# THE INTERNET OF THINGS FOR EARTH OBSERVATION (IoT4EO) PROJECT



# Low-data-rate Connectivity Architecture with Earth Observation (EO) Satellites in Low Earth Orbit (LEO)

IoT4EO Service Definition & Preliminary Specification

IoT4EO-SERV-REQ-2024-09-196

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## **Table of Contents**



## **1 Introduction**

## **1.1 Purpose and Scope**

This document defines low-data-rate connectivity services and preliminary requirements identified during the "concepts for the use of IoT in Earth Observation" parallel studies conducted under ESA Contracts "4000139168" [RD-2] and "4000139169" [RD-3] with Airbus Defense and Space (ADS) and OHB Systems respectively. This document is created to serve as a reference for translating and tracing the IoT4EO service requirements to system level. These requirements are defined in **Section [4](#page-18-0)** and frequently referenced throughout to ensure traceability at each development stage, ensuring a system perspective is maintained.

## **1.2 Background**

The rapid advancement and integration of network technologies on Earth, characterized by near-instant connectivity, offer substantial opportunities to enhance connectivity with Earth Observation (EO) satellites in Low Earth Orbits (LEO), typically between 400 to 800 km in altitude. These satellites complete orbits in approx. 90 to 100 minutes; approximately 15 times a day. However, their visibility with any given ground station (G/S) or gateway is quite limited—about 10% of the orbit period, even in the most favorable orbits.

Leveraging the widespread adoption of cellular and non-cellular Low-Power Wide-Area Network (LPWAN) technologies as part of **Internet of Things (IoT)** could revolutionize Earth Observation satellite connectivity. This concept, referred to as **IoT4EO**, could enable more dynamic satellite tasking, in addition to on-board event detection followed by the near-real-time distribution of information between space and ground nodes. This would not only increase the autonomy of satellite constellations, but also reduce operational costs. The concept could be simple, eliminating the need for complex antenna alignments on spacecraft while, thereby maintaining low yet adequate data rates. For situations requiring higher data rates, the ubiquitous communication system could integrate with more directional, complementary systems. Furthermore, the ongoing proliferation of LPWAN technology on Earth is laying the foundation for the development of ubiquitous networks also in space, by providing a **framework** that has already established important system components, including regulatory policies, physical infrastructure, data management systems, network layers, security, and protocols. It is important to note that IoT4EO intends to **complement** existing communication systems (e.g. high-speed links and traditional TT&C) by enabling cost-efficient and ubiquitous connectivity in LEO. It **is not intended to replace** these systems, given its current early stage of development and data rate limitations.

The need for ubiquitous connectivity with satellites in Low Earth Orbit (LEO) is widely acknowledged. A specific Study Group (SG) was established in 2022 through a collaboration between the European Space Agency (ESA) and other space agencies under the Inter-Agency Operational Advisory Group (IOAG) [RD-1] to explore the multidimensional aspects (i.e. technical and business) related to this ambitious goal (see **Appendix C**). This effort extends beyond institutional missions undertaken by these agencies. A primary objective of IoT4EO is to **federate** and facilitate **timely connectivity** between **institutional** and **commercial missions**.

This document synthesizes the findings and outputs from the services identified with OHB System [RD-2] and with ADS [RD-3]. These findings were further refined during IoT4EO Workshops held in February 2023 [RD-4] and will be further discussed in December 2024 [RD-5], which include a multi-disciplinary community of end users and potential service stakeholders. This document, titled "*IoT4EO Service Definition & Preliminary Specification*" outlines the **low-data-rate connectivity services** and **preliminary requirements** to address the needs of customers and users for such services, thereby laying the groundwork for subsequent system definition and requirements development. Understanding requirements translation is important because it clarifies the origin and progression of project requirements, and it ensures these requirements are accurately implemented and can be traced back at every stage of development.

**Disclaimer:** It is strongly advised that readers familiarize themselves with the system terminology used in this document to ensure a common understanding of the system definition language. Please refer to **Appendix A-2** for this information.

## **1.3 Applicable Documents**

The following list of Applicable Documents are used in the IoT4EO System Requirements Document



## **1.4 Reference Documents**

The following list of Reference Documents are used in the IoT4EO System Requirements Document



## **1.5 Structure of the Document**

The structure of this report aims to cater to multiple communities. It primarily discusses the IoT4EO Vision, which is the development of ubiquitous networks in space through an architecture focused on low-data-rate connectivity, along with its services and service requirements. These elements are clearly defined and consistently referenced throughout the report to ensure traceability at each development stage, ensuring a system perspective is maintained.

#### **Section 2 – IoT4EO Vision**

Provides an overview of the vision for the low-data-rate connectivity architecture.

#### **Section 3 – IoT4EO Service Definition & Stakeholders**

Provides a brief overview of the service definitions & requirements identified in the "Concepts for the use of IoT in Earth Observation" studies.

#### **Section 4 – IoT4EO Requirements**

Provides a collection of all the IoT4EO service requirements, categorized into performance, quality of service (QoS), scalability, security, regulatory, and interoperability requirements, to document the customer/user needs, ensuring their traceability in subsequent stages of the project development.

#### **Section 5 – Appendices**

Provides additional information that addresses the technical aspects of low-data-rate connectivity architecture and service, including:

- [Appendix A:](#page-29-0) Acronyms and terminology,
- [Appendix B:](#page-33-0) Use cases, Applications and Stakeholders
- [Appendix C:](#page-34-0) IoT4EO Project
- [Appendix D:](#page-36-0) Summary Table Services
- [Appendix E:](#page-37-0) Interoperability and Standardization Action Plan
- [Appendix F:](#page-40-0) Scenario Examples with 50+ LPWAN Gateways

## <span id="page-5-1"></span>**2 IoT4EO Vision**

## **2.1 A low-data-rate connectivity architecture**

The ongoing proliferation of Internet of Things (IoT) technology on Earth is laying the foundation for the development of ubiquitous networks in space, by providing a **framework** that addresses important system components, including regulatory policies, physical infrastructure, data management systems, network layers, and protocols. [Figure 1](#page-5-0) describes the possible top-level low-data-rate connectivity between different elements both in space and on ground, with each element representing one or more nodes in the system-of-systems, including non-traditional gateways and Geostationary / Medium Earth Orbits (GEO/MEO) relay assets.

