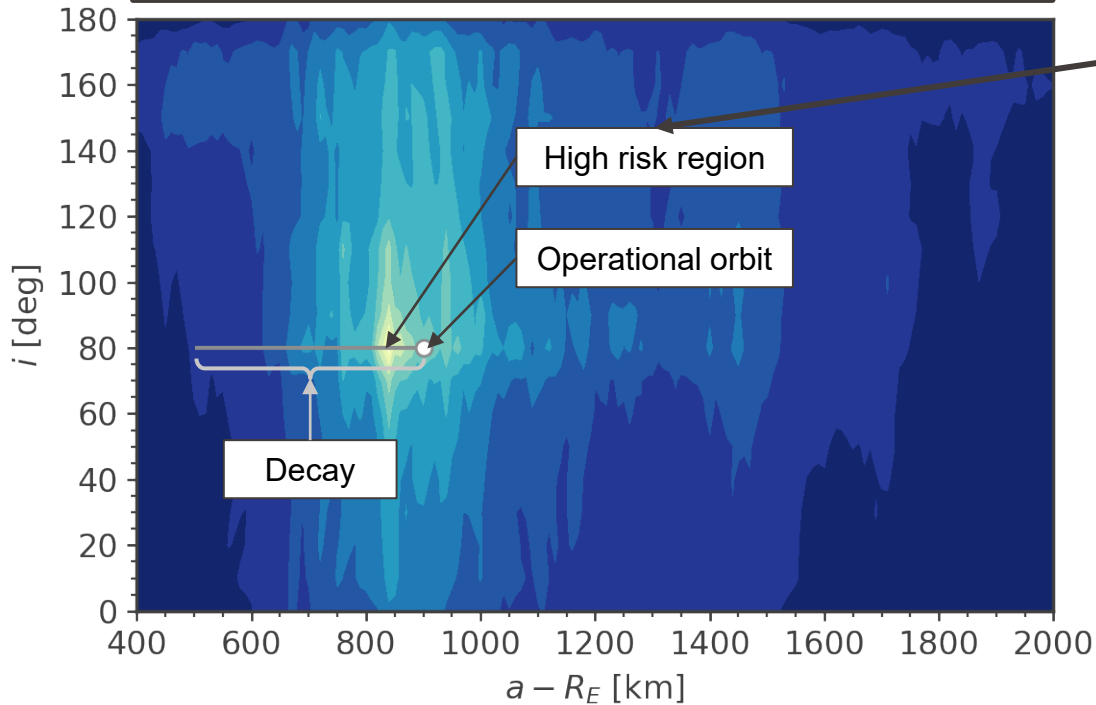
$$I = \int_{t_0}^{t_f} (p_c \cdot e_c) dt$$

Discretized index allows to account for the spacecraft trajectory evolution (e.g. orbit raising, disposal manoeuvres, orbital decay)

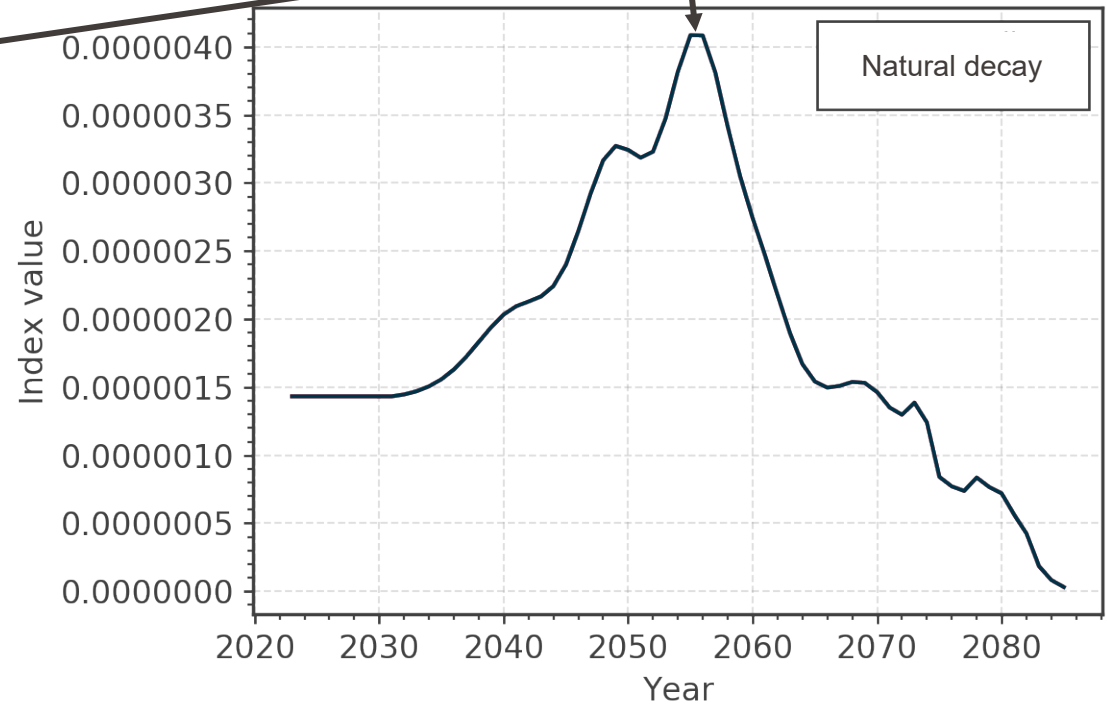


MISSION INDEX – TRAJECTORY EVOLUTION

Mock mission data:
 $A/m = 0.1$ (to highlight impact of trajectory evolution)
Initial altitude 900km
No post mission disposal (natural decay)



