



SOIS Architecture and use of Electronic Data Sheets

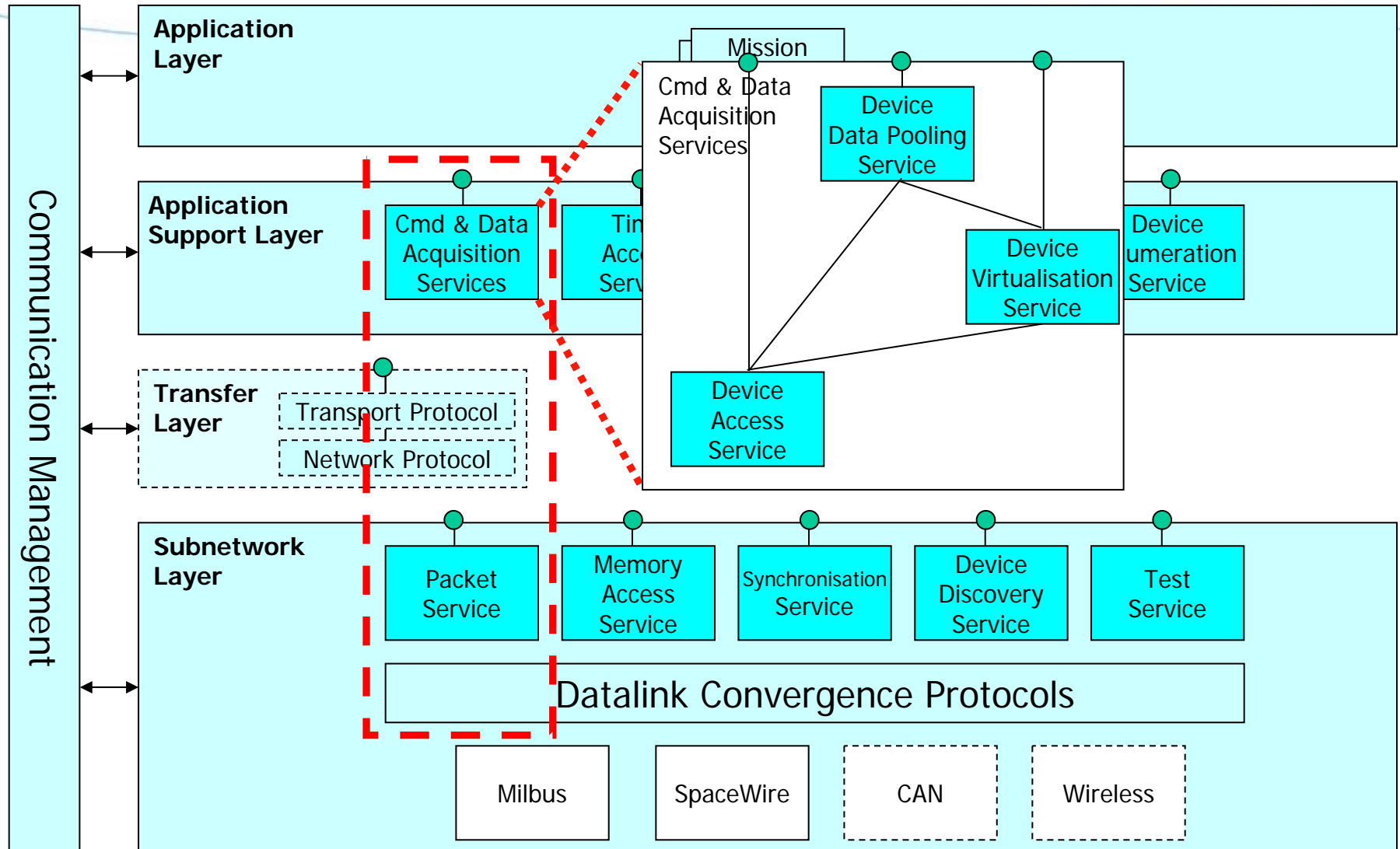
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Overview

