

Final Presentation



Synthetic Generation of a NEO Population

**ESRIN,
November 18th, 2014**



Study Team



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Motivation

- NEOs could potentially hit our planet
- Depending on their size an impact can produce considerable damage.
- Impacts of large objects are rare, but probability increases with smaller sizes.



<https://tallbloke.wordpress.com/2013/03/05/andrew-cooper-were-the-recent-asteroid-flyby-and-russian-meteor-strike-events-linked/>



© Michael Farmer

Peru, 2007

- Currently about 11,600 NEOs are known
 - 460 NEOs are currently in the risk list
- ➔ About 4% of the known NEO environment

Overview

1. Introduction

2. The new synthetic NEO population model:

*The way the new NEO model was derived
and the current status or work*

3. **N**ear **E**arth **O**bject **P**opulation **O**bservation **P**rogram (NEOPOP):

*Although more included the focus will be
on the Observation Simulation*

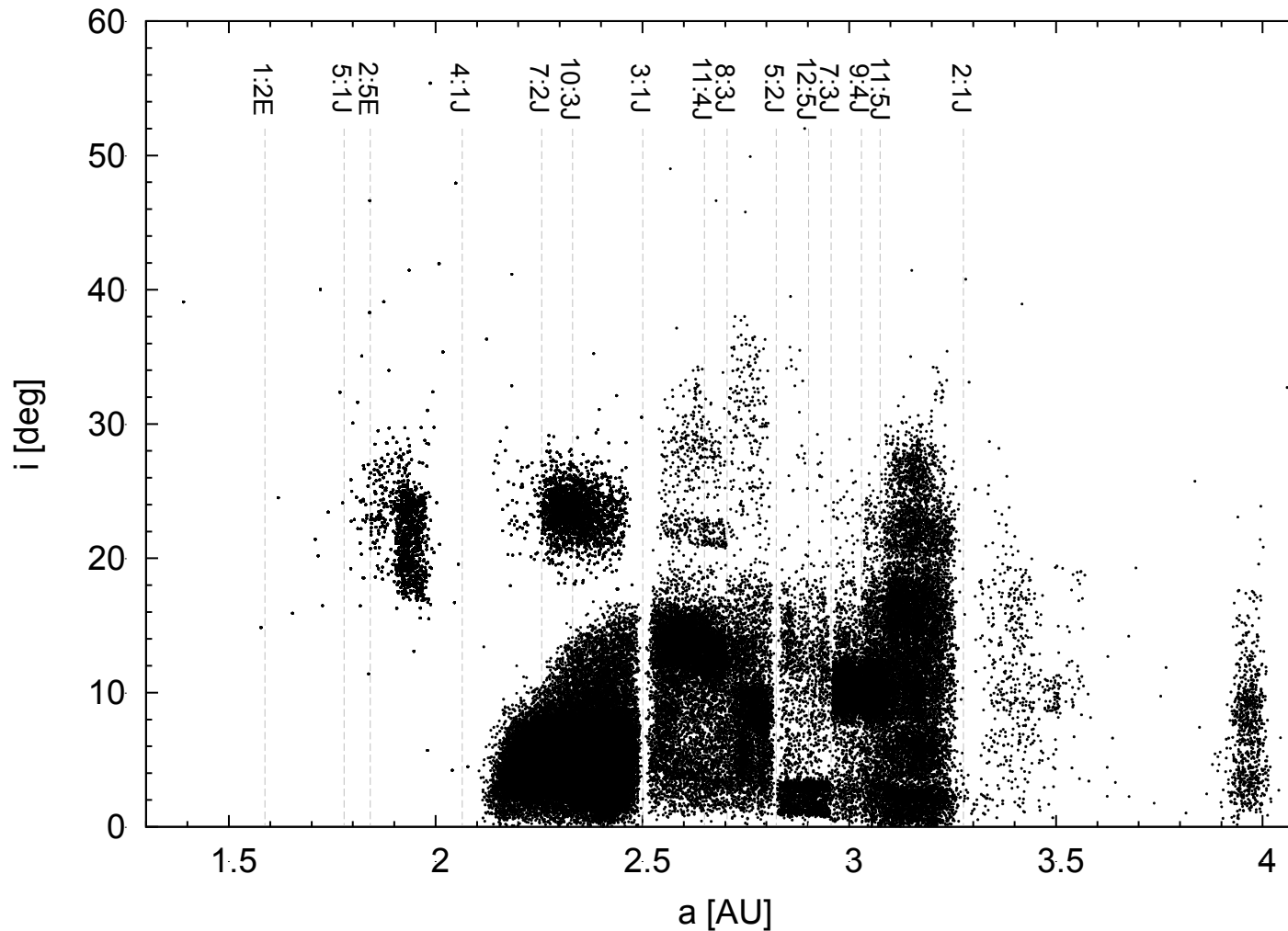
4. Demonstration of the two parts of NEOPOP:

*Population Generator
Observation Simulator*

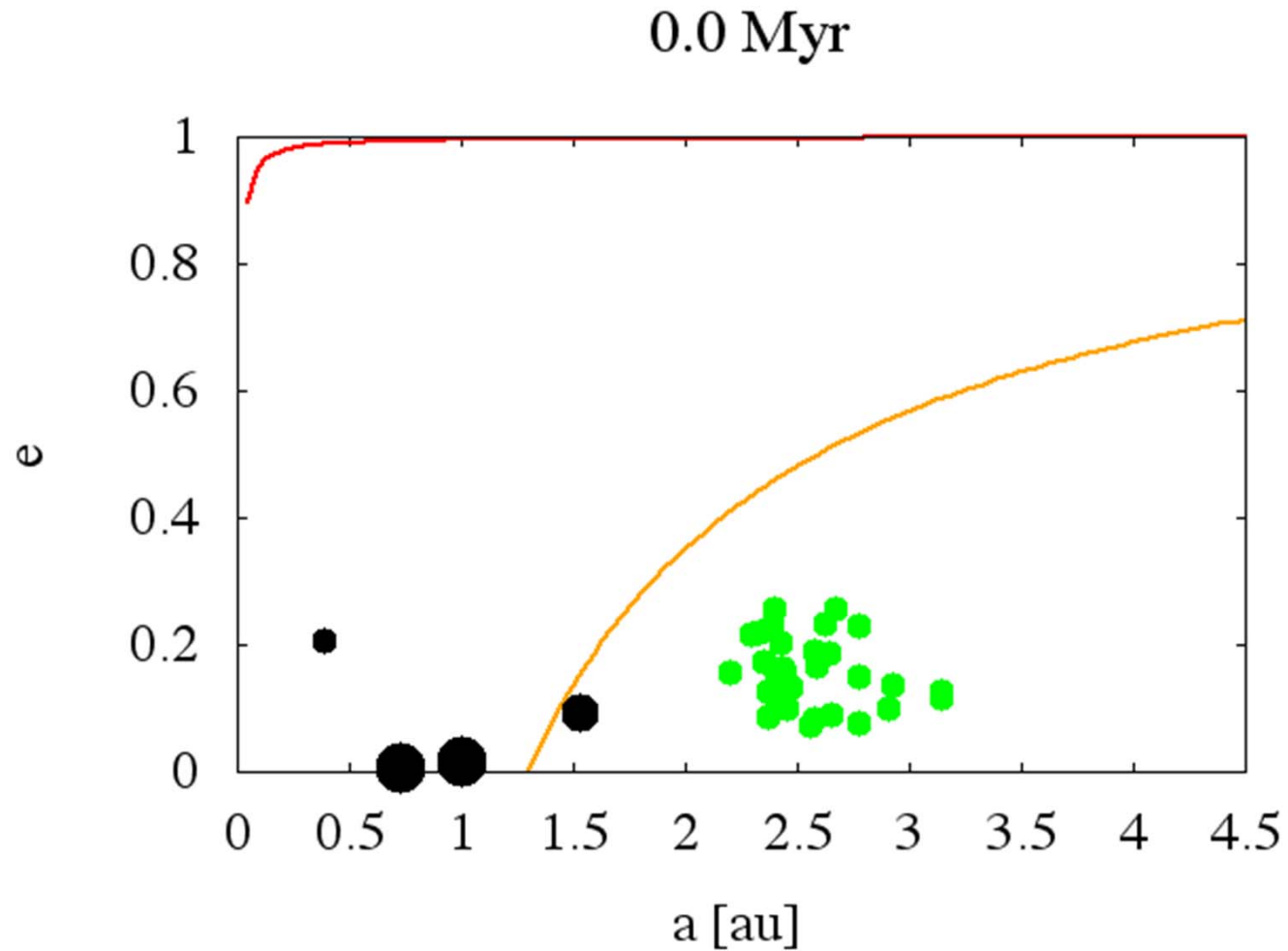
5. Conclusion & Discussion



NEOs come predominantly from the main asteroid belt: Initial conditions for residence integrations from known MBOs

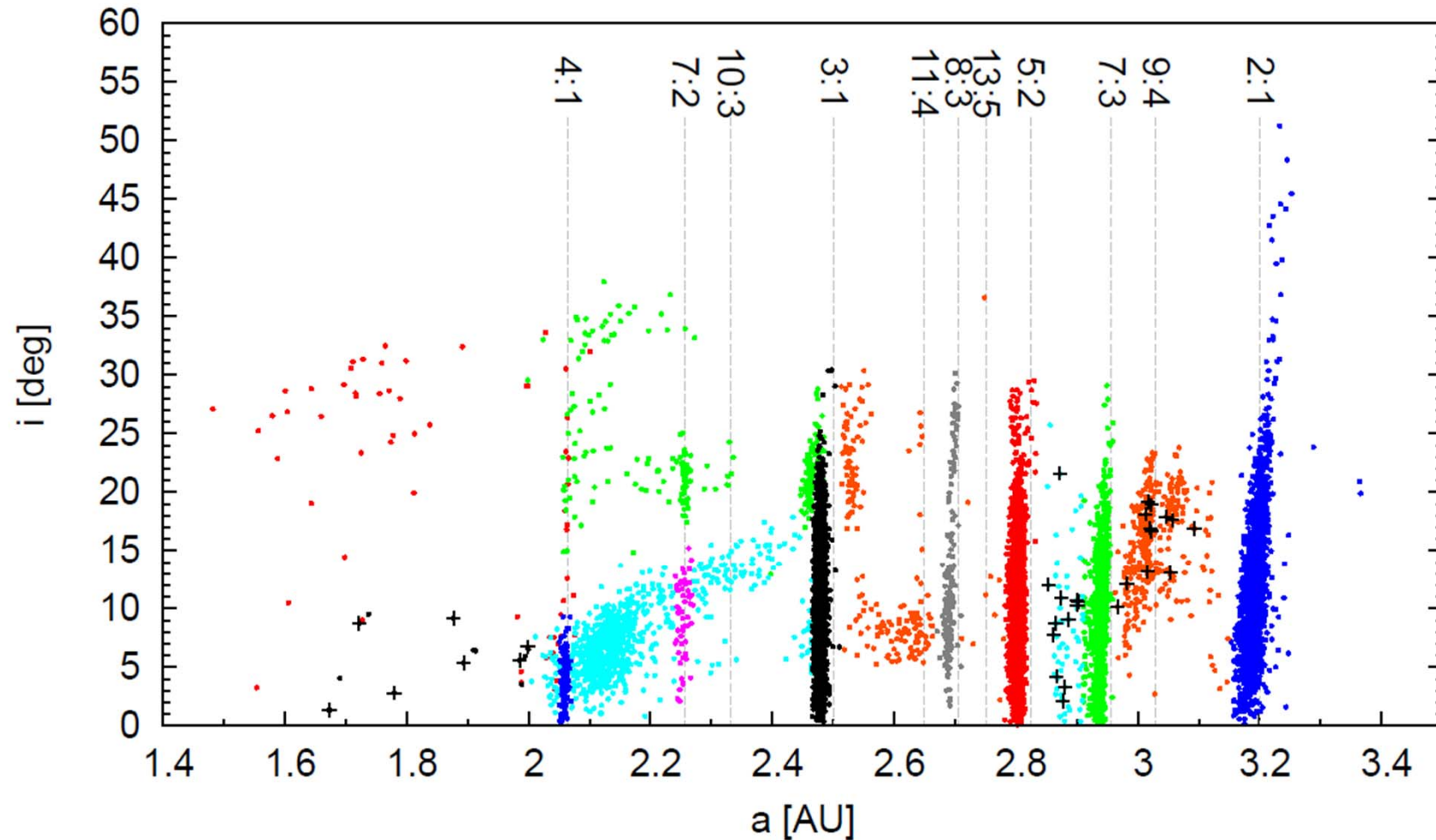


Escape routes from the main belt



The new NEO Model

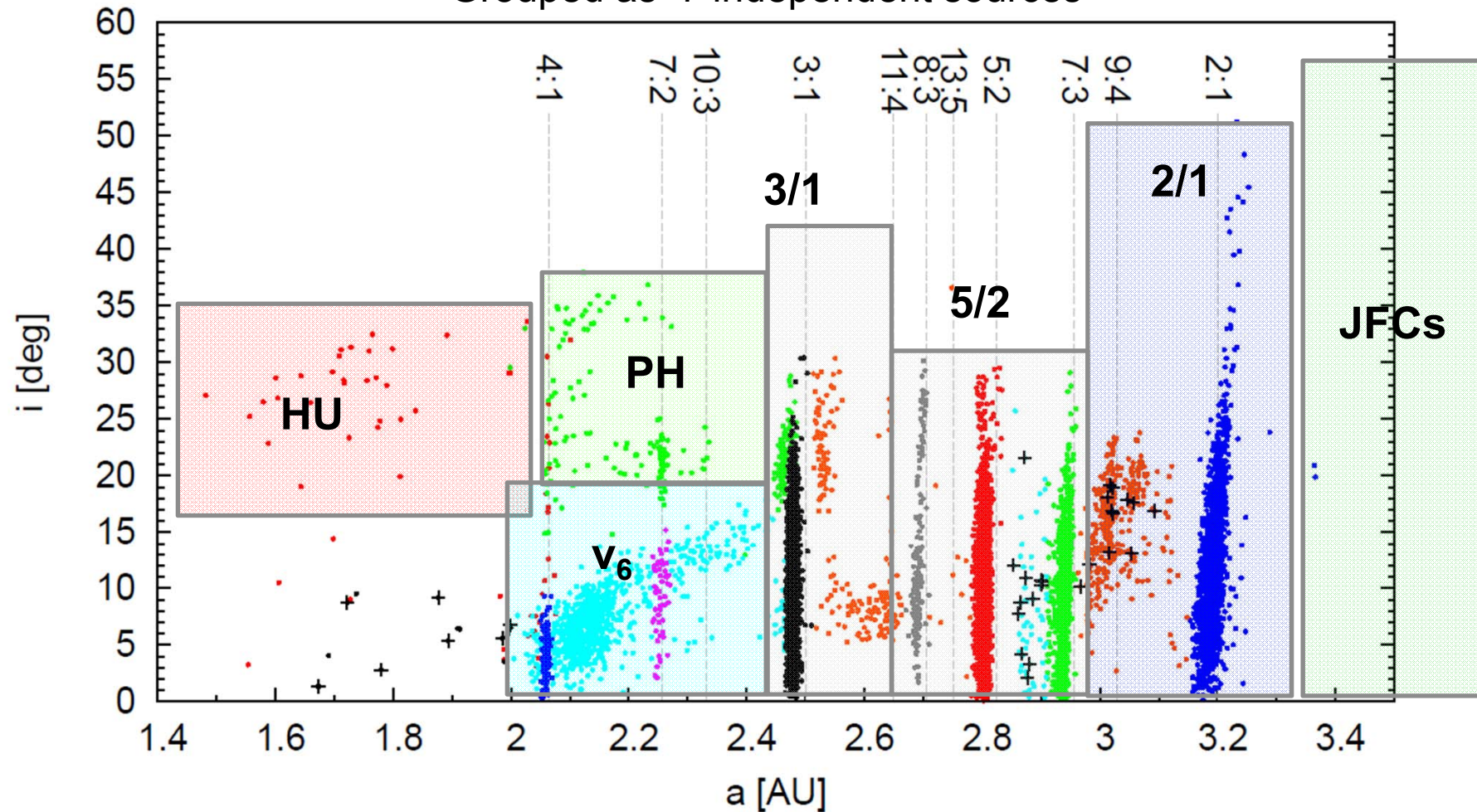
Orbits of asteroids at the moment they enter the NEO region



The new NEO Model

Orbits of asteroids at the moment they enter the NEO region

Grouped as 7 independent sources



The new NEO Model

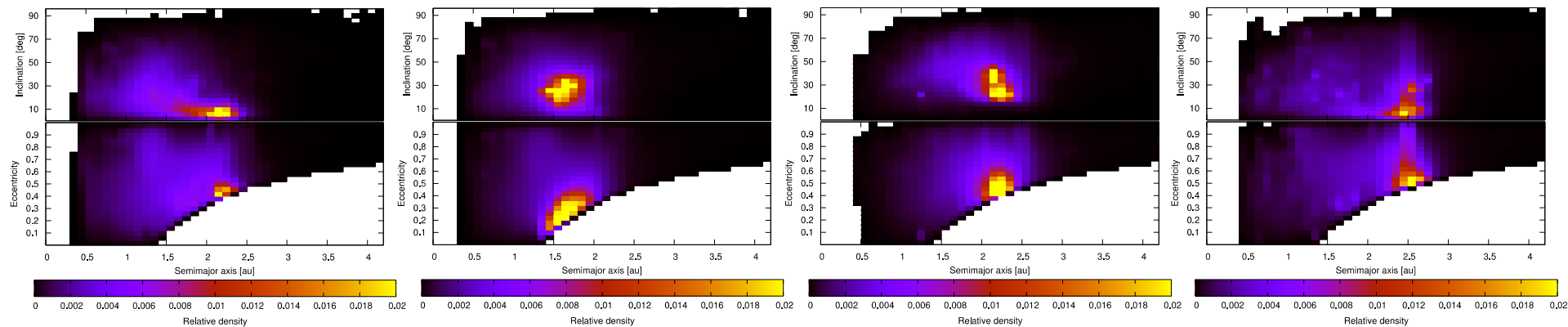
NEO orbital distribution from each source

nu6

Hungaria

Phocaea

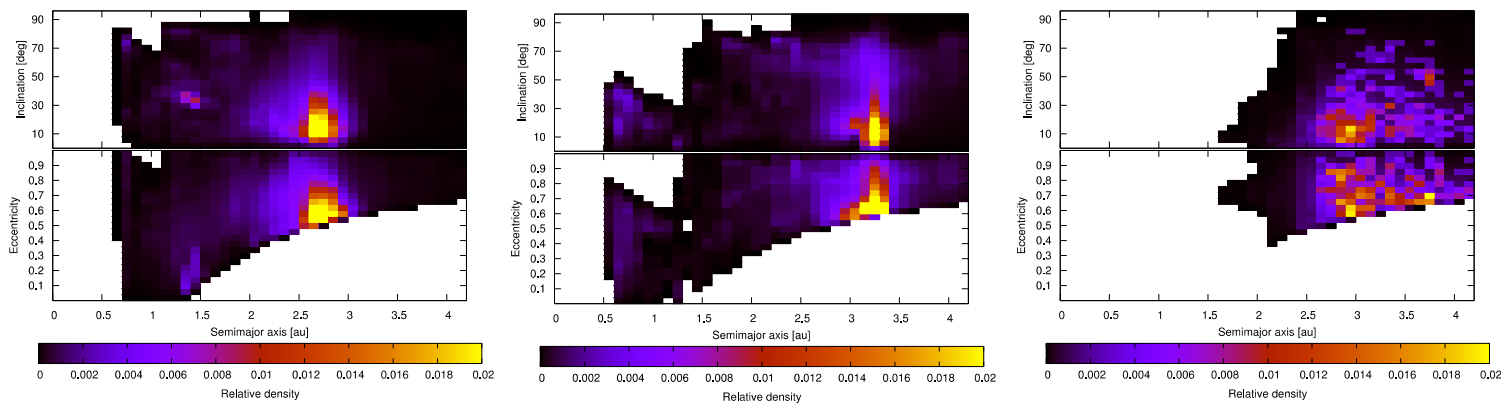
3:1J



5:2J complex

2:1J complex

JFC



The model equation

Objects detected by a survey

Source ratios (to be determined)

$$n(a, e, i, H) = \varepsilon(a, e, i, H) \sum_{i=1}^{N_S} f_i N_i(H) R_i(a, e, i)$$

Survey efficiency function (bias)

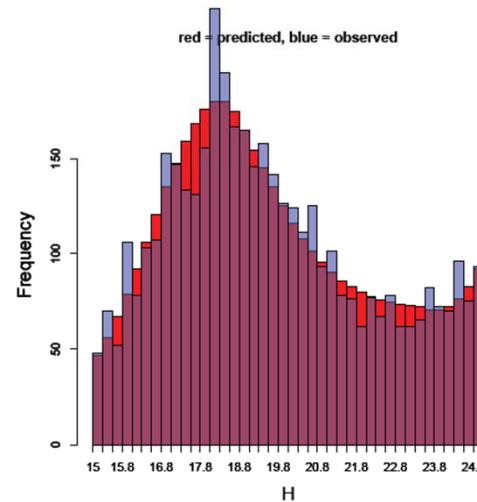
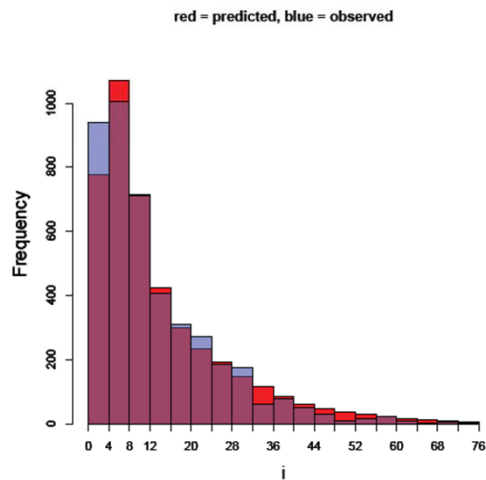
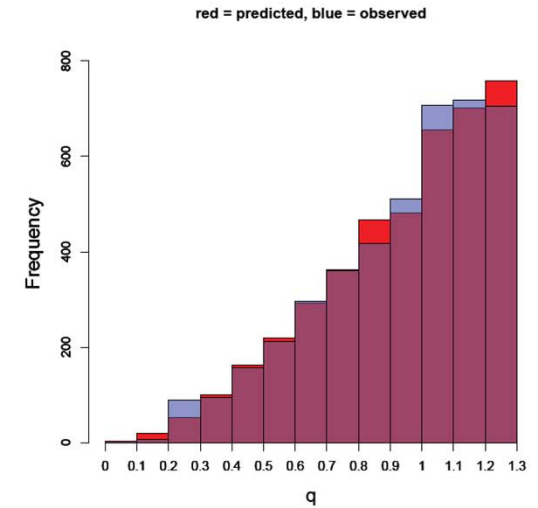
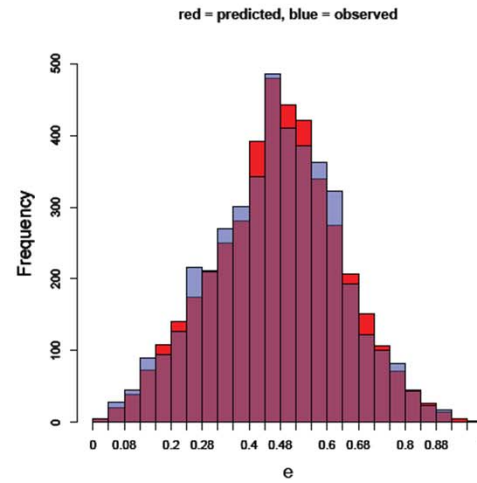
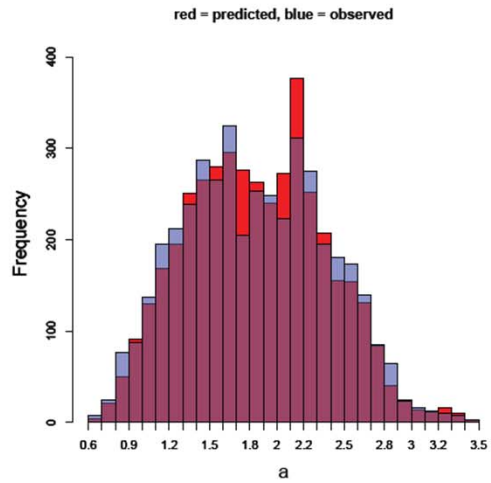
NEO orbital distribution from source (from numerical integrations)

Source H-distribution (to be determined)



The new NEO Model

Model fit (G96 data)

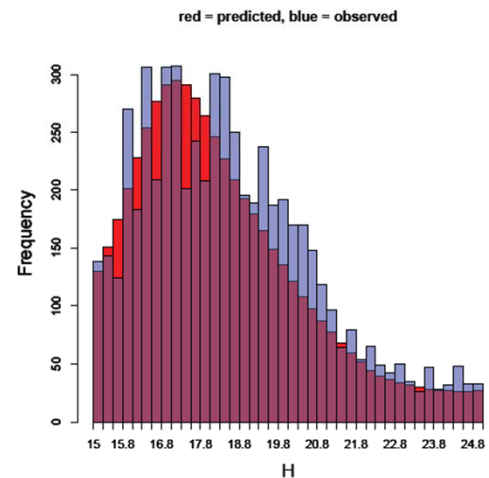
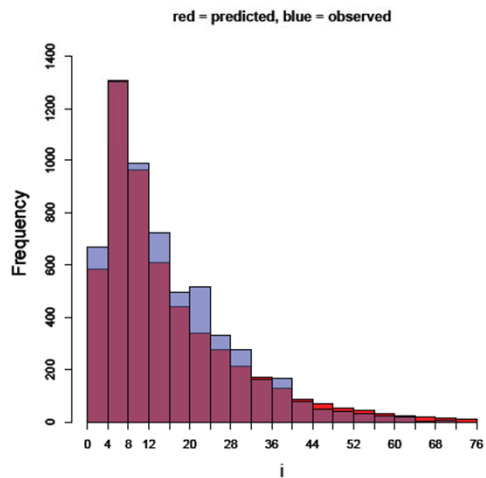
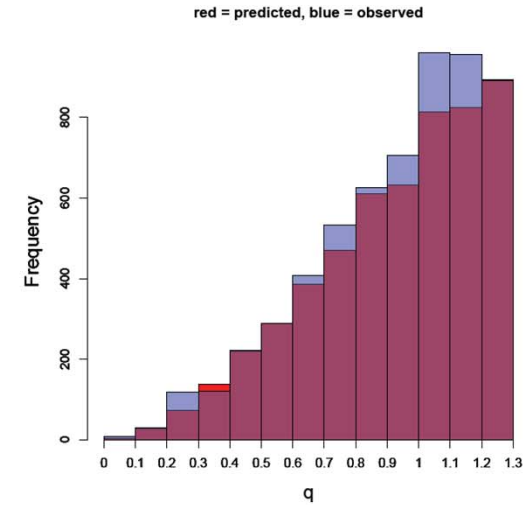
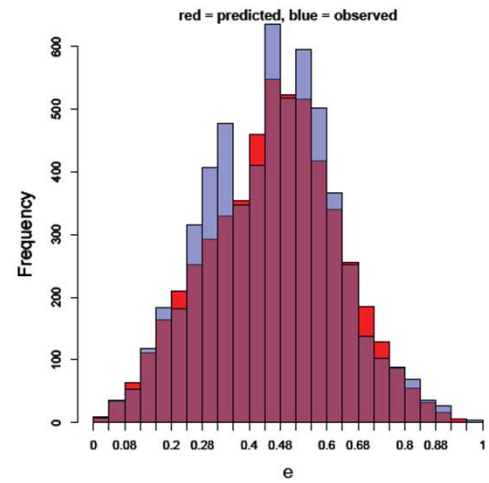
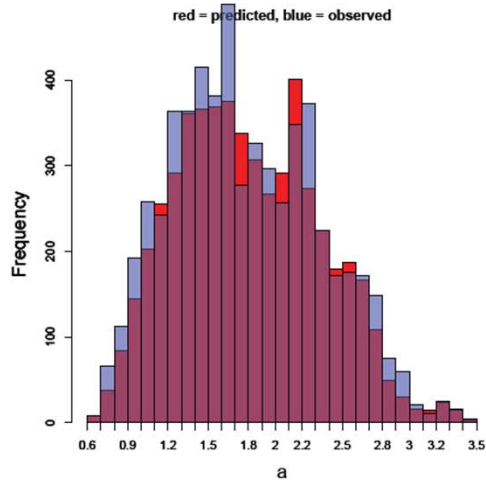


