

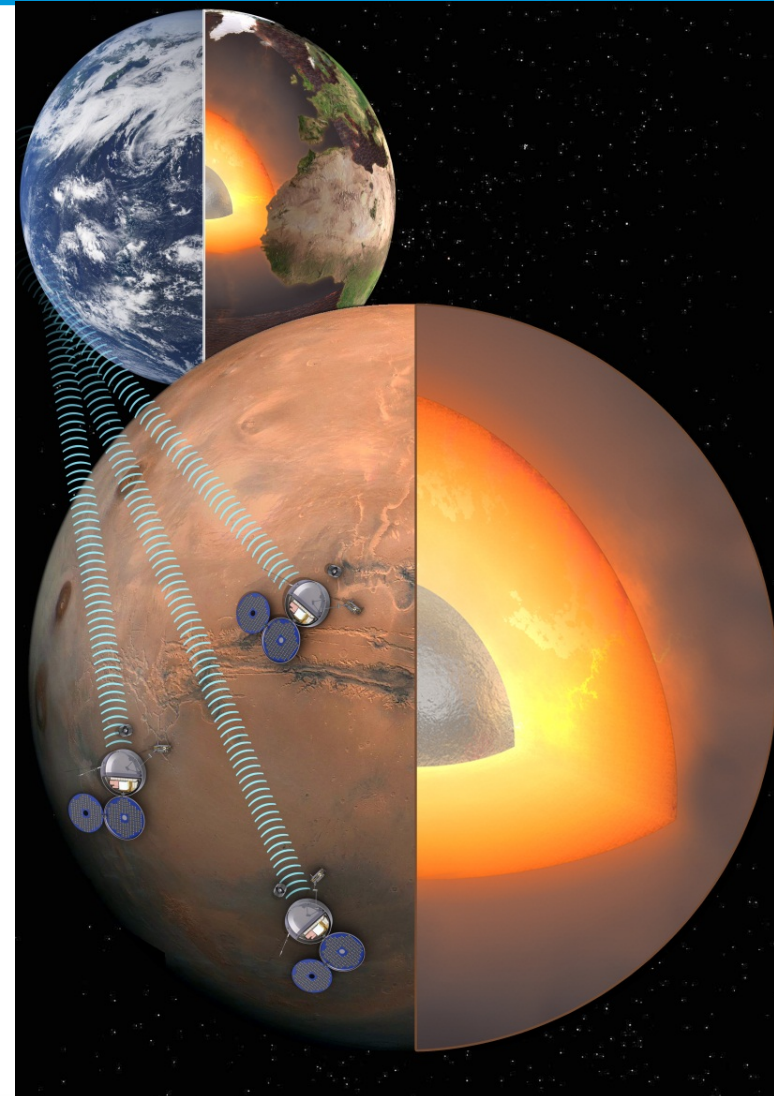
Miniaturisation needs of the Mars Network Landers