- › Location in SOIS Architecture
 - › SOIS Plug-and-Play
- › Current approach to accessing Sensors/Actuators
- › Device Virtualisation
 - › Concept: Interfaces, Protocols and Services
 - › Device Data Pooling
 - › Worked Example
- › Electronic Data Sheets
 - › Concept
 - › SOIS Plug-and-Play Architecture
 - › CCSDS Approach to Standardisation
 - › EDS Technologies
 - › EDS Structure
 - › Worked Example: Development Process with EDS
- › Interactions with SOIS-SAFI
- › Outlook

Location in SOIS Architecture



SOIS Plug-and-Play

- › SOIS taking a broad definition of plug-and-play, encompassing design-time activities as well as “run-time” activities
- › Goals
 - › **Interoperability** – Application and device portability through isolation of the two, permitting flexibility and innovation in both
 - › **Adaptivity** – Allow systems to adapt to change, probably more during the development process
 - › **Rapidity** – Shorter development times, assisting design, implementation, integration and testing
- › Use Cases
 - › **Rapid Spacecraft Development** – Development Tool Chain
 - › **Automated Integration & Test** – Adaptivity of EGSE
 - › **Dynamic Fault Recovery** – Reconfiguration aspects of FDIR
 - › **Dynamic Device Migration** – human and robotic missions
- › Not talking about subnetwork device discovery today...

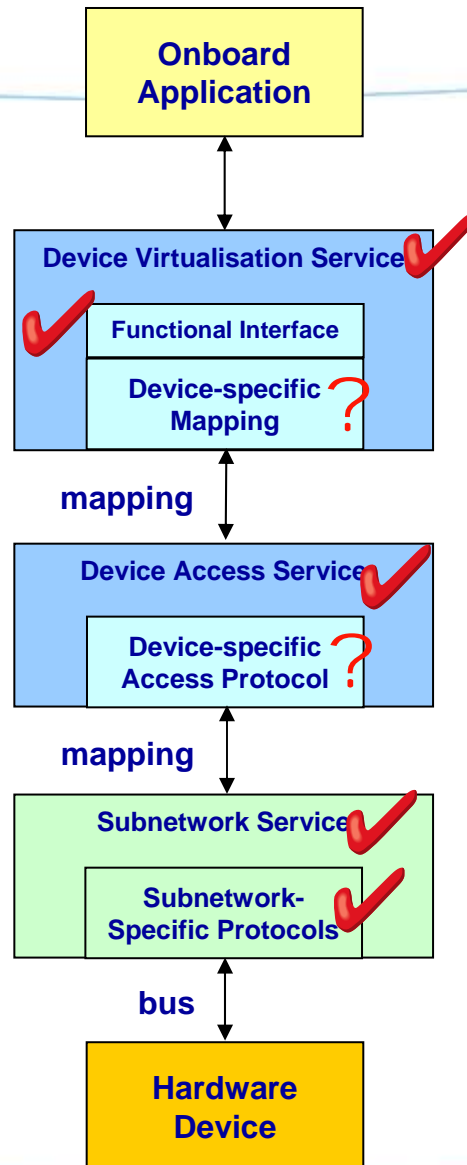
Current Approach to accessing to Sensors/Actuators

- › Information for accessing AOCS devices currently provided in ICDs and Basic Software Device Drivers
 - › Paper document, not standardised form
- › What is the impact of how its delivered today?
 - › Little is standard
 - › Not all information provided
 - › Discrepancies between ICD and actual reality?
 - › Difficult to check for discrepancies
- › How much device-specific functionality is built into applications?
 - › Device Drivers, Equipment Management software function
 - › How much changes between missions?
 - › Affecting devices, applications, device drivers etc
- › Recognised by Primes as a problem
 - › E.g. Astrium looking to use spacecraft databases as a start to auto-coding configuration of system
 - › Not standardised across industry
- › SAVOIR-SAIF addressing electrical interface but doesn't cover functional interfaces
- › How are SOIS proposing to solve it?
 - › **Device Virtualisation and Electronic Data Sheets**