Model calibrated on
G96 data
Tested against G96
data



The new NEO Model

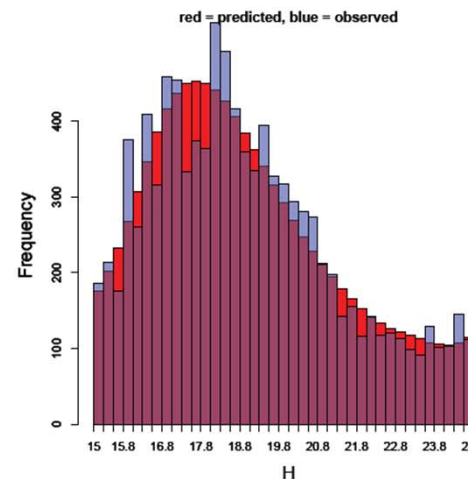
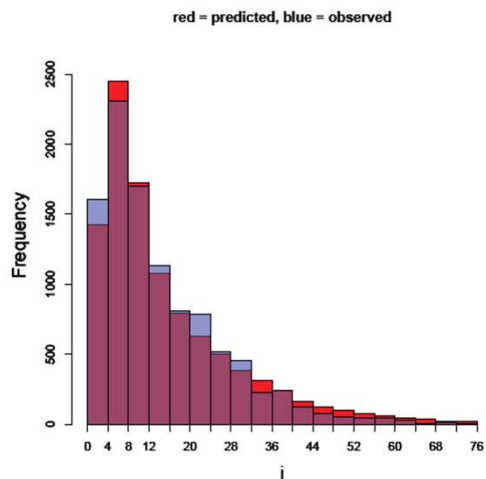
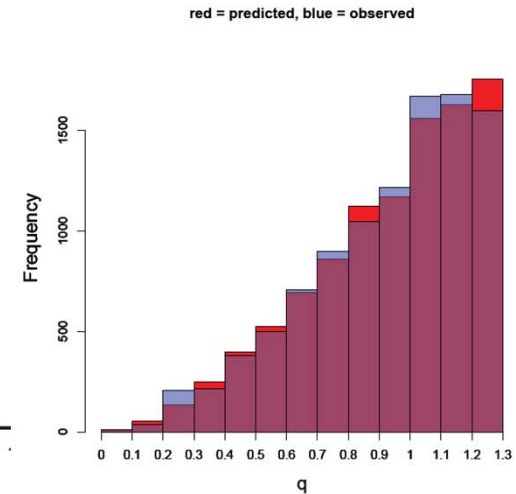
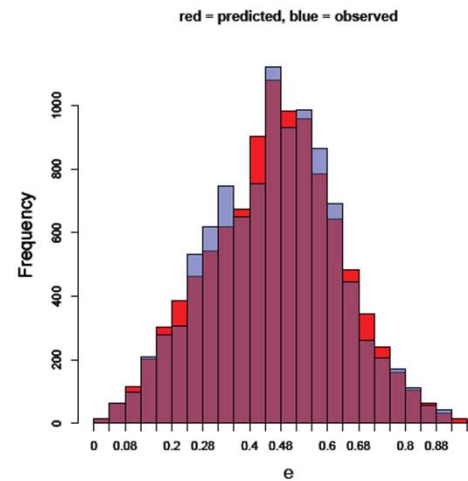
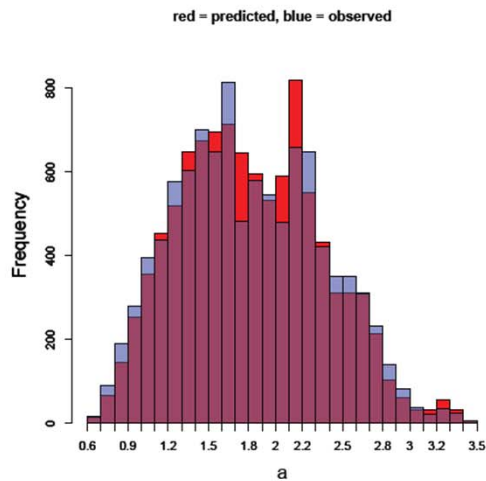
Model test (703 data)



Model calibrated on
G96 data
Tested against 703
data

The new NEO Model

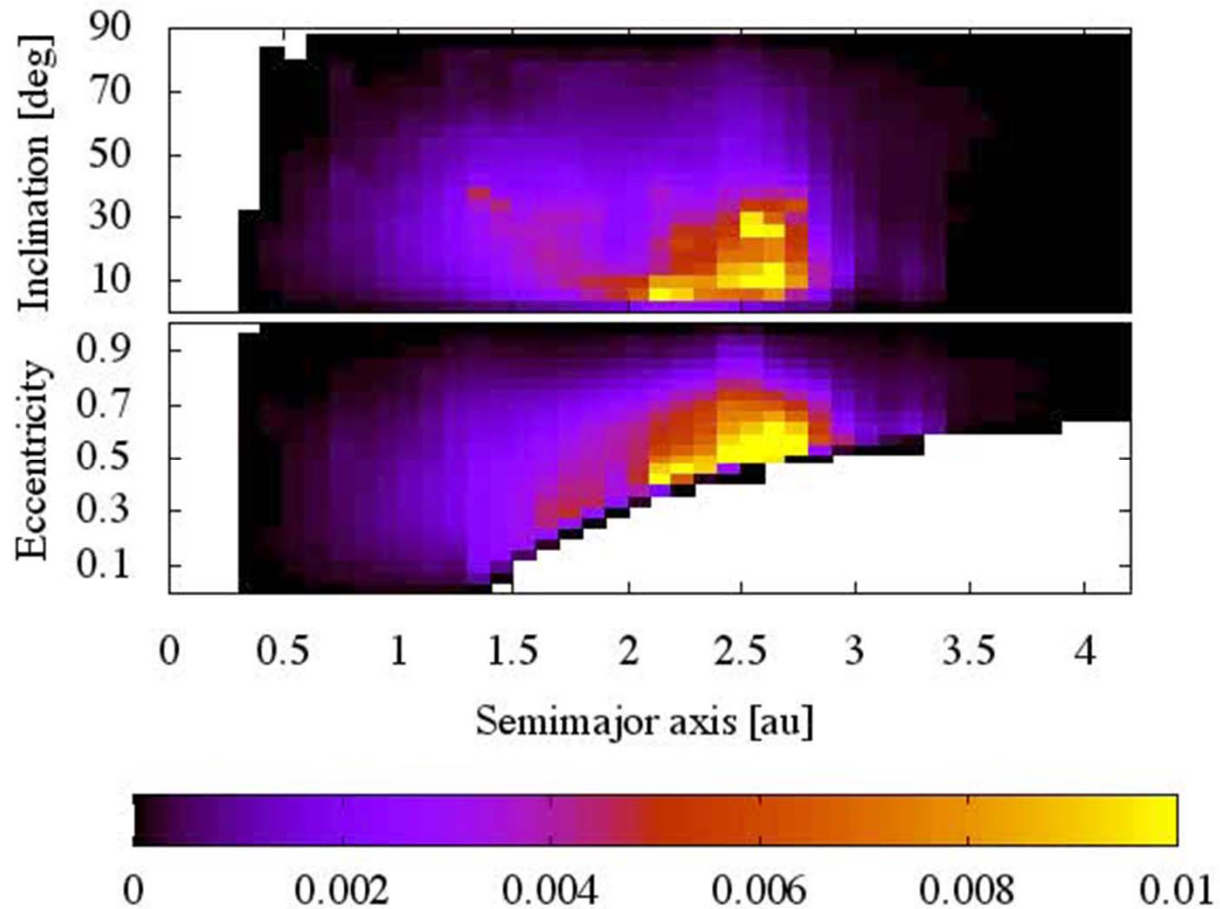
Final 7 source model: calibrated to both G96 and 703



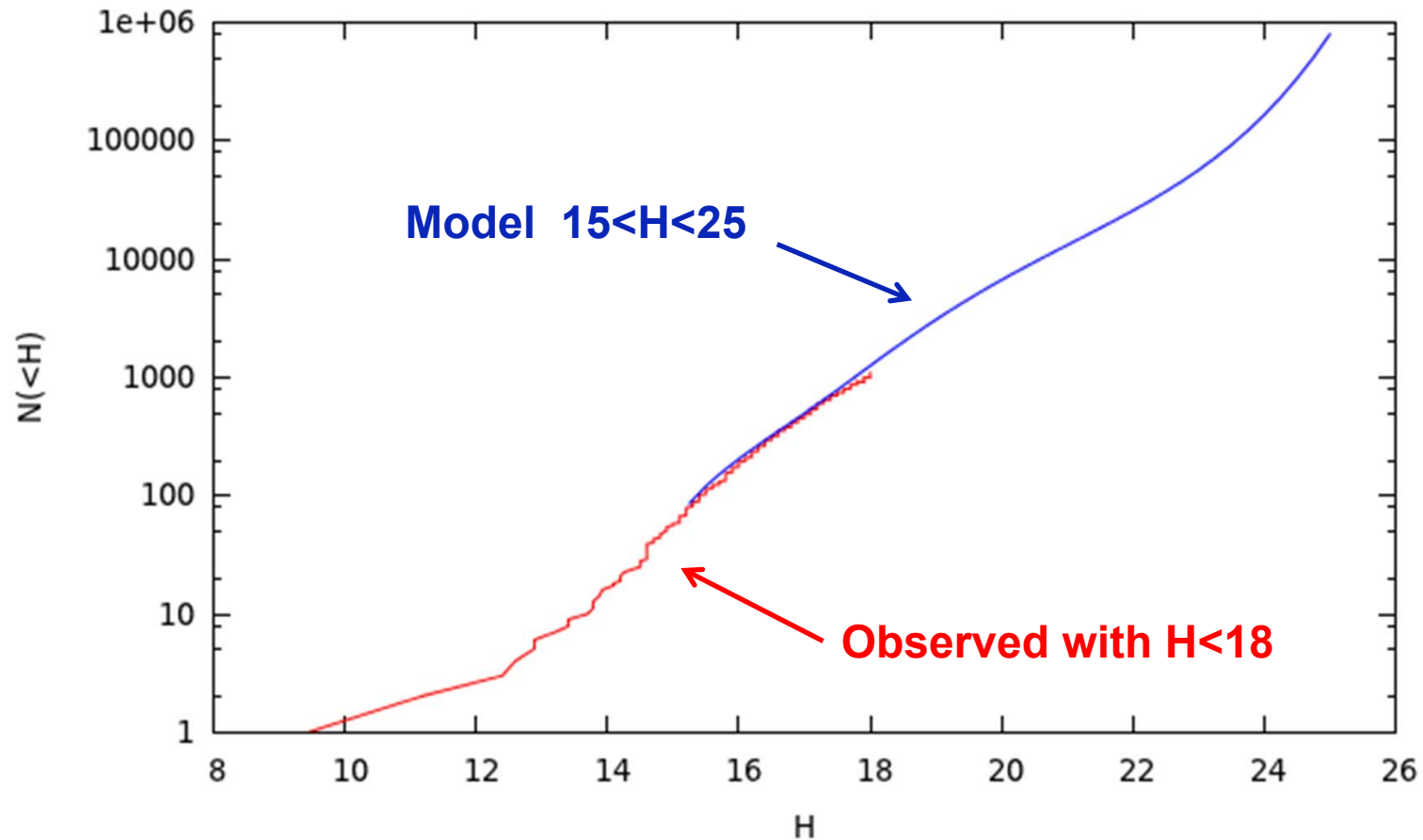
Model calibrated on
G96+703 data
Tested against
G96+703 data



The final model: orbital distribution



The final model: H - distribution

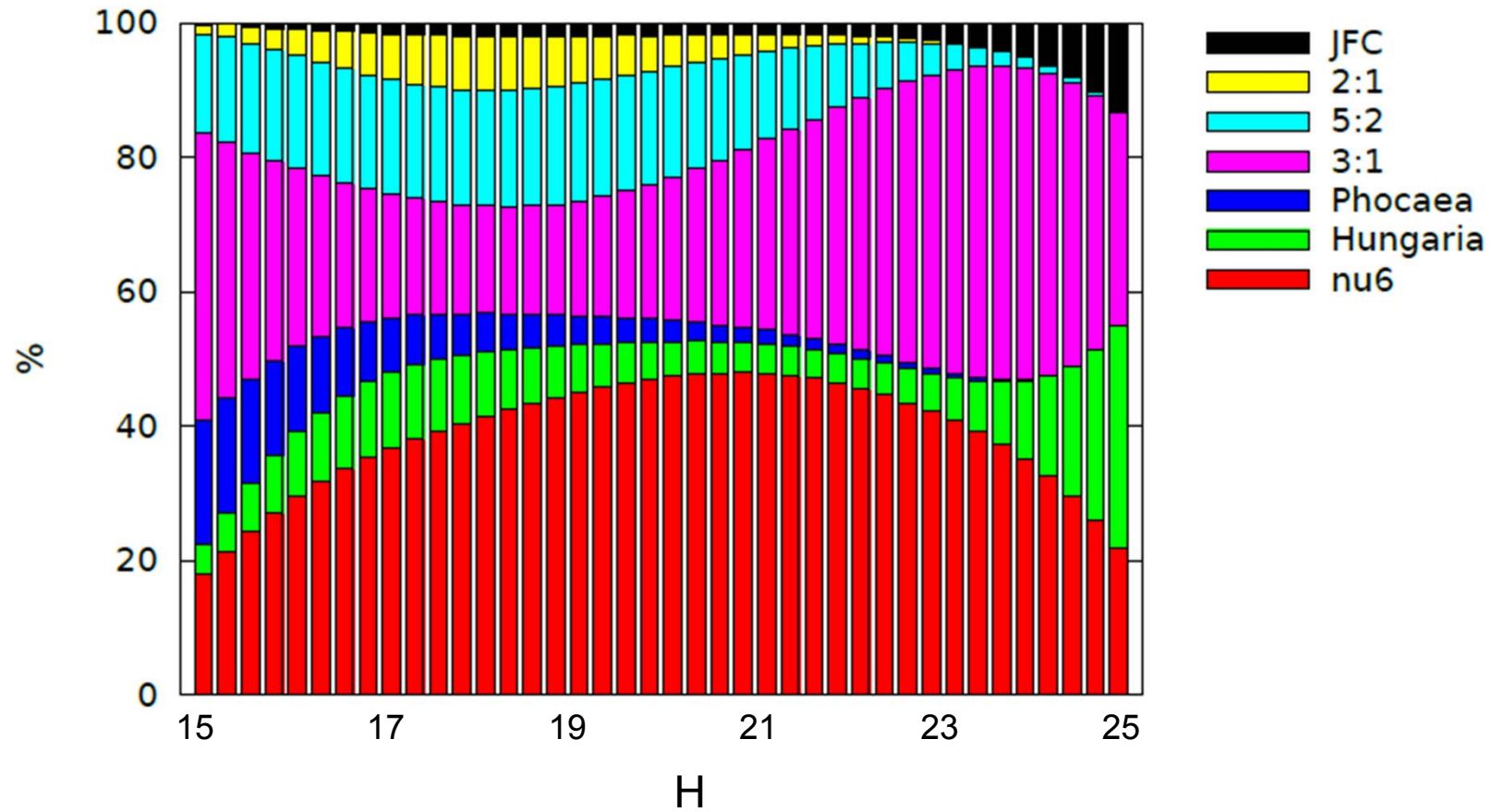


Population estimates for $D > 1\text{km}$ ($H < 17.5$)

Stuart & Binzel (2004):	1090 ± 180
Mainzer et al. (2011):	981 ± 19
Harris (2012, unpublished):	976 ± 30
OUR MODEL:	987 ± 100

The new NEO Model

Final 7 source model: source ratios as a function of H



The new NEO Model

NEO albedo model: methods

We define three albedo categories:

Category 1: p_v smaller or equal than 0.1 - flat distribution in the 0.02-0.1 range

Category 2: p_v larger than 0.1 and smaller or equal than 0.3 – flat distribution

Category 3 p_v larger than 0.3 –exponential distribution: decay by 2.6 every 0.1in p_v

We use 328 NEOs with WISE-measured albedos ($H > 15$ and $W3 < 10$). For each object we compute the albedo category. We also compute the probability that the object would have been observed if it had been in either albedo category: $B(1)$, $B(2)$, $B(3)$

Each survey s is characterized by two parameters: the fraction of objects in cat. 1, 2: $p_s(1)$, $p_s(2)$. Note: $p_s(3) = 1 - p_s(1) - p_s(2)$. In JFC source we impose $p_s(1) = 1$. We fit for the parameters $p_s(1)$, $p_s(2)$ ($s = 1, \dots, 6$) by maximizing the function

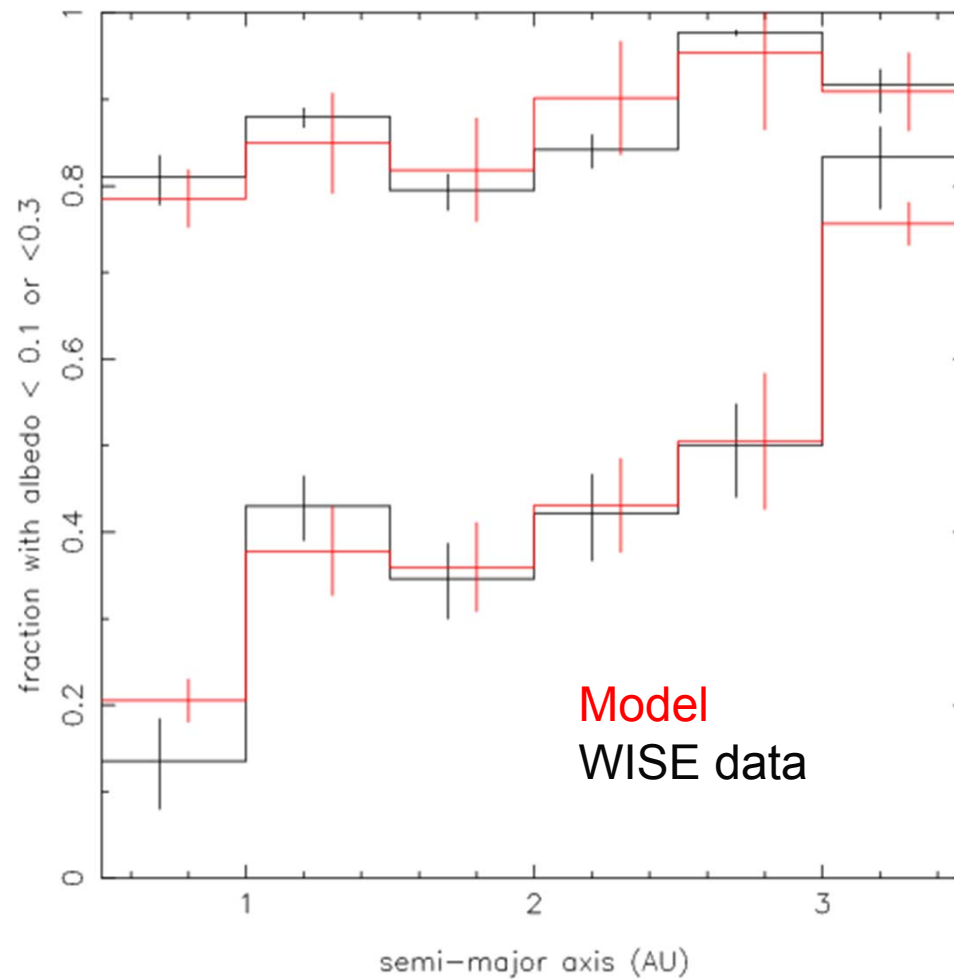
$\chi = \sum_n \text{Log}(P_n)$, where n is the index of the NEO and

$P_n = \sum_s P_s(n) (B_n(c_n) p_s(c_n)) / (B_n(1) p_s(1) + B_n(2) p_s(2) + B_n(3) p_s(3))$,

$P_s(n)$ being the probability that the asteroid n comes from source s .

The new NEO Model

NEO albedo model: results & comparison with WISE data



NEOPOP

Introduction / Overview

NEOPOP – Near Earth Object Population Observation Program

NEOPOP is written in Fortran as Command-Line Tool (CLT).

CLT consists of four modules in two components:

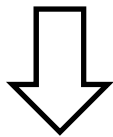
- Population Generator
 - ➔ Population Generation
 - ➔ Population Analysis
- Observation Generator
 - ➔ **Observation Simulation**
 - ➔ Observation Analysis

Graphical User Interface (GUI) uses the CLT.

NEOPOP Population Generator

Population Generation:

fictitious model
old model
new model
external population



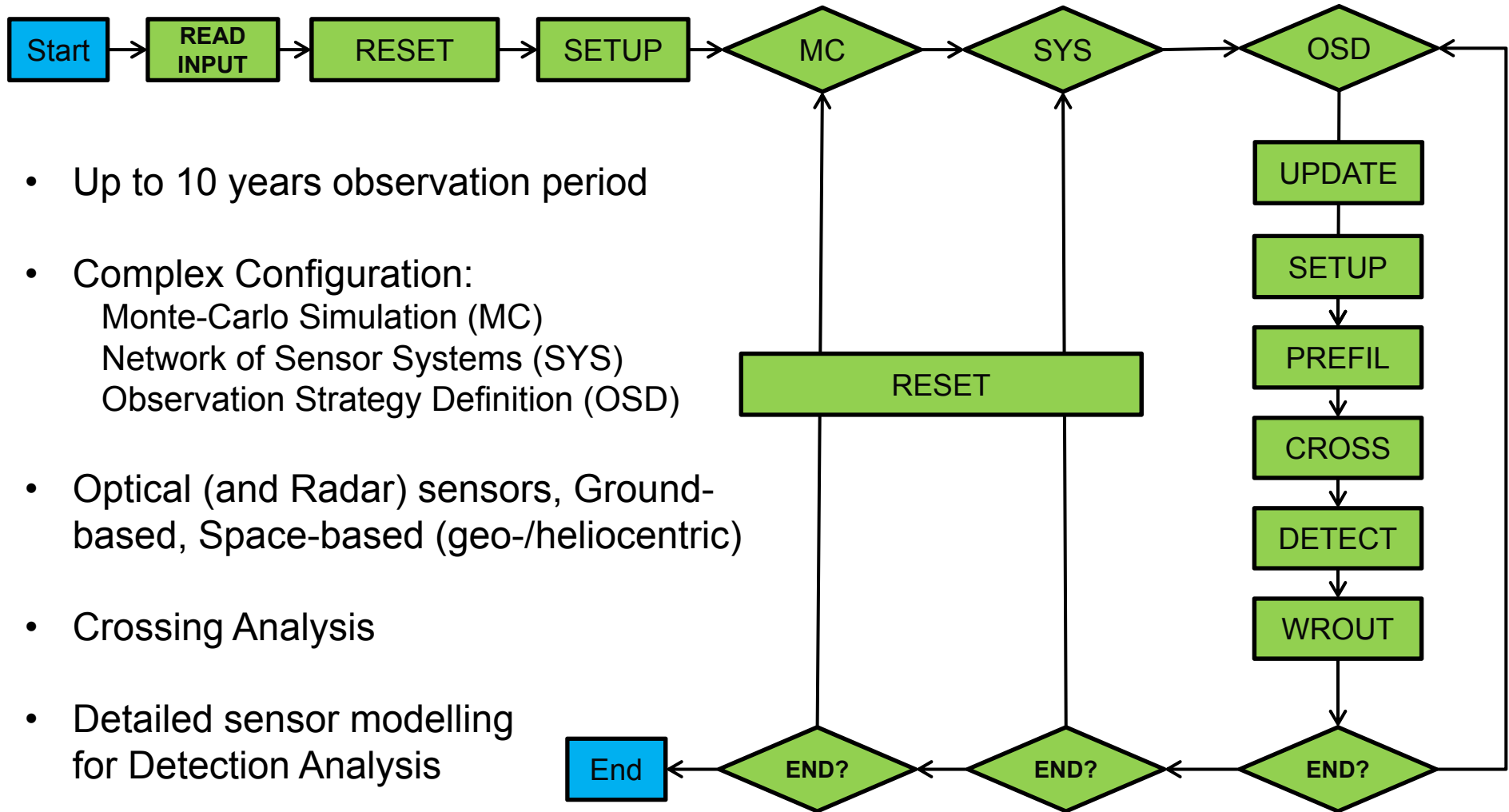
Population file (MPC,DYS, DES)
Physical properties file

Population Analysis:

- makes use of given or generated population
- user-defined analysis and filtering
 - Groups & Sources
 - Orbital and Object parameters
 - Relative distance
 - Close-Approach Analysis
- Results generated for 2D/3D/scatter/solar plots

NEOPOP

Observation Simulation: Top-Level Data-Flow



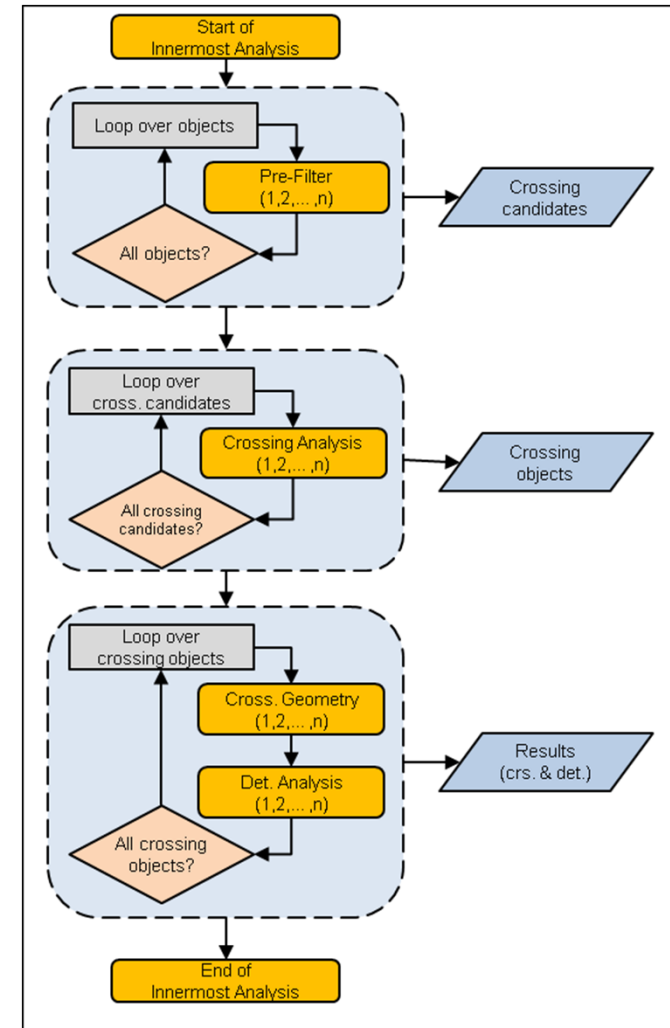
- Up to 10 years observation period
- Complex Configuration:
 - Monte-Carlo Simulation (MC)
 - Network of Sensor Systems (SYS)
 - Observation Strategy Definition (OSD)
- Optical (and Radar) sensors, Ground-based, Space-based (geo-/heliocentric)
- Crossing Analysis
- Detailed sensor modelling for Detection Analysis

NEOPOP

Observation Simulation: The Three Innermost Loops

Stepwise decrease of initial object population:

- Pre-Filter: *To skip objects not being able to cross the field of view*
 - Crossing Analysis: *To identify objects that are crossing the field of view*
 - Detection Analysis: *To identify objects that can be detected by the defined sensor system*
- ➔ All three parts are implemented in a way for being parallelized in the future.

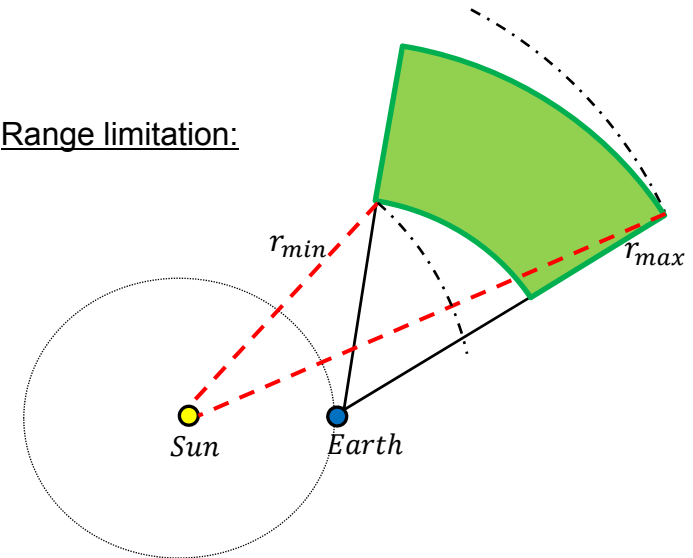


NEOPOP

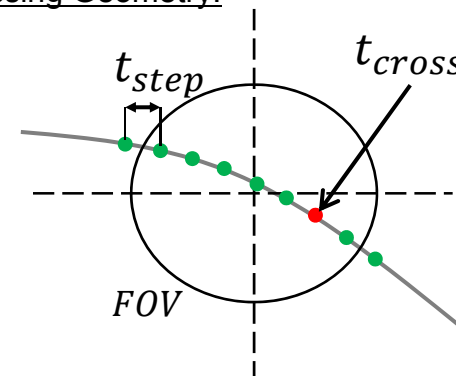
Deriving the Crossing Geometry

- Only the objects, which have successfully passed the Crossing Analysis, are analyzed for their crossing of the circular FOV.
- The task is to approximate the objects path within the FOV by a set of snapshots. Linear movement is assumed between two nearby steps.
- For each time step t_{step} the time and related coordinates of the sensor and object are stored.

