Institut Supérieur de l'Aéronautique et de l'Espace



Formal Verification of the PolyORB-HI Middleware

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Objective of TASTE COO2

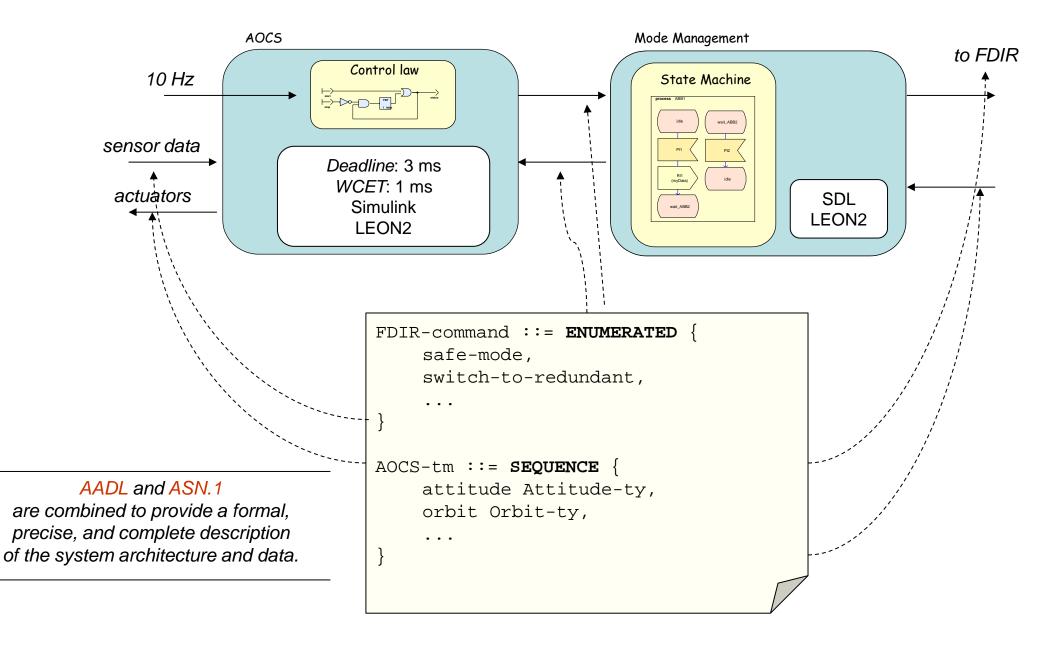
- > As part of TASTE COO2 project, ISAE was tasked to explore usage of theorem proving tools, C/ACSL and SPARK2014
 - » How can they be used to assess the quality of the code generated by the TASTE toolchains
 - » Mostly exploratory, small workforce of 1 man.month funded by ESA, dedicated to review existing tools, technologies and see how far we can go

Short answer for the TL;DR folks: it works not so bad except for pointers management and tasking Longer answer in the slides that follow ;-)