Device Virtualisation – Concept

- › What is Device Virtualisation?
 - › Applications interface with devices at a **Functional Interface**
 - › Mapped onto access protocols
 - › Not directly using protocols or device representation of commands and data values
 - › Aim is for single **standard Functional Interface per device type**
- › What does Device Virtualisation do for you?
 - › Swappable devices = reuseable applications
 - › Standard access protocols = reuseable devices
- › BUT only works if Functional Interface isolates Applications from device-specific characteristics
 - › What if the differing characteristics of the different devices affect the algorithms of the applications?
 - › Can they be input parameters to configure e.g. control loop?
 - › Can't substitute for system engineering

Interfaces, Protocols and Services

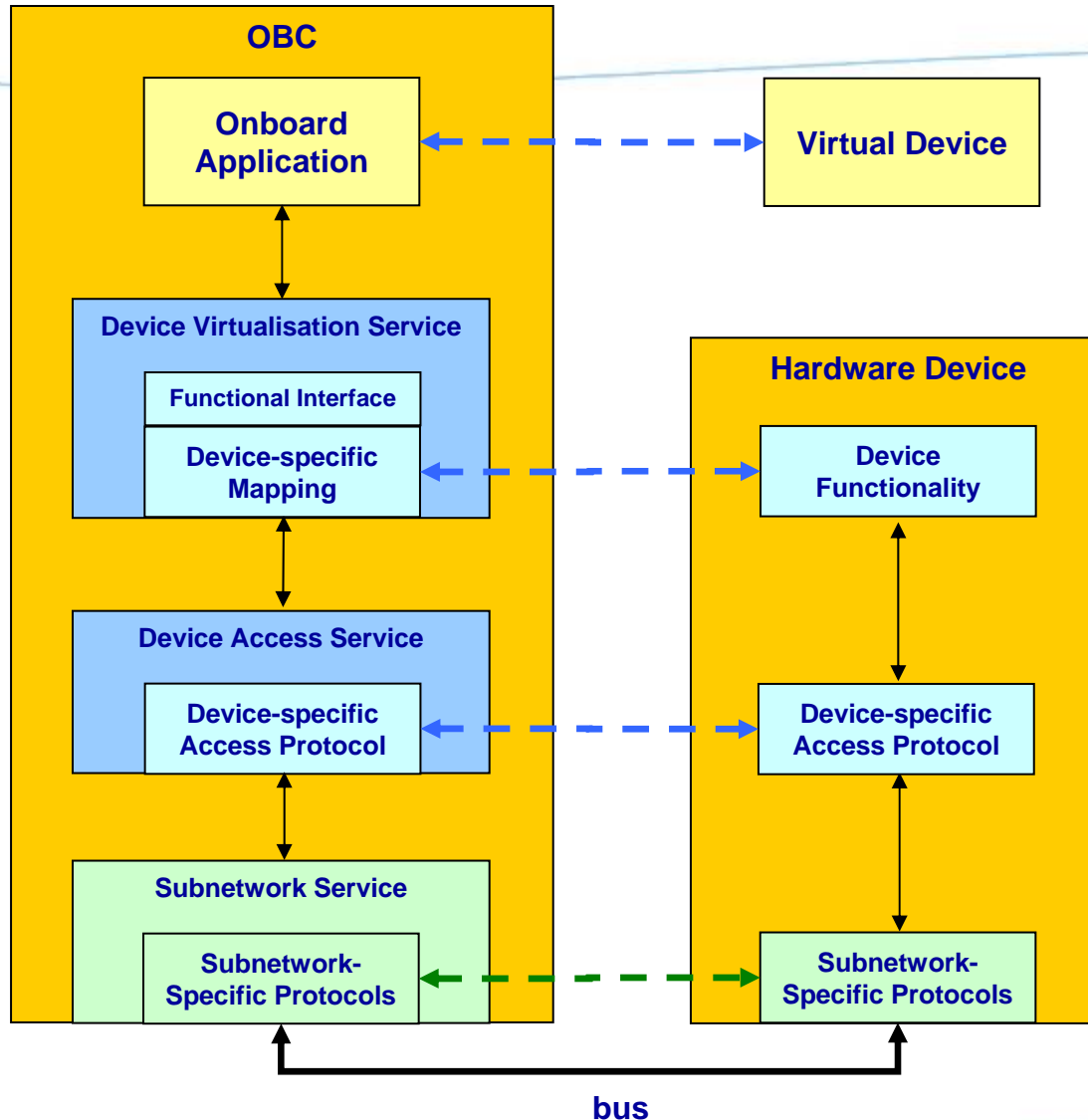


- > Subnetwork-specific protocol
 - > How to transfer data to/from device across subnetwork
 - > QoS: ack, retransmit, priority etc
- > Device-specific Access Protocol
 - > How to command and acquire raw data for specific devices using subnetwork-specific protocols
 - > State machine
- > Device-specific Mapping
 - > How the functional interface is mapped onto the device-specific access protocols