Range limitation:



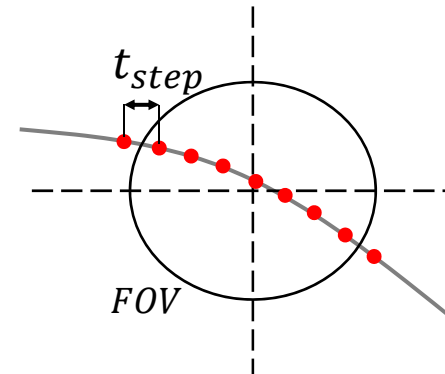
Crossing Geometry:



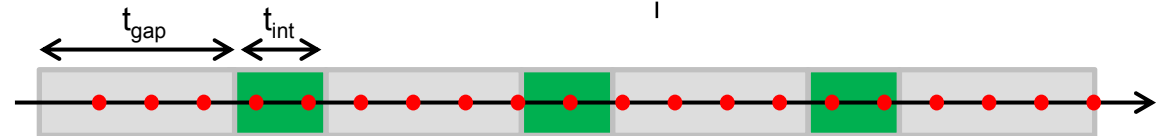
NEOPOP

Data for CCD Exposure

Consideration of integration and gap times:

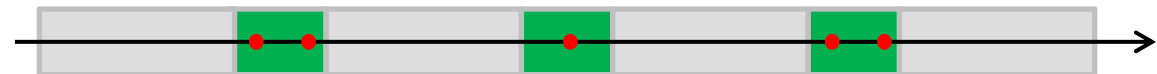


- Crossing Geometry is taken



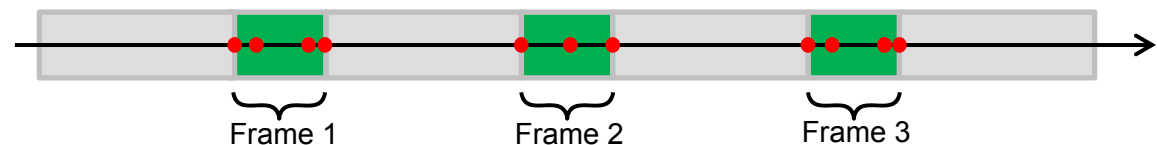
- Steps in integration time are used directly

Take valid point of crossing geometry:



- Start and end point of object is being interpolated

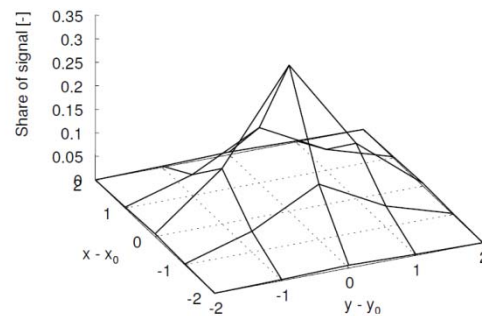
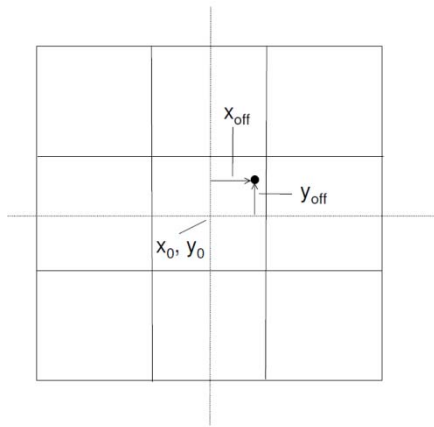
Interpolation / Extrapolation:



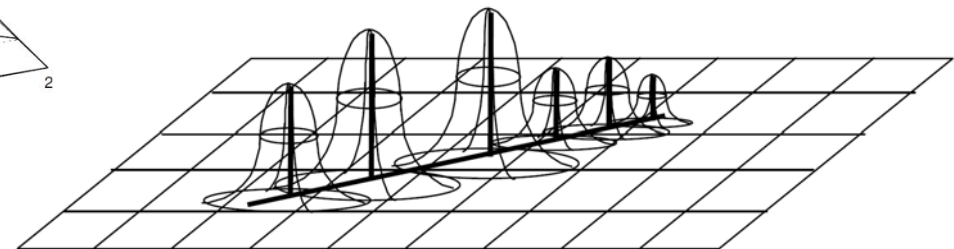
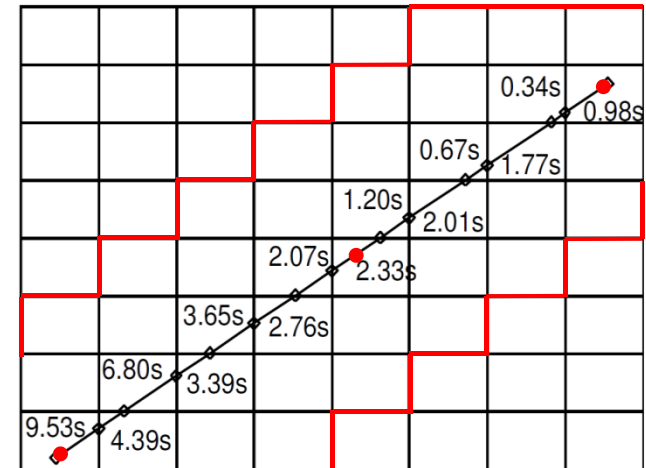
NEOPOP

CCD – Signal Modelling

- Based on the ...
- ... trace of the object
 - ... the pixel dwell times are calculated and
 - ... the signal is computed for the center and the surrounding pixels (apply PSF)



CCD – Matrix



NEOPOP

Optical Performance Model

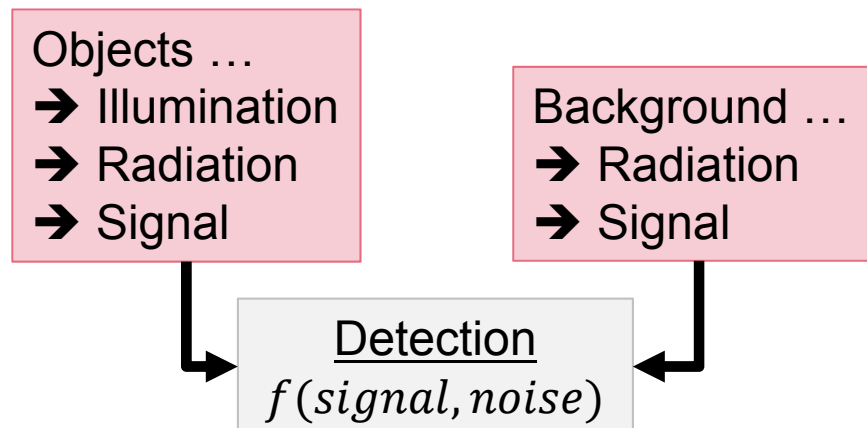
Background Sources

Visible light:

- Stars up to user-defined magnitude
- Planets
- Faint stars above user-defined mag.
- Galaxies
- Zodiacal light
- Airglow
- Atmospherically scattered Moon- & Sunlight

Infrared light:

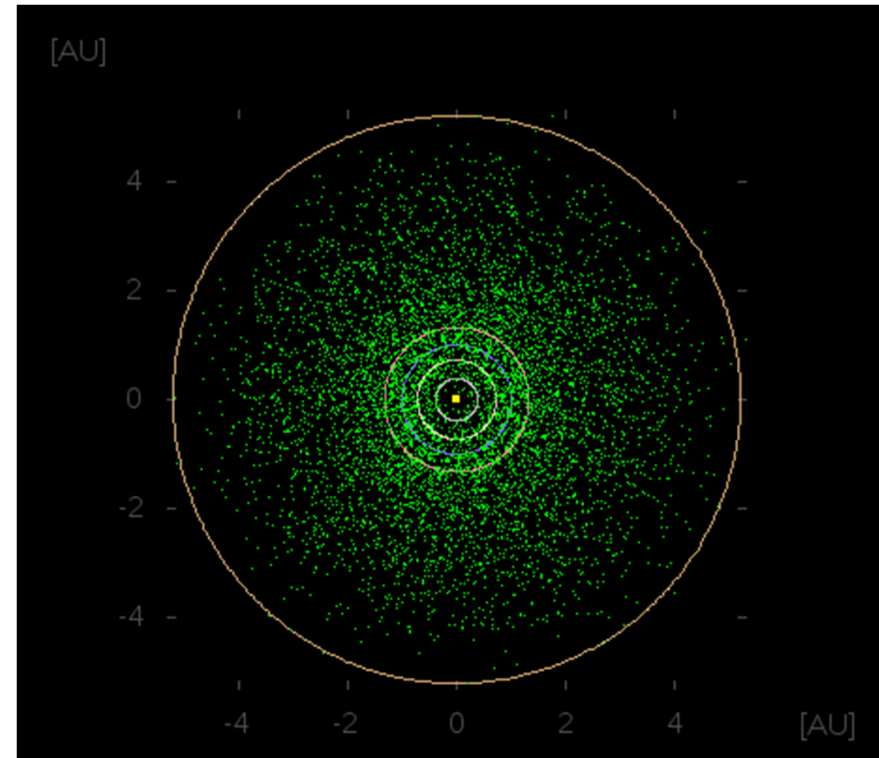
- Stars up to user-defined magnitude
- Planets
- Faint stars above user-defined mag.
- Galaxies
- Zodiacal light
- Interstellar Medium
- Extragalactic Background



NEOPOP

Further Features

- Simple Radar sensor model
- Measurement data generation (incl. bias, noise and drift errors)
- Output files contain large set of parameters: Crossing and detected objects, magnitude, SNR etc.
- Output provided per sensor system as well as for overall sensor network
- Skyplots show the objects' positions in the sky for a given time and location.
- Solar system overview plots show object positions, crossings and detections



NEOPOP

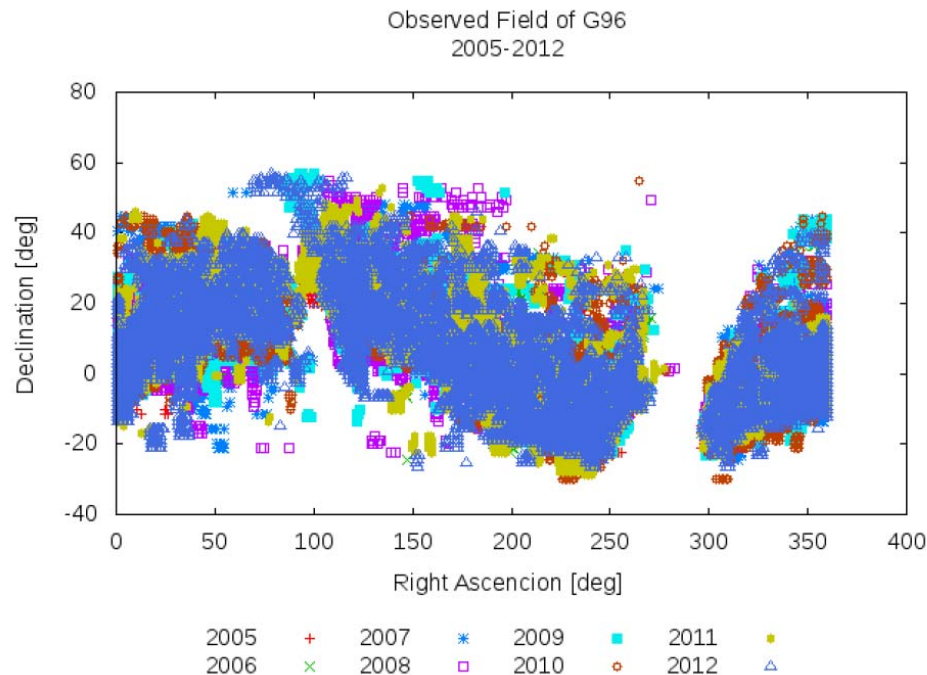
Verification by CSS-Campaign Simulation (1/5)

CSS Campaigns of G96:

CSS data (G96&703) from 2005 to 2012 has been used.



http://www.jpl.arizona.edu/css/css_facilities.html

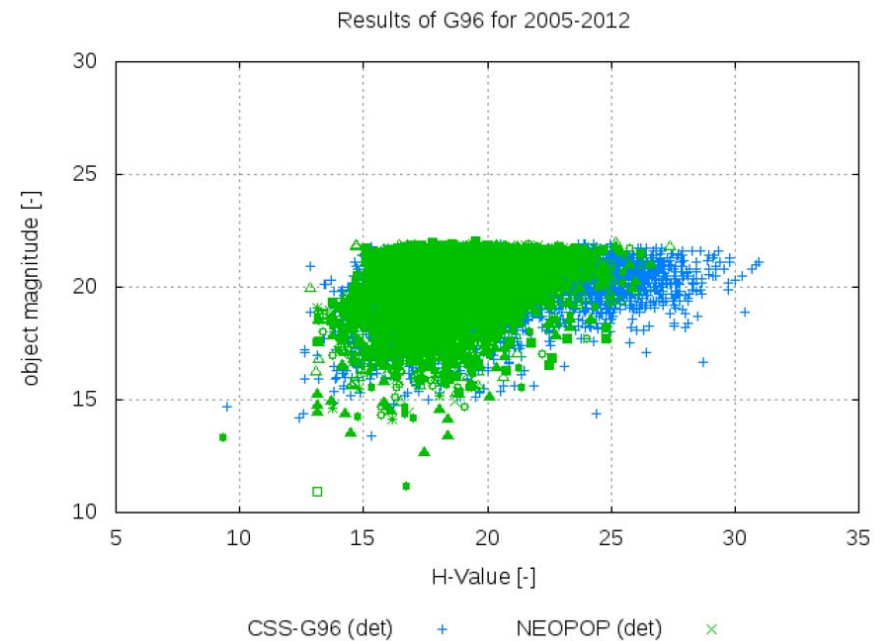
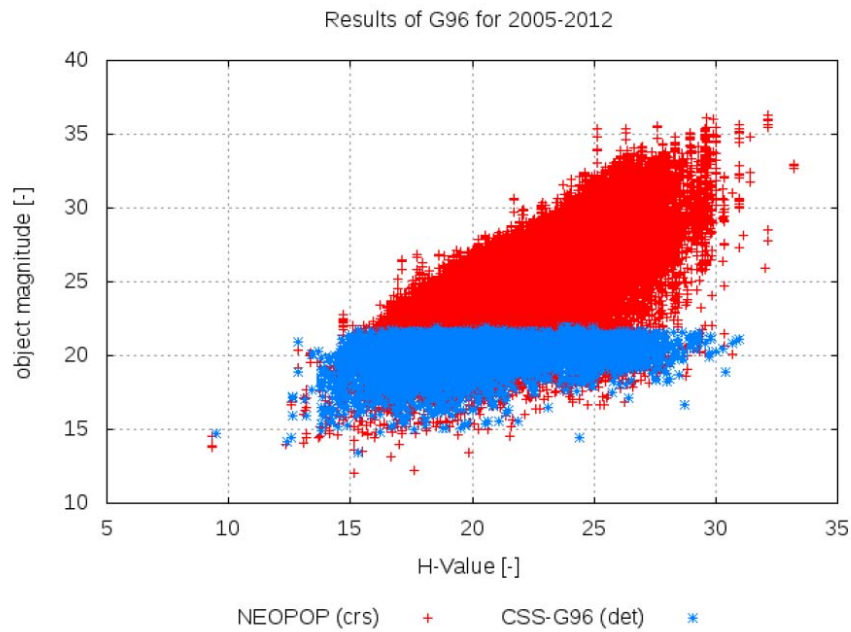


Parameters used for the simulation:

Parameter	Value
FOV	1°
Integration Time	30s
Gap Time	30s
FOV per Pixel	0.973"

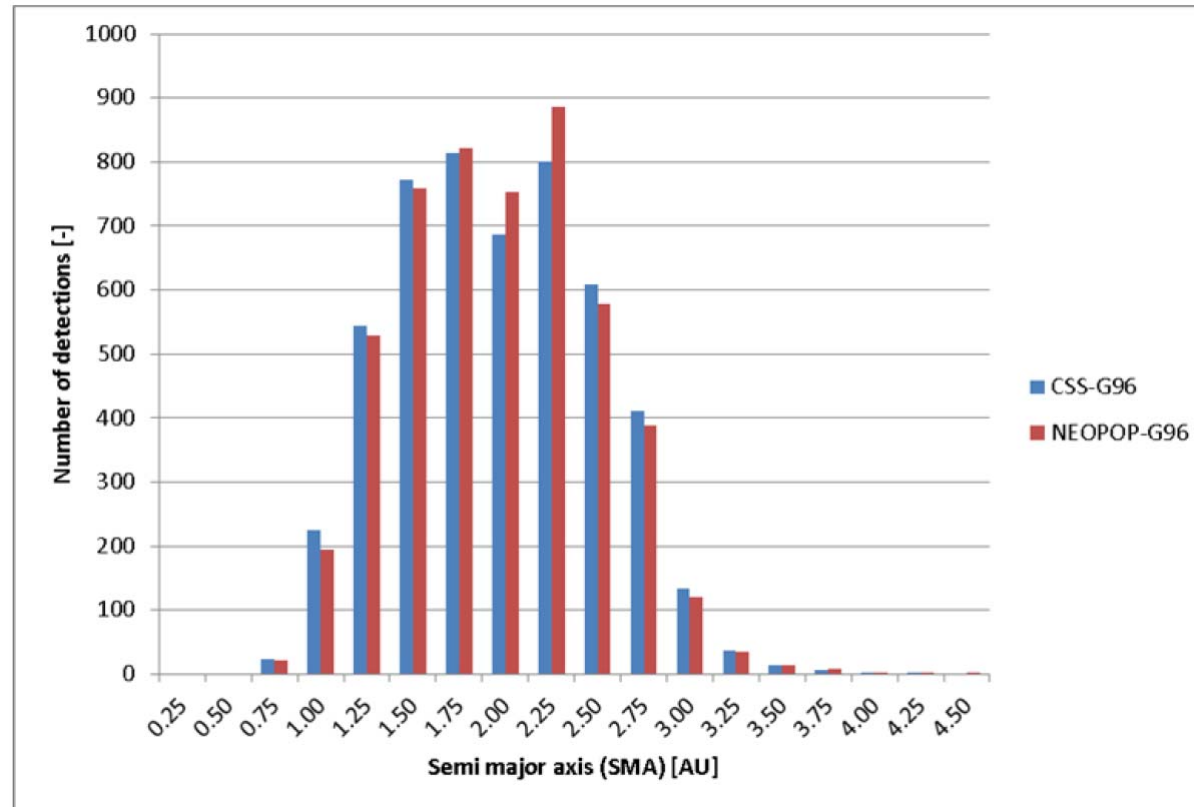
NEOPOP

Verification by CSS-Campaign Simulation (2/5)



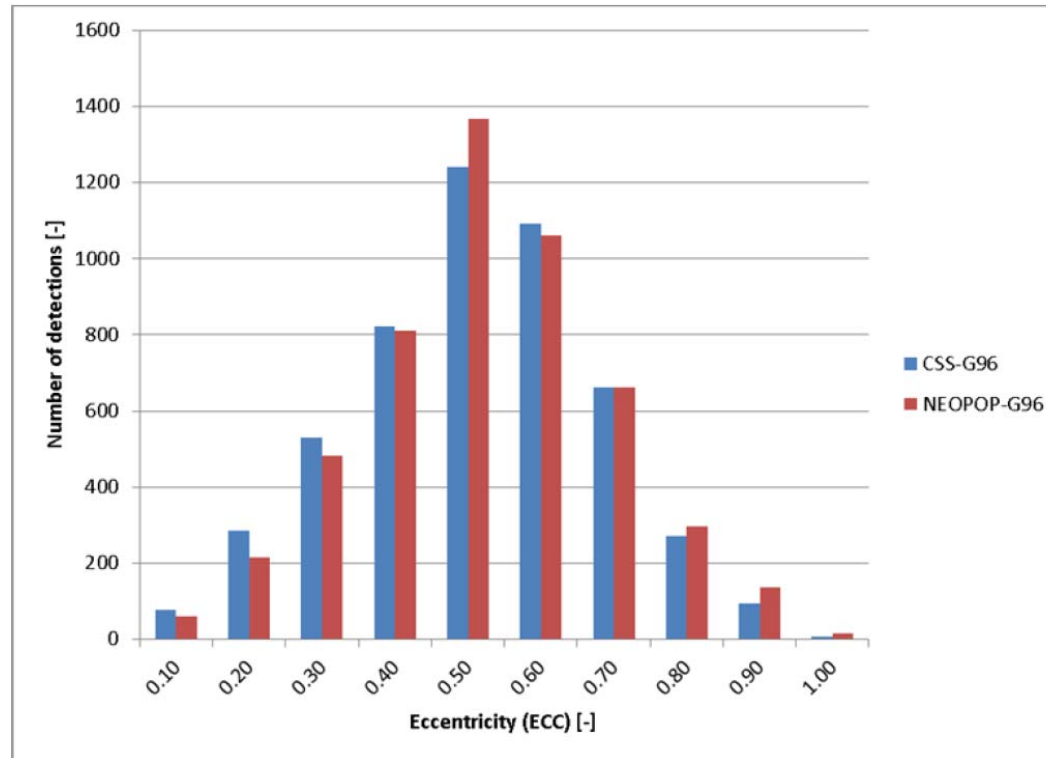
NEOPOP

Verification by CSS-Campaign Simulation (3/5)



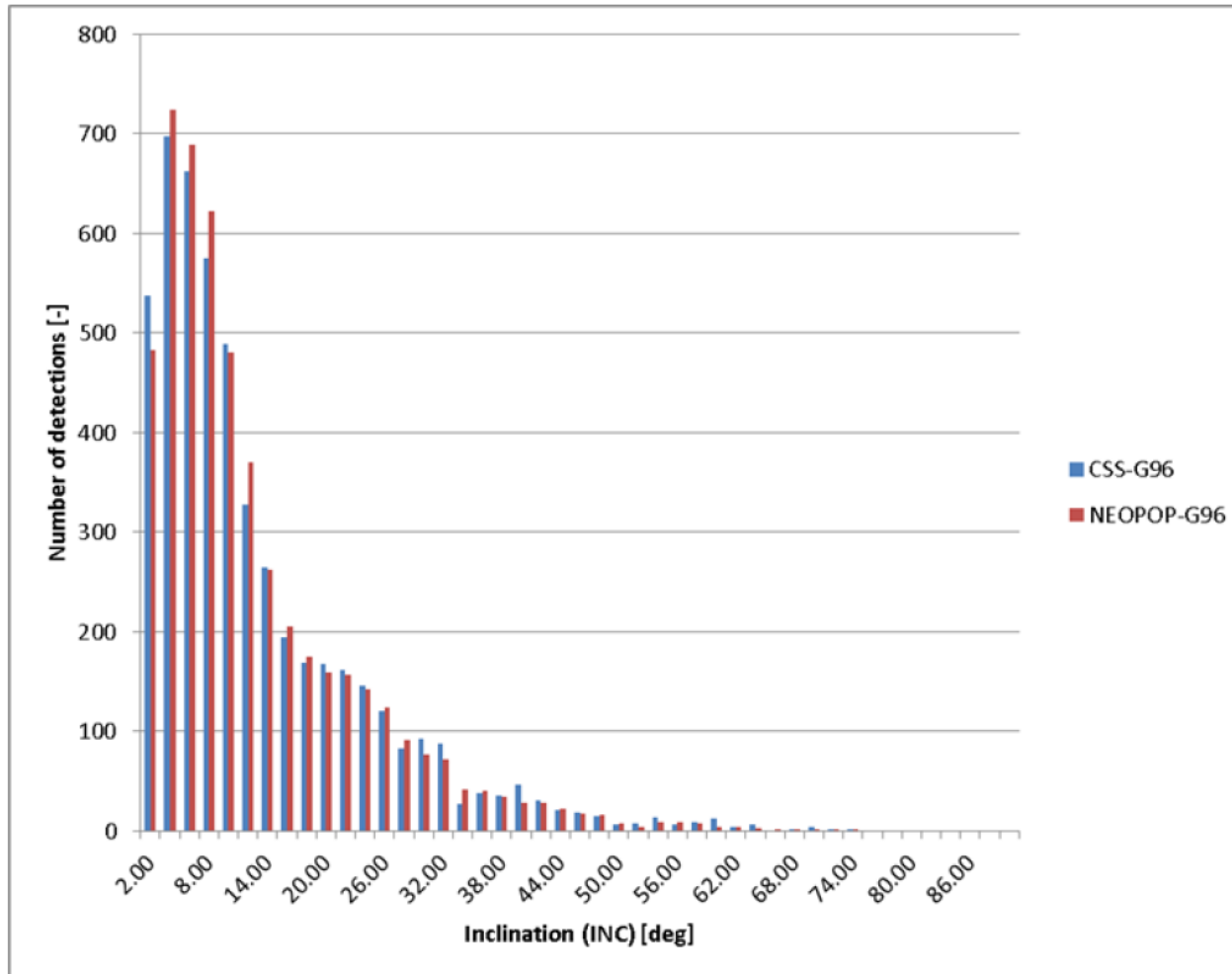
NEOPOP

Verification by CSS-Campaign Simulation (4/5)



NEOPOP

Verification by CSS-Campaign Simulation (5/5)



NEOPOP

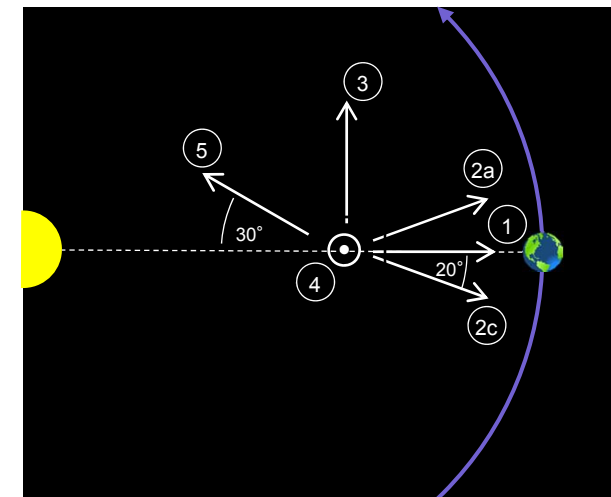
NEOPOP Application: Simulation of Observations from L1

Objective:

- Identify the viability of a NEO-detector on a L1 Space Weather mission
- Compare different potential instruments and setups
- Instrument constraint: max. mass of 3 kg

Setup:

- Observer virtually “in” L1
- Simulation over 14 days
- 3 different instruments, 8 different viewing directions
- Longer simulation (1 year, to obtain statistically more significant results) still to be done

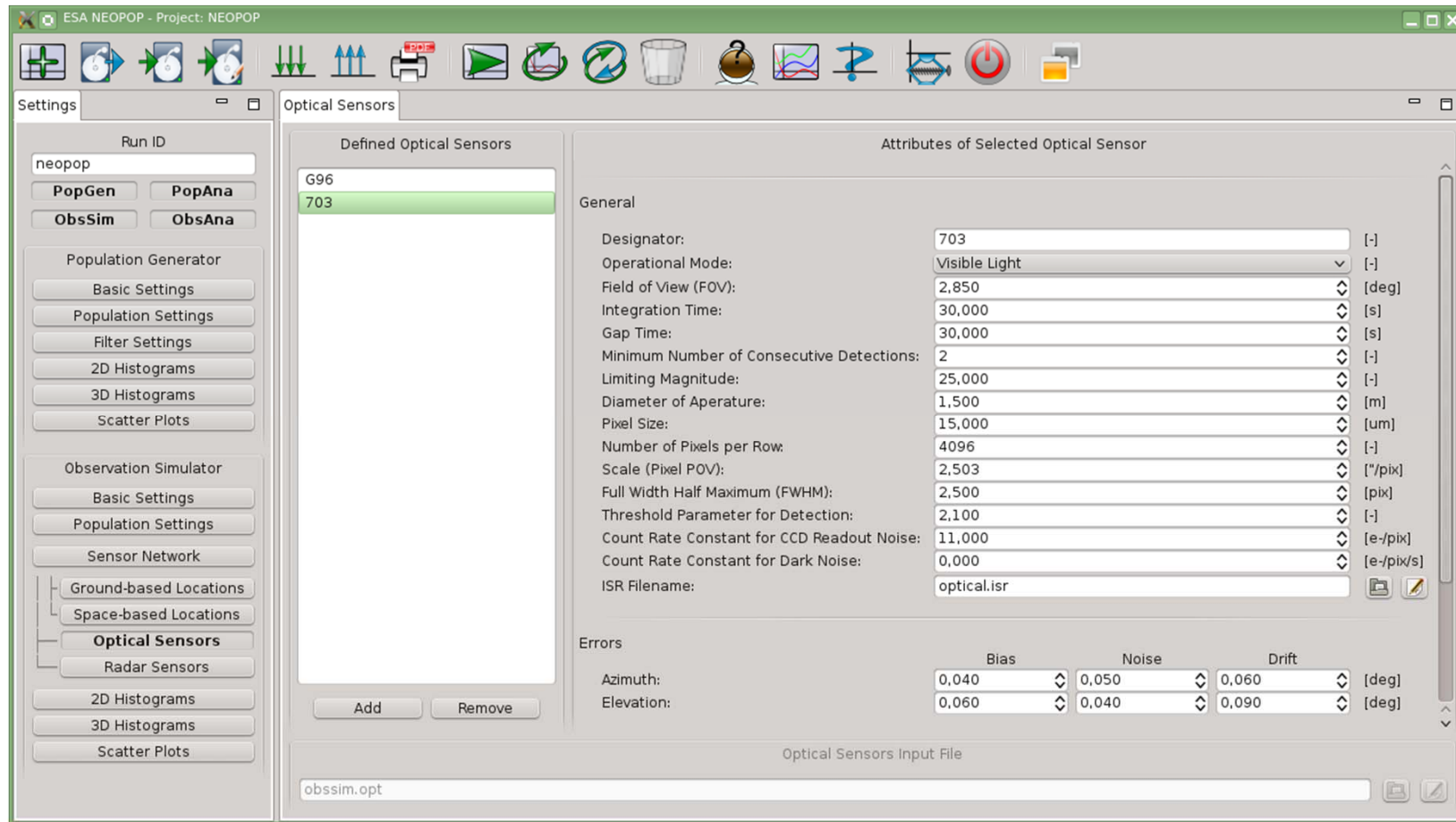


Sensor LOS orientations from L1

Results (all NEO detections):

	FoV [deg ²]	Lim. mag.		1	2 a/b/c/d	3	4	5	Probability object is newly discovered
Sensor 1	5x5	16		0	0/1/1/0	0	0	0	0 % / > 70 %
Sensor 2	22x22	14		0	1/0/1/0	0	0	0	> 92 % / > 76 %
Sensor 3	140x140	9		0	0/0/0/0	0	0	0	

NEOPOP Demonstration



Conclusion & Discussion

Conclusion

Near-Earth Object Population Observation Program (NEOPOP)

- Generation of NEO populations
 - Uses new NEO Model, calibrated to recent observation data
- Simulation of NEO population observations
 - Uses new Optical Sensor model, taking various background sources into account

Conclusion & Discussion

Discussion

Thank you very much for your attention!