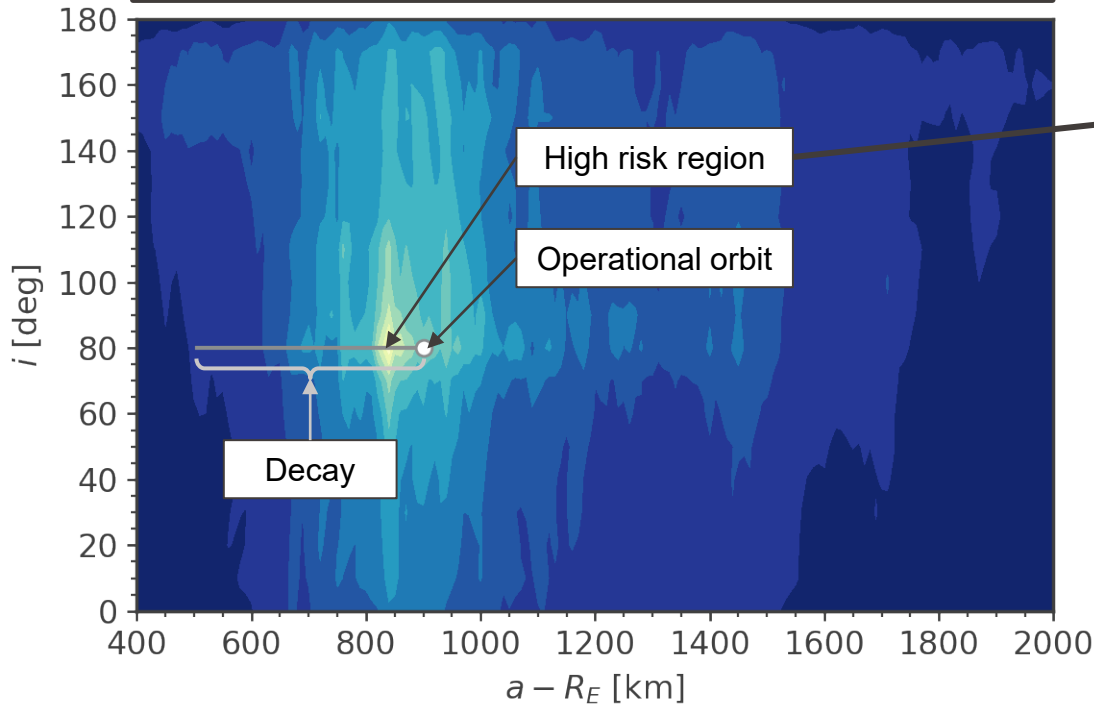
Result of satellite is crossing high risk regions during decay



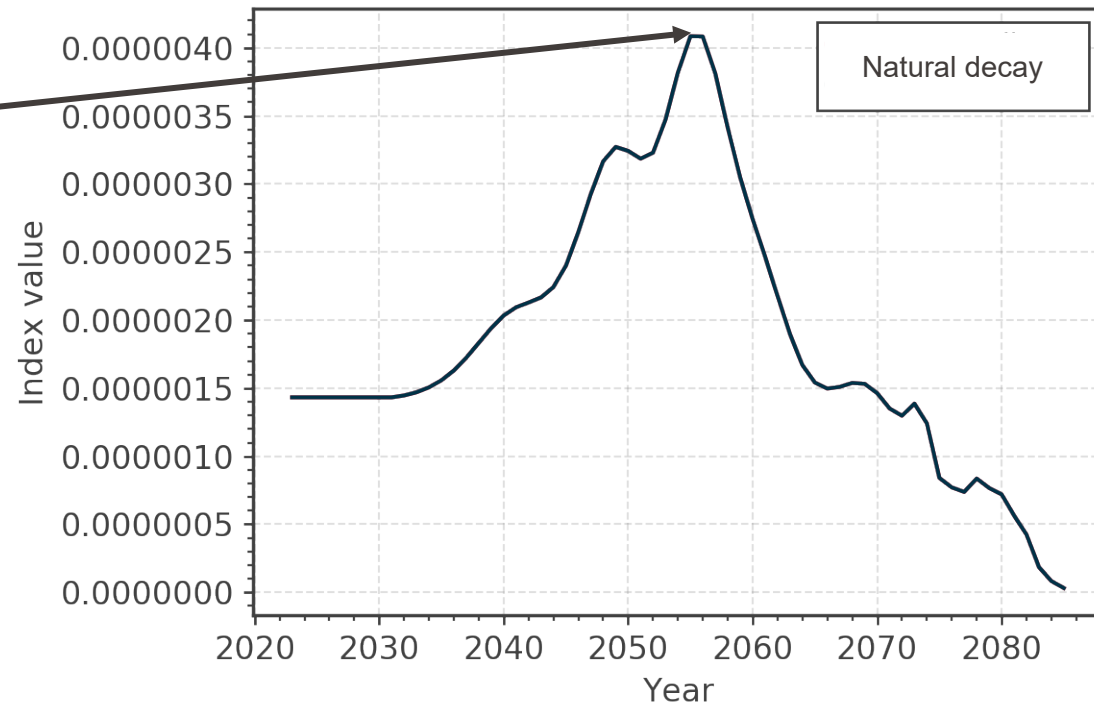


MISSION INDEX – TRAJECTORY EVOLUTION

Mock mission data:
 $A/m = 0.1$ (to highlight impact of trajectory evolution)
Initial altitude 900km
No post mission disposal (natural decay)