INSPIRE mission

Kelly Geelen
Study Manager

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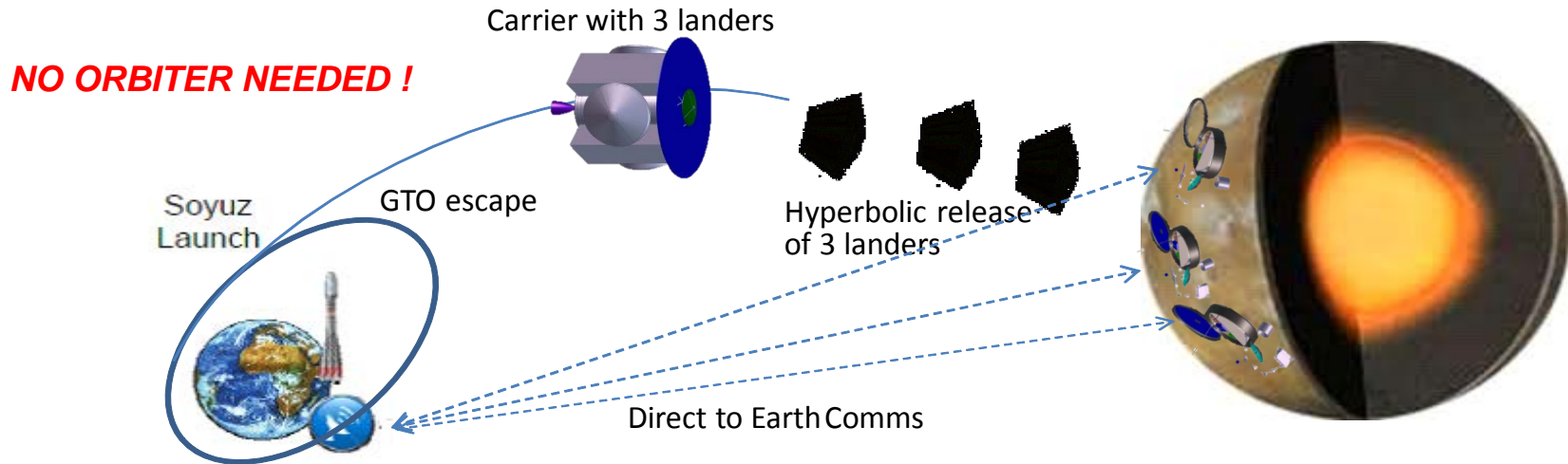
- ◆ **Background**
- ◆ **Mission Overview**
- ◆ **Need for Miniaturisation**
- ◆ **Current activities in MREP**
- ◆ **Potential future development**
- ◆ **Conclusions**

◆ Mars Network Science mission proposed within the MREP program

◆ Mars Robotic Exploration Programme (MREP/MREP-2):

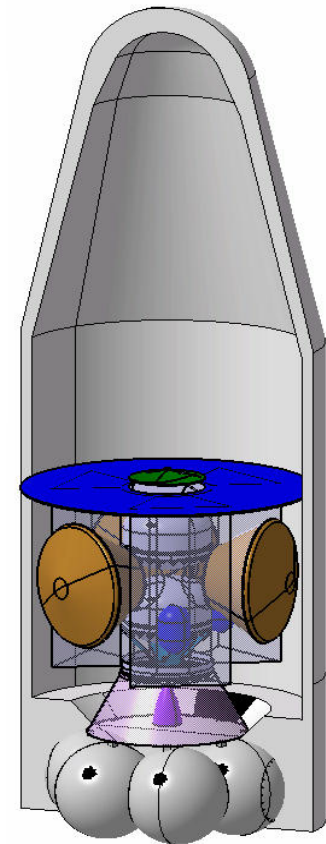
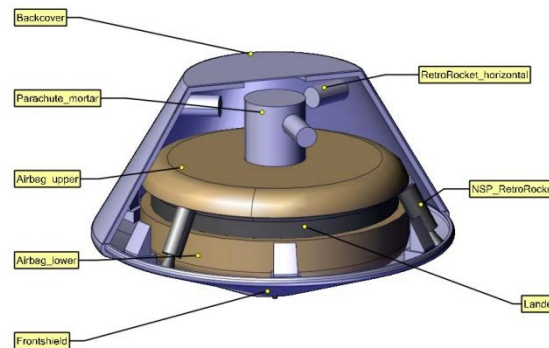
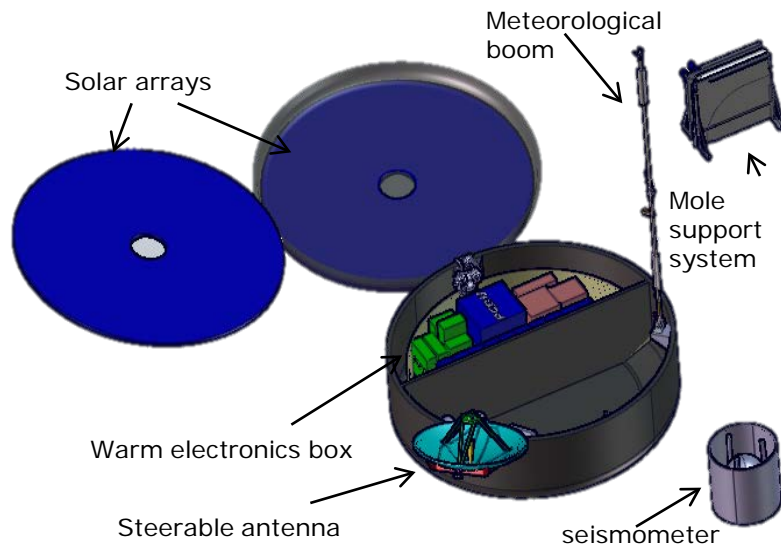
- Mars Sample Return mission is taken as long term objective
- Target is to contribute to each Mars mission slot (every ~2 years)
- Prepare post-ExoMars missions and enable decisions at next C-Min (2012)
- **Mission Studies:** 2 candidate missions for Launch from 2022 onwards for MREP-2
 - Phobos Sample Return Mission – PHOOTPRINT
 - Mars Network Science Mission - INSPIRE
- **Technology Development**
 - Short term & Mid Term: For 2022 or 2024 proposed missions
 - MSR critical Technologies
 - Long term: strategic and enabling technologies for European Robotic Exploration