Questions?



Technische
Universität
Braunschweig

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Observatoire
de la CÔTE d'AZUR



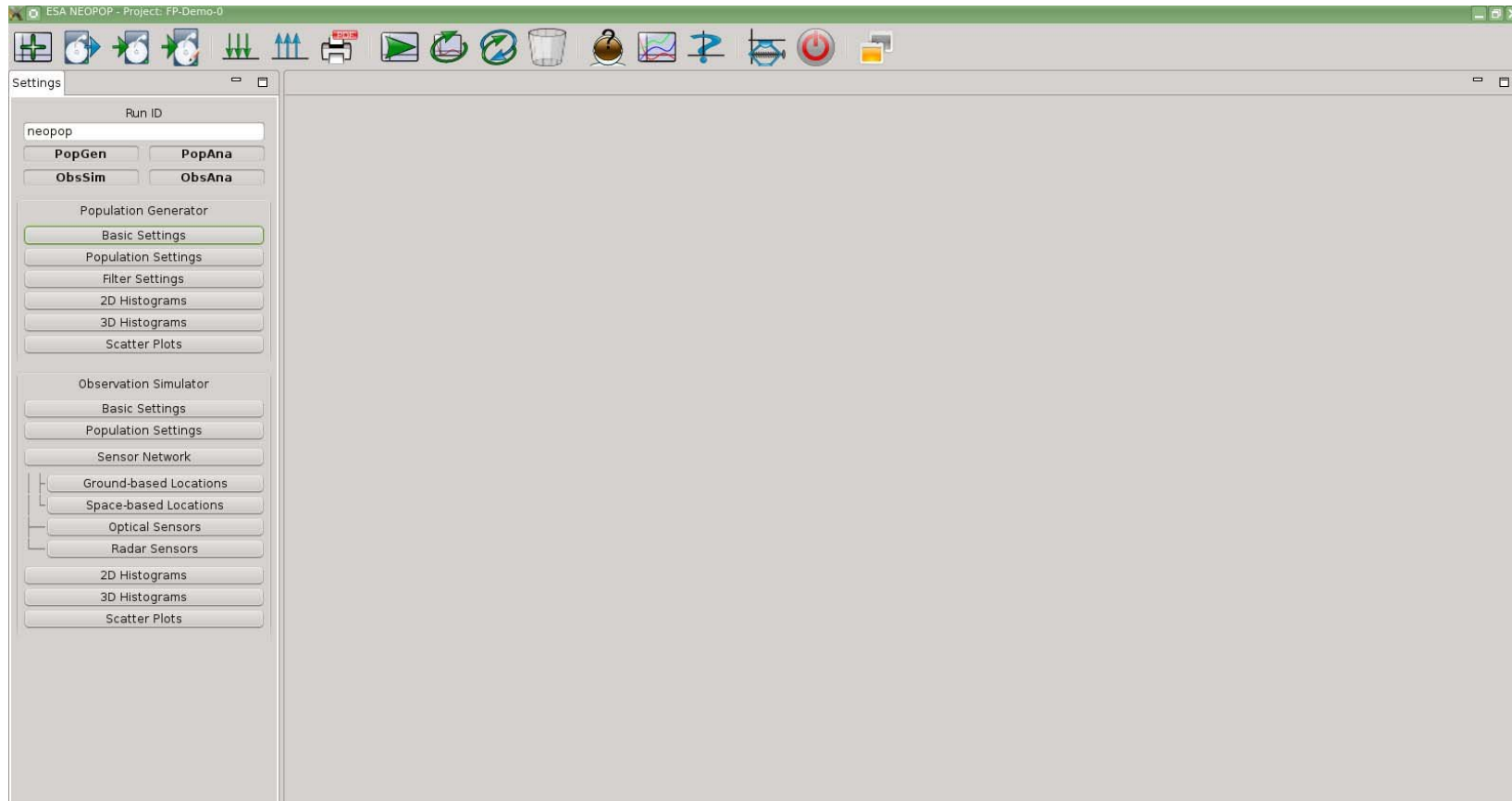
DLR

Institute of
Aerospace Systems

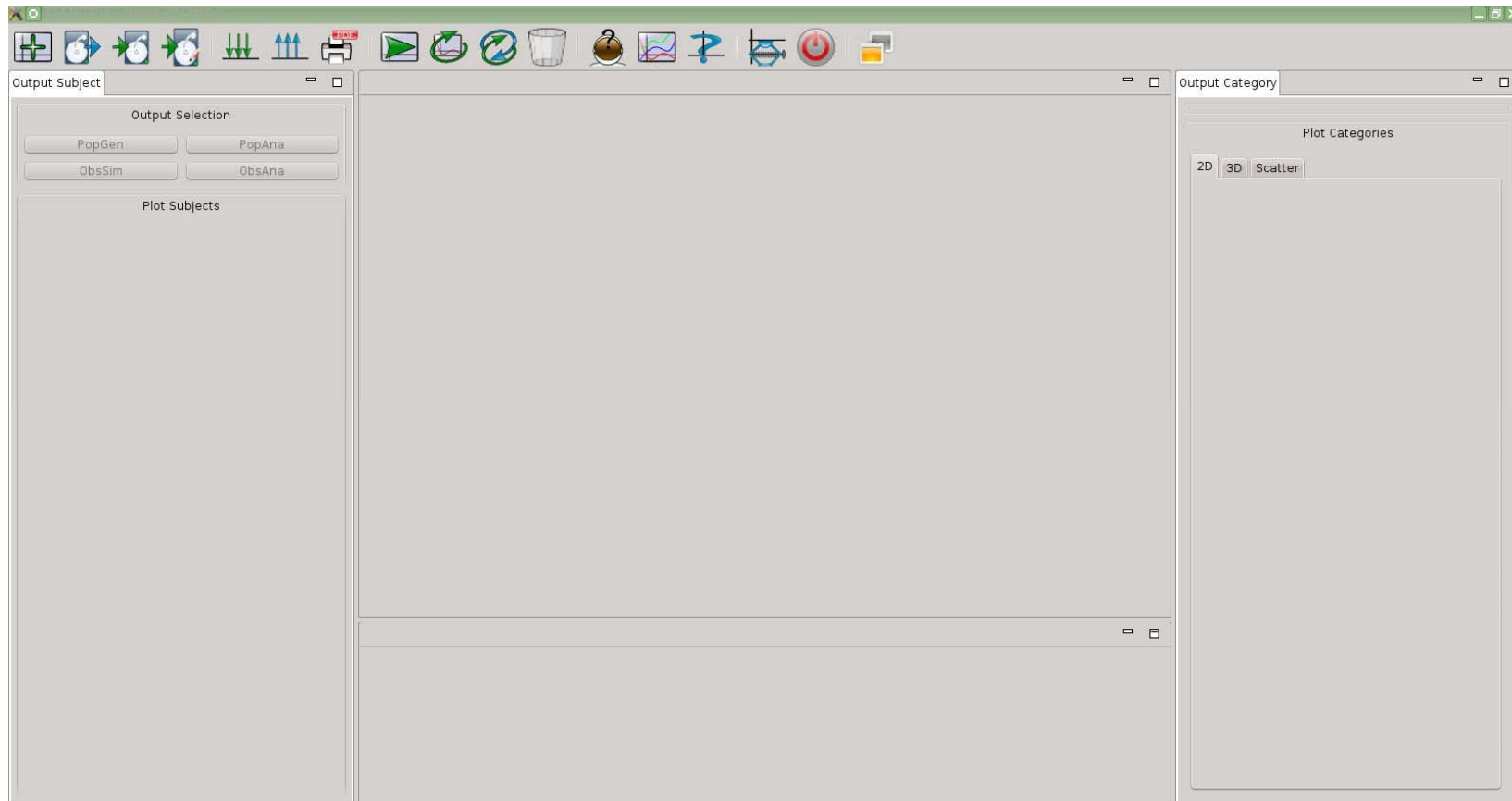


NEOPOP Demonstration

Backup 0

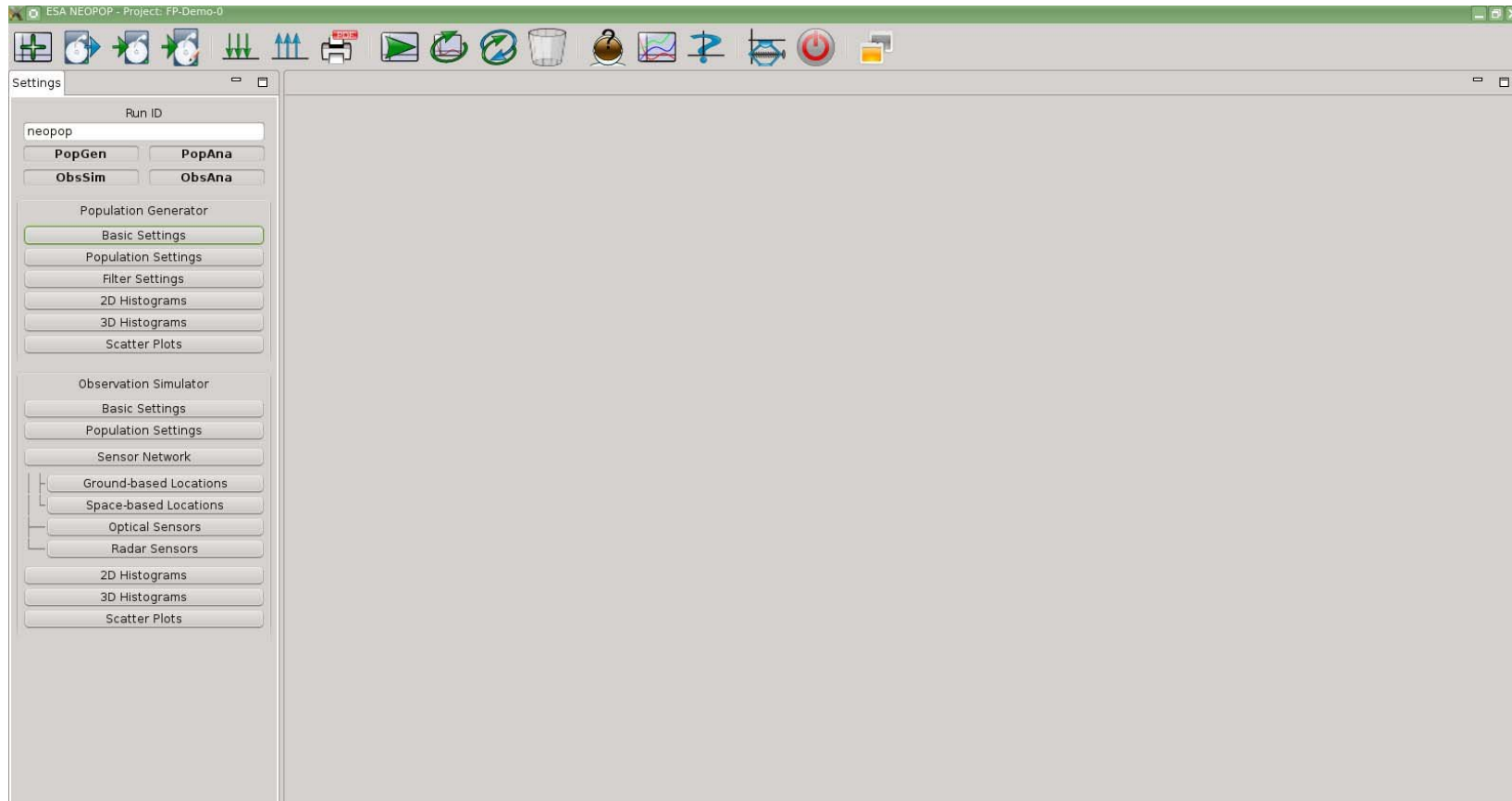


NEOPOP Demonstration Backup 1



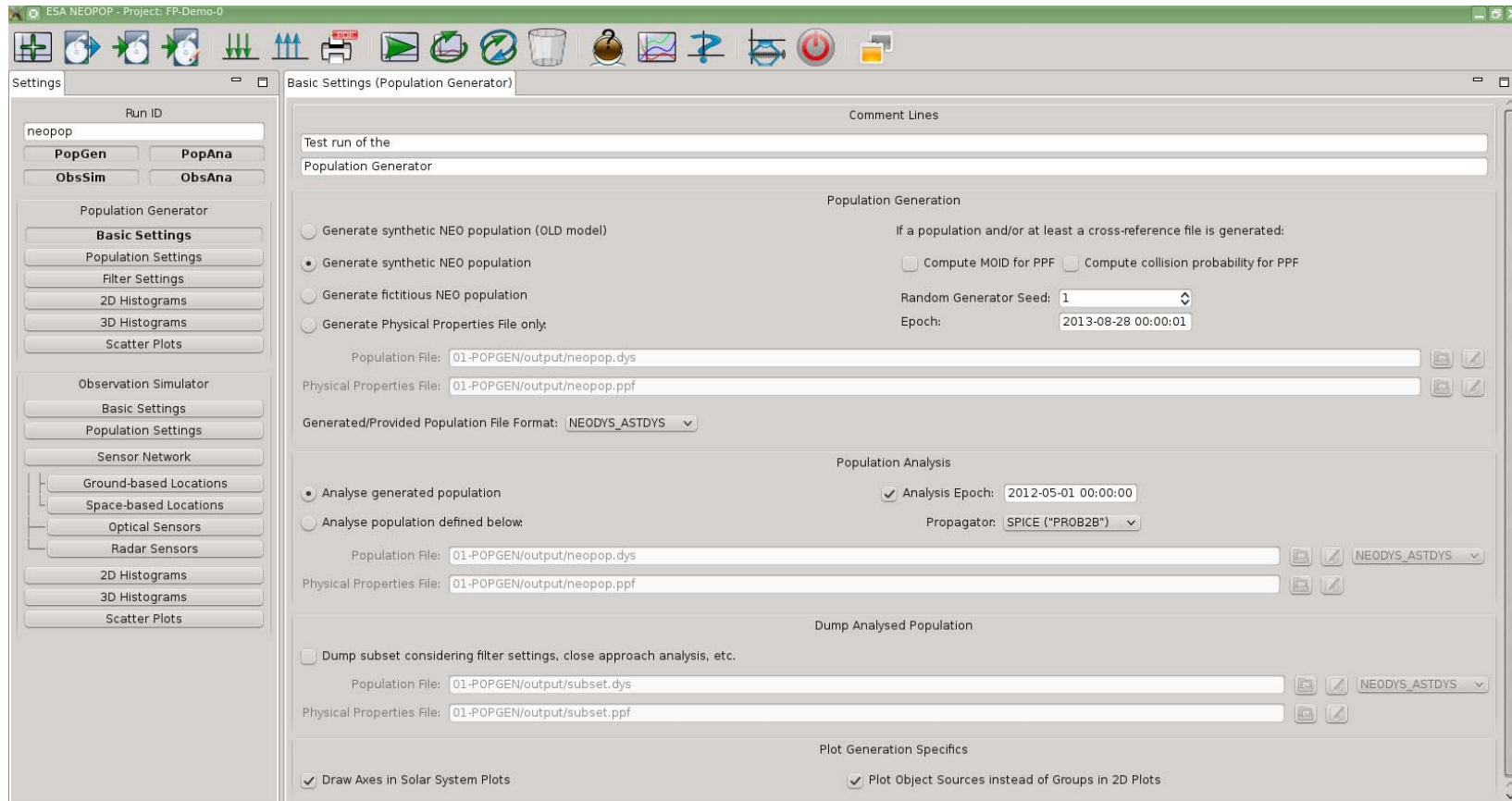
NEOPOP Demonstration

Backup 2



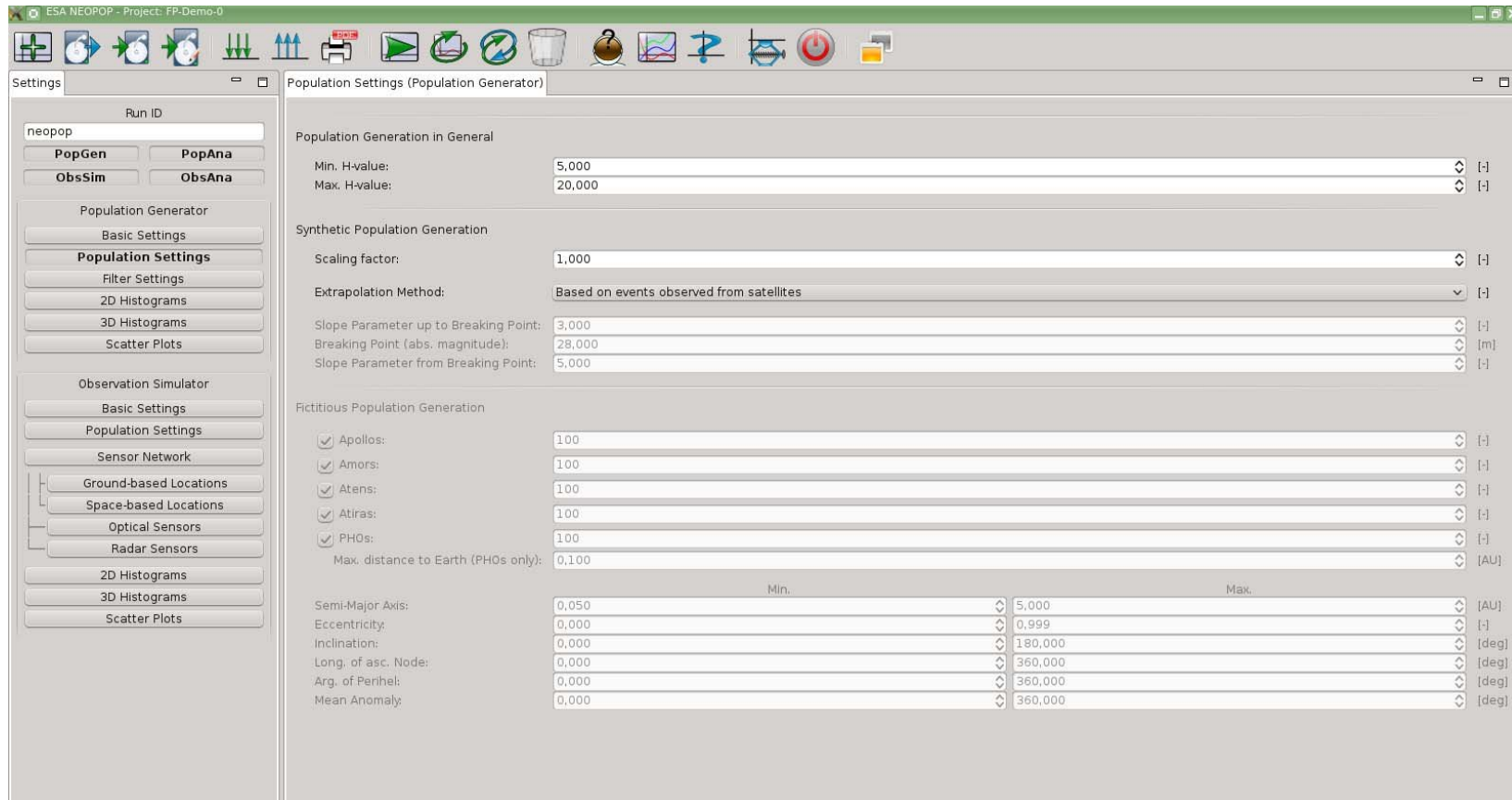
NEOPOP Demonstration

Backup 3



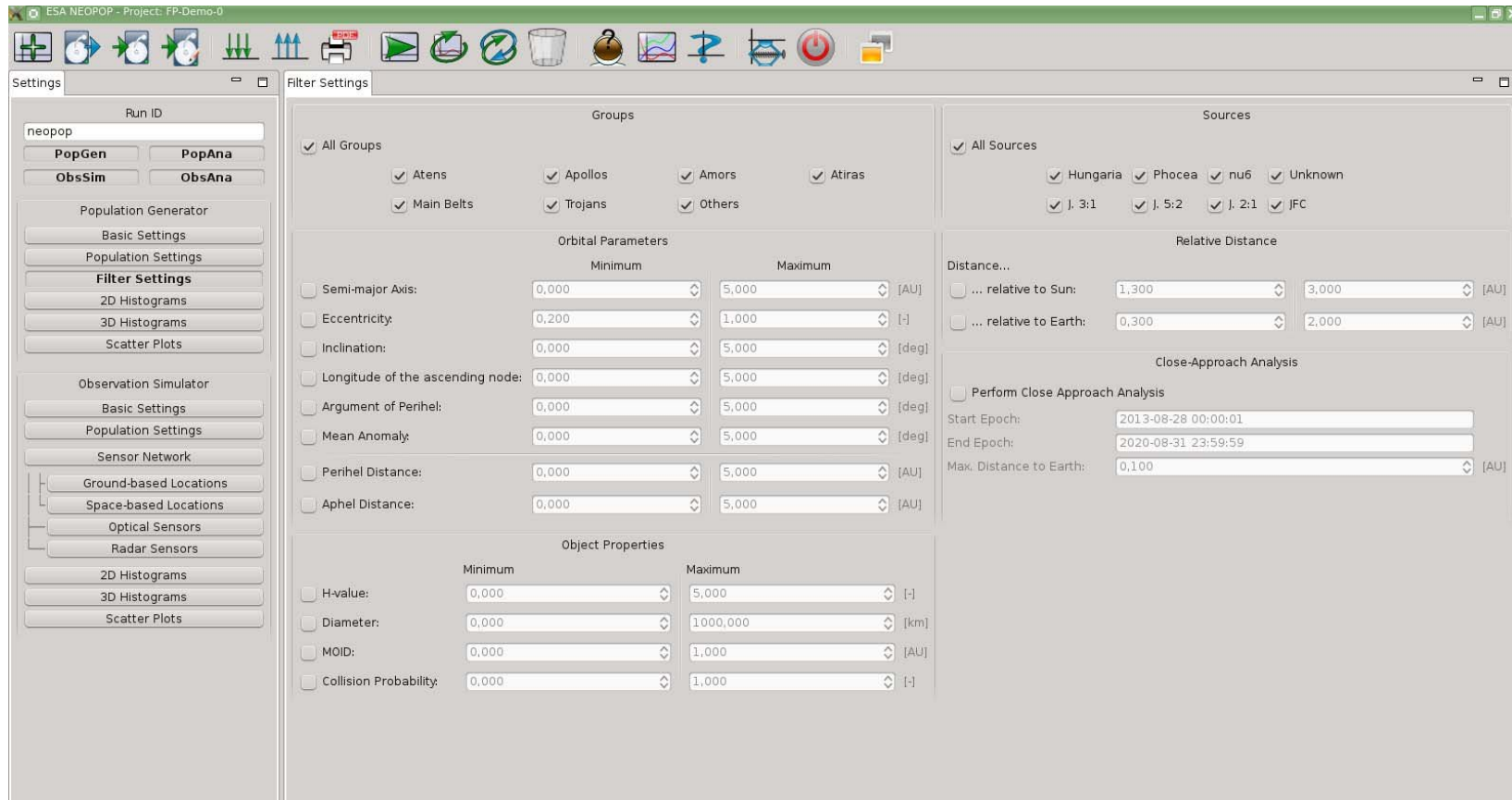
NEOPOP Demonstration

Backup 4



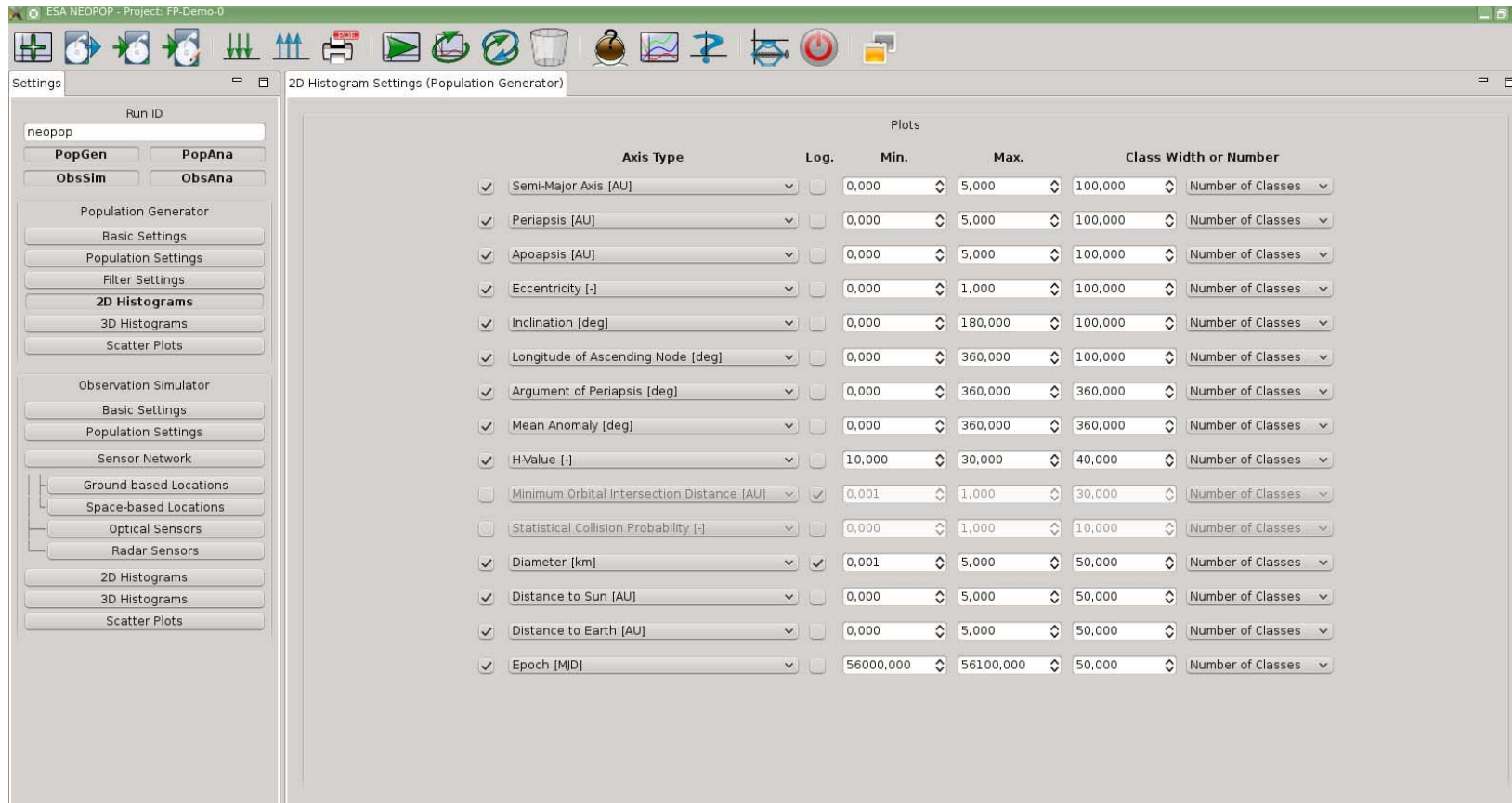
NEOPOP Demonstration Backup

Backup 5



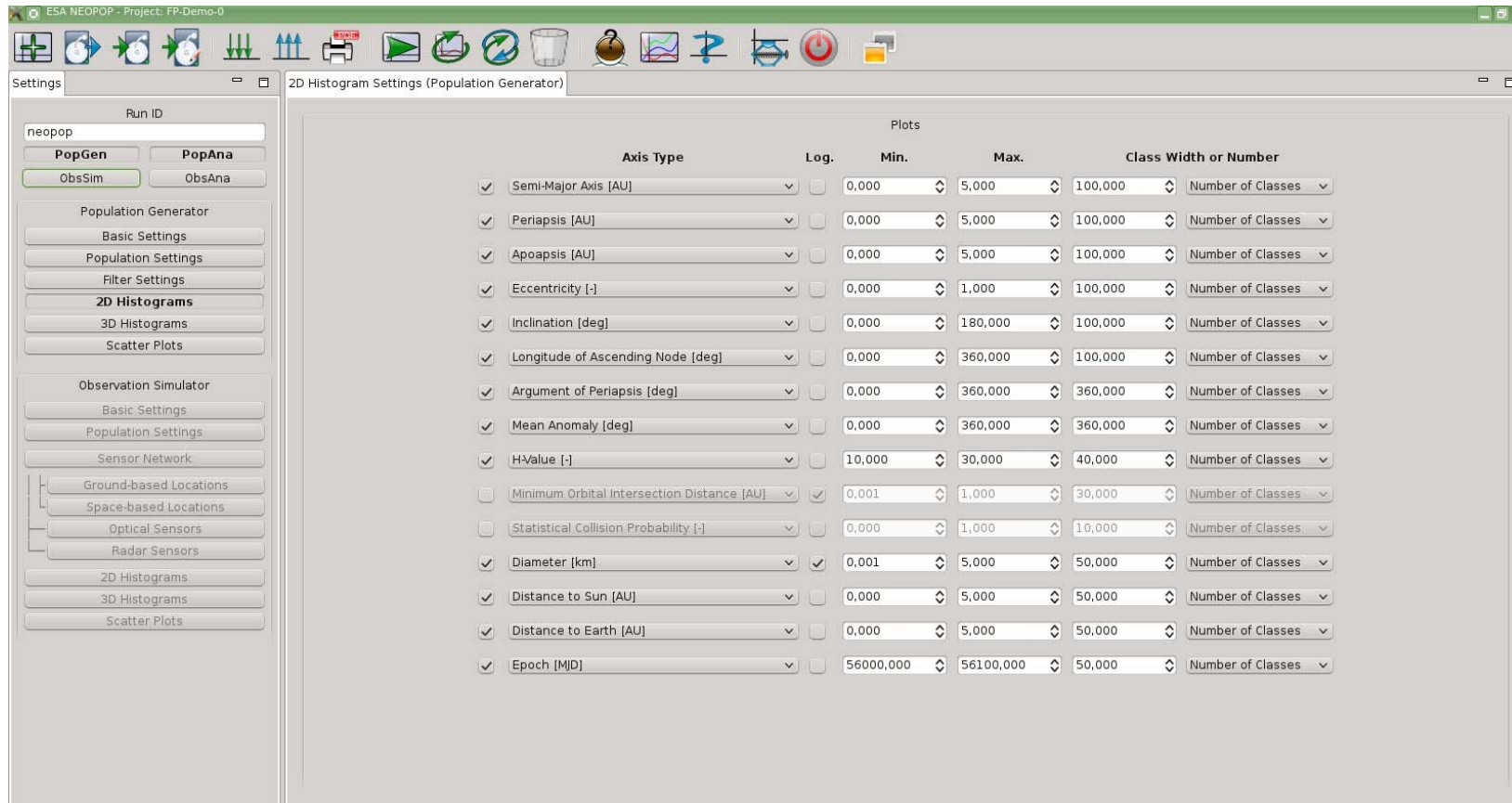
NEOPOP Demonstration

Backup 6



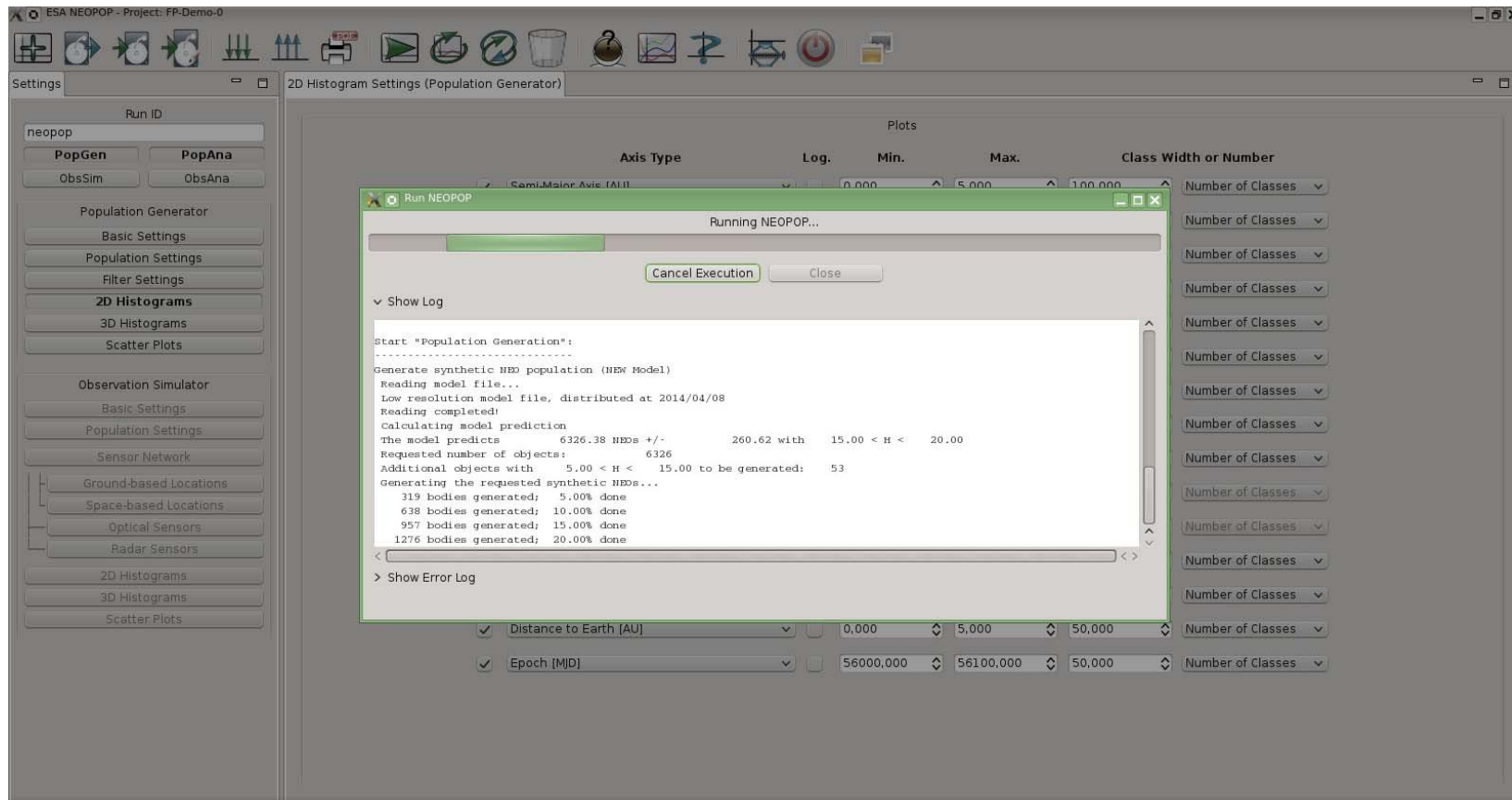
NEOPOP Demonstration

Backup 7



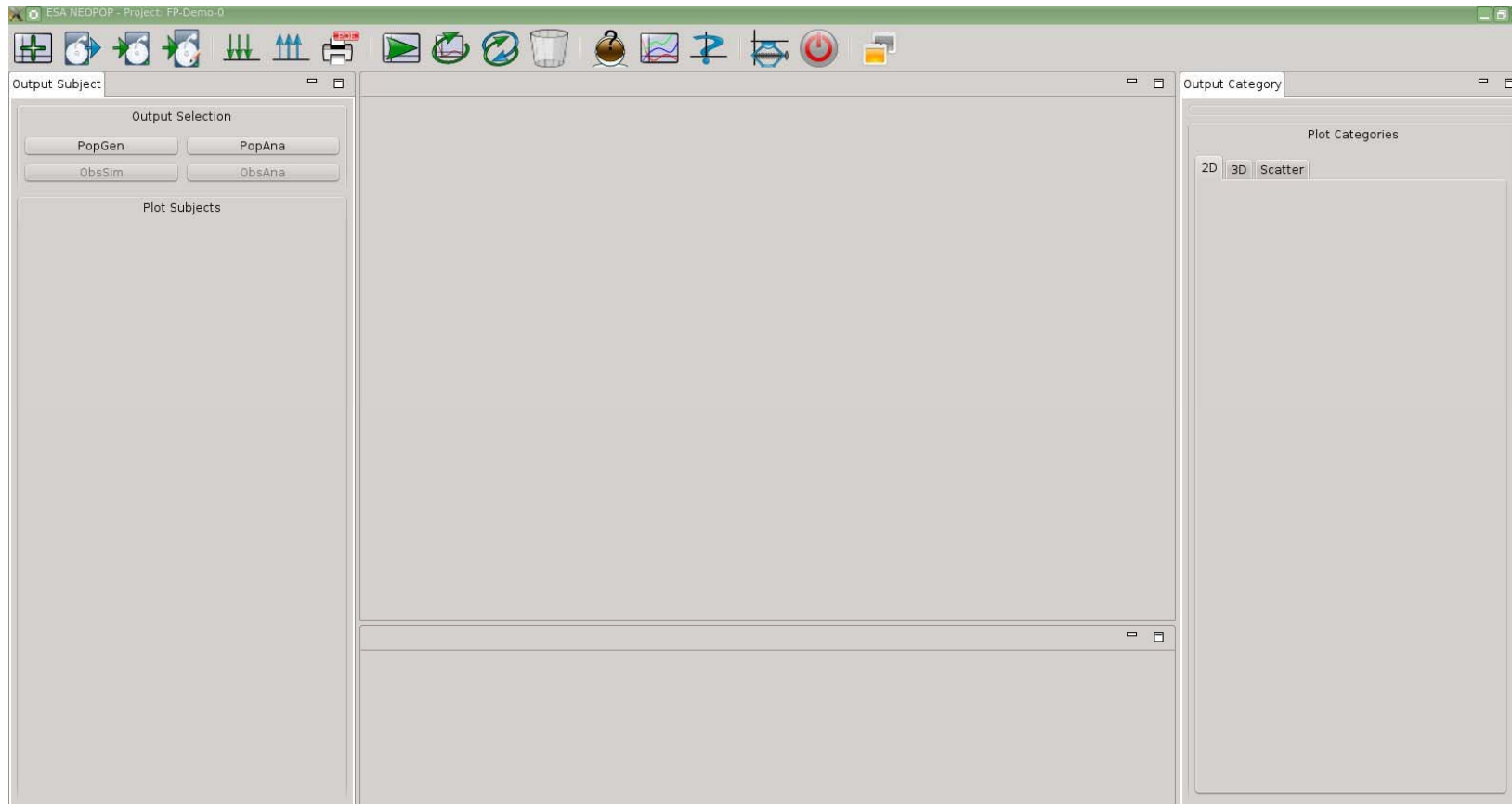
NEOPOP Demonstration

Backup 8



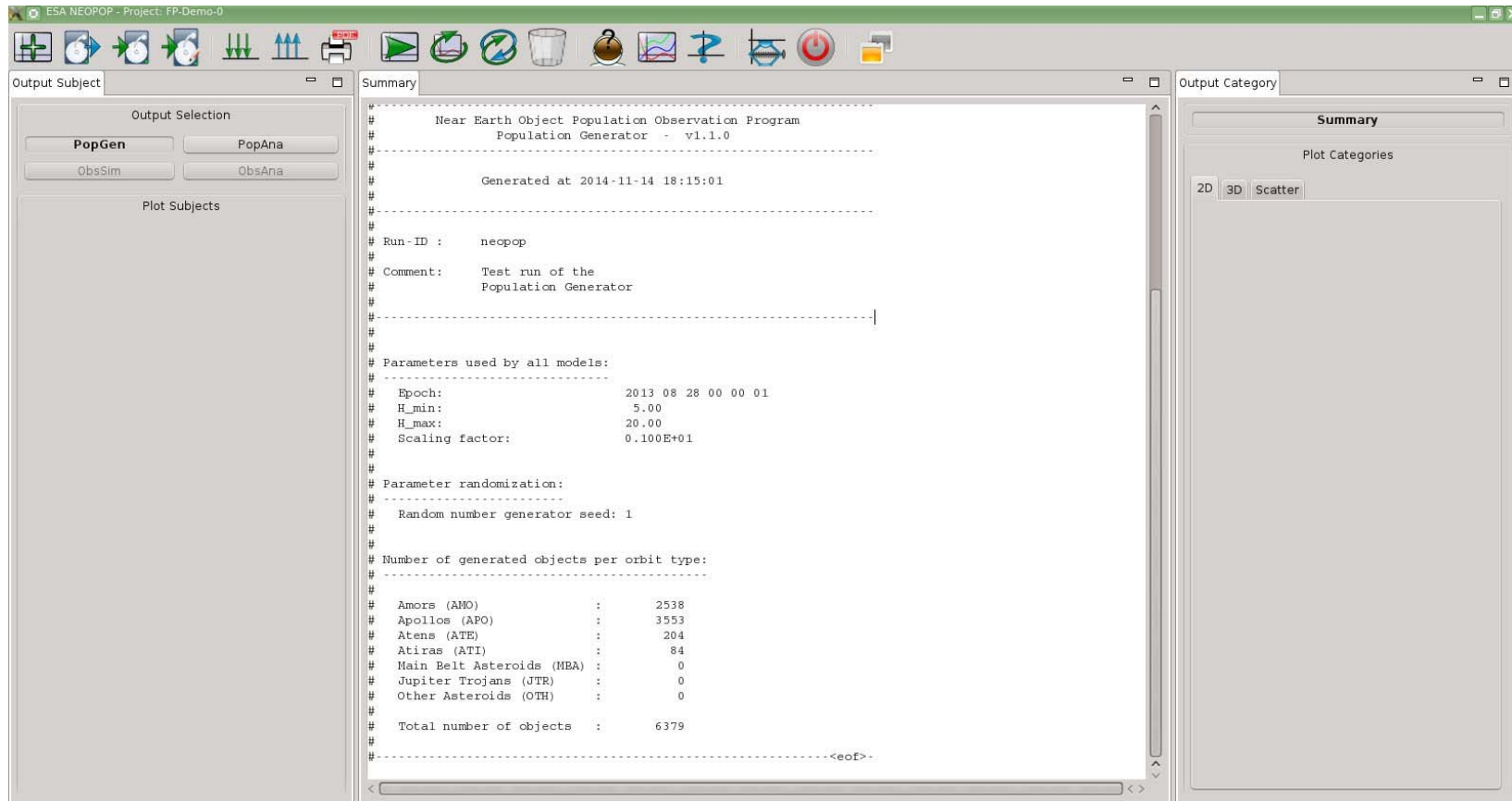
NEOPOP Demonstration

Backup 9



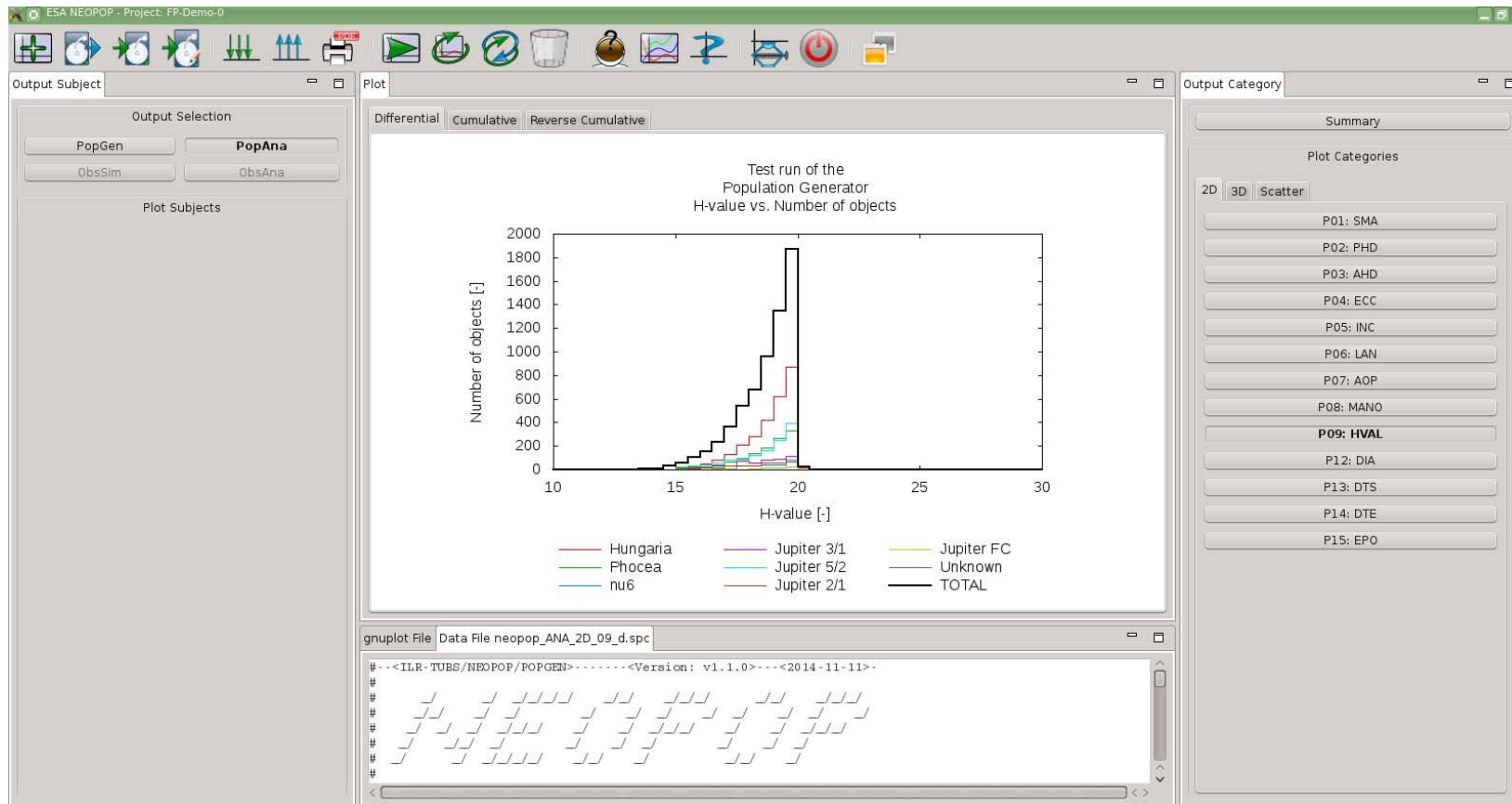
NEOPOP Demonstration

Backup 10



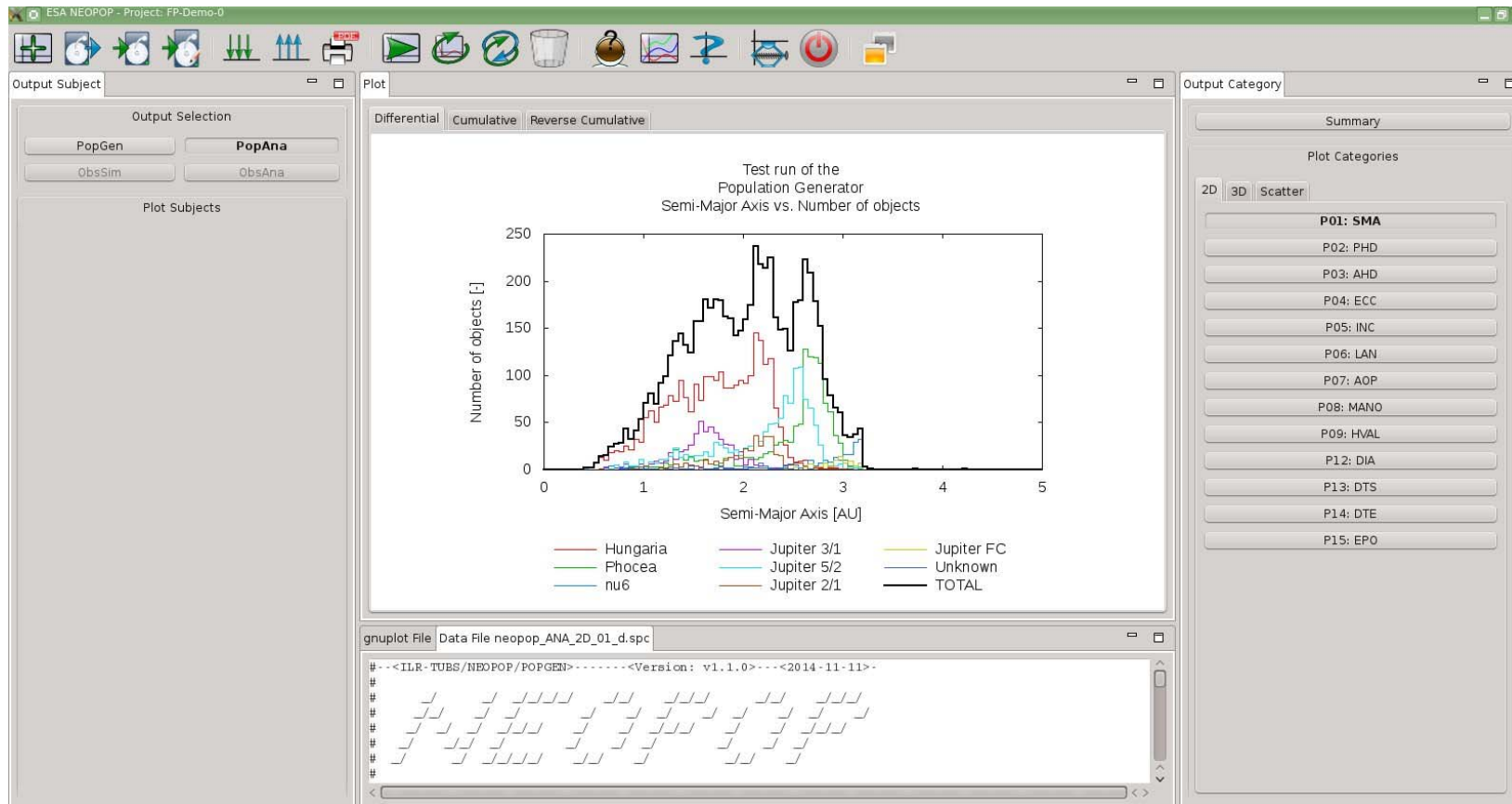
NEOPOP Demonstration

Backup 11



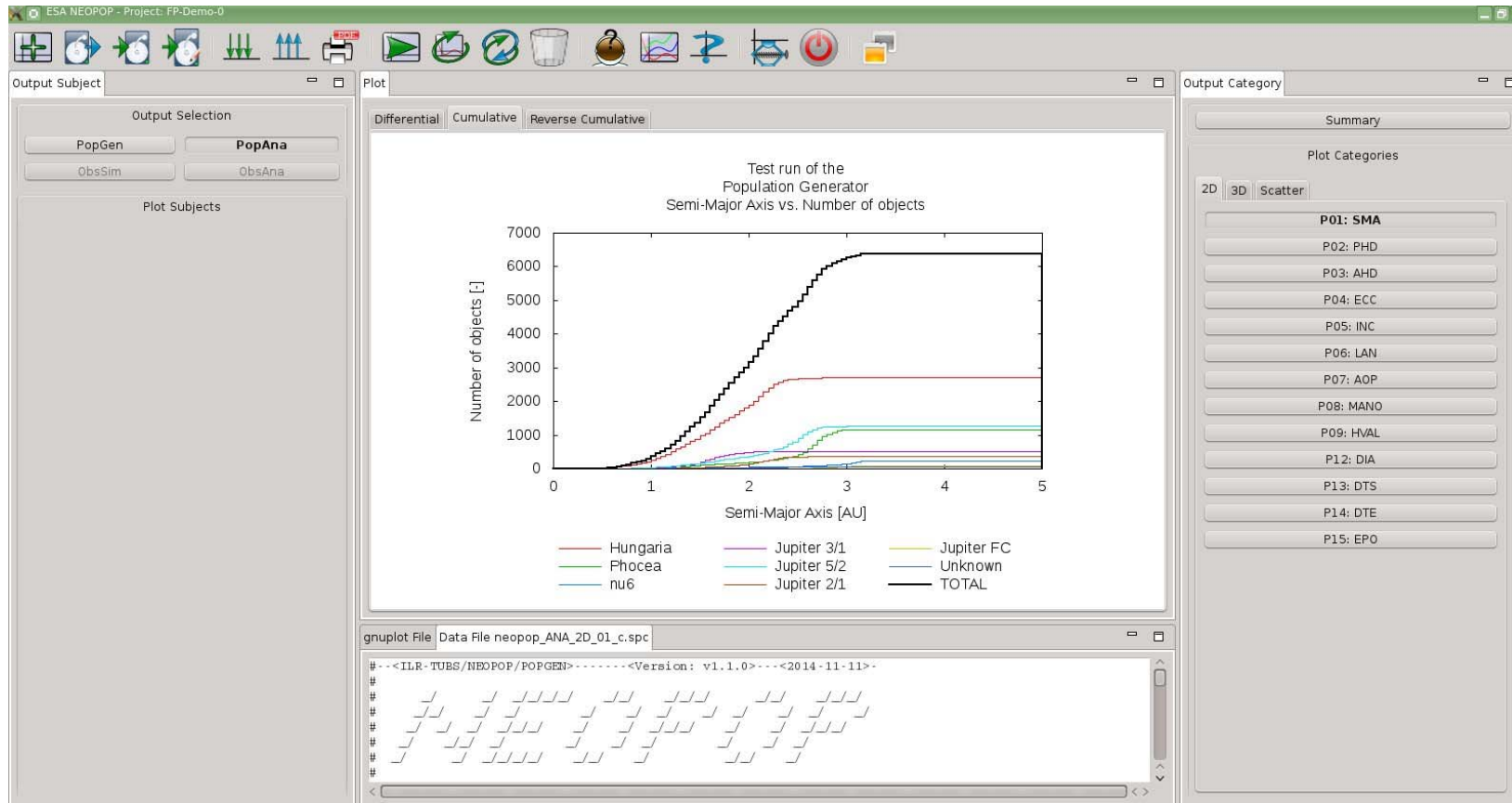
NEOPOP Demonstration

Backup 12



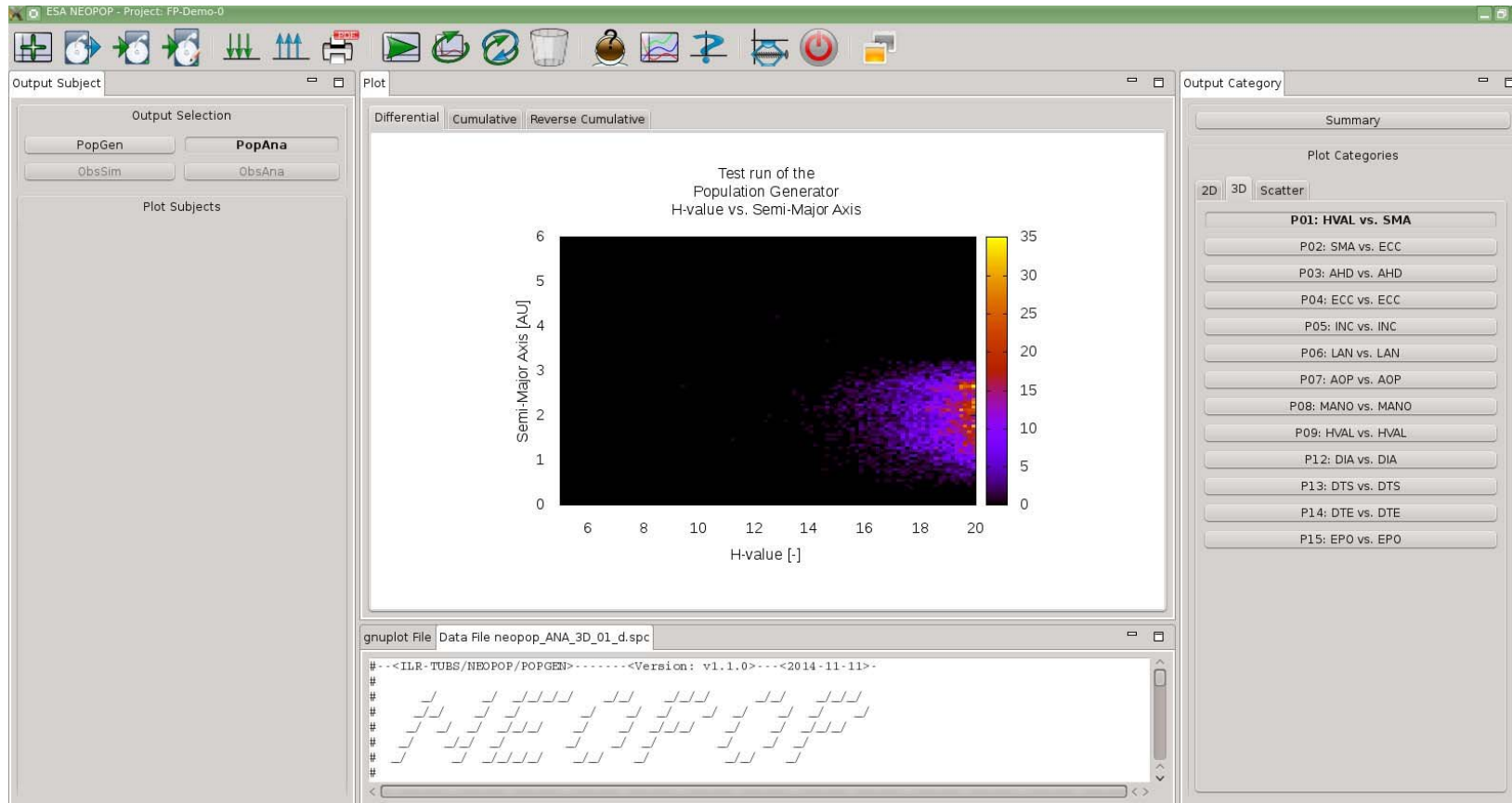
NEOPOP Demonstration

Backup 13



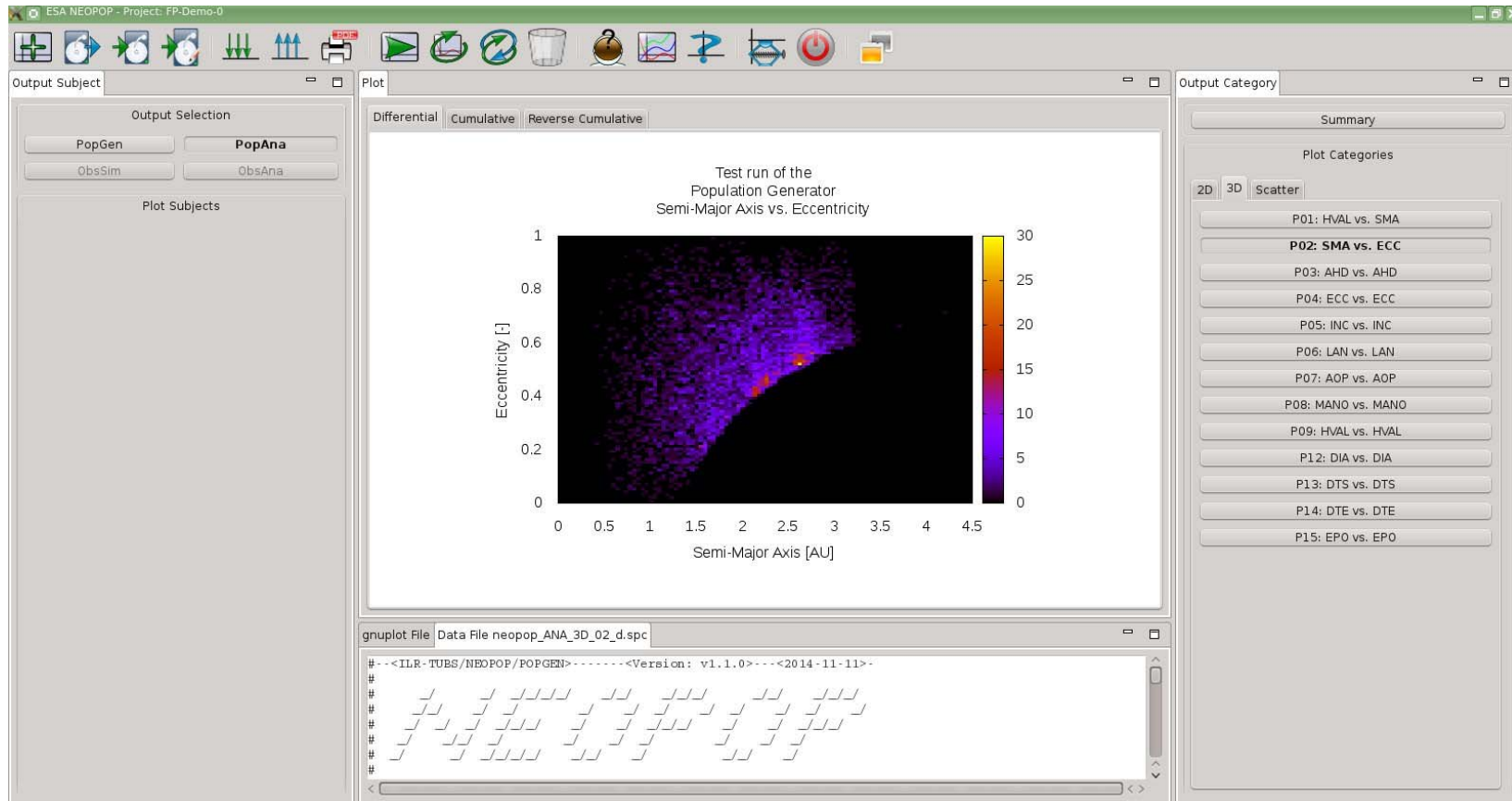
NEOPOP Demonstration

Backup 14



