

**GMV Aerospace & Defence view**

# SAVOIR Present and Future

ADCSS – ESTEC - Oct 21<sup>st</sup>, 2024



**ADCSS 2024**

18th ESA Workshop on Avionics, Data, Control and Software Systems

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INNOVATING SOLUTIONS

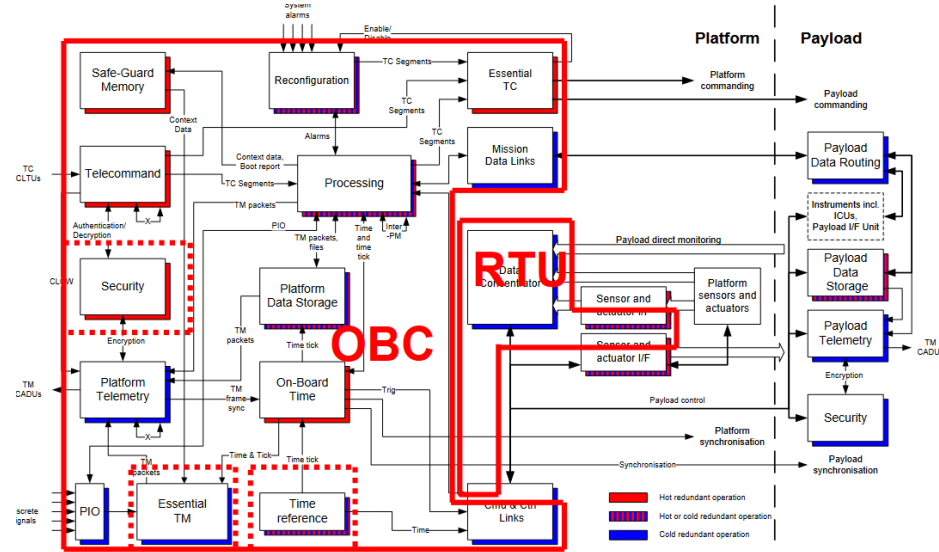
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# 1. SAVOIR TODAY

- Provides a comprehensive framework for developing highly reliable, fault-tolerant avionics systems.
- Ensures interoperability between different components and subsystems, focusing on safety, security, and reusability.
- Adopted for Spacecraft Bus mainly for larger satellites, traditional space missions, and projects with certification requirements.
- Focus on functional chains, decoupling of hardware from software. On-board systems like navigation, communication, or attitude control can be managed independently and react to real-time data.

Workers design and develop common space platform avionic and some does not even know that SAVOIR exists