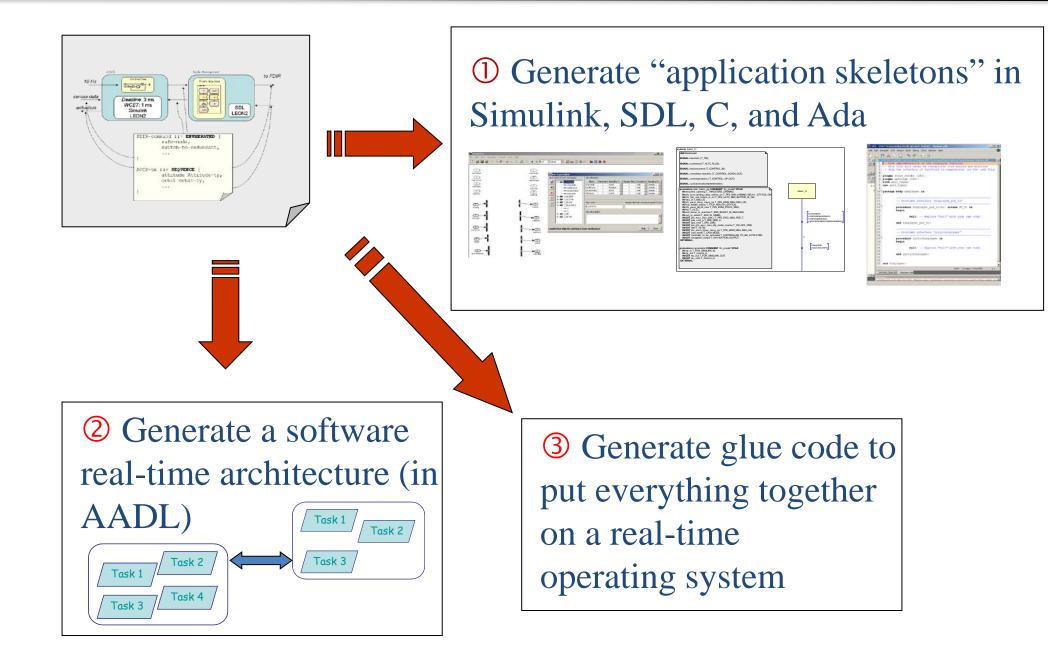
Outline

- > Context & objective
- > A little bit of theory
- > Proof of the C runtime
- > Proof of the Ada runtime
- > Some lessons learnt

About TASTE and the TASTE process



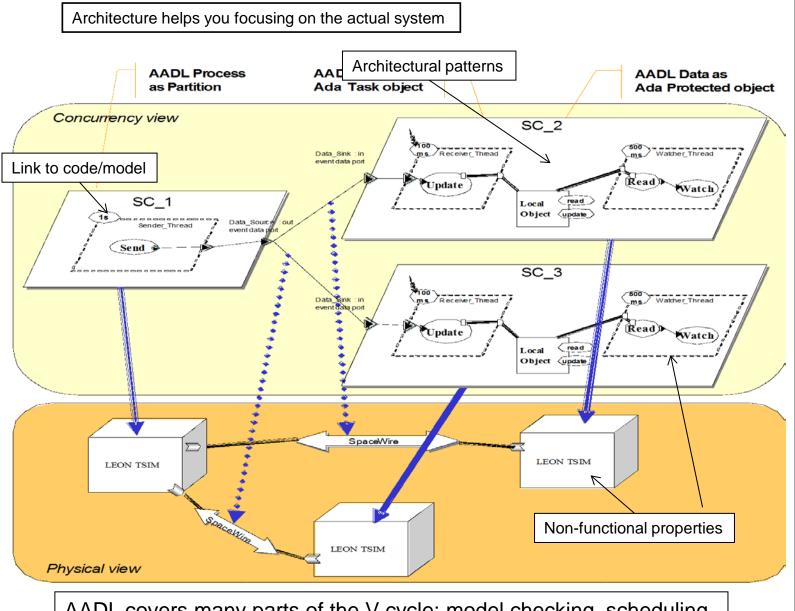
ASSERT "model compilation"



Behind the scenes

- TASTE relies on standardized languages :
 - ASN.1 and AADL to capture the software architecture and data
 - SDL, Simulink, SCADE, C, Ada, VHDL, ... to capture the software behaviour
 - MSC and Python to test
- Combine graphical AND textual notations
 - If anything goes wrong, human can fix textual syntax
 - Diagrams for easier understanding
 - But some information is textual by nature
- Avoid languages with weak semantics or syntax

What you should to know about AADL @ ISAE



ISAE contributions to SAE AADL since 2009 Lead on the Ocarina toolset, used by ESA

Code generation : Ada, C (POSIX, ARINC653), RTOS TRL 7 with ESA (ECSS E-40)

Scheduling: Cheddar, MAST TRL 4 with ESA

Model checking: Petri Nets TRL 2 (PhD contribution)

