# TAS RTU PRODUCTS

# ADCSS 2015 Noordwijk

3230356-DOC-TAS-EN-00



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23/10/2015

# TAS PRODUCTS & DEVELOPMENT

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## **TAS-BELGIUM**

#### **HIGH POWER AVIONICS**

- Development programme underway under ARTES R&D
- Modular PLDIU & PFDIU for SB NEO platform
- Complete satellite power distribution and avionics
- CAN backplane bus
- DPC-based solution

NEOSAT Qualification foreseen Q4/2016

#### **MEDIUM POWER AVIONICS**

- Generic RTU development program ongoing under GSTP R&D
- ~ Application programs:
  - 🛰 CERES
    - In partnership with EREMS
  - 🛰 Exomars CRTU
    - In partnership with Qinetiq
      Space
- DPC solution with CAN backplane



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## **TAS-ESPAÑA**

#### REMOTE TERMINAL UNITS

SPOT 5 - MGS HELIOS 2 - MGS SPOT 4 - RTU ROSETTA S/S - RTU ROSETTA P/L - RTU MARS EXPRESS - RTU VENUS EXPRESS - RTU GALILEO GIOVE - RTU



#### INSTRUMENT CONTROL UNITS

HELIOS 2 MG - CIB PLEIADES - MSI SENTINEL 3 - OEU HREOS S3 - MSI HREOS S2 - PCU SEOSAT INGENIO - ICU TAS EXPORT OBSERVATION - ICU



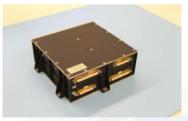
#### PAYLOAD INTERFACE UNITS

WORLDSTAR - PIU GLOBALSTAR2 - PLIU O3B – PLIU



#### MECHANISM CONTROL UNITS

ENVISAT/PPF - APME ARTEMIS - APME SESAT - APME ROSETTA - SADE MARS EXPRESS - SADE VENUS EXPRESS - SADE ATV - SADE SENTINEL 1- DCU EXOMARS RV - ADE





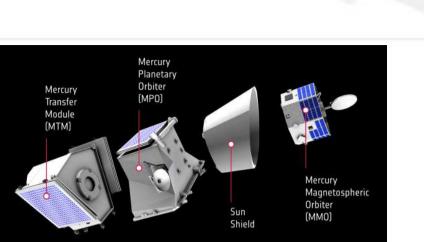
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Ref.: TAS España - Company Presentation September 2014



- 🛰 BepiColombo RIU's
  - MTM and MPO each have a TAS-UK (SEA) RIU.
  - Common modular architecture
    - reduced design time
    - reduced review cycle
    - SAVOIR-like
  - Simplicity of architecture for the customer
    - SpaceWire interface/ RMAP protocols.
    - Power management features.
    - Hot redundant operations.
    - Single point failure free.
    - >98% built in test coverage.
  - Status : MTM RIU delivered Dec 2014, MPO RIU delivered mid-2015, currently undergoing spacecraft integration









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Ref .:



#### **~** AVIONICS PRODUCT TREND

- MODULARITY
  - Unit to be fully modular based on 'plug & play' elements for I/O functions
- ∽ FLEXIBILITY
  - The elements for I/O functions as well as the unit controller to present adaptability to different needs
- SCALABILITY
  - The unit to provide capabity for extend the number and complexity of the elements

## SCALABLE, FULLY FLEXIBLE, MODULAR AND <u>AFFORDABLE</u>

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# TAS RTU ARCHITECTURE

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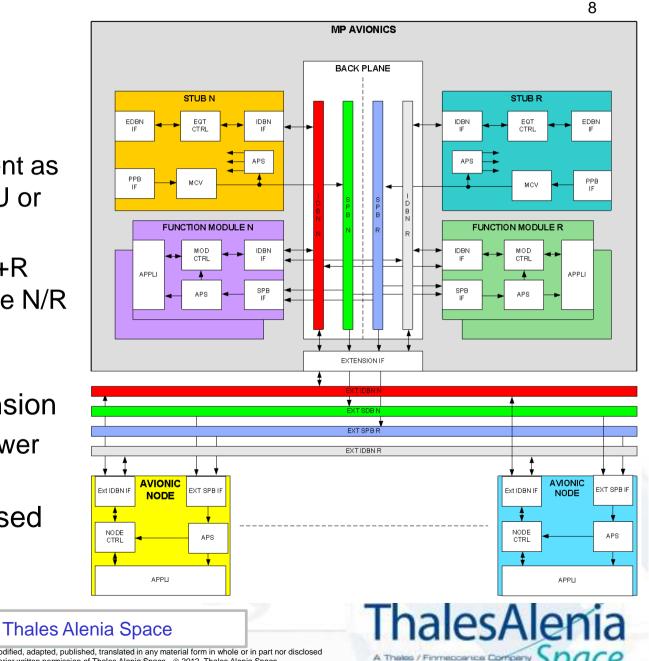
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## **ARCHITECTURAL SOLUTIONS**