The low-data-rate connectivity architecture with Earth Observation (EO) satellites in Low Earth Orbit (LEO) focuses on developing the space-Earth, Earth-space, and space-space links, using existing terrestrial networks as a foundation to build upon and as a new complementary component. In this context, the engineering of a solution will adopt a **middle-out** approach (as defined in Appendix [A.2\)](#page-30-0), focused on engineering within an existing and established system-of-systems to identify and leverage synergies, compatibility, interfaces, and integration opportunities.



<span id="page-5-0"></span>**Figure 1** Low-data-rate connectivity architecture with Earth Observation (EO) satellites in Low Earth Orbit (LEO)

It is acknowledged that federating and facilitating global and near-permanent connectivity with EO satellites in LEO, whilst ensuring scalability, availability, and longevity, will require an integrated network infrastructure with services that are **provider-agnostic** (Section [3.5\)](#page-15-0), bi-directional and of low complexity and cost. In this respect, it will be important to standardize enabling parts of the system that facilitate interoperability, and to establish technology roadmaps that support any necessary standardization. However, it is important to recognize that achieving full interoperability with existing terrestrial IoT networks (i.e., Ground-To-Ground, European Aviation Network (EAN)), which typically support a very large user base, is challenging and impractical due to our unique system constraints in LEO and a rather small EO satellite user base. Therefore, we define **interoperability** in the scope of low-data-rate connectivity architecture with EO satellite in LEO as the following:

#### *"The capability of diverse systems, devices, or software applications to communicate effectively, ensuring that they can exchange and interpret shared data accurately across various platforms and environments"*

In this context, **ubiquitous connectivity** with LEO satellites is understood as the consistent and widespread availability of connections that are always present or soon to be accessible. This ensures near-constant communication among nodes through various networks, independent of the provider. From a user's perspective, ubiquitous connectivity is the uninterrupted transfer of low-volume data packets across various networks, arriving at the user's desk without requiring any intervention. However, considering the IoT4EO vision's commitment to **provider-agnostic**, bi-directional services are in principle both low in complexity and cost, however, attaining this level of service using standard Telecommand (TC) packets through this link or a standard Ground Station (GS) network might still prove to be exceptionally challenging. The optimal strategy for arriving at a solution involves a system that is both flexible and scalable, guided by Size, Weight, and Power (SWaP) constraints in LEO Spacecraft, and **discrete event messaging**, rather than total continuous connectivity to ensure **low complexity and cost**.

It is also strategic to **leverage** technical **solutions from existing terrestrial services** that are **protocol agnostic** and offer a range of options within Low-Power Wide-Area Network (**LPWAN**) technologies, e.g., LoRaWAN, LTE-M, NB-IoT, Sigfox and even Bluetooth. This approach is particularly useful in scenarios where brief nonconnections may occur (e.g. when the network of ground gateways is not extensive enough). These technologies have recently **demonstrated** their capability for low-power and low-data-rate connectivity, including successful applications of LoRa and Bluetooth connectivity **in space**.

While the concept of a low-data-rate connectivity architecture originated from the proliferation of Internet of Things (IoT) technology on Earth, in this "*Service Definition & Preliminary Specification"* document, we purposefully avoid specific IoT terminology in favor of a more general discussion of low-data-rate connectivity. This approach reflects the fact that the technical solutions for these services have often been demonstrated to be protocol agnostic, with a variety of options available within Low-Power Wide-Area Network (**LPWAN**) technologies i.e., LoRaWAN, NB-IoT, and others. Thus, whenever **IoT terminology** appears in this document, please interpret it **in the broadest and most general sense possible**.

## **2.1.1 IoT4EO Objectives**

The IoT4EO vision encompasses the development an **interoperable low-data-rate connectivity** architecture that serves as the foundation for establishing **ubiquitous**, global, and near-permanent connectivity to Earth Observation (EO) satellites in Low Earth Orbit (LEO). This vision is characterized by several key high-level objectives, which are important for requirement traceability and translation, justification of design decisions, anticipation in the verification of the system, and are frequently referenced throughout the project's evolution to maintain a systems perspective. The IoT4EO Vision objectives are as follows:

#### **Objective 1: To establish and develop an interoperable framework for low-data-rate connectivity with Earth Observation (EO) Satellites in Low Earth Orbit (LEO)**

- **OBJ 1.1:** To identify the **key elements** of an interoperable IoT4EO **framework** that can expedite its deployment and adoption among EO Satellite End Users (UE) and Service Providers. Prioritization shall focus on the re-use of well-established **commercial elements**, while developing new components or standards to ensure the systems interoperability, ubiquity and provider-agnostic nature.
- **OBJ 1.2:** To ensure that the low-data-rate **connectivity services** are operational, featuring ubiquitous and provider-agnostic capabilities that can scale to support at least **500** Earth Observation (EO) Satellites in Low Earth Orbit (LEO)<sup>[1](#page-6-0)</sup>, alongside a scalable ground infrastructure (i.e., gateways, in-situ sensors).

**Objective 2: To enable and operationalize new services, applications, and use cases that add value to satellite operations and facilitate the integration and co-location of satellite and non-satellite measurements**

• **OBJ 2.1:** To improve **operational** efficiency and **responsiveness** of Earth Observation (EO) satellites through **dynamic satellite tasking**, quick retrieval of on-board event-detected information, and nearreal-time data sharing across global networks by **at least one** *(10<sup>1</sup> )* **or two** *(10 2 ),* **orders of magnitude** compared to traditional telemetry, tracking, and command (TT&C) systems with a single ground station.

<span id="page-6-0"></span><sup>&</sup>lt;sup>1</sup> Celestrak, a recognized resource in the aerospace sector, provides updated listing satellites. These numbers fluctuate due to ongoing satellite launches and deorbiting events. For precise alignment with real-time data and to ensure accurate comparisons or analyses, stakeholders are advised to consult the latest datasets available [\(www.celestrak.org\)](http://www.celestrak.org/)

• **OBJ 2.2:** To strengthen, align and federate **in-situ scientific measurements** with **systematic Earth observation data** to improve calibration and validation processes, enabling higher automation and offering greater reliability and scope in scientific measurements.

#### **Objective 3: To develop standardized technology and regulatory Elements that streamline low-data rate technology integration and ensure interoperability with existing systems**

- **OBJ 3.1:** To develop **standardized** technology that ensures interoperability, provider-agnostic services, and scalability, that ensure technical **compatibility** between end-user Earth Observation (EO) systems, existing relay satellite systems, and ground gateways to simplify adoption for various stakeholders.
- **OBJ 3.2:** Identify and align with the existing **regulatory** landscape (e.g., ITU, 3GPP, LoRa Alliance), ensuring compliance with current regulations and actively participating in proposing and applying modifications to existing standards or frameworks where necessary.
- **OBJ 3.3:** To develop, test and validate **technology demonstrators**, including breadboards and flight models, ensuring they meet interoperability, performance, and operational requirements
- **OBJ 3.4:** To verify and validate that the **new services**, applications, and use cases meet the needs of end-users and deliver the intended added value in satellite operations and data calibration and validation (CAL/VAL) processes.