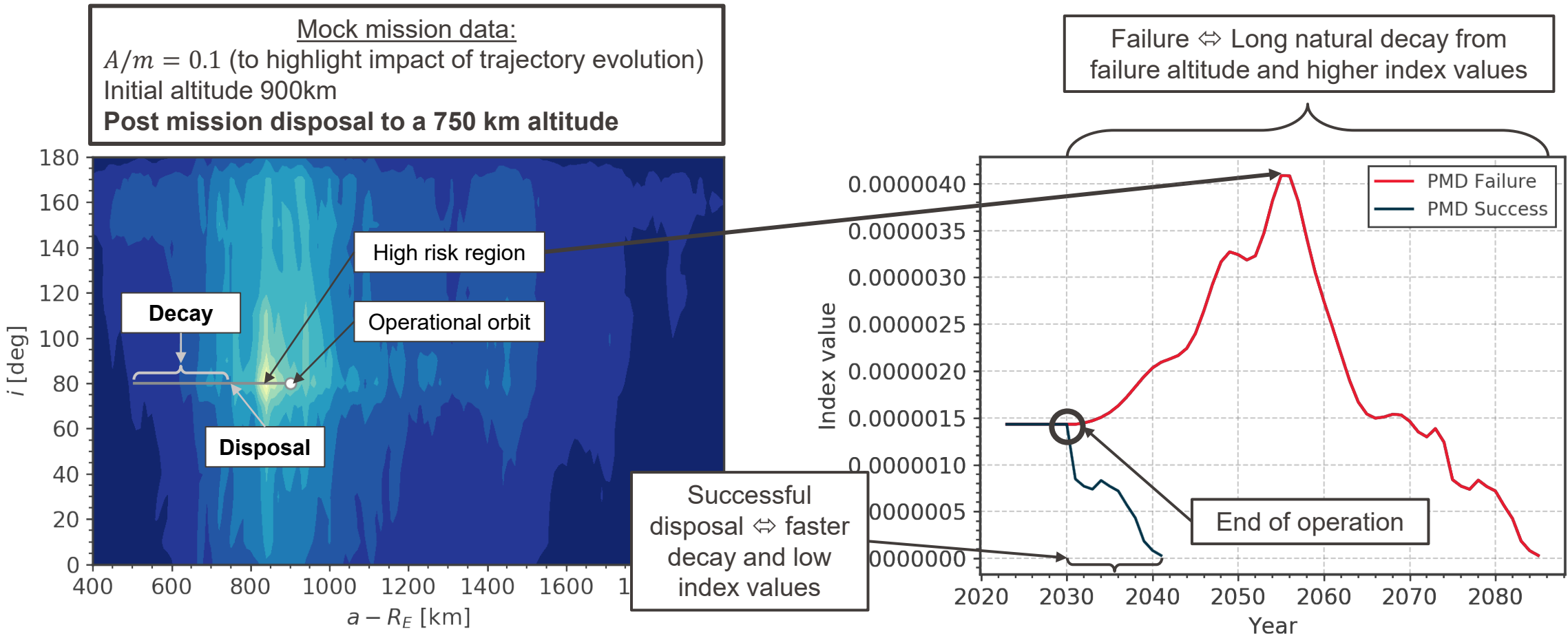


What about disposal manoeuvres?





MISSION INDEX – TRAJECTORY EVOLUTION AND PMD





MISSION INDEX – DISPOSAL RELIABILITY

Accounting for disposal failure scenario:

$$I_{disposal} = \underbrace{\alpha \int_{t_{EOL}}^{t_{fD}} I_{disposal} dt}_{\text{PMD Success}} + \underbrace{(1 - \alpha) \int_{t_{EOL}}^{t_{fND}} I_{abandoned} dt}_{\text{PMD Failure}}$$

α : Post Mission Disposal Success Rate*

Before launch:

α is obtained from spacecraft reliability analysis

During operation

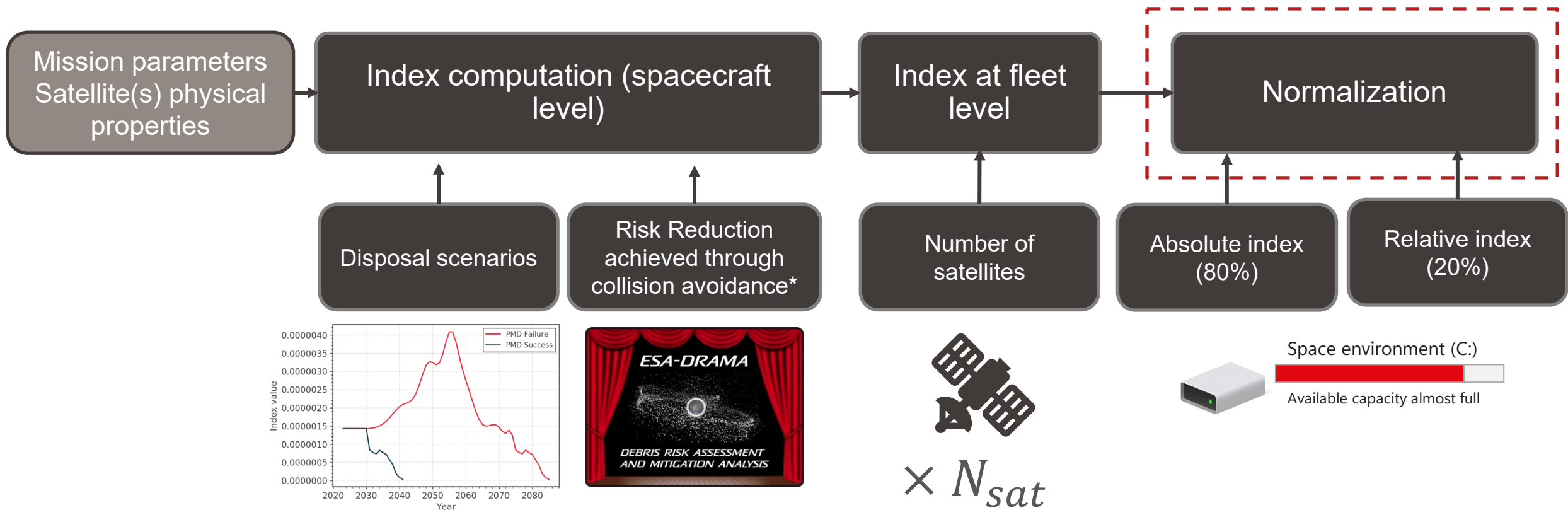
α is set to 0 if a spacecraft fails
 α is set to 1 if a spacecraft is successfully deorbited

* For a constellation, the value of α is aggregated for the entire fleet (i.e. weighted average)

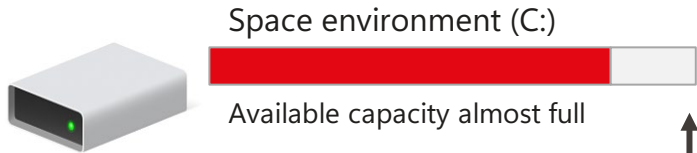


MISSION INDEX – NORMALIZATION

How to output a score?