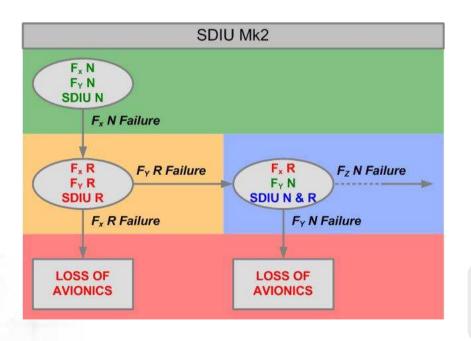
#### Electrical architecture:

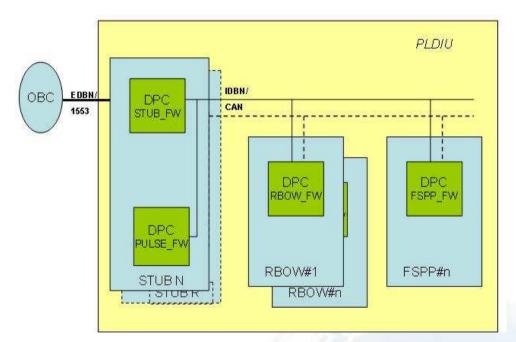
- Very high modularity and versatility
  - Adapted to small equipment as SADE up to complete RTU or PIU
  - Compatible with simple N+R redundancy up to complete N/R cross-strapping with hot redundancy capability
- Open to external unit extension
  - In terms of TM/TC and power supply architecture
- Compatible with decentralised system



# **ARCHITECTURAL SOLUTIONS**

- - Modular internal TMTC and Power supply concepts
  - Fully standardized backplane interface
  - 🥆 Full internal cross-strap
  - Double crossed-failure tolerance





