



Model-Based Avionics Verification & Validation

ESA Workshop on Avionics Data, Control and Software Systems (ADCSS)

ESTEC, Noordwijk, The Netherlands,

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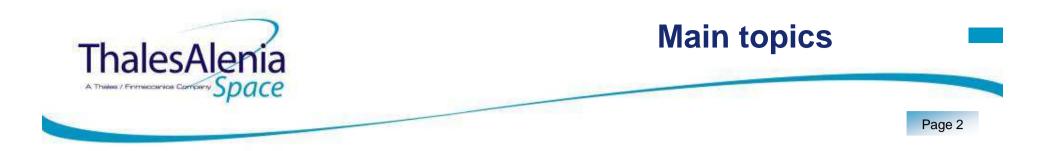
H. Bratulic, F. Maingam presented by Jean-Luc Petit (Head of Data Handling TL section) THALES ALENIA SPACE Cannes



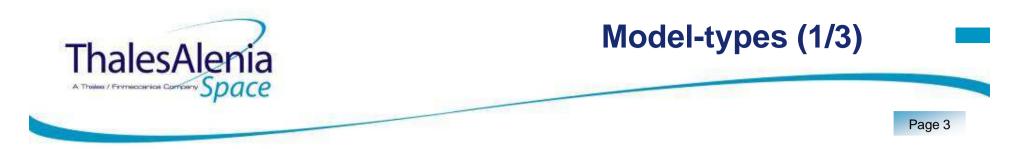
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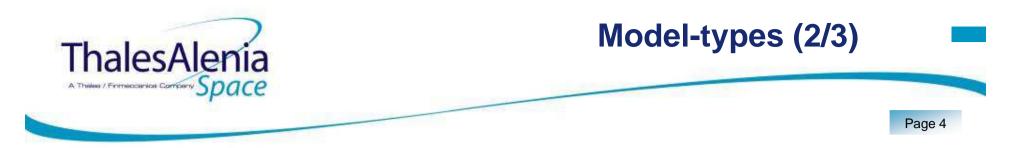
- What Model-types are involved in the avionics verification and validation process ?
- What is the impact on validation plans induced by introduction of models ? Traceability of different models and their relationship throughout the verification process ?
- Which system properties (data) are required for models, all along the avionics V&V process ?
- How are the models validated with respect to their domain of applicability, and maintained throughout the avionics lifecycle?



Several perimeters / levels are involved in Avionics Validation :

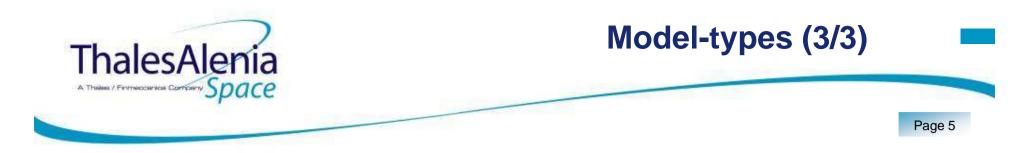
- Functional Chains (ADCS, EPS, DHS, Thermal)
 - FC performance assessment
 - Equipment unit characterization & gualification
 - FC performance and robustness verification
- On Board SoftWare Verification & Validation
 - **OBSW** verification
 - **HW/SW** integration
 - Focus on Processor module & mains interfaces (TM/TC, I/O, mass memories, buses, ...) of the On Board Computer
 - OBSW performance and robustness verification
- **Avionics Verification & Validation**
 - Functional Chains & global system test
 - Tests performed with both "real" equipment units and simulated models
 - ➔ Avionics Test Bench (ATB).





Model-type used vs perimeter :

- At Functional Chain level :
 - HW Engineering Models (EM) : Equipment characterization → calibration of simulated model
 - For example StarTracker (proton sensitivity), Sun Sensor on 3axis table, OBC running Test Application SW...
 - Equipment simulation Functional Models
 - Function modelling
 - Model must be representative of the equipment performances
 - Environment models
 - Physical behaviour of the spatial environment
 - Dynamic model
 - Physical behaviour of S/C
- At OBSW V&V level :
 - HW Engineering Models (EM or BB) to support HW/SW integration
 - OBC simulation operational model
 - High representativeness of OBC behaviour, timing, mapping & addressing is required
 - Need of processor emulator (at instructions level)



Model-type used vs perimeter :

- At Avionics V&V level :
 - HW Engineering Models (EM)
 - Essentially complex units (OBC, StarTracker, GPS, Gyro, PCDU, RIU/PLIU, ...)
 - Unit models (for all avionics equipment units having I/F with OBC) :
 - **Operational Models (Cmd/Ctrl)**
 - System Interface Model (I/O interfaces)
 - **Functional Models (Operational mains functions)**
 - **Environment models**
 - Physical behaviour of the spatial environment
 - Dynamic model
 - **Multiple Bodies link with poly-articulate links**





The benefits of the introduction of models :