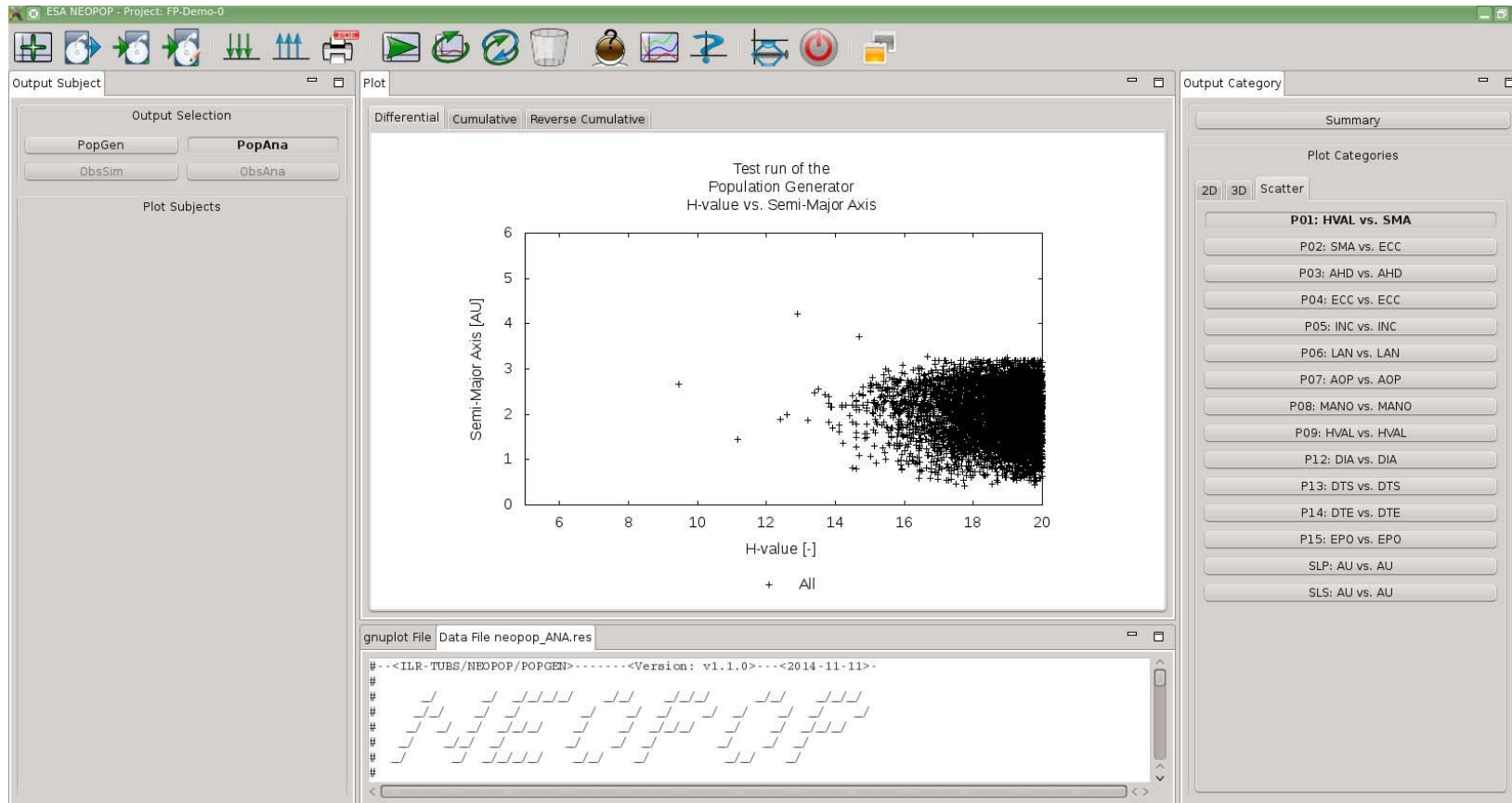
NEOPOP Demonstration

Backup 15



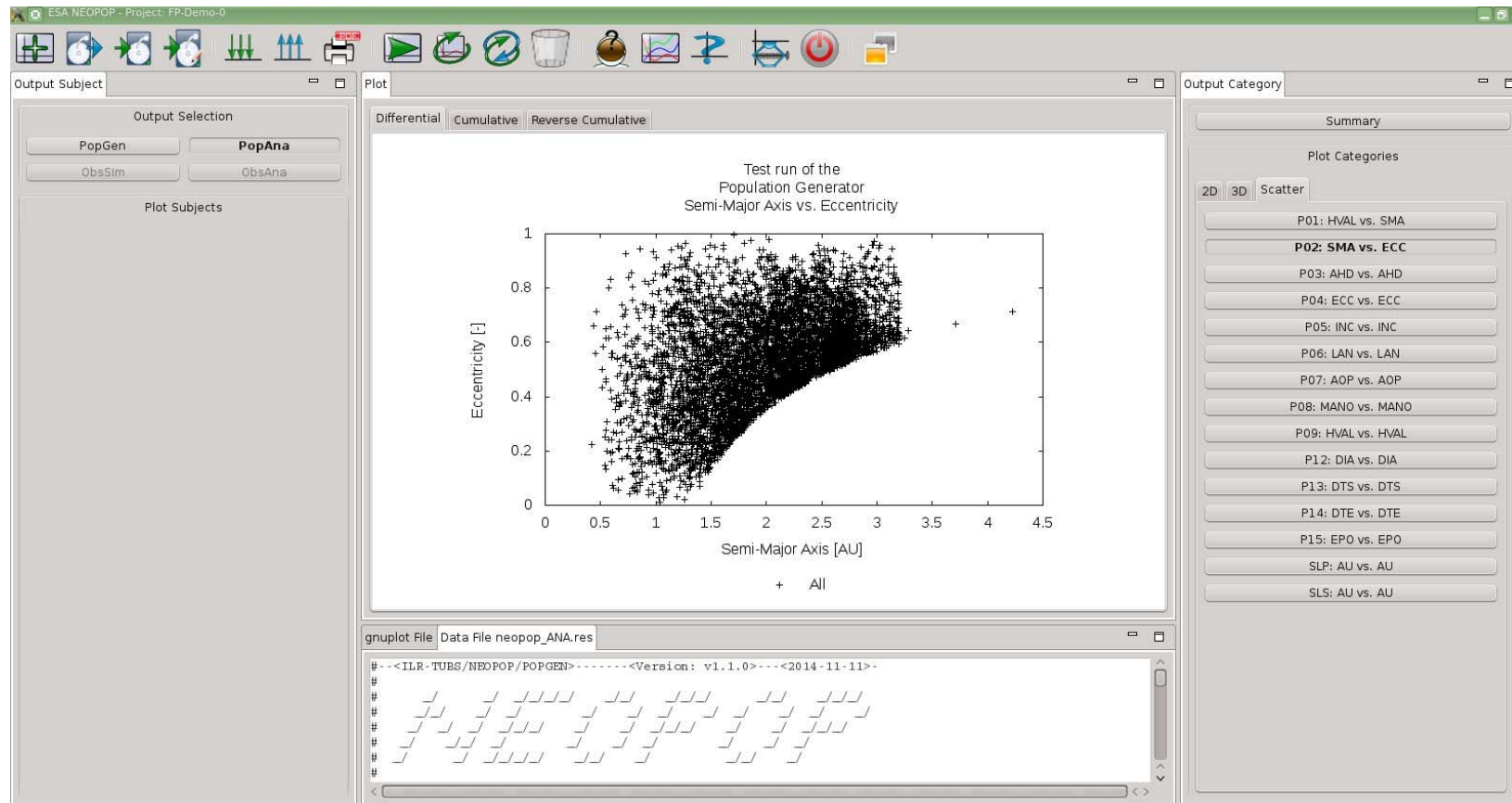
NEOPOP Demonstration

Backup 16



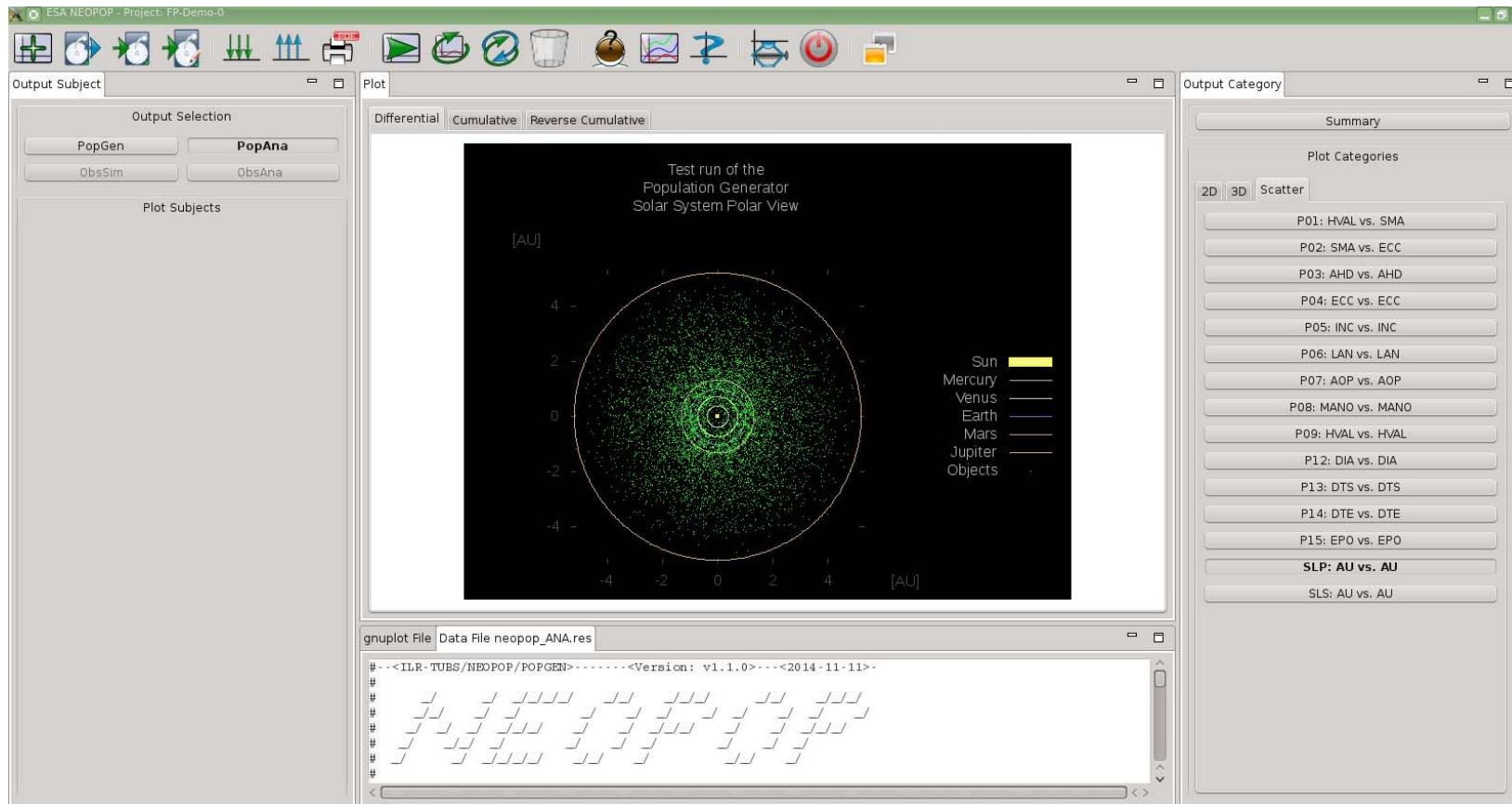
NEOPOP Demonstration

Backup 17



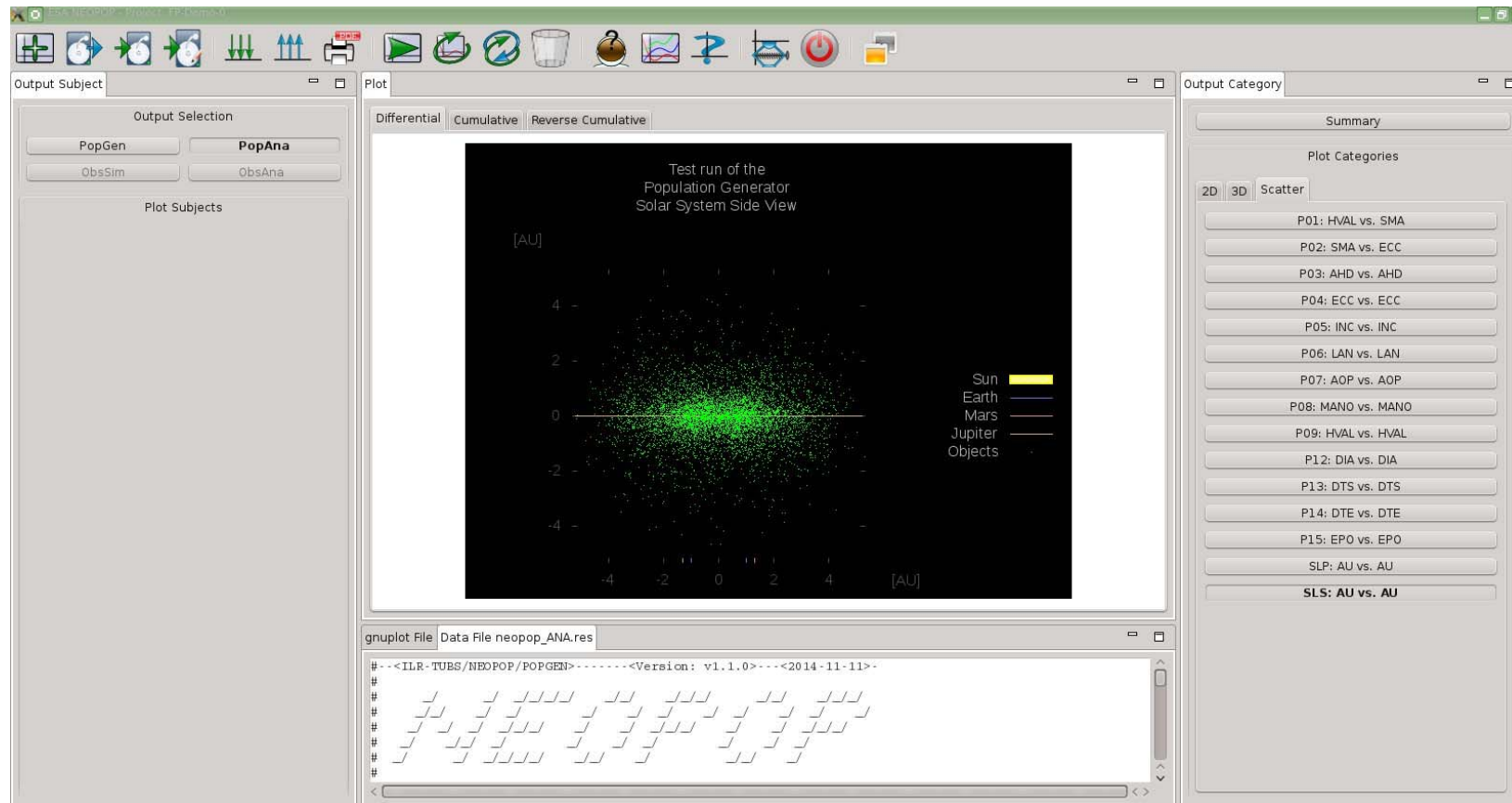
NEOPOP Demonstration

Backup 18



NEOPOP Demonstration

Backup 19



NEOPOP Demonstration

Backup 20

ESA NEOPOP - Project: FP-Demo-0

Settings | 2D Histogram Settings (Population Generator)

Run ID: neopop

PopGen | PopAna
ObsSim | ObsAna

Population Generator

- Basic Settings
- Population Settings
- Filter Settings
- 2D Histograms**
- 3D Histograms
- Scatter Plots

Observation Simulator

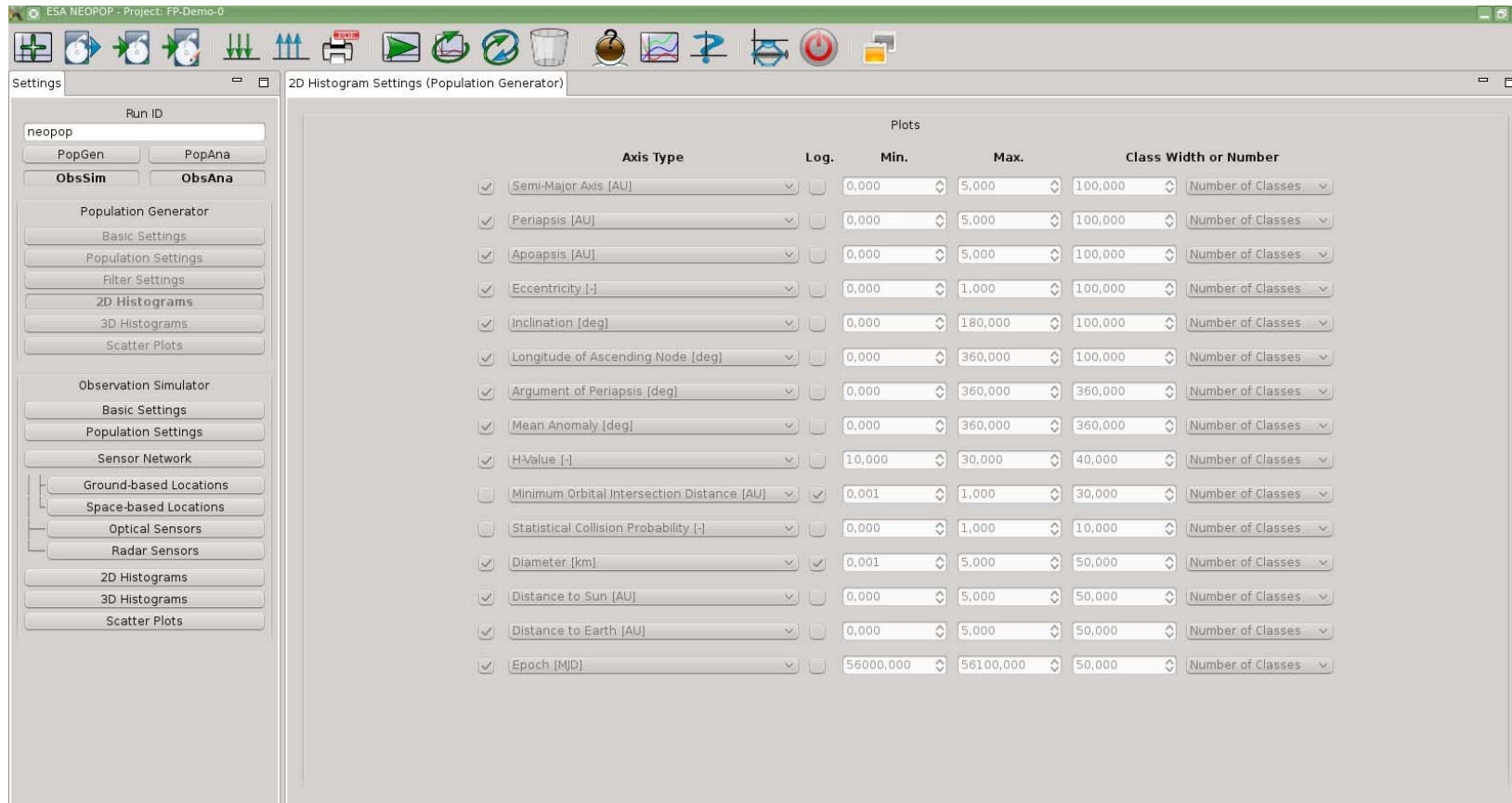
- Basic Settings
- Population Settings
- Sensor Network
 - Ground-based Locations
 - Space-based Locations
 - Optical Sensors
 - Radar Sensors
- 2D Histograms
- 3D Histograms
- Scatter Plots

Plots

Axis Type	Log.	Min.	Max.	Class Width or Number
<input checked="" type="checkbox"/> Semi-Major Axis [AU]	<input type="checkbox"/>	0,000	5,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Periapsis [AU]	<input type="checkbox"/>	0,000	5,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Apoapsis [AU]	<input type="checkbox"/>	0,000	5,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Eccentricity [-]	<input type="checkbox"/>	0,000	