# Can provide better reliability figure than classical cold redundancy

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# BUILDING BLOCKS

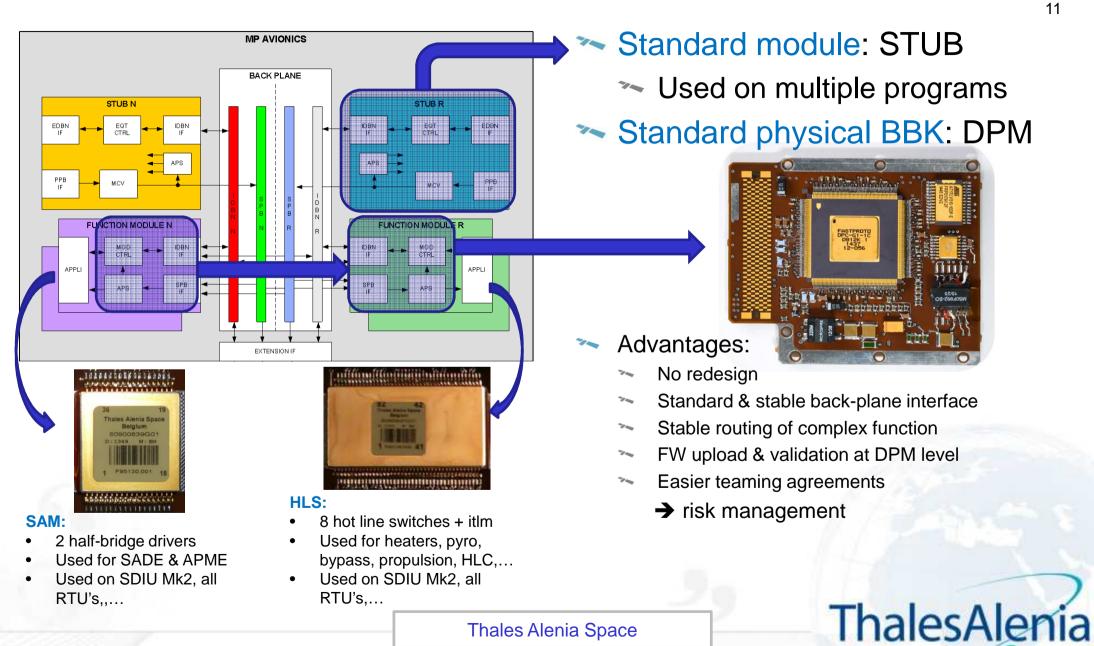
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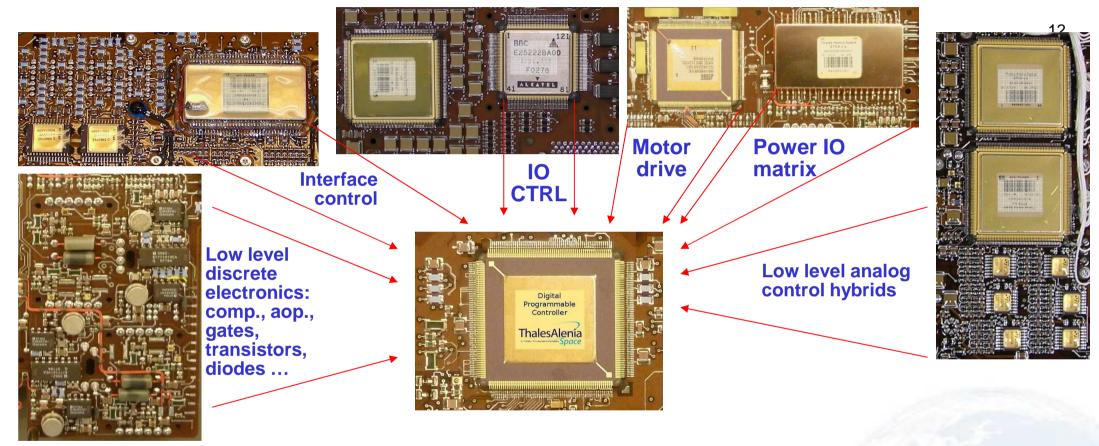


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#### DPC-G1 as key function for rationalisation of today's products



- One single chip replaces several functions !
  - Back-plane interface standard hybrid
  - Function specific ASIC or FPGA
- Firmware particularize the functionality

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## $\sim$ AFFORDABILITY $\leftarrow \rightarrow$ COMPETITIVITY

#### ➤ Development of <u>COMPETITIVE</u> Building Blocks.

- Reuse of validated elements
- Reduction of risk
- Sharing of know-how throughout TAS
- SAVOIR baseline definition
  - Common architecture definition
  - Reuse of Avionics definition for next programs

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# BACKPLANE & TMTC Approach

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## **STANDARDISED BACK-PLANE APPROACH**

# Avionic products require a different approach of Back-panel depending on the nature of the signals required in those units

- PLIU/RTU Backplane contents:
  - Supply distribution
    - 1 to 3 rails typically
  - Internal C&C distribution
    - low to medium rates <10 Mbps</li>
    - SPI, CAN, ML16/DS16 busses concept.
  - Discrete signals

- ICU Backplane contents
  - Supply distribution
    - 1 to 3 rails typically
  - Internal C&C distribution
    - low to medium rates <10 Mbps
    - SPI, CAN, ML16/DS16 busses concept.
  - Discrete signals
  - High rate data transmission
    - >10Mbps when data processing required (depending on the mission)
    - SpW, SpF, TTEth, cPCI, dedicated ones...



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### However Standardised Back-planes bring advantages Why?

