New CCS technology protoyping

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Astrium Satellites

All the space you need

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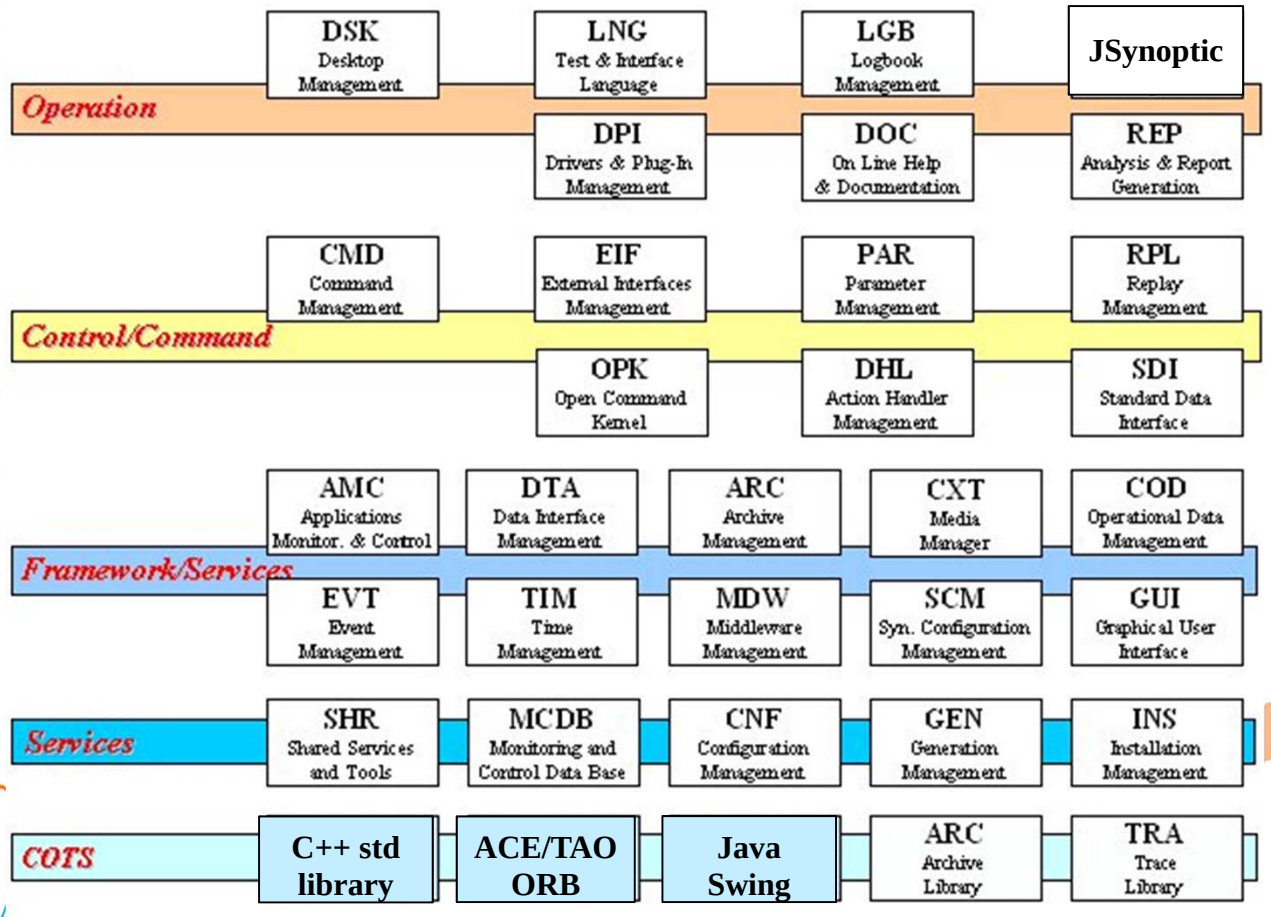
Outline

- Astrium CCS background
- Lessons learnt
- Prototyping
  - Middleware : ZeroMQ
  - Data modelling : EMF
  - Procedure language : Java