1,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Inclination [deg]	<input type="checkbox"/>	0,000	180,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Longitude of Ascending Node [deg]	<input type="checkbox"/>	0,000	360,000	100,000 Number of Classes
<input checked="" type="checkbox"/> Argument of Periapsis [deg]	<input type="checkbox"/>	0,000	360,000	360,000 Number of Classes
<input checked="" type="checkbox"/> Mean Anomaly [deg]	<input type="checkbox"/>	0,000	360,000	360,000 Number of Classes
<input checked="" type="checkbox"/> HValue [-]	<input type="checkbox"/>	10,000	30,000	40,000 Number of Classes
<input type="checkbox"/> Minimum Orbital Intersection Distance [AU]	<input checked="" type="checkbox"/>	0,001	1,000	30,000 Number of Classes
<input type="checkbox"/> Statistical Collision Probability [-]	<input type="checkbox"/>	0,000	1,000	10,000 Number of Classes
<input checked="" type="checkbox"/> Diameter [km]	<input checked="" type="checkbox"/>	0,001	5,000	50,000 Number of Classes
<input checked="" type="checkbox"/> Distance to Sun [AU]	<input type="checkbox"/>	0,000	5,000	50,000 Number of Classes
<input checked="" type="checkbox"/> Distance to Earth [AU]	<input type="checkbox"/>	0,000	5,000	50,000 Number of Classes
<input checked="" type="checkbox"/> Epoch [MJD]	<input type="checkbox"/>	56000,000	56100,000	50,000 Number of Classes