MISSION INDEX – NORMALIZATION



What is “full”?

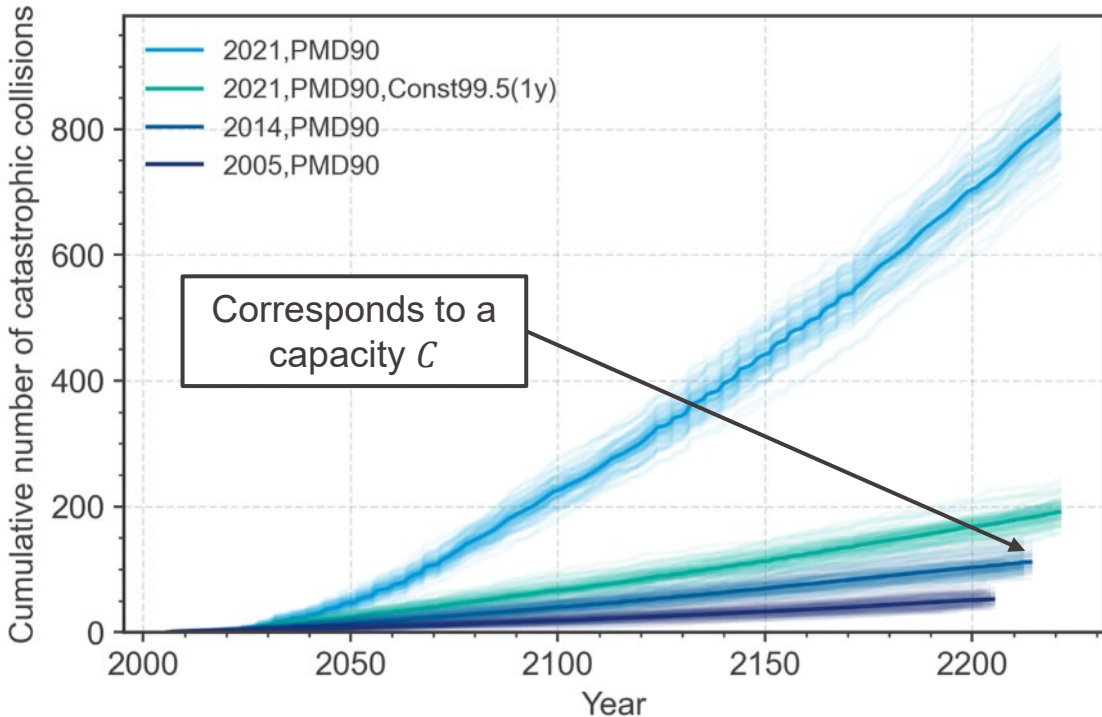
(1)

Capacity identified from long term extrapolation scenarios (the “capacity” C)

A normalized score is computed based on the **share of yearly available capacity** consumed by the mission

$$\hat{I} = I_{mission} / (C - I_{already\ used})$$

$$S_{abs} = 0.5 - \frac{1}{10} \log_{10}(\hat{I}) - \frac{\hat{I} - 1}{50}$$



“Absolute” index score, 80% of the mission index score (2)