The IoT4EO objectives are leveraged as a reference for translating and tracing the service and system requirements. They are defined and referenced frequently to allow traceability at every stage of development, ensuring a system perspective is maintained.

## **3 IoT4EO Service Definitions & Stakeholders**

## **3.1 General Service Definitions**

This section outlines the services identified from the "Concepts for the use of IoT in Earth Observation" parallel studies performed under ESA Contracts [**RD-2**] and [**RD-3**]. This involved an in-depth exploration of use cases and applications (see [Table 1\)](#page-9-0) , iterations through an IoT4EO Network architecture and CONOPS for two scenarios: (1) considering re-use of current capabilities, and (2) with more substantial developments, as well as a market survey on LPWAN services, technologies, in-situ sensors, protocols, and security measures. Although a thorough examination of the regulatory framework and preliminary discussions on frequencies and roadmaps were performed, these details are not included in this document because we consider that it should be possible to develop highly integrated equipment with multi-frequency flexibility. The goal of this section is to capture and elucidate **User Requirements** from the **perspective of service provision**, deliberately setting aside technical engineering solutions at this stage.



\*Subject to user requirements, the improvement must be at least an order of magnitude, which means a minimum increase by a factor of 10 or 100



**Figure 2** A summary of IoT4EO service features (minimum values for each service).

<span id="page-8-0"></span>Two core services were identified as solutions addressing Objective 2, covering all use cases and applications summarised in [Table 1](#page-9-0) and further detailed in [Appendix B](#page-33-0) this document. They are differentiated by their respective data types and operational objectives, which are shaped by the nature of OBJ2.1 and OBJ2.2:

- **Service A** facilitates bidirectional low-data-rate **telemetry, tracking, and command (TT&C)** exchanges between ground-based gateways and EO satellites, divided into two sub-services (Section [3.3\)](#page-10-0):
	- o **Service A-1**: Direct bi-directional connectivity via ground gateway
	- o **Service A-2:** Indirect bi-directional connectivity via relay MEO/GEO satellites

• **Service B** facilitates bidirectional low-data-rate data collection and messaging exchanges between **insitu sensors** and EO satellites (Section [3.3\)](#page-10-0)

The subsequent sections provide a detailed definition and description of low-data-rate connectivity services, including service description and architecture, key features, anticipated applications, use cases, and users. Note that the **values provided in [Figure 2](#page-8-0) are minimums**, which may be challenging to improve due to link budget limitations. However, other system parameters (e.g., daily data allowance) may be **scalable with service cost**. For further details on scalability, refer to Appendix D.

There is a broad spectrum of network technologies that deliver varying performances, from **cellular** technologies (e.g., 5G NR, LTE-M, NB-IoT) that cover long range and mid to high data rates, and **non-cellular** technologies (e.g., LoRa, SigFox) that cover very low data rates and high ranges (e.g., LoRa, SigFox). As previously discussed, this document purposefully avoids specific IoT terminology to facilitate a more flexible system design. Furthermore, to ensure readability and interoperability across various industries and stakeholders, it is important to adopt a common system definition language.

In this document we use the following **LPWAN** terminology to describe the direction of communication:

- **Upload**: LEO EO **User Equipment (UE / node)** to ground **Gateway**. This differs from EO satellite operations, as telemetry is 'downlinked' from LEO satellites to a Ground Station (G/S).
- **Download**: Ground **Gateway** to LEO EO **User Equipment (UE / node)**. This differs from EO satellite operations, as a telecommand is 'uplinked' from a Ground Station (G/S) to a LEO satellite.

The proposed low-data-rate connectivity architecture, particularly the links between the on-board UE, in-situ sensors, and Gateways, is expected to utilise **discrete event messaging** rather than maintaining continuous connectivity. This is due to a trade-off between need and implementation cost, geometric constraints (i.e. gateway distribution and GEO/MEO coverage over the poles), and a relatively small user base compared to the terrestrial LPWAN market. Moreover, to facilitate discrete event messaging, the use of a "**not-connected**" protocol or one with expanded features (e.g. for **store-and-forward**) is anticipated. This approach is designed to be **protocol-independent**, aiming to achieve a truly interoperable and **provider-agnostic** solution (Section [3.5\)](#page-15-0).

It is assumed that a discrete event message is optimal; however, additional overheads are necessary (e.g., in a bi-directional context, for system synchronization and responsiveness, and for acknowledgment (ACK) back to the source). These overheads, typically 20%, vary based on protocols and should be added to the minimum service values (e.g., daily data allowance) discussed in this document. Appendix D explores scalability options.

Due to these characteristics, *'visibility latency*' (Appendix A) is anticipated to be in the order of seconds to minutes, particularly when User Equipment (UE) is orbiting above open ocean (in the case of Service A-1) and the poles (In the case for Services A-1 and A-2). This is significant when compared to terrestrial network latencies (i.e. msec) with continuous UE-Gateway visibility; however, the requirement for continuous connectivity—and thus the latency—is driven by the needs of the potential users of the services. It might be, that accessing their satellite within a few minutes in the worst case, as opposed to the traditional 90 minutes (1 LEO orbit), might be acceptable. This document aims to explore and elucidate this need.

**Preliminary service specifications**, along with some justifications, are detailed in **Section 4** of this document.

## **3.2 Applications & Use Cases**

The following mapping of applications and use cases has been simplified, with **Appendix B** providing more detailed explanations. This mapping illustrates that Service-A (TT&C Exchanges) covers 80% of potential use cases.



<span id="page-9-0"></span>**Table 1** Applications & Use cases mapped to each service type



## <span id="page-10-0"></span>**3.3 Service A: Bi-directional low-data-rate TT&C**

**Service A** offers both:

- *direct* (Service A-1) and
- *indirect* (Service A-2)

bidirectional low-data-rate **telemetry and command (TT&C)** exchanges between ground-based Gateways and Earth Observation (EO) satellites in Low Earth Orbit (LEO). The traditional TT&C solutions lack the necessary global coverage and quick responsiveness required for dynamic satellite operations. This is due to their reliance on limited visibility of the LEO satellite from ground.

