

e.Deorbit Symposium

Tuesday, 6 May 2014

Industry Technology Update: Investigation on Envisat attitude motion (13:30 - 13:45)

-Conveners: Benjamin Bastida VIRGILI

Industry Technology Update: Progress in the Development of the Space Debris Harpoon (13:45 - 14:00)

-Conveners: Simon BARRACLOUGH

Industry Technology Update: Robotic Technologies for controlled satellite deorbiting (14:00 - 14:15)

-Conveners: Gerhard GRUNWALD

Industry Technology Update: Tentacles based clamping mechanism (14:15 - 14:30)

-Conveners: Jan-Christian MEYER

Industry Technology Update: Net debris capture (14:30 - 14:45)

-Conveners: Wojciech GOLEBIEWSKI

Industry Technology Update: Robotic Arm Spacecraft Capture Tool (14:45 - 15:00)

-Conveners: John RATTI

Industry Technology Update: Net debris capturing and GNC activities (15:30 - 16:00)

-Conveners: Mariella GRAZIANO

Industry Technology Update: AGADiR: Advanced GNC for Active Debris Removal (16:00 - 16:15)

-Conveners: Alexandre FALCOZ

Industry Technology Update: CLAMPADR activity and ADR (16:15 - 16:30)

-Conveners: Pedro Freire DA SILVA

Industry Technology Update: Optical Sensors for Space Robotics (16:30 - 16:45)

-Conveners: Florian KOLB

Industry Technology Update: The success of the PRISMA mission and the planned rendezvous between the PRISMA Mango and Picard satellites (16:45 - 17:00)

-Conveners: Camille CHASSET

Industry Technology Update: Advanced control engineering to capture un-cooperative objects (17:00 - 17:15)

-Conveners: Guillermo ORTEGA