Astrium background : Open Center

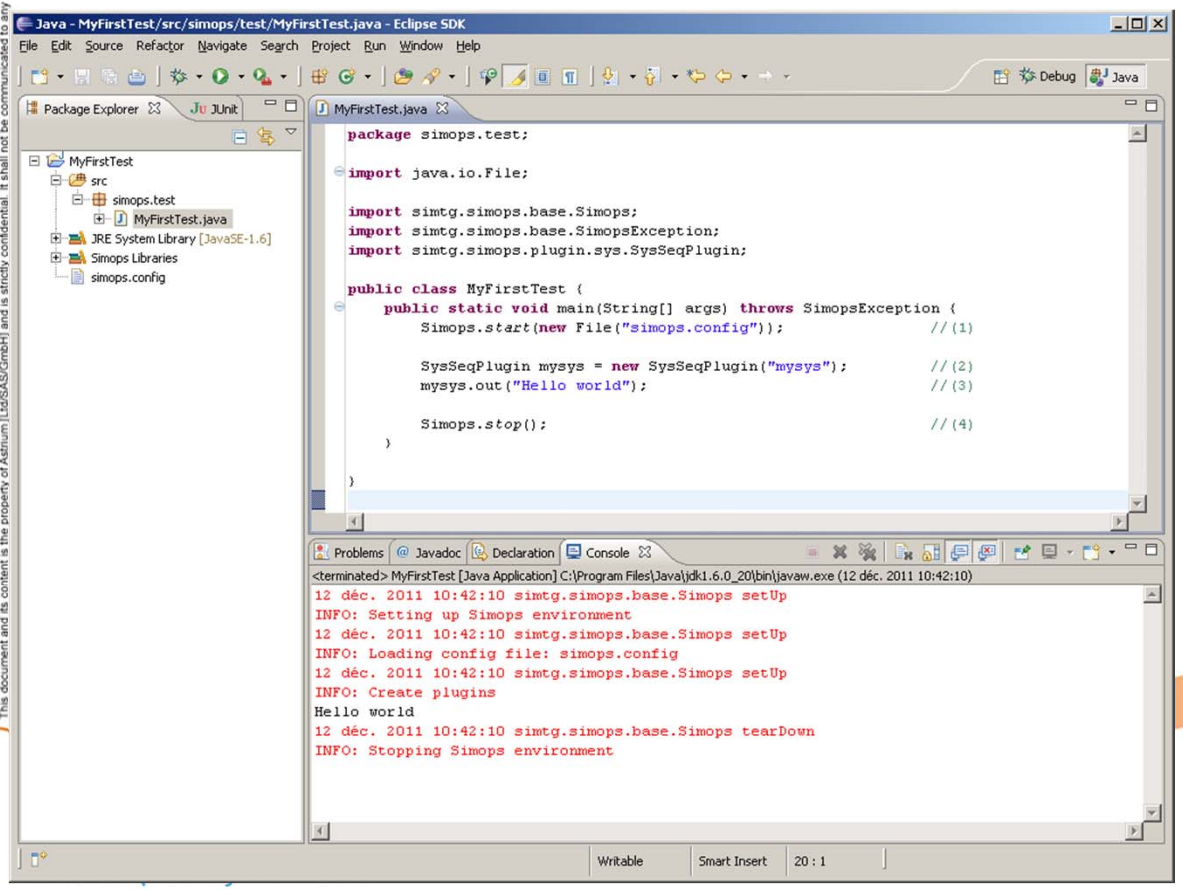
- Component framework designed for both EGSE CCS and Spacecraft Control Centers



- Designed for high scalability
- Typical configurations made of:
  - A server
  - A redundant server for Control Centers
  - 1 to many client workstations
- Generally more than 40 processes running on several Linux computers

Astrium background : SimOPS

- Lightweight monitoring and control system orginally designed for simulation verification but also used for On Board Software validation (SVF)



- User MMI is also a server
  - One process for the server and one for each running procedure
- Java language for procedures
- Plugin/ OSGi architecture
  - JDT: java editor and debug
  - JSynoptic: user defined displays
  - SimMF: simulation modelling tool

Lessons learnt (1/3)

- Complex systems are not only difficult to develop or to maintain, they are also difficult to configure by the end user
  - Select architecture enabling very simple but scalable configurations
  - Very simple configuration is a single PC with a minimum number of running processes : 1 or 2
  - Complex architecture is with a redundant server and with many client computers connected to the system

Lessons learnt (2/3)

- Use of de facto standards : some example
  - Procedure language
    - Takes benefits of well known and well supported language : not yet another language
    - OBSW team requires compiled and typed language
    - One solution is to use Java
  - Modelling language
    - UML2 for conceptual data model
    - Ecore (EMF) for technical data model

Lessons learnt (3/3)

- Real time performance is always an issue
  - Strong recommendation is to check if the most efficient solution fits with the other needs
  - A scalable solution shall take benefits of the various configurations
    - Inter thread communication for single process cases
    - Inter process communication for single computer cases

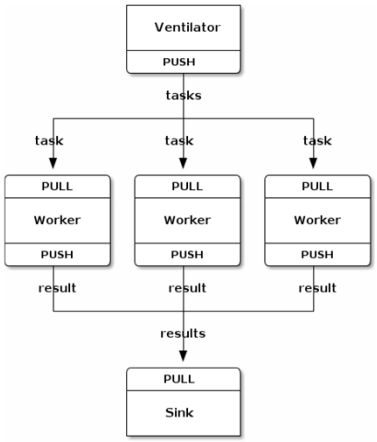
MOMs

- Message Oriented Middleware in place of remote procedure calls (CORBA, RMI, RPC,..)