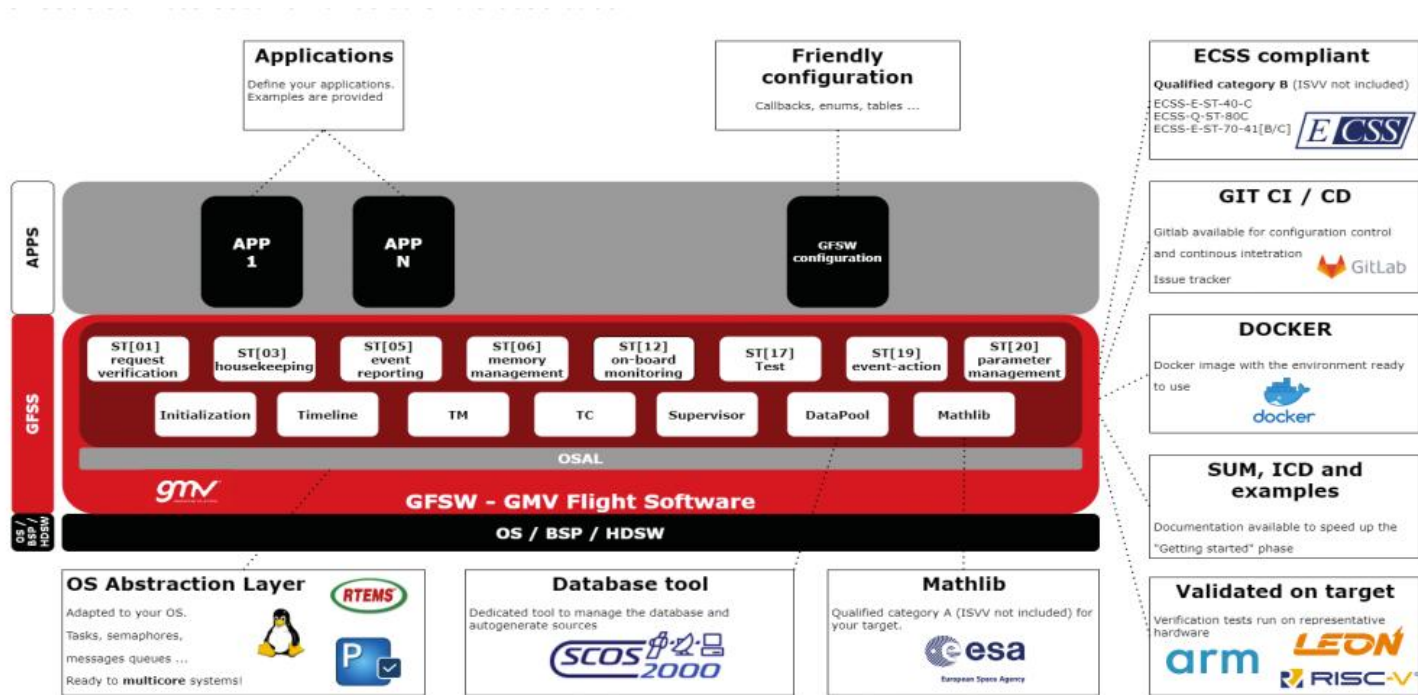
## 2. SAVOIR NEEDS UPDATES

- Working-Groups at the edge of the standardization frontiers
- Model-Based Design, from HW architecture to autocode
- HW-seamless integration – ADHA, APA, PC104 ....  
Are COTS real COTS?
- High-reuse as a goal (many effort per new mission)
  - Reinventing the wheel for mission specific functionalities, adaptations, operability
- SW re-writes for different missions, HWs, OS, ASWs...
- Cybersecurity is needed, not a tax  
Inter-operability & seamless integration vs zero-trust
- Are Payloads subject to standardization? Payload Controllers?



## 2. GMV FLIGHT SOFTWARE

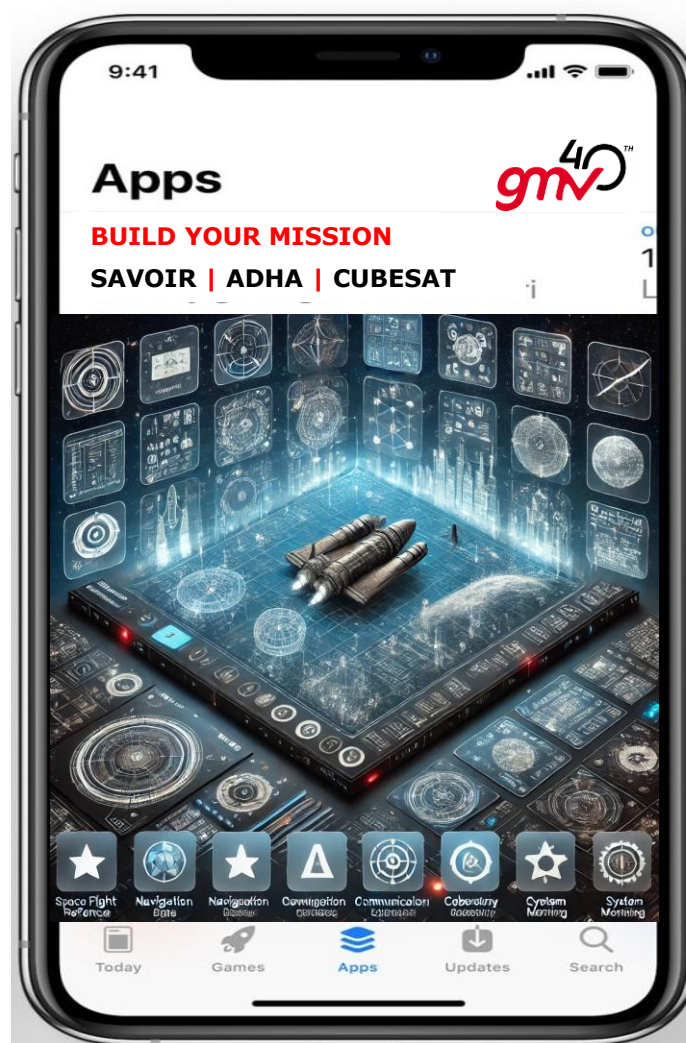
- Modularity
- Abstraction
- Layered
- GFlight SW Services
- Towards Autonomy
- OS Portability
- HW Portability