Architectural Constraints/Requirements checks

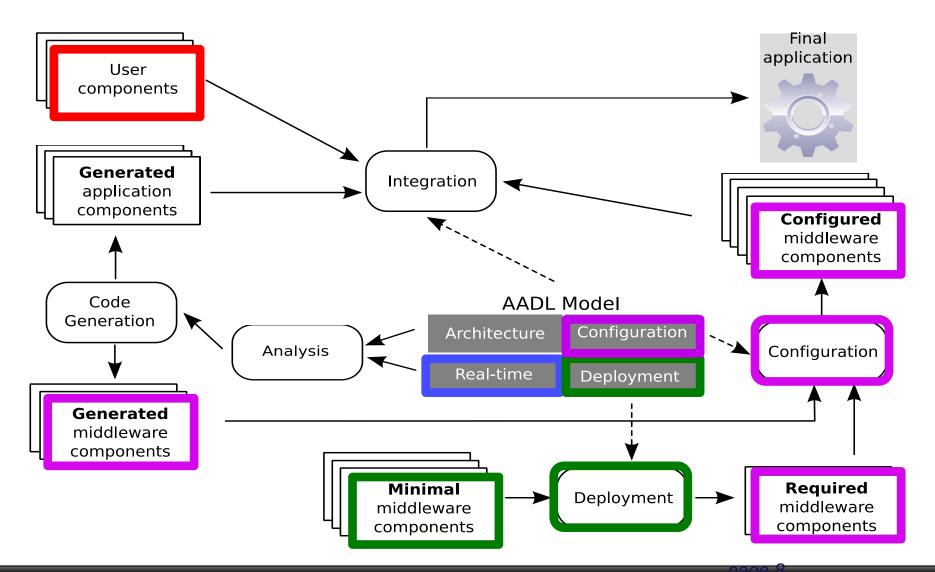
TRL 6 with SEI, being standardized

Link with SysML models TRL 1, under evaluation

AADL covers many parts of the V cycle: model checking, scheduling, safety and reliability (ARP4754) and code generation

Code generation from AADL models

> Exploits AADL models information to generate applicationtailored middleware



Ocarina: an AADL code generator

> Ocarina is a stand-alone tool for processing AADL models

- » Command-line tool, a-la gcc
- » Can be integrated with third-party tools
 - OSATE (SEI), TASTE (ESA), Cheddar (UBO), MyCCM-HI (Thales)
 - Also emacs and vim modes
- > Code generation facilities target PolyORB-HI runtimes
- > Two flavors
 - » Ada HI integrity profiles, with Ada native and bare board runtimes
 - » C POSIX or RTEMS, for RTOS & Embedded
- > Generated code quality tested in various contexts
 - » For WCET exploration, support for device drivers, ...
 - » For various RTOS
- > Written to meet most High-Integrity requirements
 - » Follow Ravenscar model of computations, static configuration of all elements (memory, buffers, tasks, drivers, etc.).

TASTE COO2 roadmap

- > Initial objective: demonstrate TASTE runtimes (PolyORB-HI/C and Ada) are free of runtime errors (RTE)
- > The leading tool for asserting code is free of RTEs are
 - » For C: ACSL framework, from CEA; combined with Why3 from Inria along with various analysis plug-ins
 - » For Ada: forthcoming SPARK2014 from AdaCore and Altran Praxis
- > Stakeholders agreed on the following roadmap
 - » Adapt existing toolchains to process runtime entities
 - » Perform annotations on source code to asses lack of RTEs

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Some theoretical background

- > We are interested in imperative programs: when executing a program P, we go from a state s_i to a state s_f
- > Specifying P is characterizing s_i and s_f with a Hoare triple { ϕ P { $\psi}$ where:
 - » ϕ is a logical formula called the precondition of P
 - » ψ is a logical formula called the postcondition of P
- Intuitive meaning: starting from a state verifying the assertions defined by φ, executing P should lead to a state verifying the assertions defined in ψ.
- Thus, verifying the correctness of P given its specification as a Hoare triple {φ} P {ψ} is to prove the Hoare triple {φ} P {ψ} in the Floyd-Hoare formal system.