Mission Overview: INSPIRE



- ◆ **Soyuz Fregat** launch from Kourou into GTO (3180 kg spacecraft composite incl adapter).
- ◆ 7-12 months transfer with carrier spacecraft providing 1.4-1.7 km/s delta-v.
- ◆ Carrier releases in sequence **3 network landers** up to 12 days before Mars arrival.
- ◆ Carrier break up and burn up in the Martian atmosphere (Planetary Protection compliant).
- ◆ Each lander performs ballistic **entry, descent and airbag landing**.
- ◆ Surface platform of ~120 kg deployed on the Martian surface with Direct to Earth comms.
- ◆ Deployment of instrumentation, some using a **robotic arm**.
- ◆ **Long duration operations** (goal >1 full Martian year) on the Martian surface to investigate the interior of the planet.

The mission elements



Spacecraft Composite in Soyuz

- ◆ Most avionics located in Warm Electronics Box protected with several cm of insulation
- ◆ Lander avionics used for entry, descent and landing as well as surface operations
- ◆ The probe has an instrumentation/payload mass of 5% or the entry mass.

◆ Accommodating 3 Mars landers on a Soyuz launch requires avionics with low mass

✧ Large **direct snowball effect on mass**

- 1 kg on surface per lander
 - → additional 1.5 kg needed for safe landing (2.5 kg penalty per probe)
 - → x 3 probes (7.5 kg penalty)
 - → + increase in carrier structure and propellant for GTO transfer of factor 2
 - → 1 kg saved per lander (3 kg landed mass) reduces launch mass by 15 kg!
- ✧ Remember: Per lander the payload mass fraction is only 5%, so every kg of avionics could be replaced by payload once launch mass margin is met
- ✧ Volume & power have additional indirect impact on launch mass

◆ Accommodating 3 Mars landers on a Soyuz launch requires avionics with low volume and power

✧ Volume

- Direct impact: driver to limit lander size to fit within launch fairing
- Indirect: Avionics volume increase → increase in surface platform size → increase in aeroshell size → large mass penalty
- Indirect: Avionics volume increase → increase in warm electronics box volume → increase in thermal power requirement → increase in power system volume and mass

✧ Power

- Avionics power reduction, translates to smaller and lighter power system → launch mass impact

◆ For long duration surface missions, there is also a benefit to have low power /hibernation modes and low temperature survivability

◆ The MREP Technology development plan :

- ✧ Can be found on: <http://sci.esa.int/science-e/www/object/index.cfm?fobjectid=47729>
- ✧ Reviewed as a minimum once a year according to mission needs