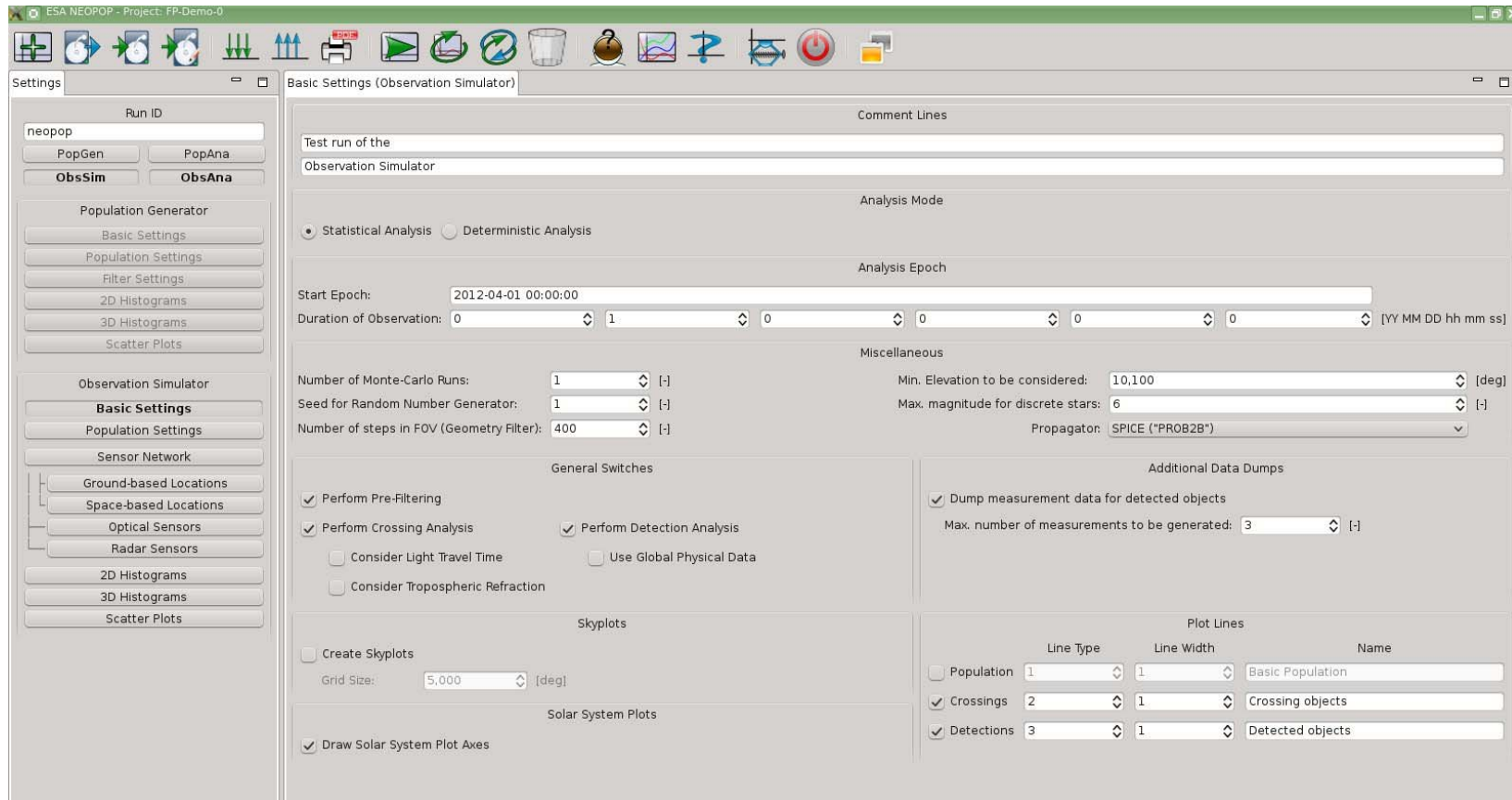
NEOPOP Demonstration

Backup 21



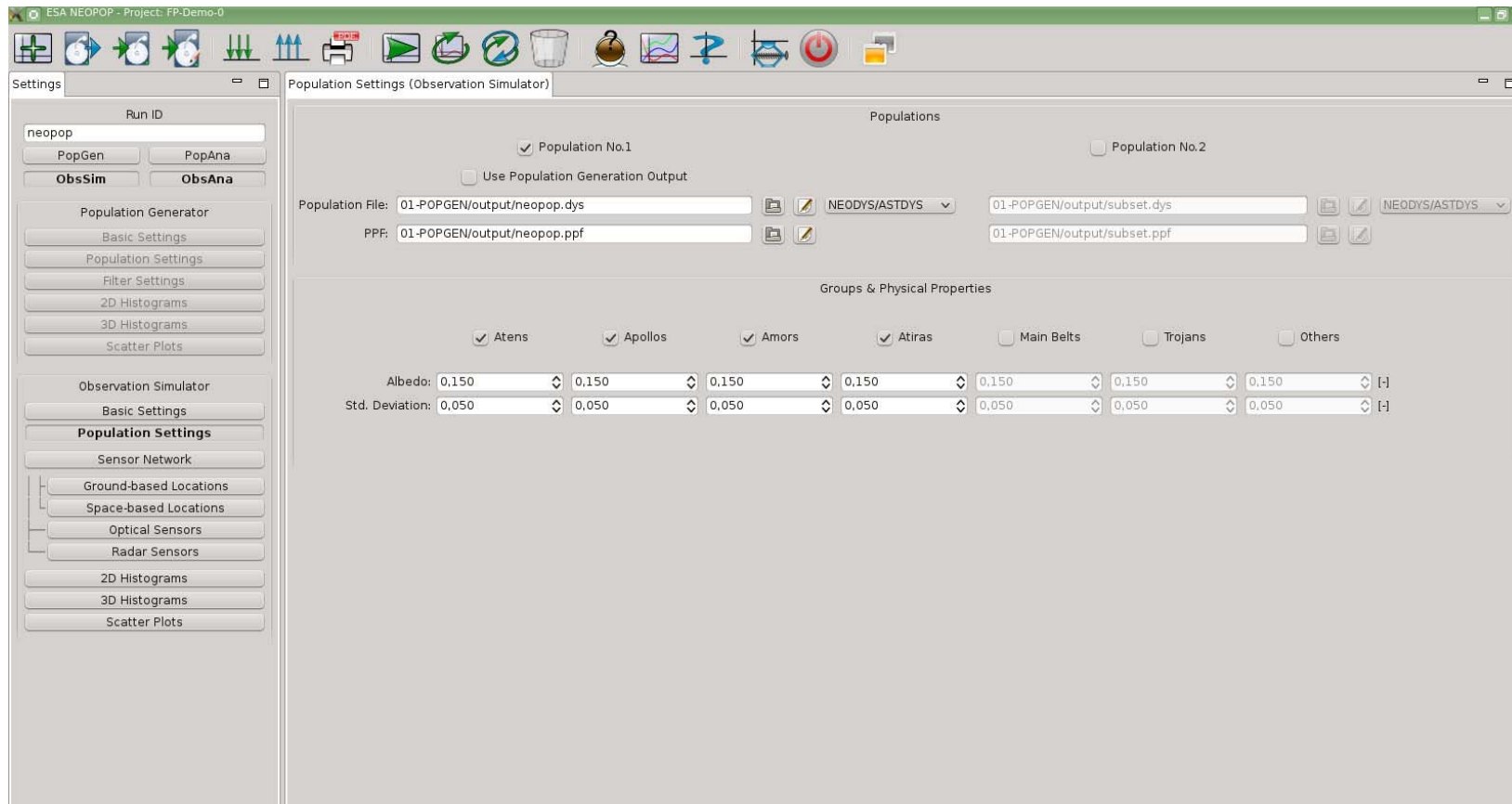
NEOPOP Demonstration

Backup 22



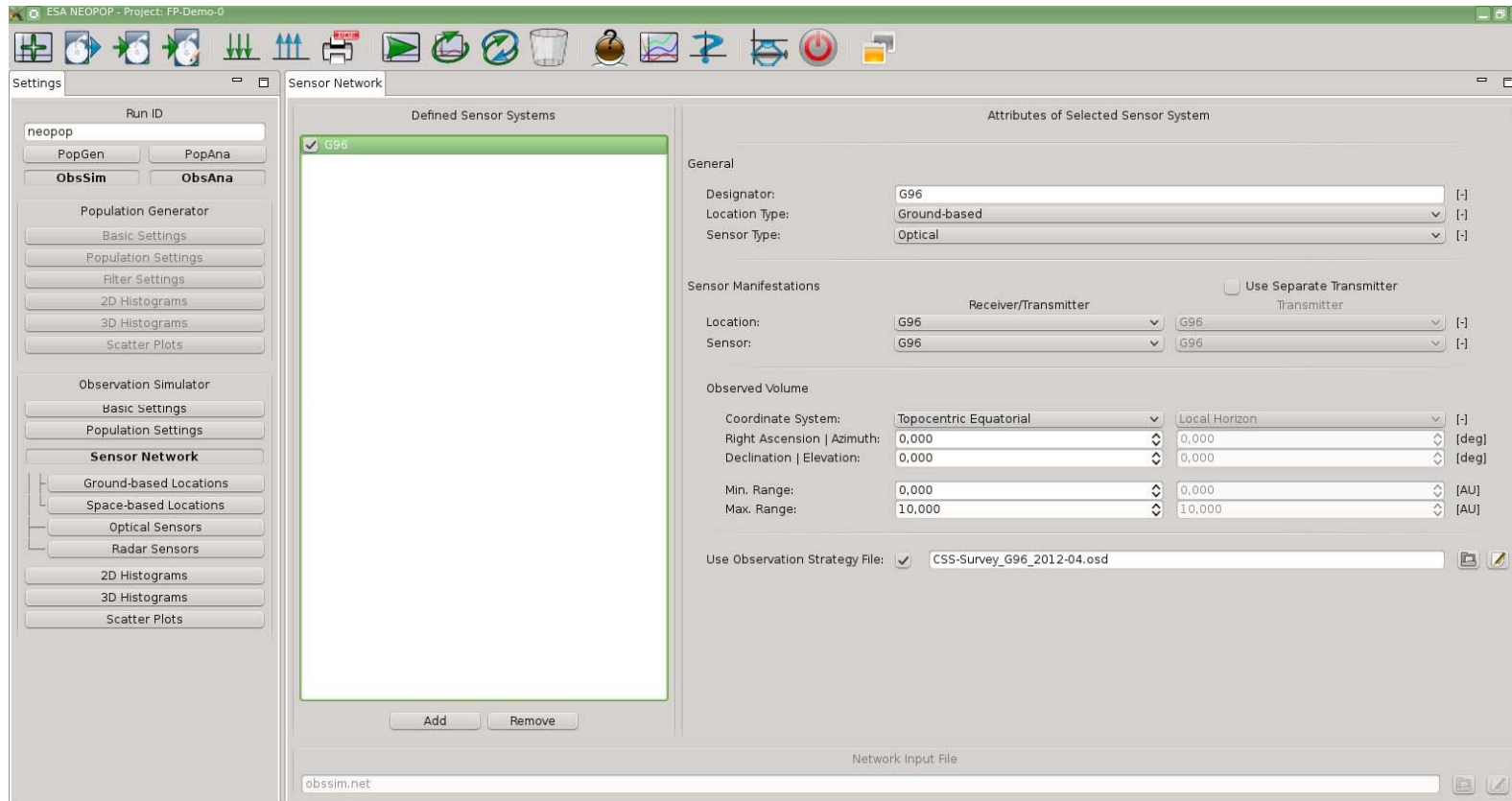
NEOPOP Demonstration

Backup 23



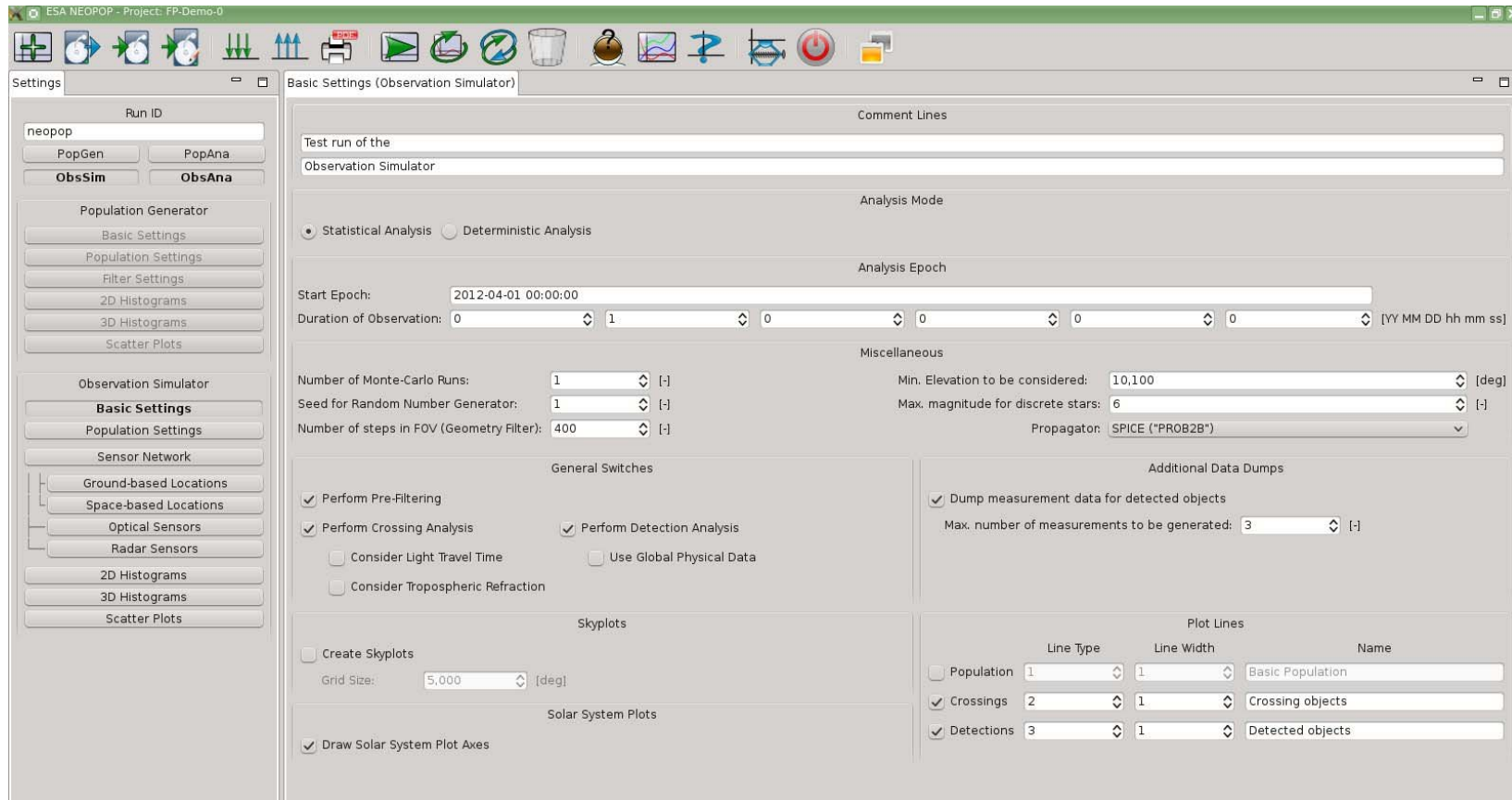
NEOPOP Demonstration

Backup 24



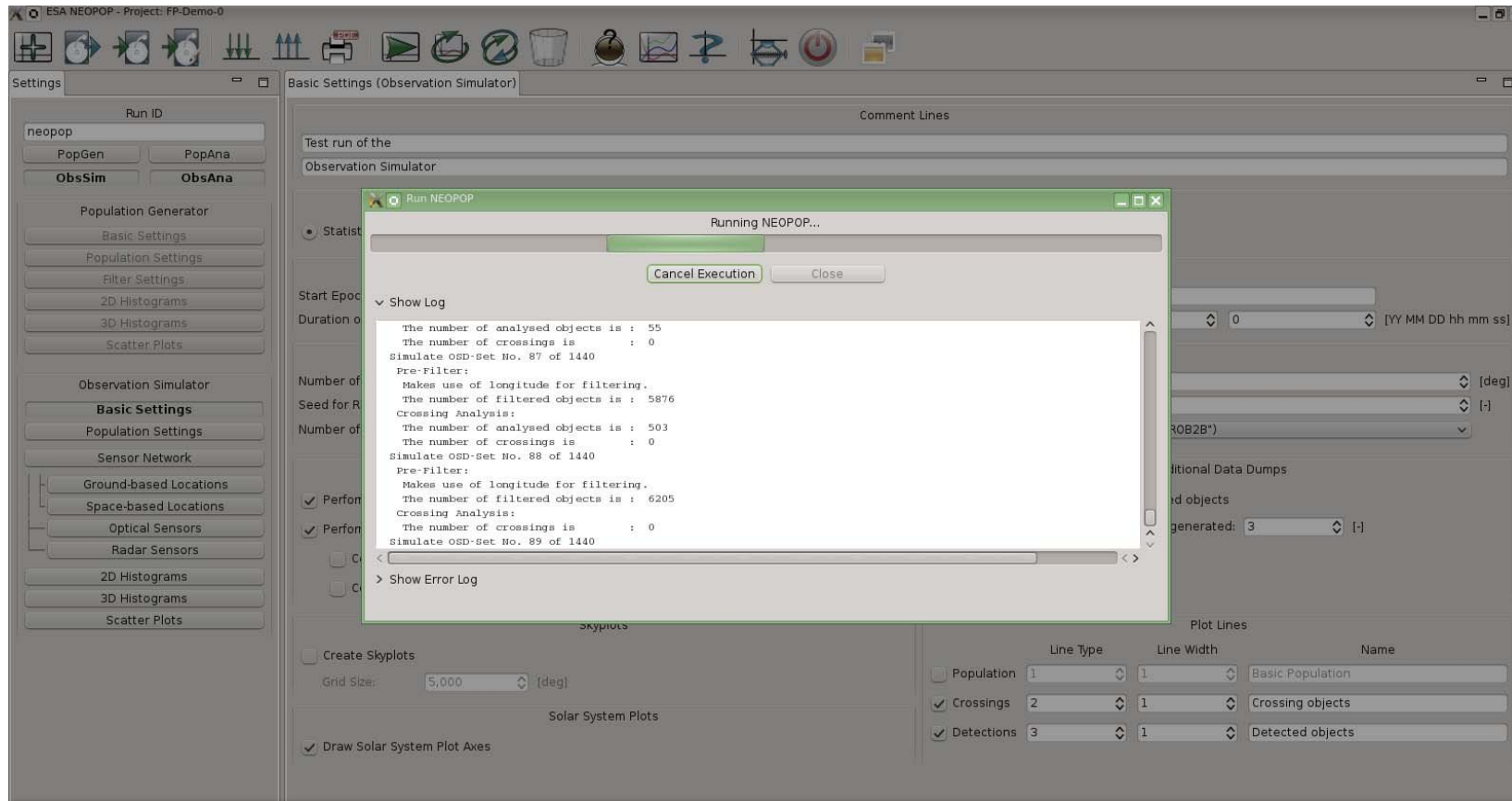
NEOPOP Demonstration

Backup 25



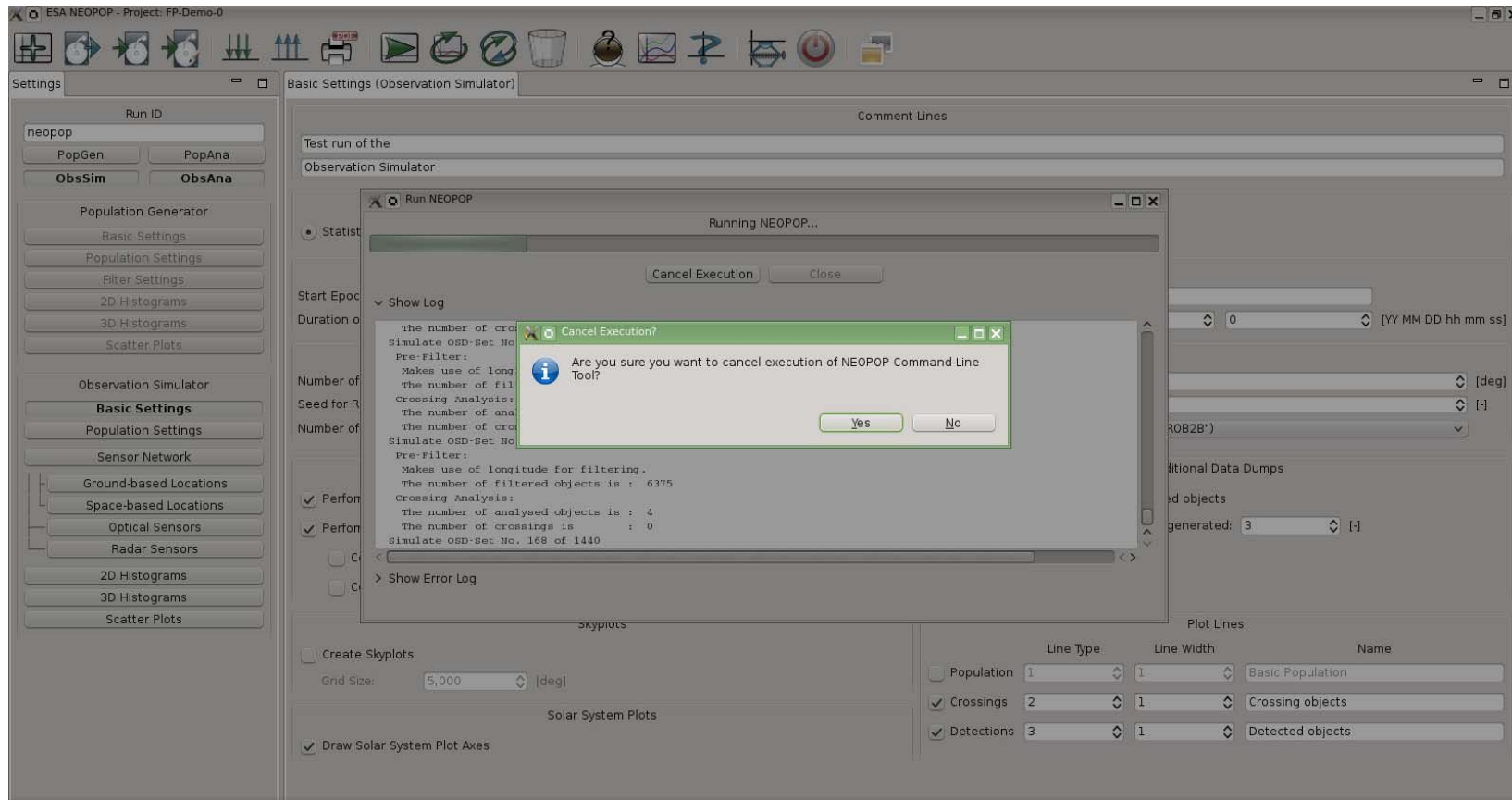
NEOPOP Demonstration

Backup 26



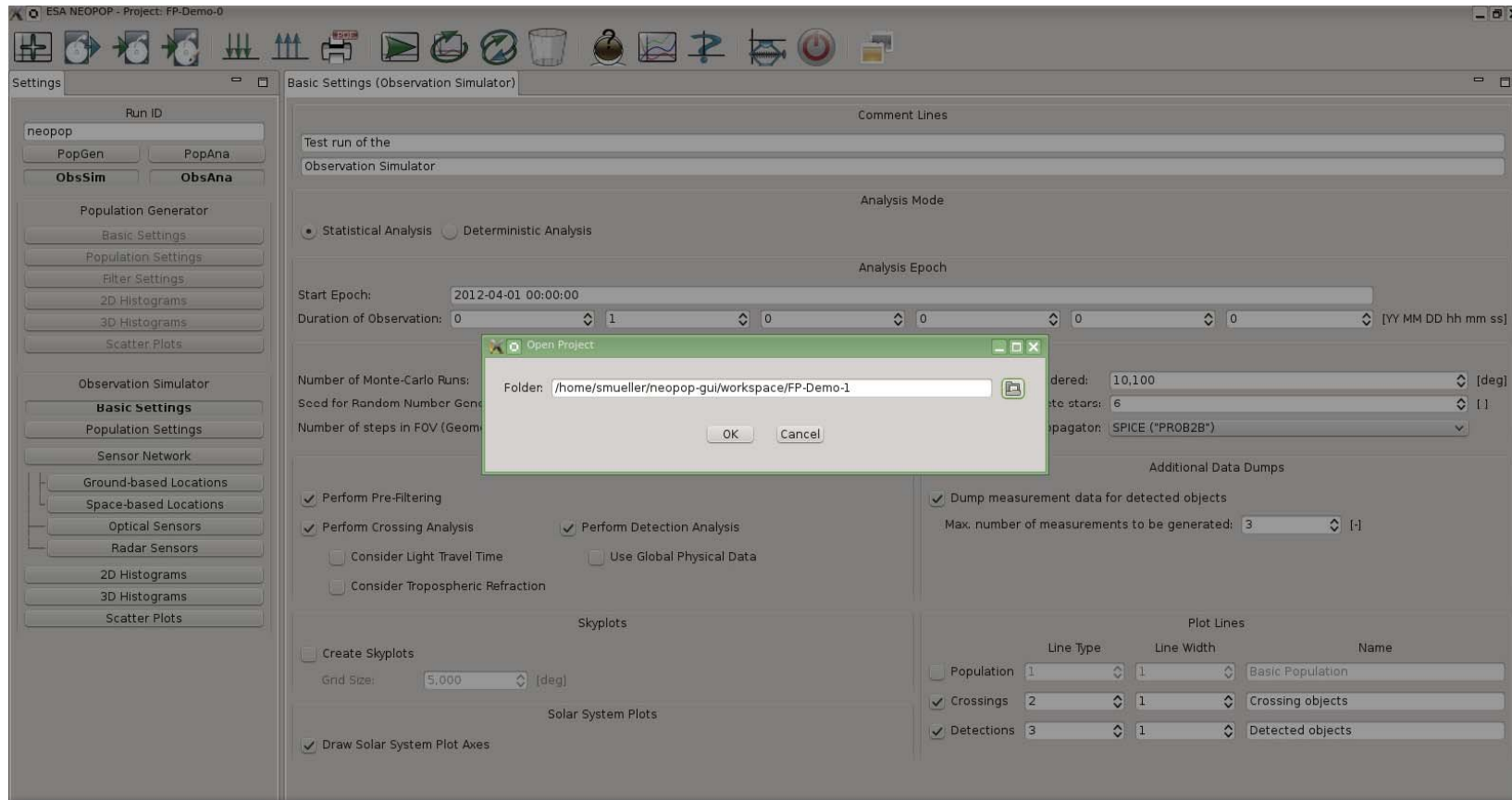
NEOPOP Demonstration

Backup 27



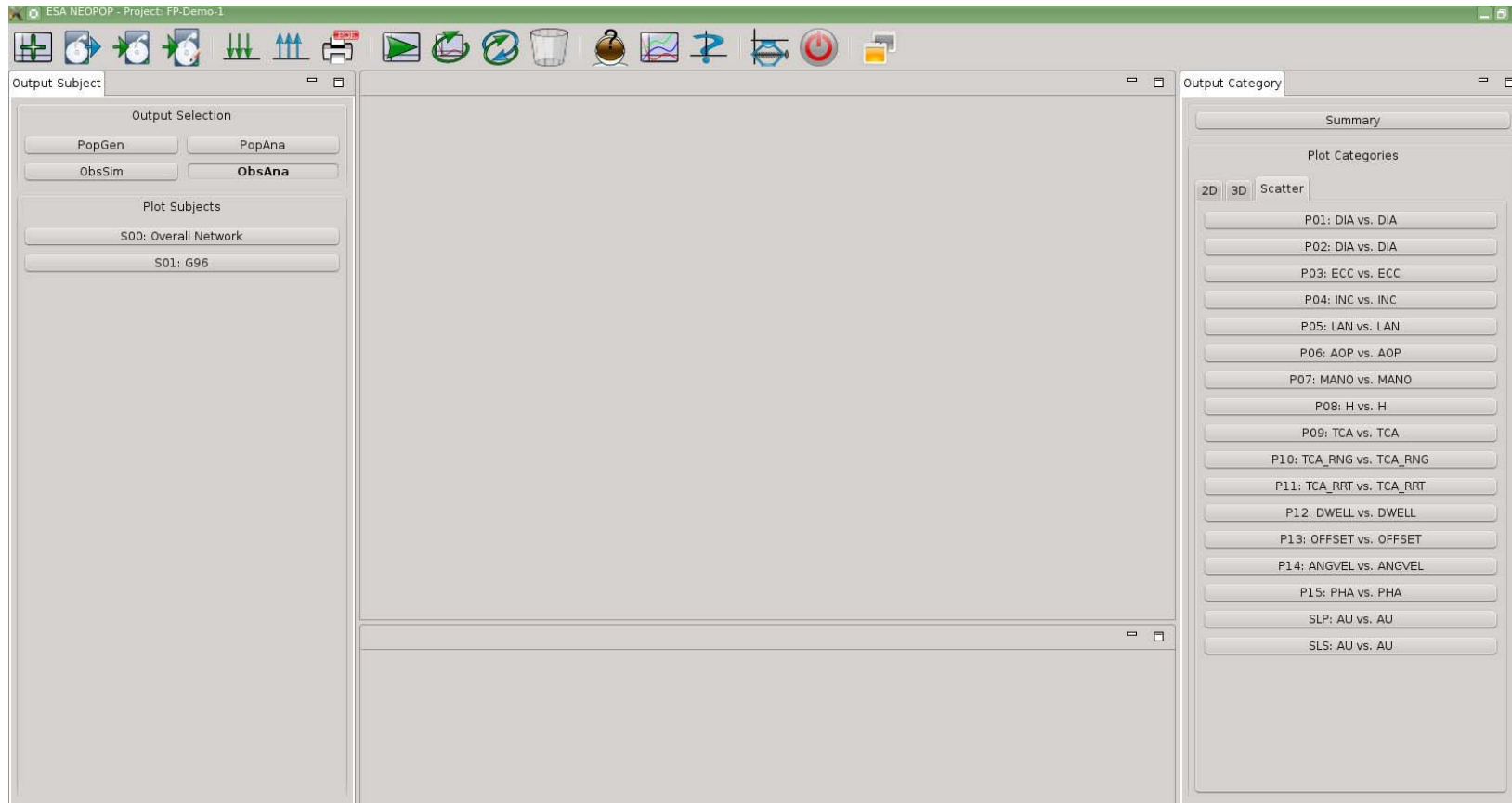
NEOPOP Demonstration

Backup 28



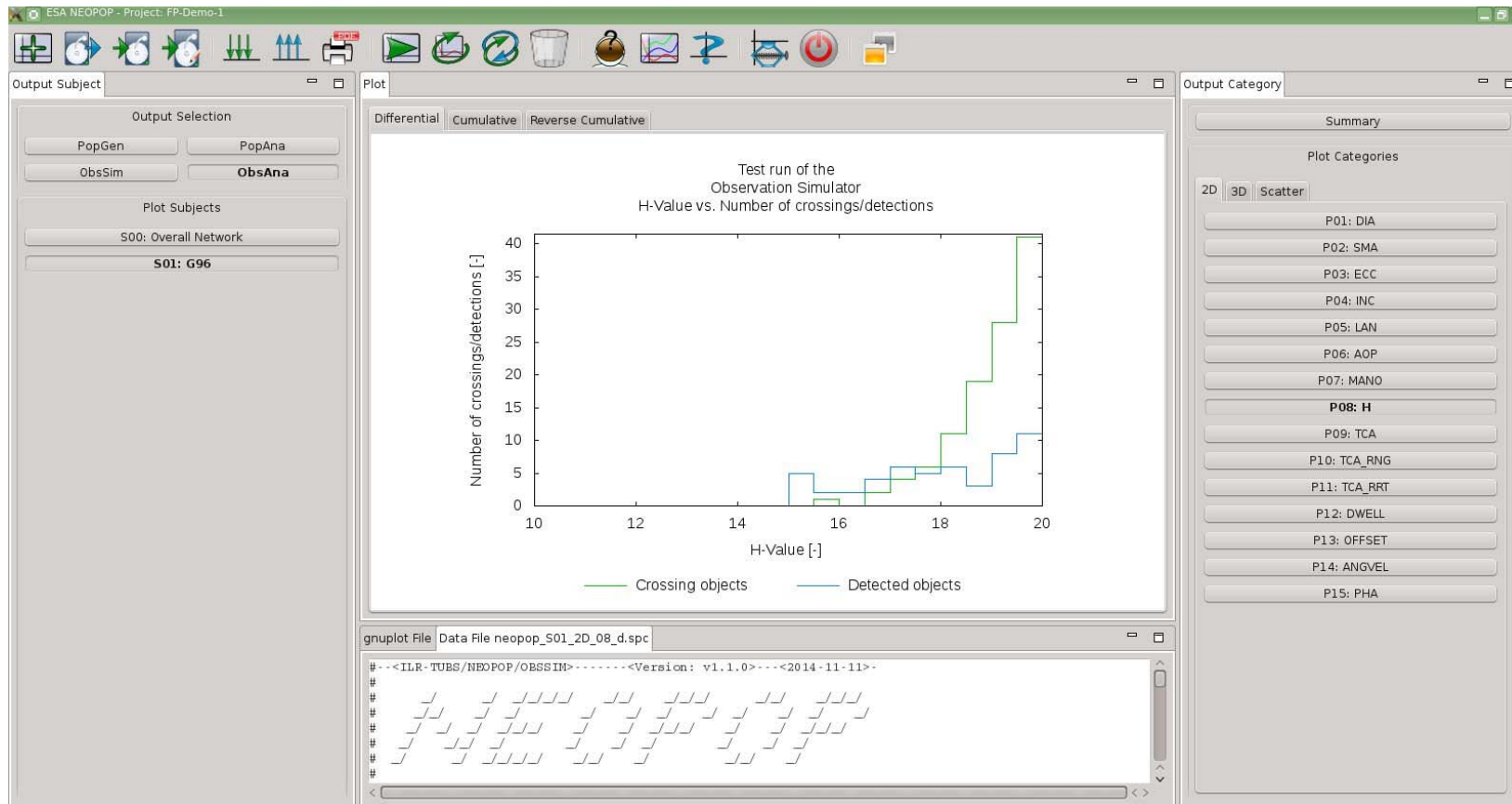