About the Floyd-Hoare formal system

> Four constructs: assignment, sequence, conditional, iteration» Enough to represent all sequential programs

$$\frac{\{\varphi \in [x/E]\} \times := E \{\varphi\}}{\{\varphi\} P \{\gamma\} \{\varphi\} P \{\psi\}} (:=)$$

$$\frac{\{\varphi \in \varphi\} P \{\gamma\} \{\varphi\} P \{\psi\}}{\{\varphi\} P \{\psi\}} (Seq)$$

$$\frac{\{\varphi \rightarrow \varphi' \{\varphi'\} P \{\psi'\} \psi' \rightarrow \psi}{\{\varphi\} P \{\psi\}} (Cons)$$

$$\frac{\{\varphi \land C\} P \{\psi\} \{\varphi \land \neg C\} Q \{\psi\}}{\{\varphi\} if C then P else Q fi \{\psi\}} (Cond)$$

$$\frac{\{\varphi \land C \land v = V\} P \{\varphi \land v \prec V\}}{\{\varphi\} while C do P od \{\varphi \land \neg C\}} (t)$$

The weakest-precondition calculus

- > The weakest-precondition calculus is a particular semantics for imperative programs that can be viewed as a complete strategy to build deductions in FH logic
- > Main idea: given a specification { ϕ } P { ψ }, start from ψ , find the minimal (weakest) precondition allowing to deduce ψ and verify that ϕ implies this minimal precondition
- > Implies exploring a proof-tree, applying FH rules
 - » Combined with higher-order theories (for naturals, memory, ...)
 - » And some specific strategies to speed up the process

$$\varphi \rightarrow I(0, X) \qquad \begin{array}{c} \{I(0, X)\} \quad \text{P1} \quad \{I(Q, R)\} \quad \{I(Q, R)\} \quad \text{P2} \quad \{I(Q, R) \land \neg (Y \leq R)\} \\ \\ \{I(0, X)\} \quad \text{P} \quad \{I(Q, R) \land \neg (Y \leq R)\} \\ \\ \\ \{\varphi\} \quad \text{P} \quad \{I(Q, R) \land \neg (Y \leq R)\} \end{array}$$

How does it relate to my source code ?

> The process is thus the following:

- » a human expert writes specification in terms of preconditions, postconditions, loop invariants, loop variants etc. for a program
- » those specifications are translated into verification conditions (VC) using weakest-precondition calculus. The VC are purely mathematical/logical statements
- » the VC are then passed to a theorem prover, automated or interactive, to be discharged

```
/*@ ensures \result >= x && \result >= y;
    ensures \result == x // \result == y;
*/
int max (int x, int y) { return (x > y) ? x : y; }
```

Specification

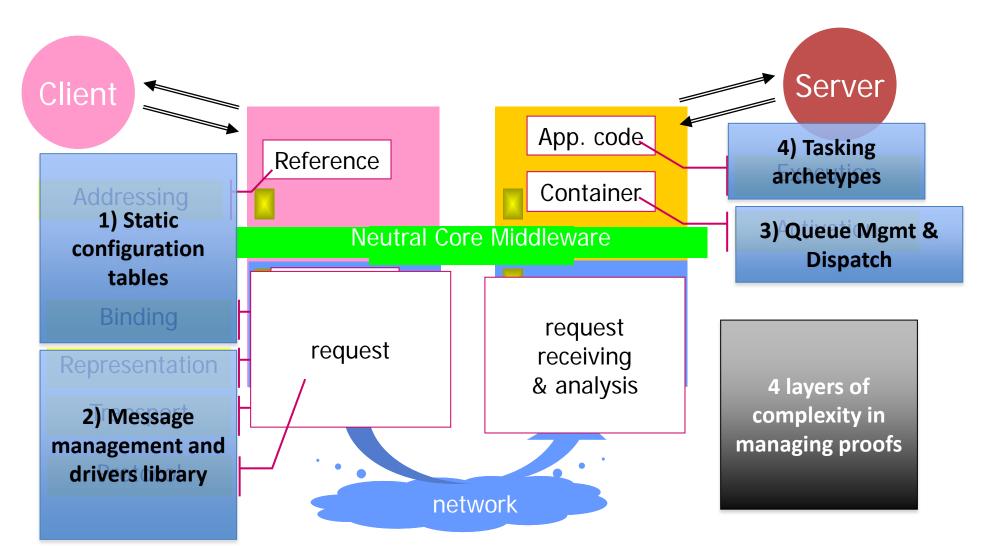
Implementation

Refining the roadmap

- > The C and Ada PolyORB-HI runtimes share a common heritage
- > Same global architecture, built on top of the "schizophrenic" middleware pattern
- > Similar code design and patterns
 - » Ravenscar archetypes for task constructs
 - » Same queueing discipline for messages
 - » Same code patterns generated from AADL description
- > Yet, different implementation choices
 - » Ada: rely on limited but rich High-Integrity subsets
 - » C: must accommodate for an abstraction layers on top of OS for tasking, concurrency and time management