## **3.3.1 Service A: Daily Data Allowance and Upload/Download Speeds**

The initial assumption that a single Telecommand (TC) packet size of **≈12kBytes** demonstrated to be too demanding for a low-data-rate connectivity architecture that is based on the emerging terrestrial Low Power Wide Area Network (LPWAN) technologies. This is primarily because a ≈12kB/message is incompatible with the most restrictive protocols (e.g., LoRa) due to their payload size limitations and supporting data rates. This limitation does not affect existing services of a similar nature that use traditional telecommunication technologies and protocols (e.g., Addvalue IDRS offers **200kbps** connectivity for indirect communication (Service A-2) via a GEO relay). These services typically offer subscription plans ranging from 100 to 500MB per month per satellite, which equates to approximately **3 to 15 MB per day** per satellite when scaled down. Therefore, for a low-data-rate connectivity service as described in this document, with data rates reduced by 100 times (i.e., **≥2kbps,** due to link budget limitations), and an improvement in current TT&C operations (assuming one exchange per orbit) by at least one (10<sup>1</sup>) or two (10<sup>2</sup>) orders of magnitude, the performance is driven by the need for:

- 10<sup>1</sup> case: A minimum of 10 messages per orbit (TBC) and approximately 150 messages per day (TBC), which results in a minimum cumulative daily data allowance of 30kB (TBC).
- $\bullet$  10<sup>2</sup> case: A minimum of 100 messages per orbit (TBC) and approximately 1500 messages per day (TBC), which results in a minimum cumulative daily data allowance of 300kB (TBC).

In both scenarios outlined above (i.e., 10<sup>1</sup> or 10<sup>2</sup>), the average message size of ≥0.2kB (TBC) is compatible with even the most restrictive protocols (e.g., LoRa), which supports message sizes up to 1kB. It is recognized that message length should be variable and flexible to accommodate the end user's needs. As detailed in Section 3.1 and Appendix A.2 and re-emphasized here, additional **overheads are necessary** (e.g., in a bi-directional context, for system synchronization and responsiveness, and for acknowledgment (ACK) back to the source). These overheads, typically 20%, vary based on protocols and should be added to the **minimum service values** (e.g., daily data allowance) discussed in this document. Appendix D explores scalability options

The order of magnitude of improvement requirement is to be confirmed by end users and feasibility evaluated by service providers based on the low-data-rate connectivity architecture described in this document.



## ≥30kB or ≥300kB Daily Data Allowance\*

Send/receive ≥150 or ≥1500 messages/day/satellite (~0.2kB each, on average) with a cumulative total daily data allowance of ≥30kB or ≥300kB.

## ≥2kbps Upload and Download Speeds

Data upload/download speeds start at 2 kbps, with priority given to higherspeed transmissions for mission-critical operations

**Figure 3** Service A Performance Baseline. It shows (left) An image of an LPWAN/IoT Gateway, (top) Daily Data Allowance and (bottom) Upload/Download speeds, both compatible with LoRa-like and NB-IoT-like protocols.

In his document, it was our intention to decouple these service performance requirements from **Service A-1 and A-2**, as both services **share the same objectives**. As discussed earlier, in this document we purposefully avoid specific IoT terminology in favour of a more general discussion of low-data-rate connectivity, which extends to frequency allocation and to a diverse range of options available within LPWAN technologies e.g., LoRaWAN, Bluetooth, NB-IoT, and others.

## **3.3.2 Service A-1: Direct bidirectional low-data-rate TT&C**

**Service A-1** offers *direct* bidirectional low-data-rate telemetry and command (TT&C) exchanges between ground-based **Gateways** and Earth Observation (EO) satellites in Low Earth Orbit (LEO). This service is designed to enable dynamic satellite tasking and distributed telemetry operations, primarily supporting Earth Observation Satellite Operators who are looking to establish near-permanent communication links with their satellites. The key features of Service A-1 are:



**Figure 4** Service A-1: Direct bi-directional low-data-rate TT&C Connectivity Architecture and key features

The strategic deployment and adoption of an extensive and well distributed number of lightweight gateways leveraging LPWAN technologies should enable global coverage (Appendix F 50+ Gateways), covering terrestrial, coastal, polar and oceanic areas in some cases. These Gateways, interconnected through terrestrial networks,

could ensure continuous connectivity anytime an Earth observation satellite enters a Gateway's field of view. Despite the lack of open ocean coverage, it benefits from the proximity of Low Earth Orbit (LEO), enabling a direct link that experiences minimal free space loss compared to Service A-2.

## **3.3.3 Service A-2: Indirect bidirectional low-data-rate TT&C**

**Service A-2** offers *indirect* bidirectional low-data-rate telemetry and command (TT&C) exchanges between ground-based gateways and Earth Observation (EO) satellites in Low Earth Orbit (LEO), via a Geostationary (GEO) or Medium Earth Orbit (MEO) Relay satellite. This service is designed to enable dynamic satellite tasking and distributed telemetry operations, primarily supporting Earth Observation Satellite Operators who are looking to establish **near-permanent** communication links with their satellites. The key features of Service A-2 are illustrated in Figure 5.

The broad beam coverage of GEO or MEO communication providers, combined with a single or a limited number of lightweight gateways utilizing LPWAN technologies, should enable full global coverage with near-zero visibility latency or near-continuous connectivity over both terrestrial and oceanic areas. Areas beyond ±70-degrees latitude—close to the poles—generally might fall outside the effective coverage area due to the curvature of the Earth and the satellite's fixed equatorial orbit. In comparison to Service A-1, the propagation pathway experiences greater free space loss, however these satellites often compensate by providing high-gain directivity through beamforming, both in the relay satellites and on the ground gateways.



**Figure 5** Service A-2: Indirect bi-directional low-data-rate TT&C Connectivity Architecture & key features

Overall, Service A-1 and A-2 can provide substantial benefits for Earth Observation, particularly in scenarios requiring rapid response times—from observation request initiation to data delivery—including **human activity**, disaster response and emergencies, which typically have latency requirements of only **a few minutes.**

## **3.4 Service B: Bi-directional low-data-rate data collection from in-situ sensors**

**Service B** offers bidirectional low-data-rate data and messaging between ground-based in-situ sensors (which are often battery-powered), and Earth Observation (EO) satellites in Low Earth Orbit (LEO). This service is designed to enable co-located (in space and in time) in-situ (ground) and EO satellite measurements to improve calibration and validation (CAL/VAL) processes and may autonomously trigger and enable spontaneous observation requests from the Mission Control Centre (MCC). It primarily supports EO data providers and users who are looking to offer greater responsiveness, facilitate automation in the federation of data, and increase the scope in scientific measurements derived from multiple EO data space and in-situ sources.