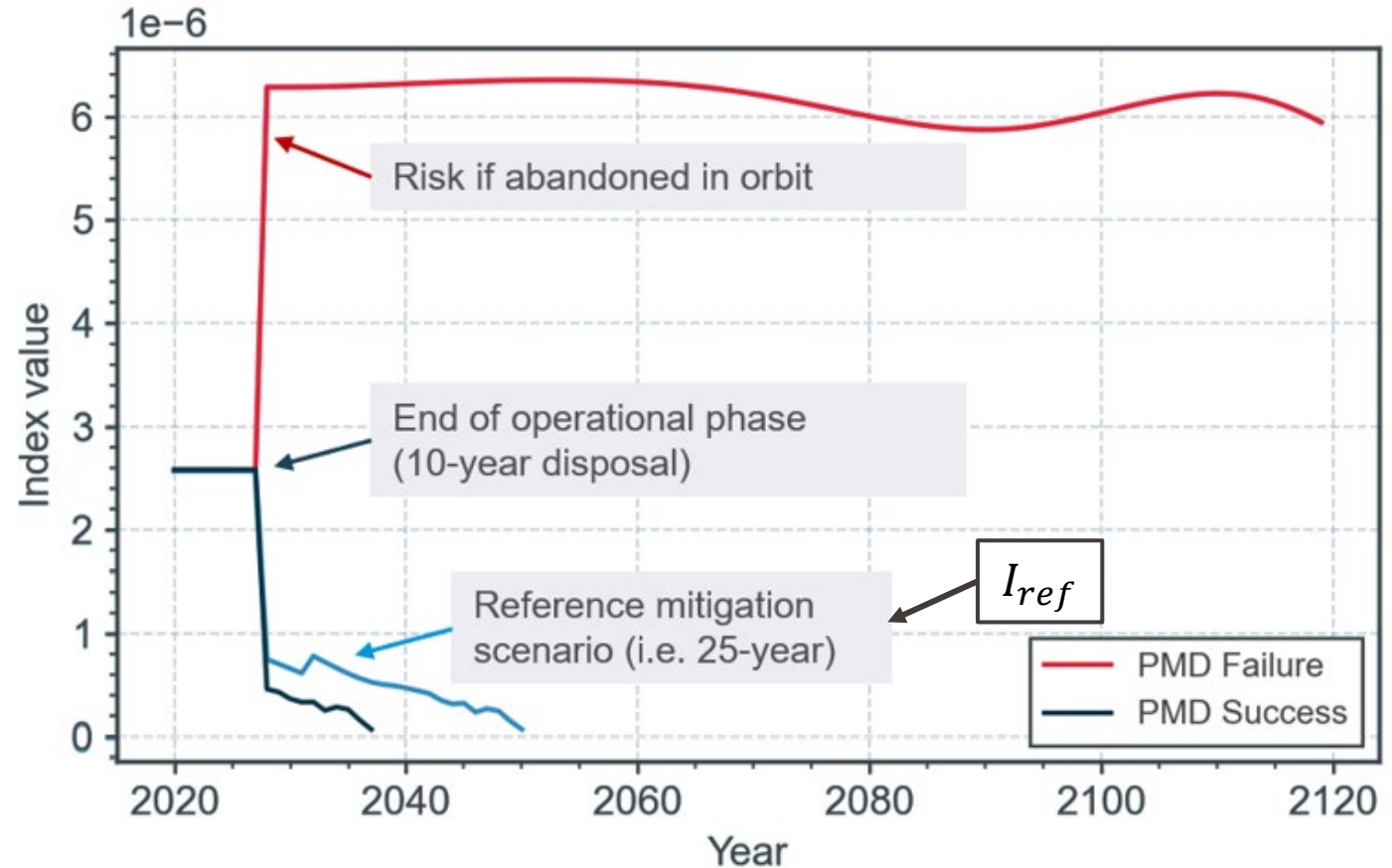
MISSION INDEX – NORMALIZATION

“Relative” mission index: going beyond recommendations

- Definition of a reference case
- Comparison to the reference case

$$I_{relative} = I_{mission}/I_{ref}$$

$$S_{rel} = 1 - (I_{rel})^\epsilon \quad \longleftarrow \text{“Relative” index score, 80% of the mission index score}$$





MISSION INDEX - APPLICATIONS

- Raise awareness: **Quantify** the impact of a spacecraft failure(s) on the space environment

Index of a failed satellite vs normal operation and disposal

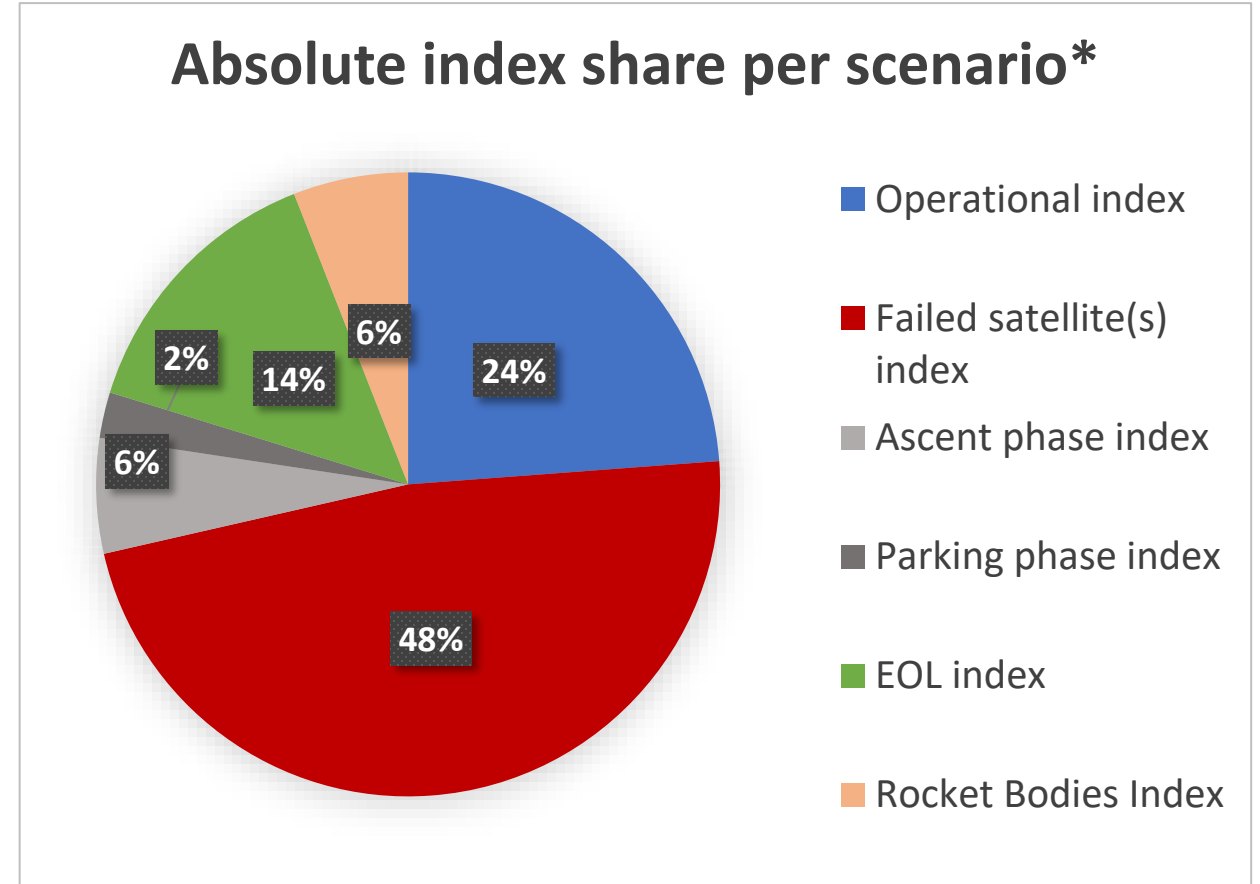


▪ Satellite failure ■ 8 years operation + disposal



MISSION INDEX - APPLICATIONS

- Raise awareness: Quantify the impact of a spacecraft failure on the space environment
- Analysis: Identification of **critical phases** (parking, raising, disposal) within mission. Derive different raising and disposal scenarios...
- PMD success rate sensitivity analysis for constellations