 - > Type conversions, operations, state-machine
- > SOIS Services
- > Standardisation:
 - > Trade-off what/where to standardise?
- > Virtualisation adds some overhead
 - > DAS can be directly accessed at a cost of tying application to particular device
 - > If devices move towards directly supporting the functional interface, the mapping becomes NULL

Device Data Pooling

- › SOIS Device Data Pooling Service maintains an image of the states of a number of devices' values
- › User applications access state of a device's value in data pool without having to generate explicit data acquisition request to actual device
 - › History of samples maintained together with QoS associated with each sample
- › DDPS periodically acquires data from devices at determined sampling rate or caches data from devices that asynchronously generate samples
 - › Samples either raw (DAS) or functional interface (DVS)
- › Avoids repetition of multiple users performing same acquisitions on devices
- › Provides a synchronisation point for multiple acquisitions e.g. synchronised to underlying subnetwork using the SOIS Subnetwork Synchronisation Service
- › What it doesn't provide
 - › Software parameter data pool
 - › PUS HKTM parameter packets

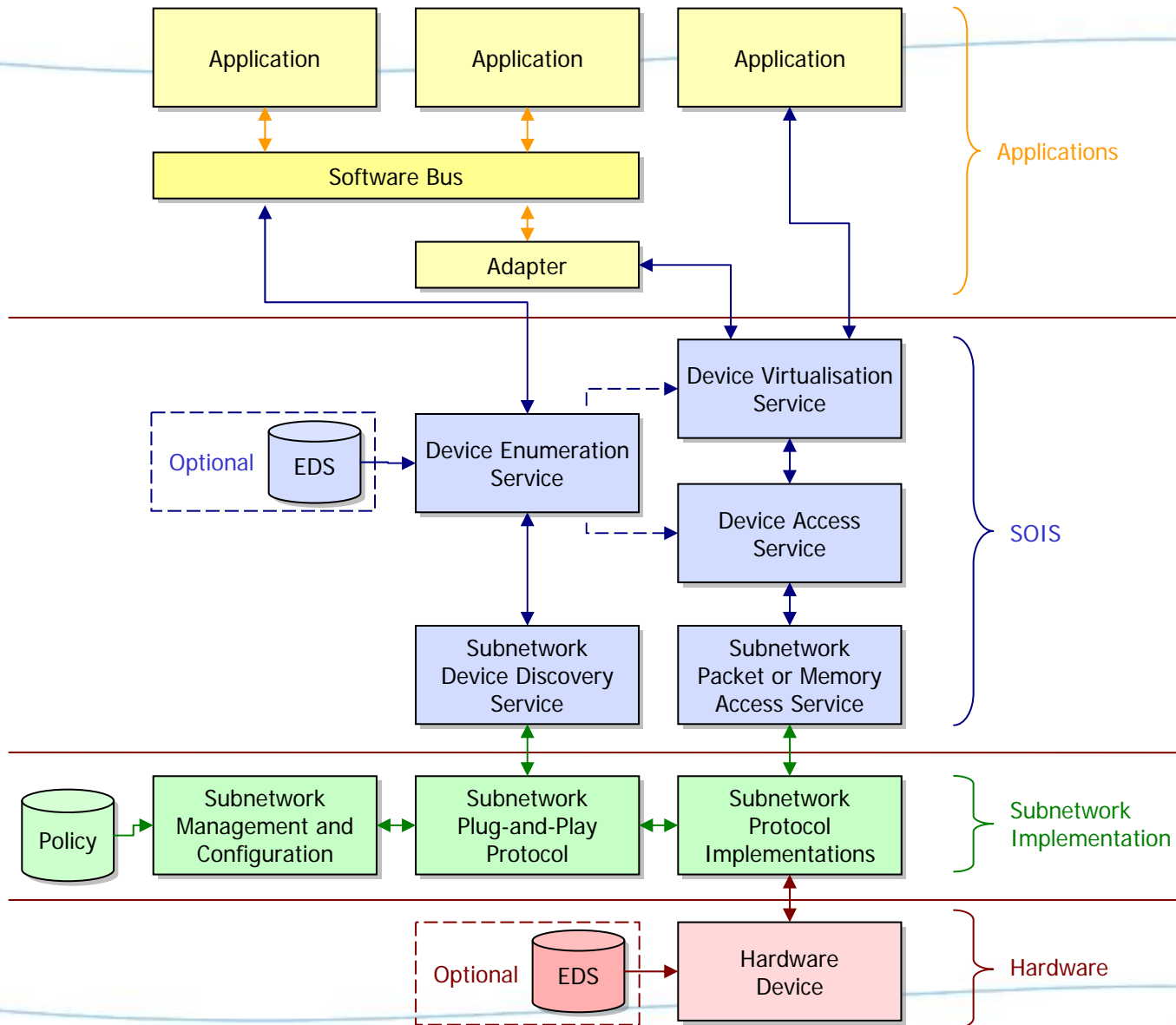
Worked Example: Accessing a Virtualised Device