NEOPOP Demonstration

Backup 29



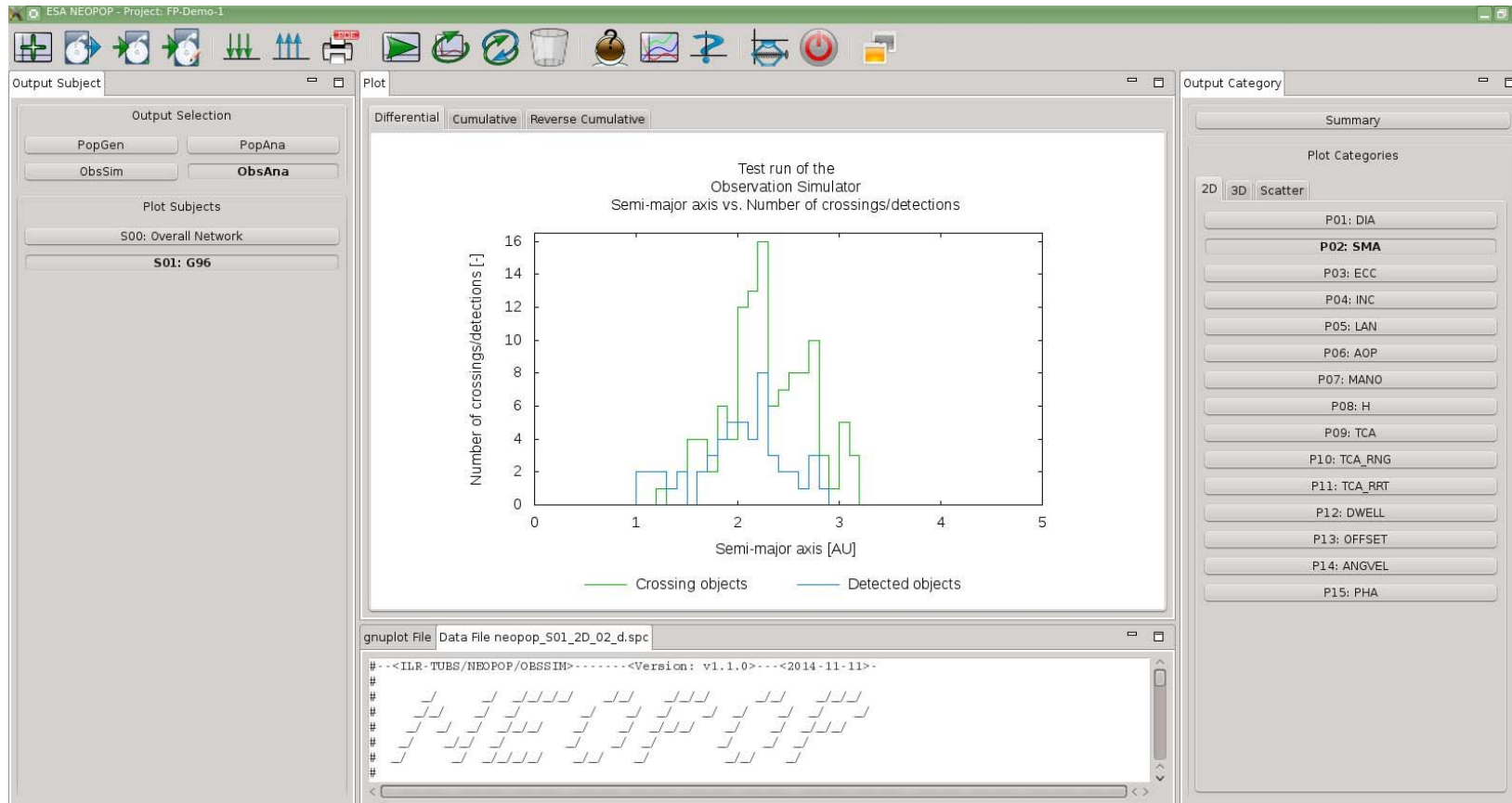
NEOPOP Demonstration

Backup 30



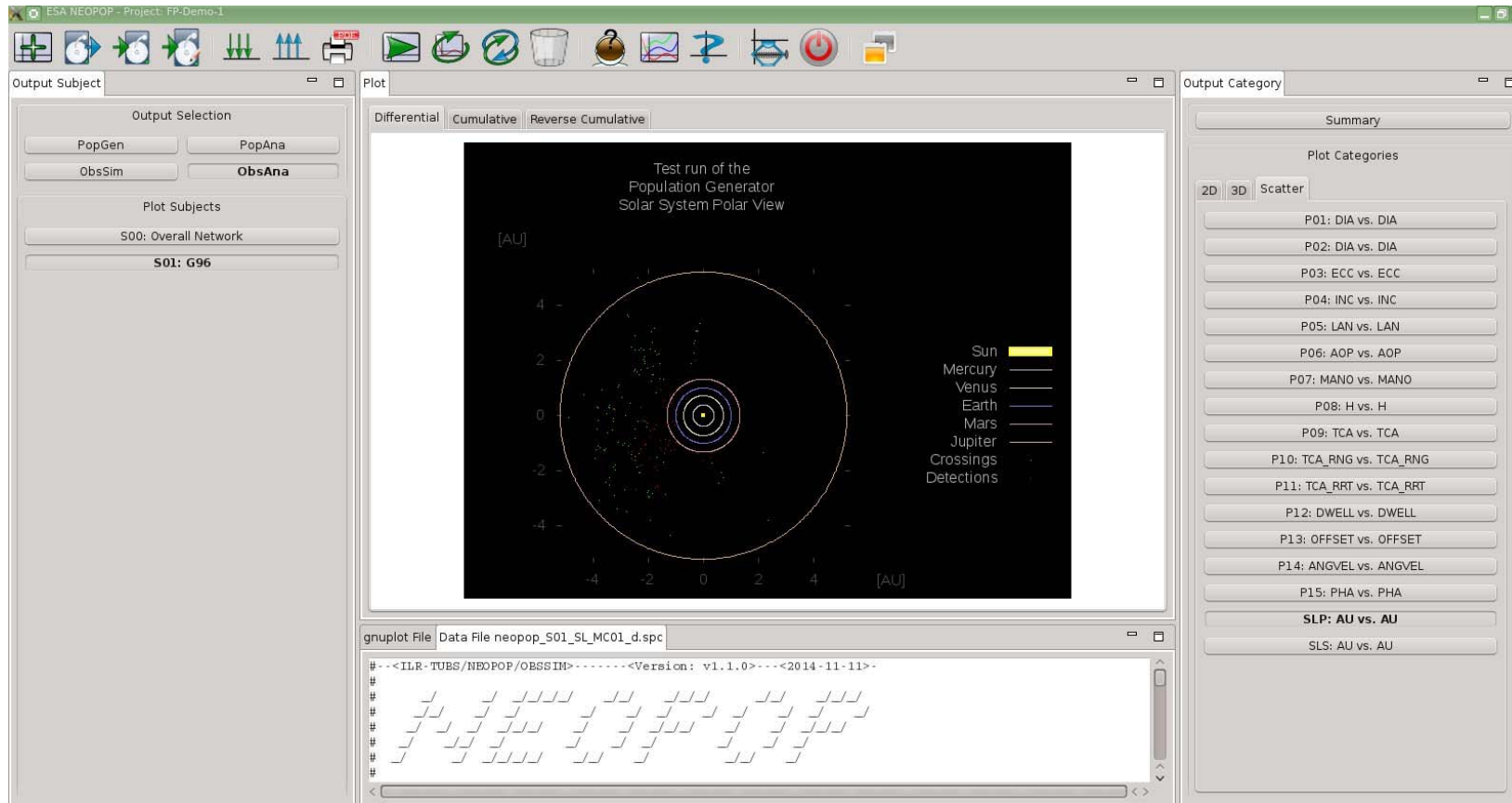
NEOPOP Demonstration

Backup 31



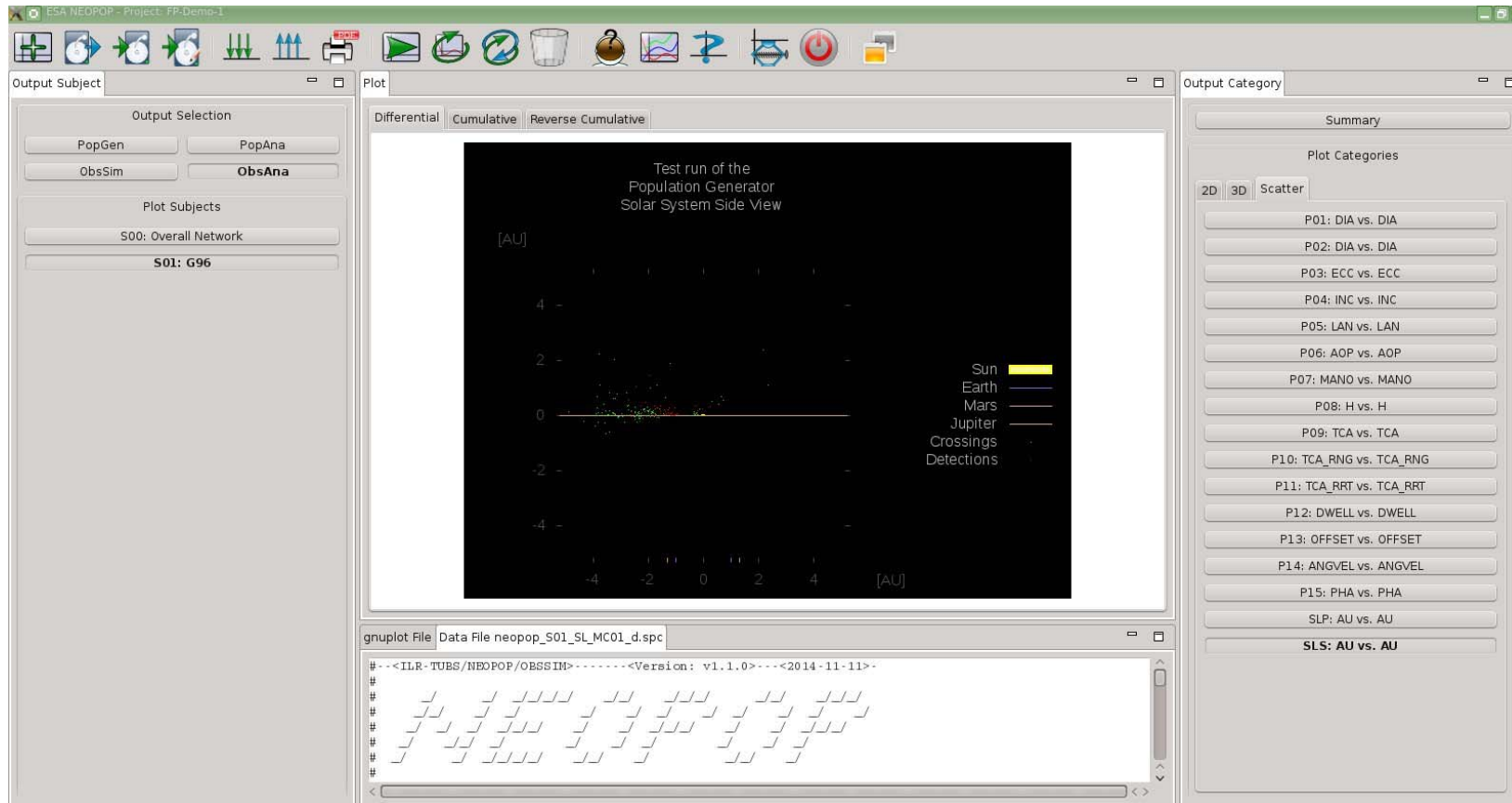
NEOPOP Demonstration

Backup 32



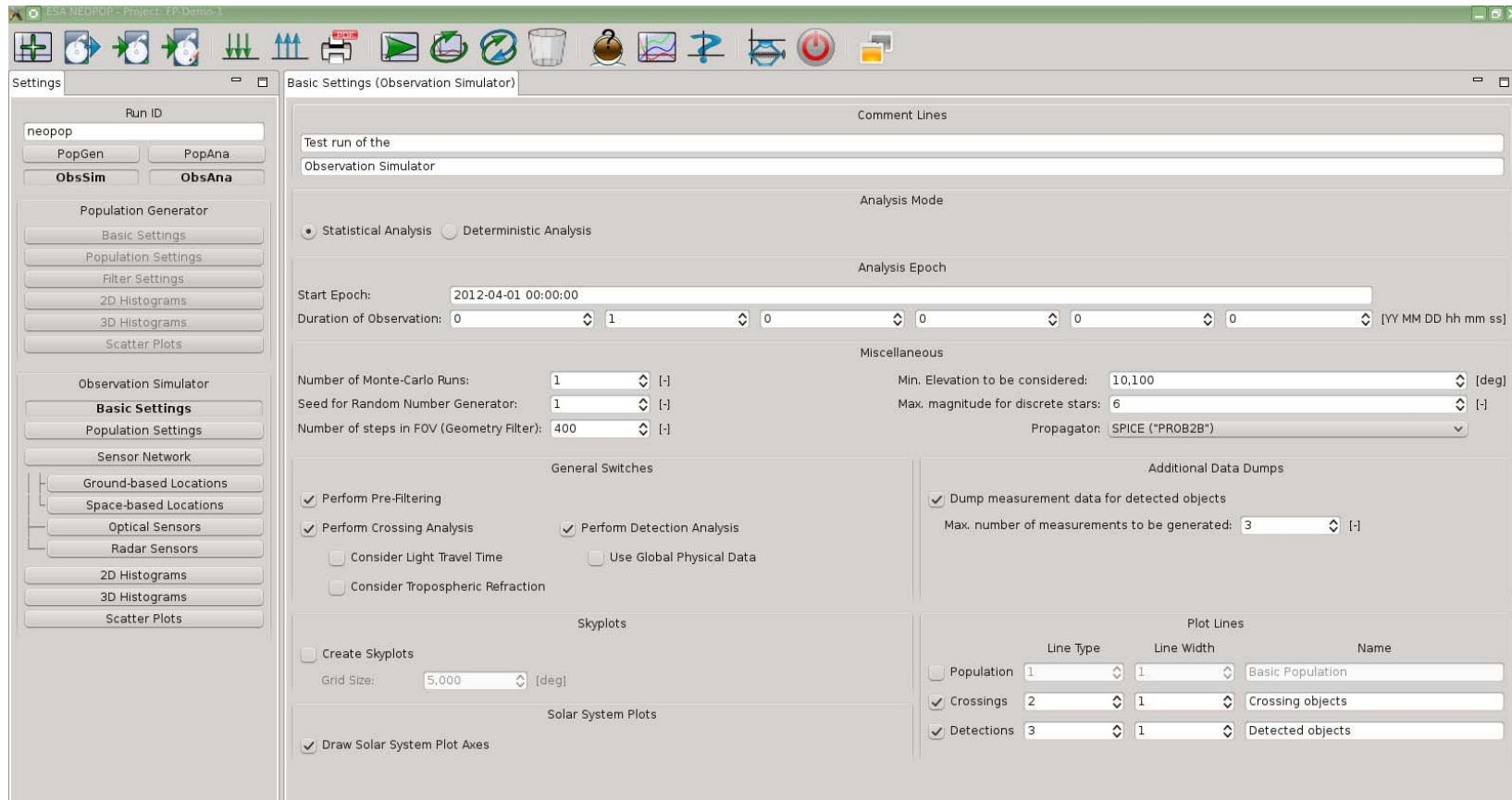
NEOPOP Demonstration

Backup 33



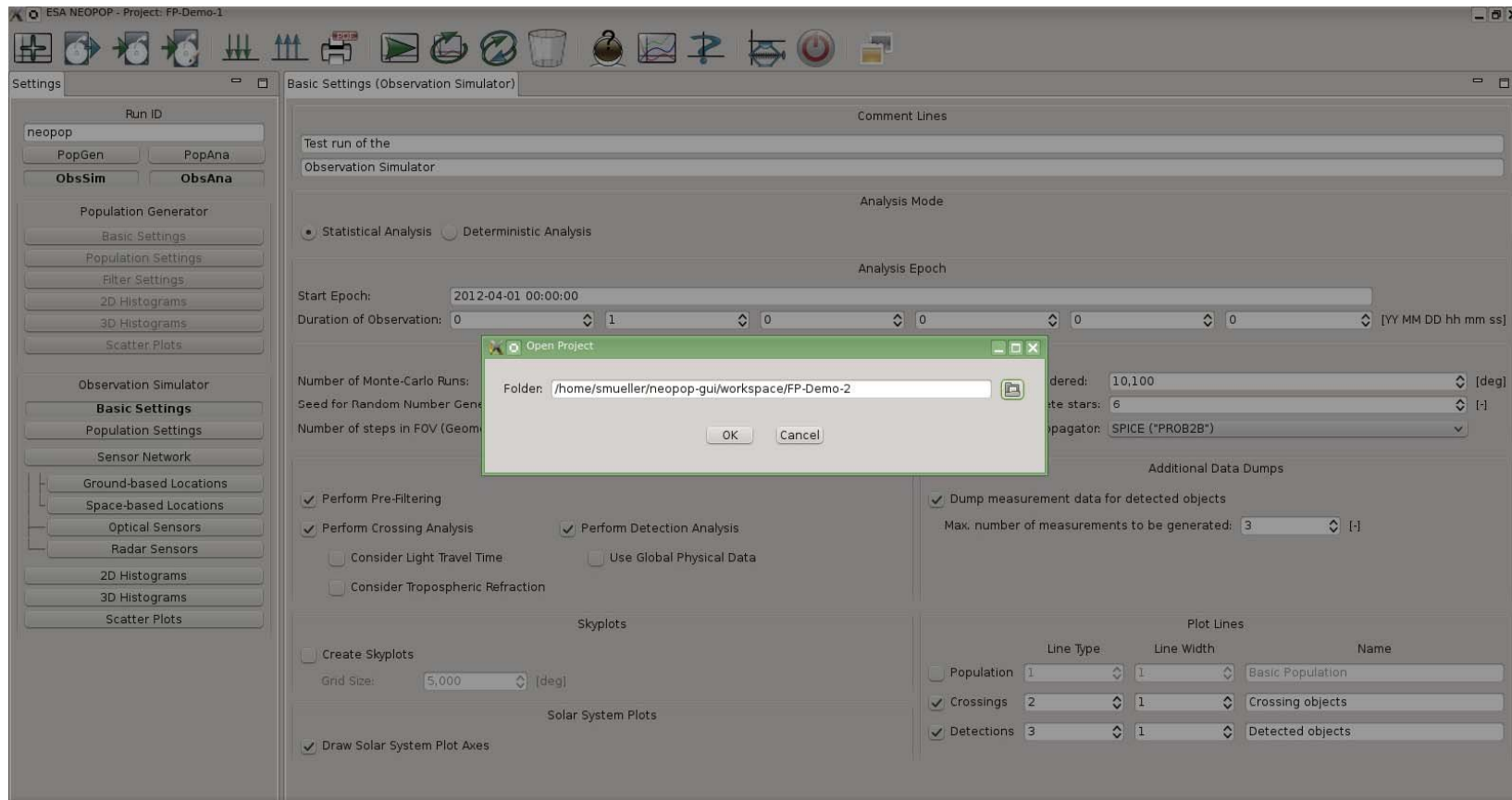
NEOPOP Demonstration

Backup 34



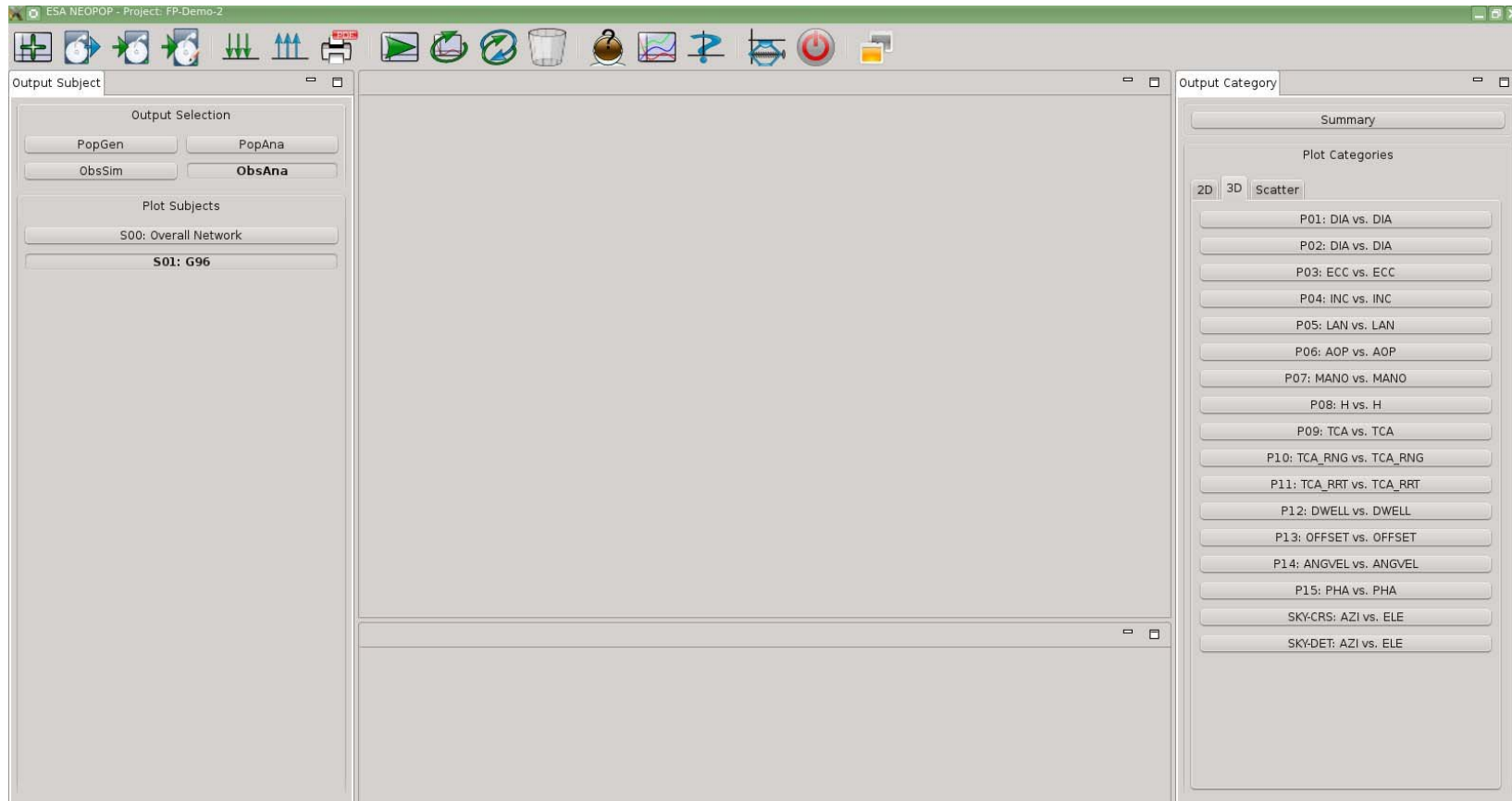
NEOPOP Demonstration

Backup 35



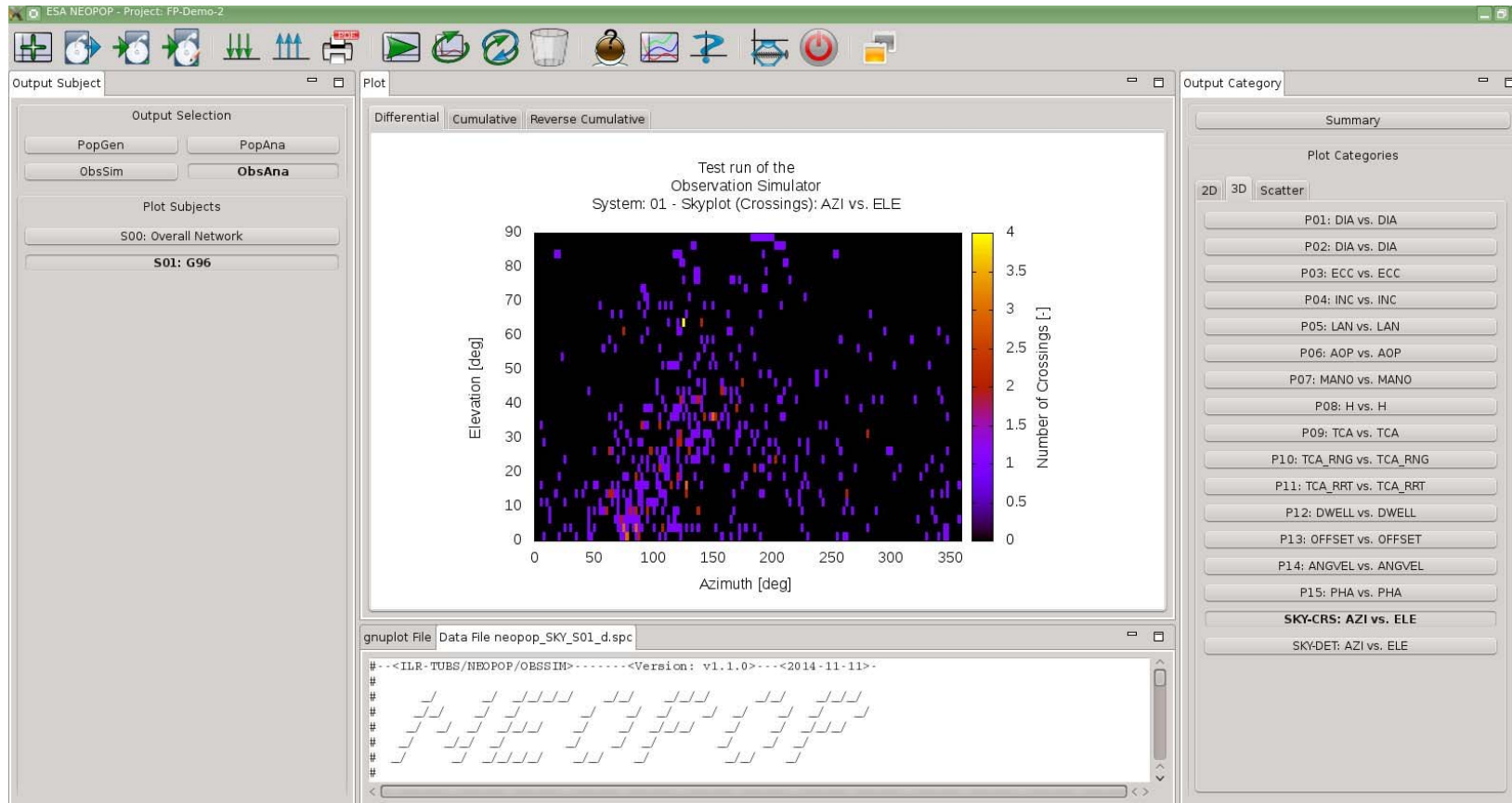
NEOPOP Demonstration

Backup 36



NEOPOP Demonstration

Backup 37



NEOPOP Demonstration

Backup 38