- The signal carrying backplane electrical interfaces within a unit are not dictated by customer requirements and are typically non-standard, consisting of discrete lines, parallel busses, device specific serial busses
- > The mechanical interfaces for each PCB module are vendor specific
- Module level AIT is complicated by the large number of interface types, so emulating a module that is still in the development cycle is non-trivial

A potential solution is to create a Backplane Standard for each type, e.g. CAN, SpaceWire, SPI

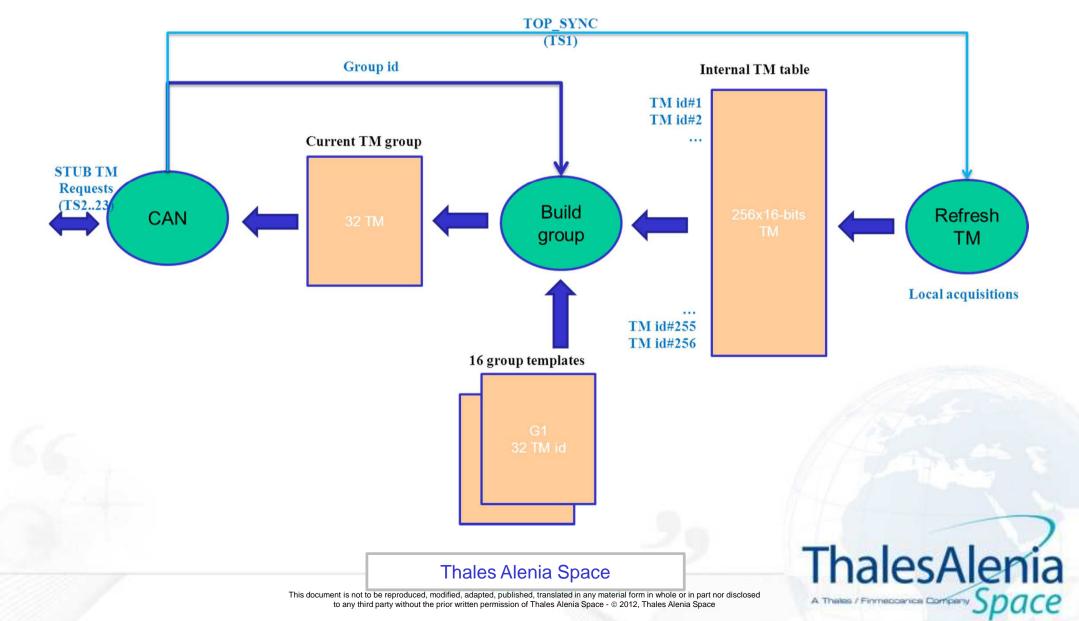
Module re-use between missions and instruments is then practical

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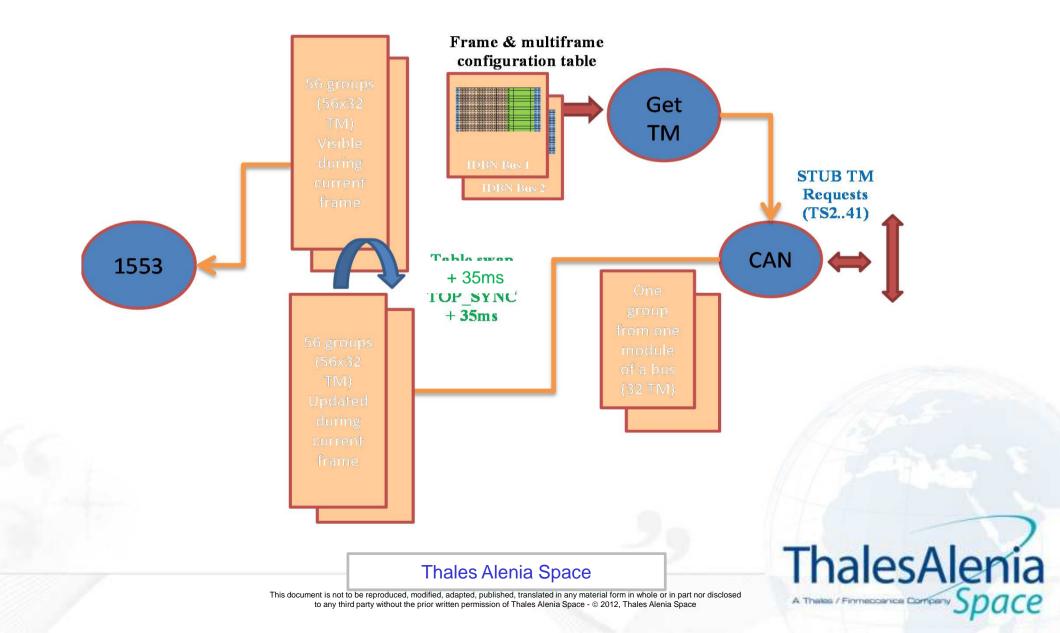
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#### CANBUS : TM processing at module side