Electronic Data Sheets

- › What are Electronic Data Sheets (EDS)?
 - › Electronic specification of information normally found in ICDs
 - › But also covers generic Functional Interface
- › Doesn't have to be used but provides:
 - › Uniformity of information
 - › Inputs for tools:
 - › Automatic coding/configuration of device drivers (SOIS)
 - › Simulation of devices
 - › Test tool for devices
 - › Automatic import into Spacecraft database
 - › Etc
 - › Online dynamic discovery of device capabilities – yeah, right! 😊
 - › Enabler for standardisation of functional interfaces across device types
- › What does EDS do for you?
 - › System Engineer
 - › Define requirements on interfaces
 - › Allows conformance testing of devices to ensure they meet interfaces
 - › Configuration support during integration of spacecraft
 - › Application Developer
 - › Allows conversion of functional interface into API, software model, etc
 - › Automatic generation of device driver
 - › Device Manufacturer
 - › Drives testing of device interface
 - › Avoids discrepancies between ICD and device, ICD and device driver

SOIS Plug-and-Play Architecture



CCSDS Approach

- › CCSDS SOIS Area
 - › ESA, NASA, UKSA & associates
- › Looking to standardise EDS
 - › EDS format standard
 - › Extensible Dictionary of Terms standard
 - › Template EDSs covering Functional Interfaces for device types (open issue)
 - › Not a straightforward thing to do!
- › What needs to be in an EDS?
 - › Understand what we are defining
 - › Structure, elements and referencing
 - › Types, interfaces and state machines
 - › Taking inputs from AIAA/AFRL SPA and SAVOIR-SAFI
- › Currently
 - › Defining use cases, deriving requirements
 - › Evaluating existing EDS technologies
 - › IEEE 1451 TEDS
 - › AIAA/AFRL SPA xTEDS
 - › CANopen
 - › OMG/CCSDS XTCE
 - › Establishing EDS structure & roadmap for prototyping/adopting technologies

EDS Technologies (1/2)