About the schizophrenic middleware architecture

- > Inherited from the PolyORB middleware
- > A generic definition of middleware architecture



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The Frama-C platform

- > We have used the Frama-C platform to prove the runtime.
 - » the ACSL specification language allows to express assertions, preconditions, postconditions, loop variants and variants etc. as special comments in the C source code
 - » the RTE plugin has been used to generate additional assertions about possible runtime errors (signed integers overflow, invalid memory access, division by zero etc.)
 - » the WP plugin has been used as VC generator for the weakestprecondition calculus
 - » the Alt-Ergo SMT solver has been used to automatically prove the generated VCs

Frama-C/Why in action

X Why3 Interactive Proof Session w <u>T</u>ools <u>H</u>elp (onset_mm_us_anonseruce___po_m_enne_t_s_value 1720 Theories/Goals Status 1496 Ο Λ proved goals 1497 | = > 0po hi time.mlw 2 1498 offset max us anonstruct po hi time t 3 val 0 Jessie model goals 1499 value) && ∇ Jessie program 2 1500 (integer of uint32 (select us_anonstruct___po_hi_time_t_3_sec_val 1501 VC for __po_hi_add_times_ensures_default 0 ∇ integer of uint32 1502 -Ergo (0.95) 0 🔈 Alt-Ergo (0.95) 1503 (select us anonstruct po hi time t 3 sec lin 2 VC for po hi add times safety Þ (offset_min us_anonstruct___po_hi_time_t_3_lim 1504 o (0.95 models) 0 1505 limit $\leq = 0 \Lambda$ VC for po hi delay until ensures default 1506 0 < =/C3 (2.4.1) 0 VC for ___po_hi_delay_until_safety 1507 offset max us anonstruct po hi time t 3 li 0 VC for _____po__hi get__time_ensures_default Þ og (8.4pl1) 1508 limit) && 1509 0 offset min us anonstruct po hi time t 3 val VC for po hi get time safety opa (0.16.6) 1510 value $\leq = 0 \Lambda$ VC for __po_hi_microseconds_ensures_default 0 Þ 1511 0 < =VC for __po_hi_microseconds_safety 2 23 (4.3.1) 1512 offset max us anonstruct po hi time t 3 v 0 1513 value)) VC for ____po__hi__milliseconds_ensures_default Þ mations 1514 end 2 VC for po hi milliseconds safety 1515 Split 0 VC for po hi seconds ensures default Þ VC for po hi seconds safety 2 Inline 273 int po hi time is greater (const po hi time t* value VC for ___po_hi_time_copy_ensures default 0 274 { 275 if (value->sec > limit->sec) VC for __po_hi_time_copy_safety 2 Edit 276 { VC for po hi time is greater ensures default 0 277 return 1: Replay VC for __po_hi_time_is_greater_safety 0 278 } if (value->sec == limit->sec) 279 280 { if (value->nsec > limit->nsec) 281 Remove 282 { 283 return 1 Clean 284 } onitoring 285 } Vaiting: 0 286 return 0; heduled: 0 287 } lunning: 0 < 111 file: /home/hugues/local/ocarina/include/ocarina/runtime/polyorb ~ Ш Interrunt

Proving PolyORB-HI/C

> The following C compilation units must be considered

- » po_hi_types.h: definition of simple types and a function to copy arrays of bytes
- » po_hi_time.h: time management, with definition of a struct embedding time decomposed into seconds andnanoseconds. Several functions to add, initialize etc. such structures
- » po_hi_marshallers.h: conversion functions for marshalling/unmarshalling data
- » po_hi_messages.h: messages management functions (write message, append message, move part of a message etc.)
- » po_hi_main.h: defines functions for a synchronized start of the system
- » po_hi_protected.h: mutex management functions
- » po_hi_task.h: link to concurrency library
- » po_hi_gqueue.h: queue management functions
- » po_hi_transport.h: communications between tasks functions