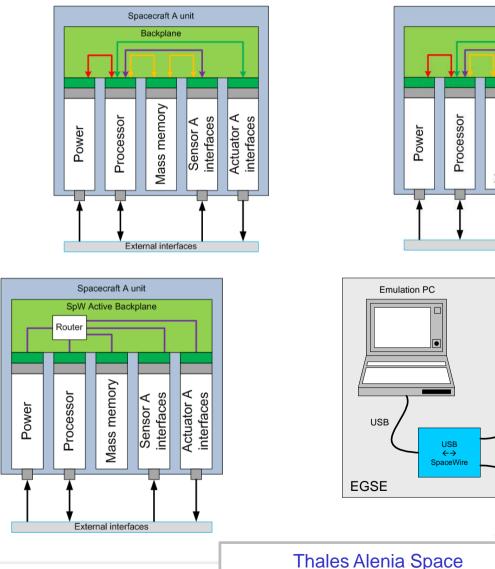
## EX1: CAN BACK-PLANE – Management

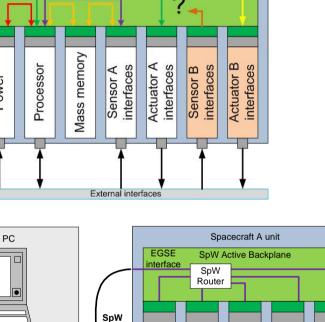
#### CANBUS : TM processing at STUB side



## EX2: STANDARDISED BACK-PLANE – SpaceWire

#### SpW : Adhoc interconnect v. SpW backplane





Connect how?

Mass memory

SpW link for sensor emulation

Processor

Power

Adapter

Actuator A interfaces

Spacecraft B unit

link

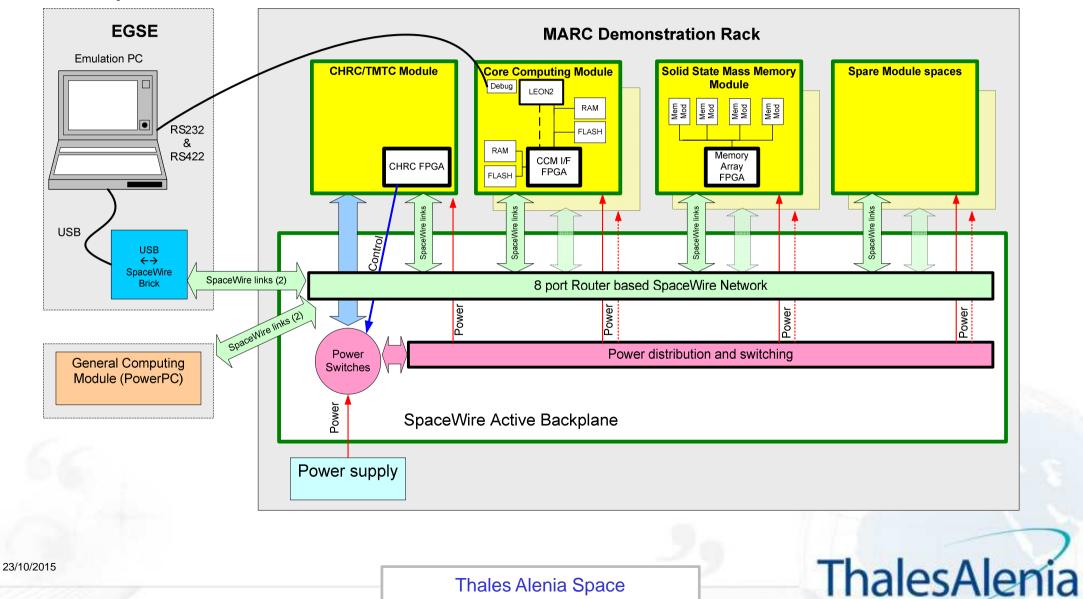
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#### SpW: MARC demonstrator



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Certain core functions may be standardised but architecture must allow scalability

>>> BBK can be physical modules as well as physical elements

➤ Varied applications can imply a number of backplane standards → CAN, SPI, SpW,....

Inclusion of third party suppliers comes through standardised backplane interface

## Thank you for your attention!

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