■ Risk based approach:

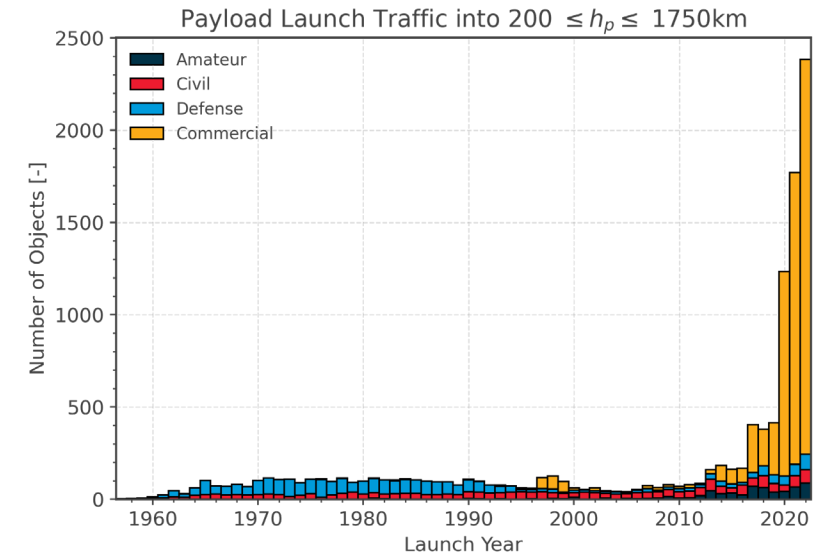
- More robust considering the increasing launch rate
- Available capacity value can evolve (e.g. due to fragmentations, removal)

■ Applicability to a rating scheme:

- Can be applied now!
- Easier scoring threshold establishment
- Complementary with compliance based modules

SPACE SUSTAINABILITY RATING

CONCLUSION



SPACE SUSTAINABILITY RATING



GOLD



SSR as a tool to incentivize further adoption of the zero debris approach?

- 1 Definition of valuable orbits**
 - Extend orbital protection to other earth orbits e.g., GNSS operational orbits
- 2 Guarantee successful disposal**
 - Improve probability of successful self-disposal
 - Prepare for removal
 - Removal services
- 3 Improve orbital clearance**
 - Reduce time left in protected regions below 5 years *
 - Improve clearance in other Earth orbits
- 4 Avoid in-orbit collisions**
 - Improve collision avoidance strategy
 - Cumulative probability of collisions after EoL $< 10^{-3}$ *
 - Share maneuver data
 - Improve trackability
- 5 Avoid internal break-ups**
 - Mandatory passivation features
 - 0.99 * probability of successful passivation
- 6 Prevent intentional release of space debris**
 - Prevent release of launcher related objects and interference with valuable orbits
- 7 Improve on-ground casualty risk assessment**
 - Standardize models and methods to assess demise
 - Impact on ground of launcher related objects
- 8 Guarantee dark and quiet skies**
 - Mitigate impacts on astronomy

* final numerical values under consolidation



2023 Clean Space Industry Days

SPACE SUSTAINABILITY RATING

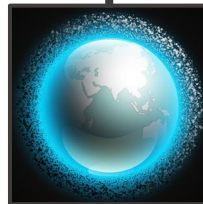
2

Guarantee successful disposal



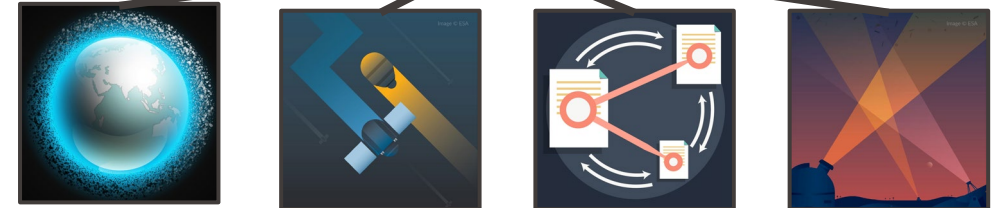
3

Improve orbital clearance



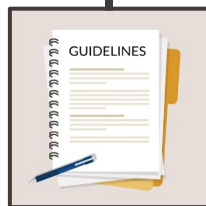
4

Avoid in-orbit collisions



5

Avoid internal break-ups



8

Guarantee dark and quiet skies

Development of a Dark and Quiet Skies module for the Space Sustainability Rating

Vincent Python^{1,*}, Nicolas Bouron¹, Adrien Saada², Scott Dorrington³, Emma Chehab¹, Koki Kimura¹, Ambre Ghisalberti⁴

¹ Ecole Polytechnique Fédérale de Lausanne (EPFL), Switzerland

² Space Sustainability Rating, Switzerland

³ Space Enabled Research Group, Massachusetts Institute of Technology (MIT), United States

⁴ Institut Polytechnique de Paris (IPP), France



SPACE SUSTAINABILITY RATING

Credit: [ESA - SHORT INTRODUCTION TO ESA'S ZERO DEBRIS APPROACH](#)



2023 Clean Space
Industry Days

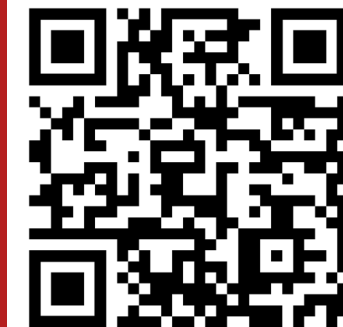


*EPFL continuing education for
professionals – Space Sustainability
Course: “How to design more
sustainable missions?”*