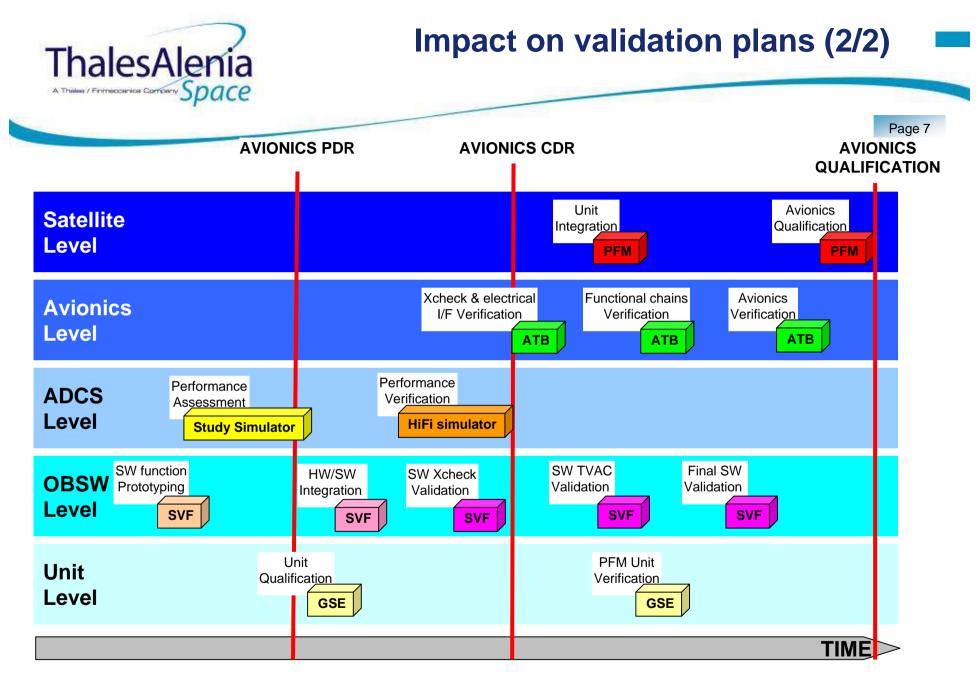
- Verifying system feasibility and performance,
- Allowing design trades during system design,
- Early demonstration and testing before hardware is available,
- Avoidance / optimization of building hardware prototypes / models,
- System Verification and Training.

These benefits allow :

- To spread V&V activities on an incremental development approach,
- To parallelize V&V activities, getting rid of the need of HW models.
 - Planning optimization
 - Cost optimization
- To increase the efficiency of the V&V activities, using means best fitted to the test objectives.



Page 6



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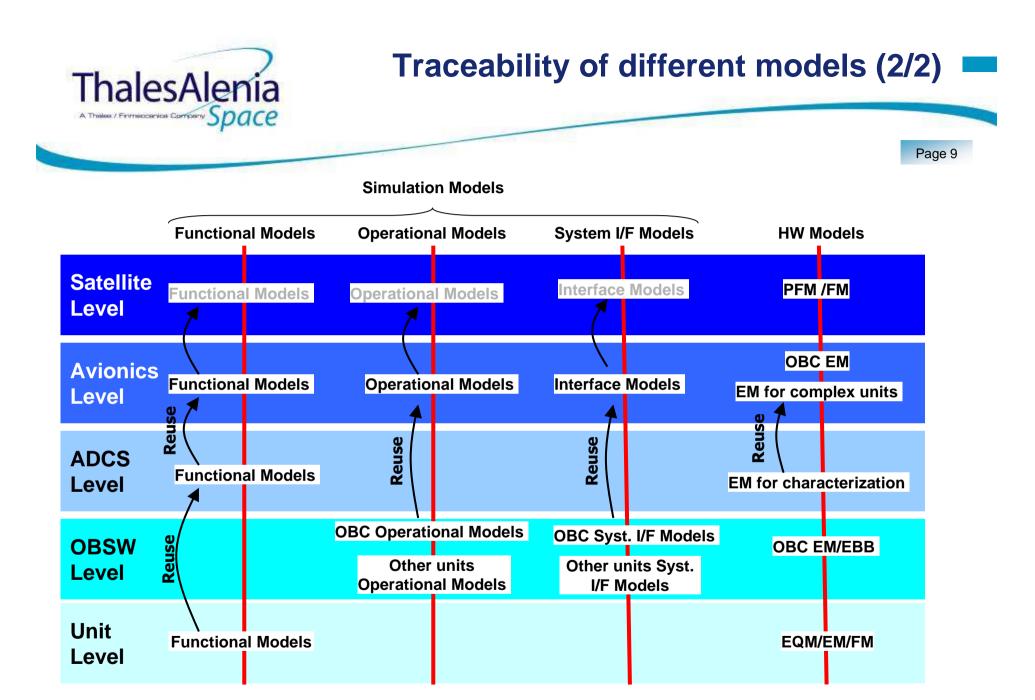


Models code & simulators are configured

- Their limitations are listed
- Their traceability is ensured
 - Evolutions
 - Corrections

Industrialisation of the simulator assembly insure the simulator composition vs model versions





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Model level :

- Eunctional Models :
 - Physical data (Mass, Center of Mass, inertia, Position, Orientation, ...)
 - Performance features (Bias, Noise, Delay, ...)
 - Specific data (star catalog, calibration data, ...)
- Operational Models :
 - Equipment : User Manual, State Machine, TM/TC, Transfer functions, ...
 - OBC : memory mapping,
- System Interface Models
 - Interface features : Bus Address, data rate, Electrical ICD...

Simulator level :

- S/C Harness (Pin allocation)
 - To integrate the simulator assembly
- Model instances
 - For example nominal and redundant unit
- Model scheduling table
 - Define order and frequency for scheduling





Two cases are considered :

- 1. Models provided by equipment manufacturer :
 - Validation of simulation model is performed by the provider
- 2. Models developed by Prime :
 - **SW** model verification / validation against SRS/RB documents
 - Functional Unit tests
 - Integration / validation tests
 - X-Validation against results obtained on real unit
 - OBC : Calibration of the OBC simulation model is performed in parallel of the OBSW development (HDSW development and HW/SW integration).
 - Other complex unit : Reference results are obtained during
 - ATB integration/validation
 - Equipment characterization tests
 - X-Check and Avionics tests
 - Dynamics & Environment : Reference results from previously validated simulators (by agency)