About the complexity of annotations

> C memory model is a pain

```
/ @ requires \valid (((char □) dst)+(0..size - 1));
@ requires \valid (((char □) src)+(0..size - 1));
@ requires \separated (((char □) dst)+(0..size - 1), ((char □) src)+(0..size - 1));
@ assigns ((char □) dst)[0..size - 1] \from ((char □) src)[0..size - 1];
@ ensures \forall int i; 0 <= i < size ==> □(((char □) dst)+i) == □(((char □) src)+i);
@□/
void __po_hi_copy_array (void dst, void src, __po_hi_uint32_t size);
```

> The specification reads as follow:

- » Pointer parameters are valid, at least for the length size specified as a parameter.
- » The memory regions of the two pointers do not overlap (\separated clause).
- » Only the dst pointer will be assigned, using the src pointer.
- » as the \from clause is an experimental feature, we have to specify the complete postcondition, i.e. that the size first bytes of src has been copied into dst.

About memory models

- > All memory is statically allocated in the heap
 - » As we deal with values living inside the heap, we have to use a memory model allowing to map each C value in the heap to logical expressions in the ACSL specification.
 - » Of course, the more precise the memory model is, the more difficult the generated VC are to discharge.

> Limitations ⊗

- » We have used the Typed memory model that allows reasoning with pointers with an efficient mixed memory model.
- » Unfortunately, the Typed memory model does not allow all possible casts between pointer types (for instance int * to void * is not allowed).

Abstracting OS primitives

> Use of external libraries require precising expected outputs » Normal and error case, as this is propagated back to clients

```
/ @ behavior __tp_not_valid:
      assumes !\ valid(__tp);
 @
 @
    assigns \nothing;
      ensures \result == EFAULT;
 @
 @ behavior clock_not_valid:
 @
      assumes ! clock_valid(__clock_id);
 @
     assigns \nothing;
 @
      ensures \result == EINVAL;
 @ behavior normal:
 @
      assumes \valid(__tp);
 @
     assigns __tp->tv_sec;
 @
@
      assigns __tp->tv_nsec;
      ensures \ = 0;
 @
      ensures \valid(__tp);
 @
@
      ensures __tp == \int old(_tp);
      ensures _tp \rightarrow tv_sec \geq 0 \&\& _tp \rightarrow tv_sec \leq UINT32_MAX;
 @
      ensures __tp->tv_nsec < 100000000 && __tp->tv_nsec >= 0;
 @□/
extern int clock_gettime (clockid_t __clock_id, struct timespec __tp) __THROW;
```

Basic computations

- > Some complex corner cases to evaluate even basic arithmetics
 - » Ex: byte swapping, shifting and integers do not mix very well

```
/ @
@ ensures \result == ((value & 0x00000ff) << 24) +
@ ((value & 0x0000ff00) << 8) +
@ ((value & 0x00ff0000) >> 8) +
@ ((value & 0x00ff00000) >> 8) +
@ ((value & 0xff000000) >> 24);
```

» But this can be proved

```
unsigned long __po_hi_swap_byte (unsigned long value)
{
    unsigned long v = 0;
    v |= (value % 256) □ 16777216;
    v |= ((value / 256) % 256) □ 65536;
    v |= ((value / 65536) % 256) □ 256;
    v |= (value / 16777216);
    return v;
}
```

• Runtime penalty limited thanks to compiler optimizations

> Proving basic units, except queue management and tasking

VC	To be proved	Proved	Time (ms)	Qed	Alt-Ergo		
Qed	65	65	56]	Tool
Alt-Ergo	156	152	28376				Ĕ
Pre	16	16	668	12	4	3	
Post	41	41	12156	18	23	Z	>
RTE	92	90	9888	13	79	7	Category
Assigns	58	56	1732	16	42	Ž	Cate
Loop	10	10	3940	6	4	5	0
Other	4	4	48	0	4		
Total	224	017	00400				
Total	221	217	28432				