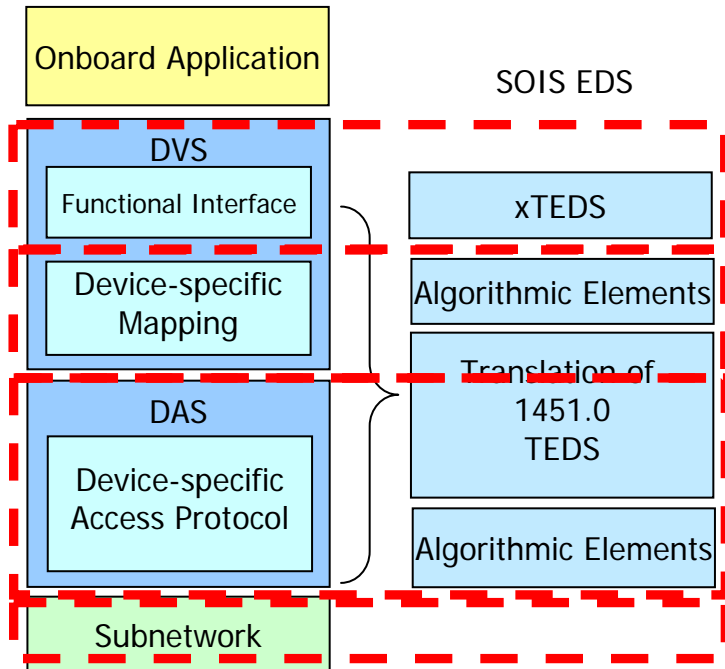
- › IEEE 1451 TEDS
 - › Suite of standards which defines access to “smart transducers”
 - › Each transducer connected to intermediate Transducer Interface Module (TIM) that acts as its representative to rest of the system
 - › Complete TIM interface to a transducer defined by 1451.0 base specification TEDS and 1451.X network technology-specific TEDS
 - › TEDS have variety of formats, inc. text, binary and (subset in) XML
 - › Widely used in other domains, candidate for “spin-in”

- › AIAA/AFRL SPA xTEDS
 - › Space Plug-and-Play Architecture (SPA) over-arching architecture for s/c and components for rapid assembly and integration, from AFRL for Operationally Responsive Space programme
 - › Published in draft form by AIAA, covering architecture, electrical, coms and mechanical specs
 - › Comms in SPA is message passing, with network-connected intelligent devices communicating in identical manner to software applications
 - › Applications and devices communicate at same level & are effectively interchangeable
 - › Message exchanges follow number of pre-defined patterns and transported over network by predefined protocols
 - › Valid messages defined in an EDS that comes with product (software or device), may be stored with device or in central database of spacecraft
 - › Common Data Dictionary defined semantic terms
 - › Publish-subscribe
 - › EDS inspired by IEEE 1451 TEDS and in XML format (xML) TEDS => xTEDS

EDS Technologies (2/2)