◆ Current activities for miniaturised or compact avionics:

- ✧ Compact dual UHF/X band Communication Package study
- ✧ Tailored OBC EM for planetary landers

◆ Developments needed in coming years

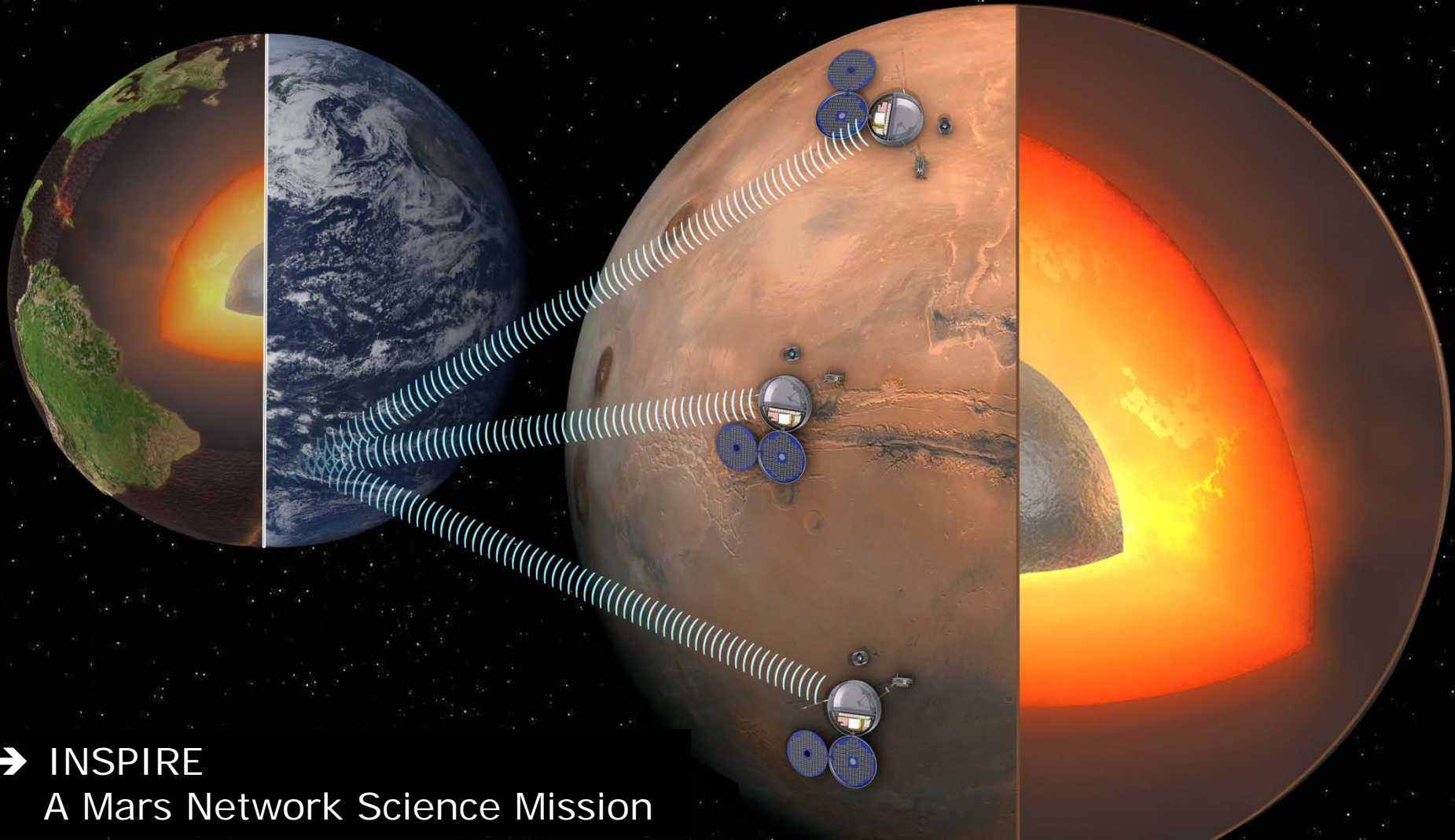
- ✧ Miniaturised PCPU for Mars landers/rovers
- ✧ Miniaturised Dual UHF X band EM development
- ✧ Miniaturised gyros and accelerometers (IMU), altimeter