## **3.4.1 Service B: Daily Data Allowance and Upload/Download Speeds**

The typical data volume for an in-situ sensor transmitting data via local area network or satellite can vary based on the application, transmission frequency, and data type. Small-scale sensors (e.g., temperature, humidity) typically generate very small data packets, often between **10 - 200 bytes per message**. In contrast, larger data applications (e.g., cameras, advanced environmental sensors) can transmit data volumes ranging from kilobytes to megabytes per session. Despite this, the transmission of large data volumes is not common in standard IoT applications over satellite, primarily due to cost and bandwidth limitations. In current satellite-based IoT systems, particularly those using Low Power Wide Area Network (LPWAN) technologies (e.g., LoRaWAN, NB-IoT, Sigfox), data volumes are purposely kept minimal to manage costs and power consumption effectively.

There is a broad spectrum of network technologies that deliver varying performances, from **cellular** technologies (e.g., 5G NR, LTE-M, NB-IoT) that cover long range and mid to high data rates, and **non-cellular** technologies (e.g., LoRa, SigFox) that cover very low data rates and high ranges (e.g., LoRa, SigFox). In this scenario, **noncellular LPWAN** technologies (e.g. LoRa, SigFox) establish the baseline for data allowance and upload/download speed performance. Therefore, by leveraging established standard practises from the existing IoT constellation landscape—and without requiring an order of magnitude improvement in operational efficiency and responsiveness (i.e., OBJ2.1)—Service B provisionally offers the possibility of **at least two messages per in-situ sensor(s) per orbit**, which corresponds to about **30 messages per in-situ sensor per day** to Low Earth Orbit (LEO).

The two messages per orbit is **arbitrary** and depends on:

- Application (e.g. Acknowledgement (ACK) requirement),
- Visibility opportunities (e.g. In-situ sensor latitude and orbit)

For more detailed information on this topic, refer to Section 4.3 IOT4EO-PRF-320. Moreover, it is worth noting note that each in-situ sensor (i.e. User Equipment (UE)/Node) might want to connect to multiple LEO EO Satellites (i.e., LEO Gateways). Section [4.4](#page-24-0) explores scalability requirements.

This results in a **daily data allowance** of at least 3kB per sensor (TBC), aligning with established IoT standards that typically feature **message sizes of 100 Bytes or more.** However, it is likely that the service would usually be offered in **SERVICE BUNDLES** (e.g., 100 sensors with 0.3 MB, or 1,000 sensors with 3 MB). This document describes it this way to provide granularity down to a single sensor to characterize the link. Initial link budgets, even from battery-based in-situ sensors, indicate that connectivity to LEO EO satellites at **≥2kbps** data rates should be possible.



## ≥3kB Daily Data Allowance

Send/receive ≥30 messages/day/sensor (~0.1kB each, on average) with a cumulative total daily data allowance of ≥3kB.

## ≥2kbps Upload and Download Speeds

Data upload/download speeds start at 2 kbps, with priority given to higher-speed transmissions for mission-critical operations

**Figure 6** The current performance baseline for service B. It shows (left) An image of an in-situ sensor, (top) Data Allowance and (bottom) Upload/Download speeds, both compatible with LoRa-like and NB-IoT-like protocols.

As for Service A, additional **overheads are necessary** (e.g., in a bi-directional context, for system synchronization and responsiveness, and for acknowledgment (ACK) back to the source). These overheads, typically 20%, vary based on protocols and should be added to the **minimum service values** (e.g., daily data allowance) discussed in this document. Appendix D explores scalability options

It should be noted that to directly notify an in-situ sensor from an EO Satellite ahead of its ground track—thus preparing it for data collection and transfer, or as part of an alert system for environmental disasters, and to dynamically task the satellite to target the area with the in-situ sensors—this service may need to be used in conjunction with other TT&C services (e.g. Service A-1 and/or A-2, or classical TT&C).

## **3.4.2 Service B: Direct bi-directional low-data-rate data collection from in-situ sensors**

**Service B** offers *direct* bidirectional low-data-rate data and messaging between ground-based in-situ sensors and Earth Observation (EO) satellites in Low Earth Orbit (LEO) orbit. This service is tailored for direct data collection and transfer between the ground sensors and the satellite. In this setup, the **satellite** functions as a **Gateway**, communicating with multiple in-situ sensors (i.e., User Equipment (UE)/Nodes) through Service B, and with the Mission Control Centre (MCC) and end-users through Service A-1 and/or A-2, or classical TT&C. Thus, the system terminology adopted here is reversed compared to Service A and more closely resembles the terminology used in the earth observation industry.

- **Upload**: Ground **User Equipment (UE / node)** to LEO EO **Gateway**. This refers to communication from ground-based in-situ sensors (UE) to the LEO EO satellite (Gateway).
- **Download**: LEO EO **Gateway** to ground **User Equipment (UE / node)**. This refers to communication from the LEO EO satellite (Gateway) to ground-based in-situ sensors (UE).

The IoT Constellation landscape is already well-developed, with a variety of providers operating IoT Constellations in LEO Orbit and utilizing Low Power Wide-Area Network (LPWAN) technologies for in-situ and IoT data collection. As done today, in-situ validation of EO measurements systems is already performed with sensors distributed near the satellite ground track, their data is used to calibrate the measurements made by the satellite as it passes overhead. **Rather than competing, this service aims to complement by providing a scalable solution that** can facilitate the automation and federation of co-located in-situ and remote sensing measurements, across spatial and temporal dimensions.



**Figure 7** Service B: Indirect bi-directional low-data-rate TT&C Connectivity Architecture & key features

This low-data-rate connectivity architecture, supported by the advanced on-board intelligence capabilities, might enable much higher reactivity based on autonomous satellite decisions in real-time to immediately monitor events using data or signals triggered from in-situ sensors. A service of this quick reactivity and nature could bring great value into, for example, the international space charter for disaster response. It should also enable EO data providers and vertically integrated EO companies to deploy in-situ sensors, helping to overcome the common limitations associated with a lack of onboard calibration tools.

Refer to [Appendix D](#page-36-0) for the Service Summary Table, which outlines **scalability** considerations for certain service parameters that may impact service costs. Initial specifications are detailed in Section 4.