- > Still a lot to do at Frama-C/ACSL tool-support level
 - » No support for complex pointers, required for queues
 - » No support for concurrency constructs, impossible to demonstrate absence of interferences between task, or respect of Ravenscar!
- > Recall this was a 3 man.month combined effort

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About SPARK2014

> SPARK2014 leverages Ada2012 aspects to enable definition of contracts that can be either evaluated at run-time, or proved formally

procedure Push (R : in out Ring_Buffer; X : Integer)
with Pre => (not Is_Full (R)),
Post => (R.Length = R.Length'Old + 1);

- » Annotation through valid Ada code + special attributes
- » Part of the compilation process
- > GNATProve GPL2013 then GPL2014 used in this study
 - » First a prototype, now supported by AdaCore and Altran Praxis
 - » Requires adoption of Ada2012 to support all annotations

Proving PolyORB-HI/Ada

- > The following packages must be considered
 - » PolyORB-HI.Output: logging facilities
 - » PolyORB-HI.Utils: helper functions
 - » PolyORB-HI.Messages: message management
 - » PolyORB-HI.Marshallers_G: marshalling functions
 - » PolyORB-HI.Thread_Interrogators: message queues
 - » PolyORB-HI.*_Task: task archetypes
- > GNATProve allows one to control which package to analyse
 - » E.g. do not consider drivers
- > GNATProve generates VCs for code that lead to RTEs
 - » Exclude safe code after compiler analysis

Adapting the Ada runtime

- Compared to C, annotations define pre/post conditions
 » Hypothesis on behavior shared with client
 » Mostly invariants on validity of data being exchanged
 - E.g. message well-formed, non-empty arrays, etc.
- No need to tell a lot about memory model
 » No need for pointers in High-Integrity Profile in Ada !
- > No need to abstract OS services
 - » These are part of Ada semantics
 - Copy of arrays, time management
- > No need to precise bounds on types
 - » Use subtype mechanism of Ada
 - Simplify many annotation when doing packet construction for instance

Global results

- Proving basic units, except queue management and tasking
 » Exact same subset as the C runtime
- > 95 VCs to be discharged
 - » 77 proved already
 - » 18 unproved due to limitations in toolset
 - Mostly related to slicing and copies, need to adapt proof strategies
 - Easy to solve at tool level support
- > Similar limitations to Frama-C/ACSL tool-support level
 - » No support for concurrency constructs, impossible to demonstrate absence of interferences between task, or respect of Ravenscar!
 - » Recall we have no need for pointers ③

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SPARK2014 vs ACSL

> SPARK2014

- » Better language semantics
- » Leverage Ada profiles
 - Restrictions enforced
- » Annotations compilable

> ACSL

- » Weak semantics of C
 - Annotations more complex
- » No enforcement of profiles
- » Annotations external
 - Risk of discrepancies
 - Compiled with E-ACSL
- > Same backend technology: Why3, VCGen and Alt-Ergo
 - » Similar strategies applied
 - » Main difference in strategy to generate VC and management of input language semantics

PolyORB-HI/C & Ada

- > Same subset of the runtime proved
 - » Message marshalling, constructions and basic helper functions
 » Cover 50% of the code
- Limits in toolset to process complex queues of messages
 » To be addressed shortly, mostly a time issue
- Limits in theoretical framework to address concurrency
 » Must be abstracted away, through model of computation
 » Use of the Ravenscar model at must
- > Which one to chose ? Portability of Ada helps !
 - » 2 times more VCs to be discharged for the C variant!
 - » Needs adaptation of the C runtime for every RTOS variants $\boldsymbol{\varpi}$

Future work

- > Complete integration with TASTE toolset
 - » Integrate new variants of the runtime to baseline
 - » Provides script to automate proof as part of user-visible GUIs
- > Extend proof also to user code
 > Needs better modeling artefacts at TASTE
 - » Needs better modeling artefacts at TASTE process-level
- > Study evolution of theorem provers » A very active community!