- ◆ **Exploration missions in general have large mass snowball effects and tight volume constraints, due to the large amount of propellant required and entry, descent and landing system for planetary landers**

- ◆ **Miniaturising avionics is essential!**
 - ✧ Can enable missions (meet launch margins)
 - And/or
 - ✧ Increase science return by increasing the payload mass.

- ◆ **Miniaturised avionics identified as enabling building blocks within MREP-2 Technology Development Plan**

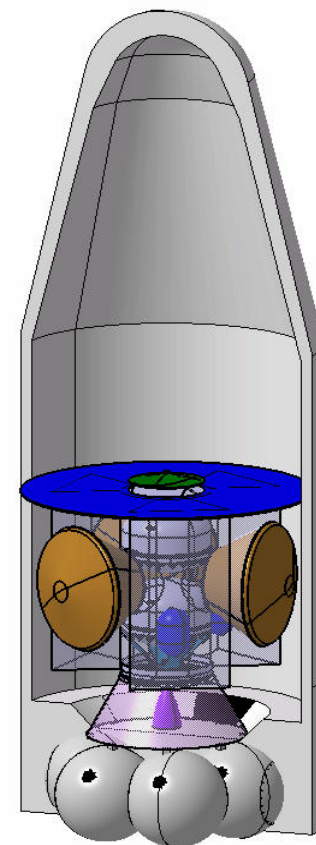
Questions ?



➔ **INSPIRE**
A Mars Network Science Mission

- ◆ “Smart” carrier design totally independent from the landers:
 - ✦ No subsystems shared with the landers
- ◆ Launch mass: dry 516 kg, wet 1915 kg

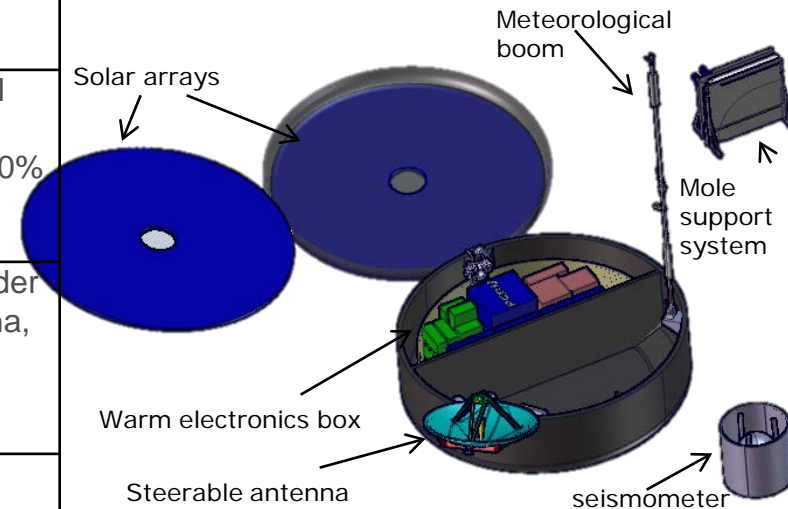
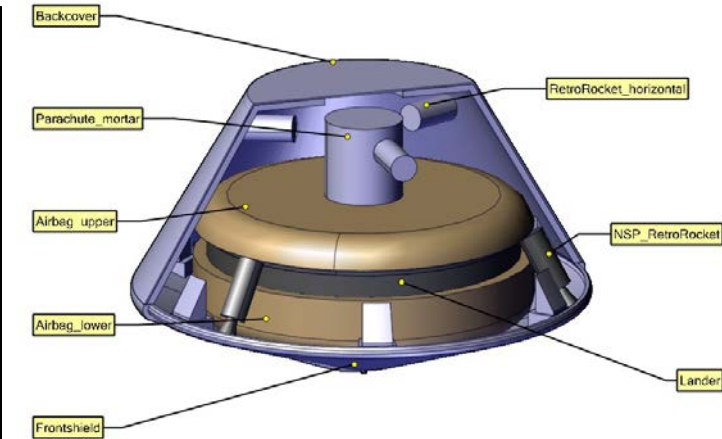
Configuration	<ul style="list-style-type: none"> • Standard interface of 937 mm diameter • Central cylinder accommodating tanks • Circular top panel to accommodate solar cells • 1m HGA integrated in top panel • 3 landers spaced by 120 degrees on side panels
Propulsion	<ul style="list-style-type: none"> • Bipropellant (Isp =322 s), 400 N main engine • Maximum 1400 kg of propellant in 2 large tanks
Thermal	<ul style="list-style-type: none"> • Standard passive thermal control design
Power	<ul style="list-style-type: none"> • Total area of 10.2 m² for the fixed solar panel • MPPT in an unregulated bus • Rechargeable Li-Ion battery
Communications	<ul style="list-style-type: none"> • X-band communications to ESA DSN • 1m fixed HGA • 65 W RF power • 8 kbps downlink @2.6 AU
AOCS	<ul style="list-style-type: none"> • 3-axis stabilised • 12 x 10N RCS thrusters • 2 star trackers, 2 IMU and sun sensors
Mechanisms	<ul style="list-style-type: none"> • 3 spin up and eject mechanisms for the landers