## <span id="page-15-0"></span>**3.5 IoT4EO Provider-Agnostic System Architecture**

This section, which is further detailed in [Appendix E,](#page-37-0) explores the **interoperability** landscape of a low-data-rate connectivity architecture to identify interventions where standardization can enable an IoT4EO provideragnostic solution. The objective of having a Provider-Agnostic system is to quickly **build up the scalability** of the envisaged services for 500+ EO satellites in LEO orbit and increasing number of ground Gateways and accessibility to thousands of in-situ sensors. Thus, the inclusion of an *'IoT4EO Provider-Agnostic System Architecture'* in this document aims to stimulate stakeholders, users, and service providers to identify their location in the '*value chain'* of the service provision. This is expected to further define the system later in the development process and support the creation of a standardization and interoperability action plan. Two complementary approaches have been identified:

- **Modification to Existing Standards → Identify existing standard elements that vary across service** providers and suggest modifications to unify them. This task is particularly challenging due to the existing systems across industries and technologies sharing the same standards, where modifications can have a ripple effect. Additionally, the relatively small size of the IoT4EO market means there is limited momentum to implement significant changes.
- **Middle-Out Engineering Approach → Identify system elements and interfaces that vary across service** providers and develop a middleware architecture or standard that enables technology solutions to integrate with existing systems without altering current standards. A focus on middleware development ensures common middleware standards for all providers.



**Figure 8** A simplified IoT4EO Provider-Agnostic System Architecture for Service A-1 (left) and A-2 (right)

<span id="page-15-1"></span>A more elaborated and detailed Provider-Agnostic System Architecture is provided in Appendix [E.1,](#page-37-1) expanding on [Figure 8](#page-15-1). Two potential architectures have been identified:

- **Bent-pipe Architecture** in the Relay satellite, featuring common paths (highlighted in green) shared by both Service A-1 (direct space-to-ground) and Service A-2 (via the Relay satellite).
- **Regenerative architecture** in the Relay satellite, where Service A-2 follows a distinct path (shown in yellow) from that of Service A-1 (shown in green).

In either of these system architectures, the user equipment (UE) must be engineered for interoperability across various network frameworks to ensure compatibility with a range of frequencies and protocols (e.g., NB-IoT, LoRaWAN, DVB-S) based on identified solutions. This **middle-out** engineering approach focuses on developing middleware capable of interfacing with both existing and future systems across various service providers and aims to establish **common middleware standards** that promote a **provider-agnostic** solution and stimulate competitiveness and scalability within the service provision.

**Service B** should also benefit from the scale that could be achieved under a provider-agnostic architecture, which would give access to a larger number of ground in situ-sensors and LEO Gateways. However, scaling up will raise several questions, incl. which stakeholders will manage the LEO Gateways, and what business agreements will be necessary among stakeholders (see section 3.6). These considerations are outside the scope of this document but will undoubtedly play an important role in the future.



**Figure 9** Example of IoT4EO System Architecture Standardization Snapshot. Note: Although two solutions, LoRa and NB-IoT, are mentioned here, this document continues to remain solution agnostic

The System Architecture is complex and will affect multiple stakeholders in the area of User Equipment, Gateways, Regulatory and Network management. Flexible approaches (e.g. use of SW Defined Radio, SDR) in UE equipment will be needed to ensure the scalability towards a Provider-Agnostic architecture.

For further details on interoperability and a provider agnostic architecture, refer to [Appendix E.](#page-37-0)

## <span id="page-16-0"></span>**3.6 Stakeholders**

This section explores the potential stakeholders in the low-data-rate connectivity architecture, including those expected to use the service, those who assist in its development and provision, and third parties impacted by it.

**Table 2**: Potential end users





#### **Table 3** Service provision value chain



#### **Table 4** Third party stakeholders



The aim is to encourage stakeholders to identify their roles within the *'IoT4EO Provider-Agnostic System Architecture*' introduced in Sectio[n 3.5,](#page-15-0) by mapping their location within the value chain and identifying potential areas for standardization to develop an interoperable middleware solution. For example, LPWAN Gateway Operators could capitalize on the opportunity to develop and distribute ground Gateway infrastructure, offering 'shared' access via a flexible, interoperable interface.

In this scenario, an intervention point for Space Agencies could then be:

- Promote the development of middleware standards that ensure compatibility between User Equipment (UE), Gateways and LPWAN & GEO/MEO Relay Operators' frequencies and protocols.
- Facilitate and support interaction with other commercial Operators of the system. This arrangement should alleviate the burden on potential end users by eliminating the need to manage the development, deployment, and maintenance of existing infrastructure and services.

## <span id="page-18-0"></span>**4 IoT4EO Service Requirements**

## **4.1 Requirements Translation & Traceability**

The following section outlines the translation of requirements to clarify the origin and progression of project needs, ensuring they are accurately implemented and traceable at every stage of development:

- **Customer/User Needs**: These are the needs and desires of potential users of the proposed low-datarate connectivity services e.g., EO Data providers, EO Data users.
- **IoT4EO Vision:** These are the objectives (Section [2\)](#page-5-1) envisioned by the ESA IoT4EO team to provide ubiquitous low-data-rate connectivity to Earth observation satellites in Low Earth Orbit (LEO).
- **Service A & B Requirements**: These requirements elucidate user needs and desires from the perspective of service provision, deliberately setting aside technical engineering requirements at this stage. The service definitions are detailed in Section 3 of the "*IoT4EO Service Definitions and Preliminary Specification"* document. The preliminary specification is covered in Sections 4.2 to 4.8.
- **System Requirements**: These requirements relate to the system and network aspects of the low-datarate connectivity architecture, derived from all the previously mentioned components. They describe the functional behaviour and technical architecture of the system. They are captured in the '*'System Definition and Preliminary Specification''* document, which will serve as a source for deriving subsystem requirements. This document has not been written yet and will be developed based on the evolution of the Service Specification.

The following block diagram outlines the thought process and proposed method for translating requirements and ensuring their traceability from the source to the system level. This formed the basis of this document and serves as a starting point for discussion at IoT4EO Workshop 2 [**RD-5**]. This discussion aims to invite feedback from EO Users and potential Service Providers, enabling them to influence the direction and framework of the efforts. It promotes a collaborative approach towards standardizing and validating technology to ensure interoperability, scalability, and easy adoption among various stakeholders.



**Figure 10** Low-data-rate connectivity architecture Requirements Translation & Traceability block diagram

The following sections detail user needs by translating them into Service Requirements from the perspective of service provision, deliberately setting aside technical engineering requirements at this stage.