LEARN MORE



GET IN TOUCH



Adrien Saada

Operations Officer

adrien.saada@ssr.space

spacesustainabilityrating.org



SPACE
SUSTAINABILITY
RATING

SPACE SUSTAINABILITY RATING

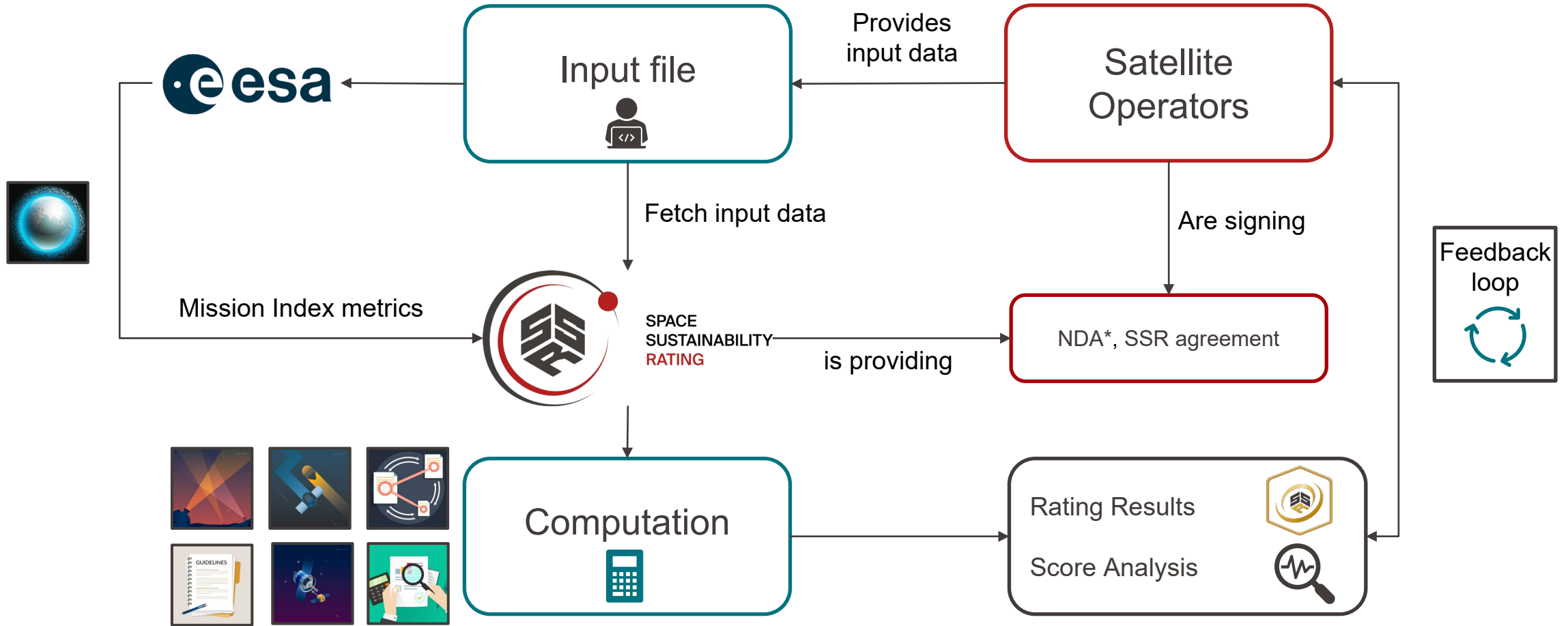
BACKUP SLIDES

SSR PROCESS





THE RATING PROCESS IN A NUTSHELL



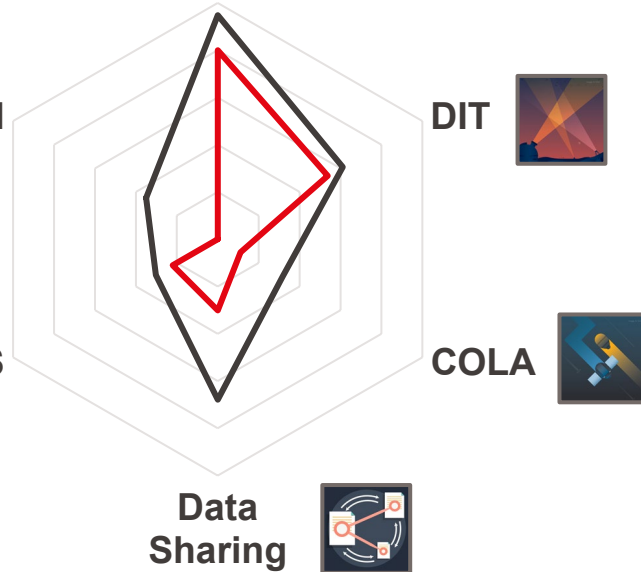


2023 Clean Space Industry Days



Mission Index

— Mission — Mission_Reco



SPACE SUSTAINABILITY RATING

SSR FEEDBACK LOOP

Reco.	Description	Score increase (module)	Score increase (Tier)
MI_1	Comment	+3.5%	+1.75%
DS_1	Comment	+4%	+0.66%
COLA_1	Comment	+12%	+1.98%
DIT_1	Comment	+5%	+0.6%
...
Total SSR Score increase			+8.29%
New tier			Gold

Tier Score 87.71 % from 64.65 % ↑ 23.06 %		Bonus Score 79.85 % from 57.71 % ↑ 22.14 %	
Mission Index 96.67 % from 61.03 % ↑ 35.64 %	Collision Avoidance Capabilities 100 % from 89.44 % ↑ 10.56 %	Data Sharing 95.95 % from 52.93 % ↑ 43.02 %	
Detection, Identification and Tracking 33.33 % from 69.17 % ↓ -35.83 %	Application of Design and Operation Standards 60.92 % from 46.88 % ↑ 14.05 %	External Services 100 % from 50 % ↑ 50 %	