Spacecraft Composite in Soyuz

Surface Platform

Configuration	<ul style="list-style-type: none"> • 1.15 m diameter clamshell lander • Solar panel deployed from lander lid
Landing Site	<ul style="list-style-type: none"> • Latitude: -15 to +20 degrees • Altitude: < 0 km MOLA • Accuracy: ~100 km
Lifetime	<ul style="list-style-type: none"> • Goal >1 Martian year
Data Handling	<ul style="list-style-type: none"> • Based on “Tailored On-Board Computer for planetary landers” MREP development • ~5 Gbits of mass memory to store data during solar conjunctions
Thermal	<ul style="list-style-type: none"> • Warm electronics box (WEB) with aerogel insulation up to 10 cm • Potential use of RHU to enhance mission lifetime • Loop heat pipe connecting WEB to radiators
Power	<ul style="list-style-type: none"> • Solar array of ~2 m² sized for 550 Wh/sol at optical depth of 2 • 6.2 kg Li-ion battery sized to deliver 550 Wh with 60% DoD • Dust removal system to extend lifetime
Communications	<ul style="list-style-type: none"> • MREP development of dual UHF-X band transponder • X-band direct to Earth link, 40 cm steerable antenna, >1.4 kbps @2.6AU • Data relay capability compatible with any existing orbiter using proximity-1 protocol
Mechanisms	<ul style="list-style-type: none"> • Self-righting hinge • Robotic arm for instrument deployment



Entry, Descent and Landing

Coast Phase:

- ✧ From Carrier separation to entry

Entry:

- ✧ (1) Entry into Martian Atmosphere detected

Descent:

- ✧ (2) DGB Parachute opens at Mach 1.8
- ✧ (3) Front Shield is jettisoned
- ✧ (4) Lander with its Airbags system is lowered along a bridle from the Back Cover
- ✧ (5) Airbags are inflated
- ✧ (6) At predefined altitude, the retrorockets are ignited.
- ✧ (7) Bridle is cut ; the Back Cover is propelled away from the Lander;

Landing:

- ✧ (8) Lander free fall to the surface
- ✧ (9) Lander protected by its airbags bounces several times
- ✧ (10) Lander stops and comes to rest
- ✧ Airbags system is separated from the lander;

Clamshell lander is opened and surface operations begin