## **4.2 Service Requirements Identification**

All requirements in this document are uniquely identified according to the following convention:

• IOT4EO-XXX-nnn

Where:

- IOT4EO represents Low-data-rate Connectivity Architecture
- 'XXX' represents the requirements group identifier.
- 'nnn' represents the requirement number.

The following requirement group identifiers are defined:



**Table 5** Requirement group identifiers

## **4.3 Performance Requirements**

The performance-defining requirements listed below were identified, where the first digit in the 'nnn' sequence indicates the specific service as identified in this document (i.e., '1nn' for Service A-1, '2nn' for Service A-2, and '3nn' for Service B).









**Table 7** Service A-2 (*Indirect, via relay*) - Performance defining requirements







**Table 8** Service B (*Direct, via in-situ sensors*) - Performance defining requirements



The subsequent Section [4.4](#page-24-0) discusses scalability requirements, while Section [4.5](#page-26-0) focuses on interoperability requirements. These sections cover how a single LEO EO Satellite, acting as a Gateway, can connect to numerous in-situ sensors acting as User Equipment (UE), and the necessity to enable access for multiple in-situ sensors to multiple LEO Gateways

## <span id="page-24-0"></span>**4.4 Scalability Requirements**

The following requirements were identified as common across all services

**Table 9** Scalability requirements







## <span id="page-26-0"></span>**4.5 Interoperability Requirements**

The following requirements were identified as common across all services

**Table 10** Interoperability requirements



## **4.6 Quality of Service (QoS) Requirements**

The following requirements were identified as common across all services





## **4.7 Data Security and Privacy Requirements**

The following requirements were identified as common across all services

**Table 12** Data Security and Privacy requirements



## **4.8 Legal and Regulatory Requirements**

The following requirements were identified as common across all services





## **5 APPENDIX**

## **5.1 Supplementary Material & Information**

The following Appendix provides supplementary materials and detailed data supporting the analyses and conclusions presented in this report. These additional resources are intended to expand understanding and provide transparency into the methodologies used.

## <span id="page-29-0"></span>**Appendix A Glossary**

### **A.1 List of Acronyms**

The following acronyms and abbreviations are used in this document

**Table 14** List of Acronyms



## <span id="page-30-0"></span>**A.2 List of System Terminology**

The following terminology and definitions are used in this document

## **Table 15** List of System Terminology





#### **Table 16** List of Service Terminology





## <span id="page-33-0"></span>**Appendix B Applications, Use cases, and Stakeholders**

## **B.1 Reference Use Cases**

The following list of Reference Use Cases Documents are used in this Service Definition and Preliminary Requirements Document. These were identified as potential applications by customers and users.

**Table 17** The full list of anticipated applications of a low-data-rate connectivity with Earth Observations and their estimated added value



## <span id="page-34-0"></span>**Appendix C IOT4EO Project**

## **C.1 Overview**

As previously discussed in Section 2.1, the ongoing proliferation of Internet of Things (IoT) technology on Earth is laying the foundation for the development of ubiquitous networks in space, by providing a **framework** that is already establishing important system components, including regulatory policies, physical infrastructure, data management systems, network layers, and protocols. It was on this foundation that the "*Concepts for the Use of IoT in Earth Observation*" studies were funded and conducted under two ESA Contracts with OHB [RD-2] and ADS [RD-3]. The purpose of these studies is to explore the synergies, opportunities, and feasibility of integrating low-data-rate connectivity with Earth Observation (EO) in Low Earth Orbit (LEO). In addition, a specific Study Group (SG) was established in 2022 through a collaboration between the European Space Agency (ESA) and other space agencies under the Inter-Agency Operational Advisory Group (IOAG) [RD-1] to explore the multidimensional aspects (i.e., technical and business) related to this ambitious goal.

The ongoing ESA studies, currently progressing through Task 3, are structured as follows:

- Task 1 EO Use Cases, Requirements, and Market Survey.
- Task 2 Concept of Operation (ConOps) and Architecture Definition.
- Task 3 Detailed Architectural Design.
- Task 4 Technology/Standardization roadmap and IOAG Draft Report.

Two public workshops are planned over the course of these studies, with the following objectives and outcome:

- **Workshop 1** was held at ESA-ESTEC on 16-17 February 2023, with the focus on integrating multiple disciplines and communities to participate in the process of learning, interest formation/positioning, coalition building, and strategic planning. The workshop details and executive summary can be found on the Indico website [here,](https://indico.esa.int/event/438/) and in [**RD-4**].
- **Workshop 2** will be held at ESA-ESTEC on 2-3 December 2024, with the focus on consolidating the Service A and Service B described in this document and gather feedback from potential users and service providers on the proposed approach, unify the community under a cohesive strategy, and determine the next steps. The workshop preparation details can be found [here,](https://indico.esa.int/event/513/) and in [**RD-5**].

## **C.2 Project statement**

The following statement was drafted during the "*Concepts for the Use of IoT in Earth Observation*" studies. Its purpose was to clarify and contextualize the IoT4EO Vision, define the project's scope, and facilitate communication by serving as a reference for all involved parties, from team members to external stakeholders:

*The integration of low-data-rate connectivity with Earth Observation (EO) satellites in Low Earth Orbit (LEO) has the potential to revolutionize satellite operations by improving responsiveness by an order of magnitude to facilitate dynamic satellite tasking, on-board event detection with near-real-time distribution of information between ground and space nodes. Moreover, it will strengthen and align in-situ scientific measurements with systematic Earth observation data to improve calibration and validation processes, offering greater reliability and scope in scientific measurements. The IoT4EO project exists to connect the idea with its implementation, through standardization and validation of technology that ensures interoperability, scalability, and ease of adoption across multiple stakeholders into an operational environment with cost-effective ubiquitous connectivity for EO LEO satellites.*

## **C.3 Project Objectives**

The following objectives were listed in the Statement of Work (SoW) for the "*Concepts for the Use of IoT in Earth Observation*" studies [RD-2], [RD-3]and are reiterated here for convenience.

#### **Table 18** IoT4EO Statement of Work (SoW) objectives





## **Appendix D IoT4EO Service Summary**

## **D.1 Summary table**

This appendix summarizes three low-data-rate connectivity services identified in the "*Concepts for the use of IoT in Earth Observation*" studies under ESA Contracts [RD-2] and [RD-3]. It includes scalability considerations for service parameters that could affect costs.