SPACE SUSTAINABILITY RATING

RISK REDUCTION FROM COLLISION AVOIDANCE IN THE INDEX COMPUTATION





MISSION INDEX – COLLISION AVOIDANCE

$$I_{phases\ COLA} = \int_{t_0}^{t_{EOphase}} \left[\underbrace{(1 - \gamma)(p_{c_{trackable}} \cdot e_c)}_{\text{Collisions with trackable debris can be avoided}} + p_{c_{non-trackable}} \cdot e_{c_{non-trackable}} \right] dt \quad t_{EOphase}: \text{End of phase}$$

γ : Mitigated Collision Risk

Collisions with trackable debris can be avoided

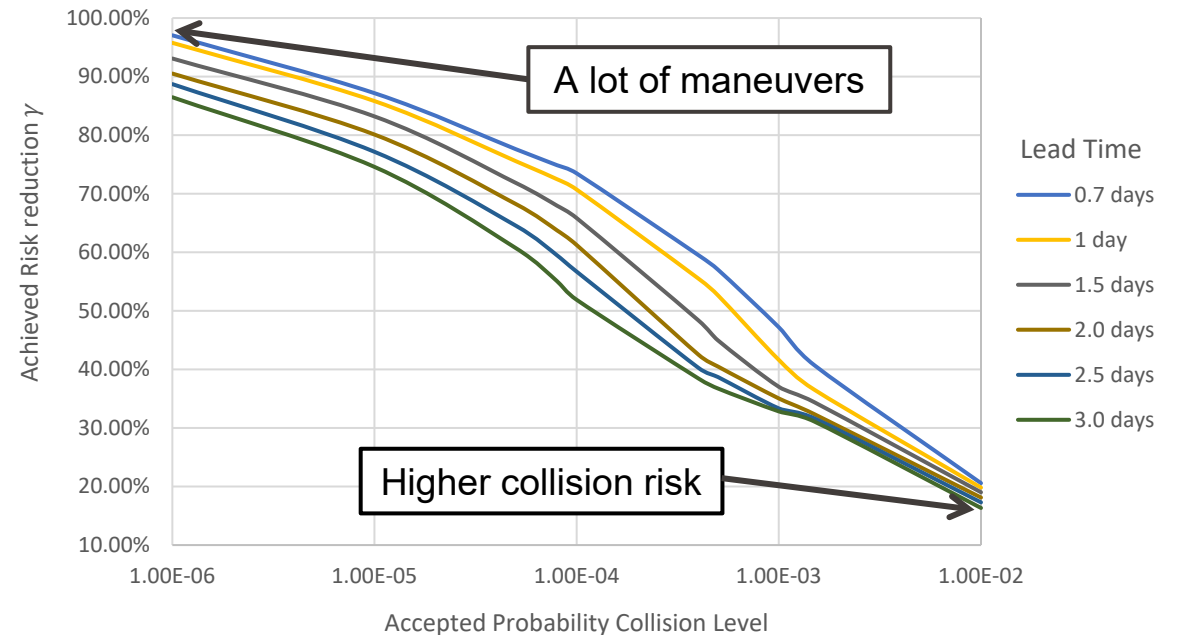
Risk reduction achieved by the implemented collision avoidance strategy **with respect to the case where no maneuver is performed**

mainly driven by two parameters:

Time required to perform a maneuver

Accepted Collision Probability Level

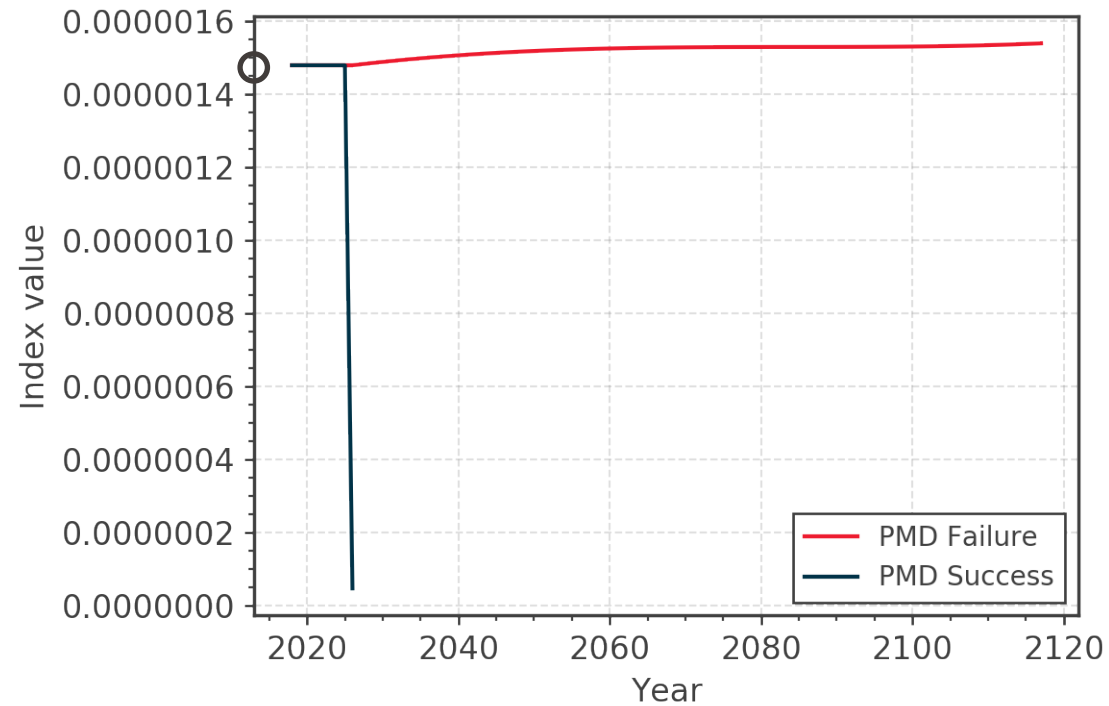
Mitigated Collision Risk vs. Accepted Collision Probability Level *





MISSION INDEX – COLLISION AVOIDANCE

Index value over time, no collision avoidance*





MISSION INDEX – COLLISION AVOIDANCE

Index value over time, with collision avoidance*