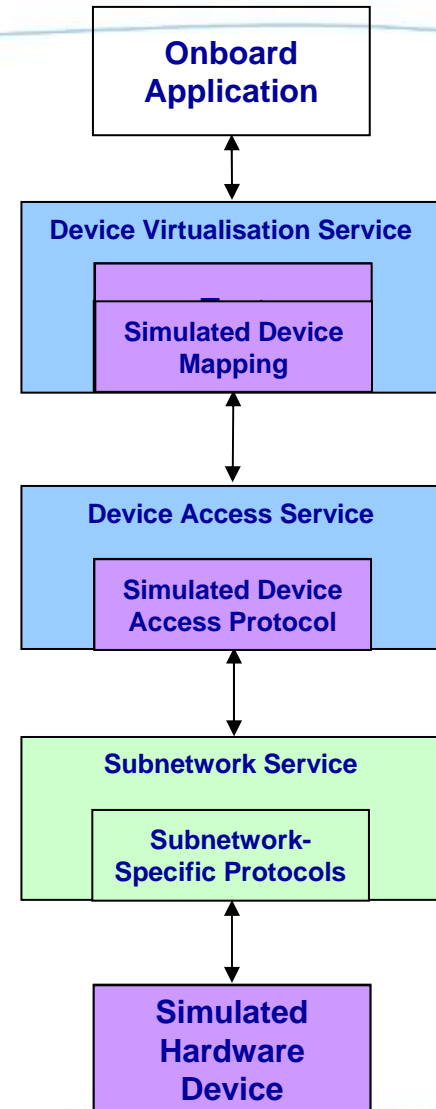
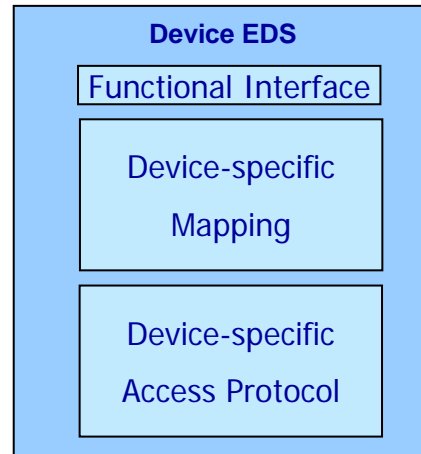
- › CANopen
 - › Provides functionality equivalent to network & above OSI layers through basic CAN message
 - › 8 data bytes + 11-bit identifier
 - › Protocols of CANopen use identifier for device & function identifier
 - › Service Data Object (SDO) protocol transfer of data objects between nodes through get/set iof objects in remote object dictionary in a client/server model
 - › Process Data Object (PDO) protocol broadcast of data objects, mapped to object dictionary entries
 - › Object Dictionary core to CANopen
 - › Each entry has index, symbolic object name, descriptive name, data type, access rights and mandatory/optional flag
 - › Basic and composite data types
 - › Device Object Dictionary
 - › Conform to base specification of CANopen
 - › Device Profiles (fuller object dictionaries) specified for device types
 - › Device conforms to one or more device profiles
 - › Object Dictionary defined as an EDS, originally in text and now in XML (XDD)
- › OMG/CCSDS XTCE
 - › XML Telemetric and Command Exchange (XTCE) defines communications data format and protocol in XML
 - › Aimed at allowing information for monitoring & control of spacecraft to be defined in XTCE file
 - › Includes:
 - › variable packet formats, with elements conditional on packet contents
 - › Simple processing/conversion algorithms or referencing external algorithm implementations
 - › Not strictly a datasheet technology but has many interesting characteristics

EDS Structure



- › EDS elements mapping to DVS and DAS data
 - › Candidate technologies
 - › Functional Interface
 - › Device-specific Mapping
 - › Device-specific Access Protocol
- › Who provides/uses what?
 - › System Engineer
 - › Application Developer
 - › Device Manufacturer
 - › Device Driver Developer (no longer exists?)

Worked Example: Development Process with EDS



1. System Specification
 1. Application, Bus and Device Functional Specification
 2. SOIS, Device Virtualisation and EDS Technology Selection
 3. Device Functional Interface Selection
2. Component Development:
 - i. Device development & testing against EDS
 - ii. Application development & testing against Functional Interface
3. Progressive integration:
 - i. Auto-generation of device drivers & integration with device
 - ii. Integration with application
4. Run-time

Interactions with SAVOIR-SAFI

- › ETSI SSDHI original attempt to define generic functional interface
 - › Inspired by SOIS
- › SOIS provides Framework
 - › Specification of Functional Interface and mapping onto Device-specific Access Protocol for each device
 - › Can be captured in an EDS
- › SAVOIR-SAFI
 - › Define **generic** Functional Interface for device types
 - › Sensors: Start tracker, Gyro, Sun sensor
 - › Actuators: Reaction wheel, Magneto torquer
 - › Check mapping to generic Functional Interface to specific devices' Device-specific Access Protocols
- › Allowing SOIS to provide
 - › Specification of template EDS for device types

Outlook

- › Standard Electronic Data Sheets
 - › Need to consolidate structure and candidate technologies
 - › Prototyping leading to drafting of standard (2013?)
- › Standard Functional Interface for device types
 - › SAVOIR-SAFI output (2012?)
 - › Associated SOIS EDS per device class (2013?)