<span id="page-36-0"></span>

## <span id="page-37-0"></span>**Appendix E Interoperability and Standardization Action Plan**

## <span id="page-37-1"></span>**E.1 IoT4EO Provider-Agnostic System Architecture**

As previously discussed in Section [3.5,](#page-15-0) this Appendix expands on the interoperability landscape of a low-datarate connectivity architecture to identify interventions where standardization can enable an IoT4EO provideragnostic solution. The inclusion of an 'IoT4EO Provider-Agnostic System Architecture' in this document aims to stimulate stakeholders, users, and service providers to identify their location in the 'value chain' of the service provision. This is expected to further define the system later in the development process and support the creation of a standardization and interoperability action plan.



**Figure 12** IoT4EO Provider-Agnostic System Architecture (Bent-pipe)

In these provider-agnostic system architectures, two key differentiating features have been identified that affect the solution and future standardization efforts, particularly regarding the functionality of the GEO/MEO Relay:

- **Bent-pipe Architecture** in the Relay satellite, featuring common paths (highlighted in green) shared by both Service A-1 (direct space-to-ground) and Service A-2 (via the Relay satellite).
- **Regenerative architecture** in the Relay satellite, where Service A-2 follows a distinct path (shown in yellow) from that of Service A-1 (shown in green).

The success of the Service A value chain heavily depends on the willingness of stakeholders to participate and the adoption rate among existing service providers. Currently, it is anticipated that the Mission Control Centre (MCC) (i.e., Earth Observation Satellite Operator) will interface solely with the service provider. This arrangement alleviates their need to interface with application and network servers or to handle the development, deployment, and maintenance of gateways. All they need to do is to purchase the User Equipment (UE) for their satellite and subscribe to the service. The service providers manage everything else.

There are several key characteristics that appear to define the IoT4EO Provider-Agnostic System Architecture. These include network topology, which distinguishes between two types of possible networks:

- **Network 1 (Bent-Pipe):** This connectivity framework would utilize only LPWAN (e.g. NB-IoT, LoRaWAN) protocols to facilitate communications between ground and space segments. It leverages existing TCP/IP and IP over LTE protocols between the Mission Control Centre (MCC) and ground gateways. This approach would result in a reduced dependency on numerous stakeholders due to minimal technical differences between Services A-1 and A-2, especially when the User Equipment (UE) uses both services to guarantee widespread access
- **Network 2 (Regenerative):** This connectivity framework would utilize both LPWAN and DVB-S protocols, depending on the solutions implemented at the GEO/MEO Relay satellites. In a regenerative solution, which involves demodulation and re-modulation of the signal in the Relay satellite, compatibility with the service provider's established network protocols is necessary for facilitating communication through the entire chain. While a regenerative solution offers increased flexibility for the Relay provider, it could also lead to variable paths, interfaces, coordination and greater number of dependencies when utilizing both Service A-1 and A-2.

This ultimately affects whether the solution needs to interoperate with existing 'traditional' GEO Relay infrastructure, such as interfacing with additional protocols like DVB-S for sending and receiving through their network. Conversely, a bent-pipe system does not require demodulation of the LPWAN protocol, thereby reducing complexity from the LPWAN perspective. Cooperation from service providers is needed.

## **E.2 Standardization Action Plan**

The purpose of this Appendix is to encourage stakeholders identified in Sectio[n 3.6,](#page-16-0) along with users and service providers, to identify their location and role within the 'value chain' of service provision. This shall assist ESA in standardizing system components towards an interoperable solution. This section presents our preliminary strategy for developing an action plan focused on interoperability and standardization.

The two "*Concepts for the use of IoT in Earth Observation*" studies under ESA Contracts [RD-2] and [RD-3] have preliminary identified two potential solutions that use LPWAN technologies: LoRa and NB-IoT. The highlighted dotted box indicates areas where intervention is likely needed to facilitate interoperability through standardization and middle-out engineering.



**Figure 13** Example of IoT4EO System Architecture Standardization Snapshot. Note: Although two solutions, LoRa and NB-IoT, are mentioned here, this document continues to remain solution agnostic

To create a provider-agnostic environment, a review all Service Provider solutions and system architectures is needed to identify common elements, then further categorize them into components with standardization potential. Note two types of standardization impacts:

- 1. Service Performance Improvement
- 2. Enabling Multi-service Interoperability

In this context, the IoT4EO Vision focuses on identifying areas that enable multi-service interoperability since performance improvements should be driven by the service providers themselves to stimulate competition and drive down deployment and operational costs. Creating an environment that supports provider-agnostic solutions is a prerequisite. Key technical assumptions include:

- A User Equipment (UE) is sufficiently versatile (e.g. Software Defined Radio (SDR) technology) to support compatibility with multiple solutions from multiple Service Providers.
- A User Equipment (UE) may subscribe to more than one service of the same type (e.g., A-1 for a subset of Gateways, and another A-1 for an additional subset) or of different types (e.g., A-2 to expand coverage, or B to connect with in-situ sectors). These services may operate concurrently (e.g., A-1 and B) or exclusively (e.g., A-2 only when A-1 is unavailable) with multiple subscriptions.

The Provider-Agnostic architecture outlined in Appendix E.1, which is also be applied to Service B, consists of various system components that also include User Equipment, Gateways, and Regulatory and Network aspects. Several questions could emerge about the stakeholders' readiness to embrace these Services:

- Is it safe, for instance, to route TT&C messages through public networks and Gateways?
- Does the added cost of these Services justify the value provided by their ubiquitous capabilities?



**Figure 14** Initial attempt to identify system elements that would require standardization to enable a provider-agnostic solution

## <span id="page-40-0"></span>**Appendix F Scenario examples**

## **F.1 LoRaWAN**

The following scenario offers an example of a Low Power Wide Area Network (LPWAN) low-data-rate connectivity architecture utilizing LoRa technology to achieve global coverage and minimize visibility latency, with the potential to improve operational efficiency and responsiveness for Earth Observation (EO) satellites by an order of magnitude. The assumed altitude for LEO satellites is 600 km. A clear trade-off needs to be considered to balance coverage and cost, involving the number of Gateways and the Minimum Elevation Angle (MEA) per Gateway. The following analysis is provided by ADS [AD-3].





**Figure 15** Potential coverage of 50+ LPWAN Gateways with a Minimum Elevation Angle (MEA) of 20 degrees. In this scenario, 40% / 75% global coverage is achieved, with a near-zero / 10 min average visibility latency.

**Figure 16** Potential coverage of 50+ LPWAN Gateways with a Minimum Elevation Angle (MEA) of 10 degrees. In this scenario, 66% / 85% global coverage is achieved, with a near-zero / 10 min average visibility latency.

**Source:** Fig.31 Technical Note provided by ADS under ESA Contract [RD-3]