### 3. SAVOIR EVOLUTIONS

- App-store concept for space flight hardware/software architecture over the SAVOIR avionics reference
- Model-Based Design with ideal plug&play for enhanced flexibility
- Logic architecture adding and removing software components dynamically, leveraging the API and “as-a-service” concept
- RestFul and the publish-consume. Software components can be switched in and out during runtime, without requiring a system reboot or a complete software rebuild.
- Programmable HW – SDR, SDN, SW-Define-Payload, Regenerative Payloads (exploit re-configuration, dynamism)
- On-Board Autonomy
- Anchor Trust – Security-Safety



### 3. SAVOIR EVOLUTIONS

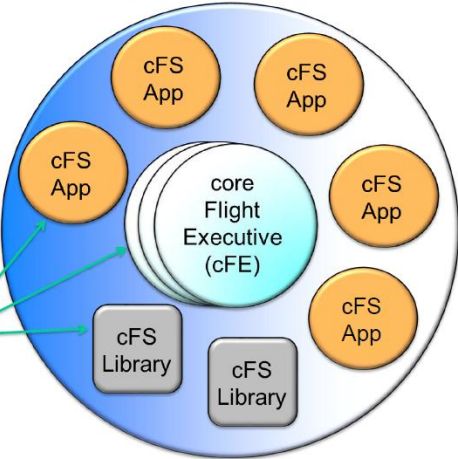
- Enhance modularity, scalability, and lifecycle management
- Agile frameworks – DevOPs  
incorporate new technologies or updates later in the development cycle
- Modularity & Isolation  
Time-Space Partitioning, Trusted Executions Environments  
Docket/Podman containers  
Microservices Architecture
- Cubesat – PC104 – real COTS
- Support for Distributed Systems (the cloud above the clouds)  
Constellations, Load-balancers, Planners, Task Distribution
- New Communication protocols – speed – AI-routing - quantum



## 2. cFS - NASA

- **core Flight System (cFS)**
- A Flight Software Architecture consisting of an OS Abstraction Layer (OSAL), Platform Support Package (PSP), cFE Core, cFS Libraries, and cFS Applications

core Flight System (cFS)



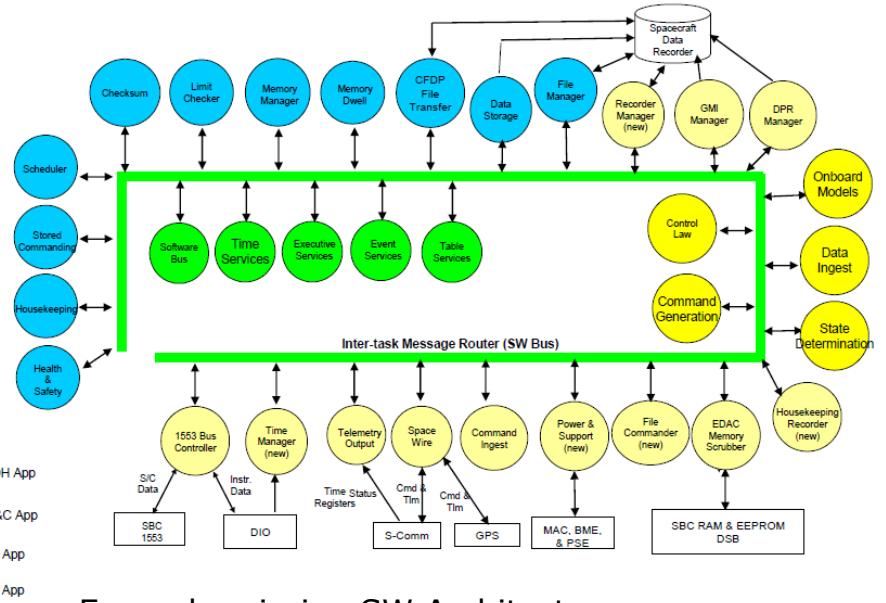
- **core Flight Executive (cFE)**
- A framework of *mission independent, re-usable, core* flight software services and operating environment

- **Each element is a separate loadable file**

- **cFE services include:**



- **Support services include:**
  - File utilities



- Example mission SW Architecture
- Easy rapid prototyping with heritage code that was cFEcompliant
- Layered architecture has allowed COTS lab to be maintained through all builds



#### 4. SHALL WE OPEN DISCUSSIONS?

# Brainstorming - Questions



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**Thank you**

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