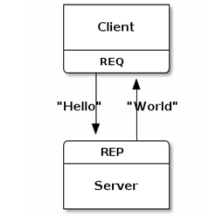
- Most popular solutions
  - RabbitMQ
    - Compliant with AMQP protocol
    - Broker achitecture
    - Easy to use and deploy but some latency due to the central broker
  - ActiveMQ
    - Compliant with JMS standard
    - Broker or P2P architecture
    - Very generic and easy to use but slower than RabbitMQ
  - ZeroMQ
    - Lightweight messaging system
    - Library architecture, no broker
    - More complex to use (low level) but faster than the other ones (takes benefits of the configuration and manages multicast TCP/IP)

ZeroMQ, parallelization

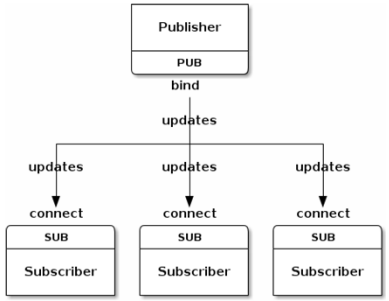
- A generic solution to parallelize computations, less taking care about synchronisation issues



Parallel pipeline with PUSH/PULL



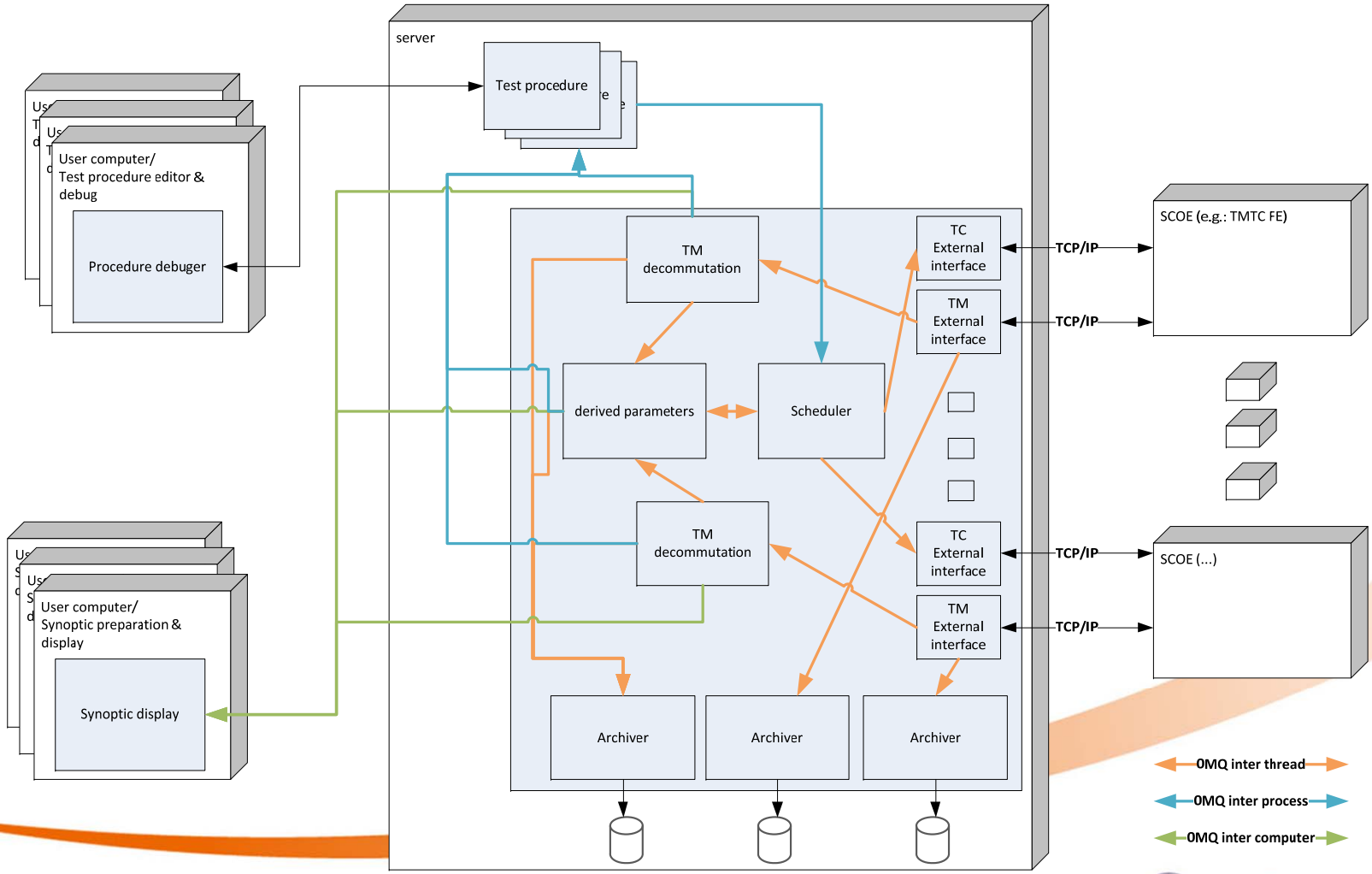
Request and Reply



Publish-Subscribe

- To be combined with a marshalling solution where needed (e.g. not for TM packets)

ZeroMQ, analysed architecture



Eclipse Modelling Framework and related technologies

- Application of proven technologies
  - From UML to java
    - UML to eCore
    - Technical data model
    - eCore to Java

      Data persistence : XMI (and binary format)

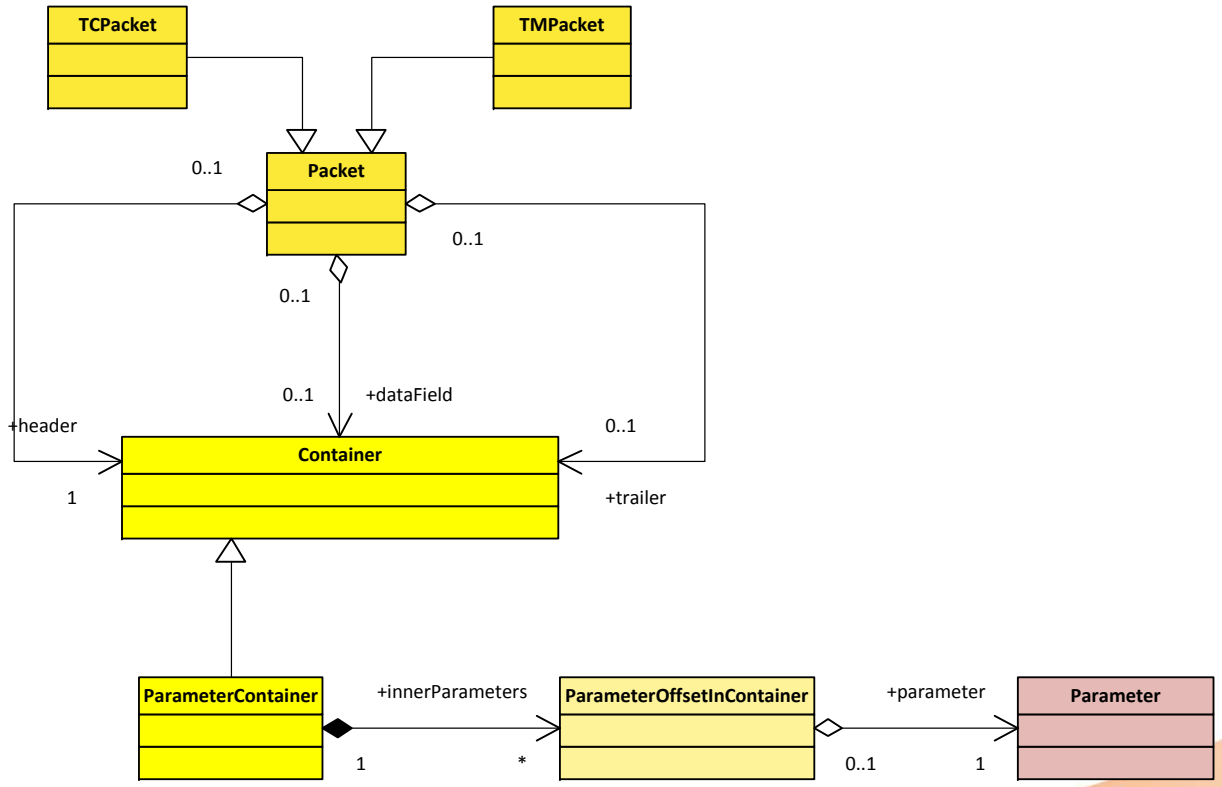
      Simple editors (need for a customized code generation)
  - Use of OCL to define constraints
    - Constraints are embeded in the metamodel to define their scope of application
  - Use of QVTO for model to model transformation
    - Example :

      UML metamodel for MIB files

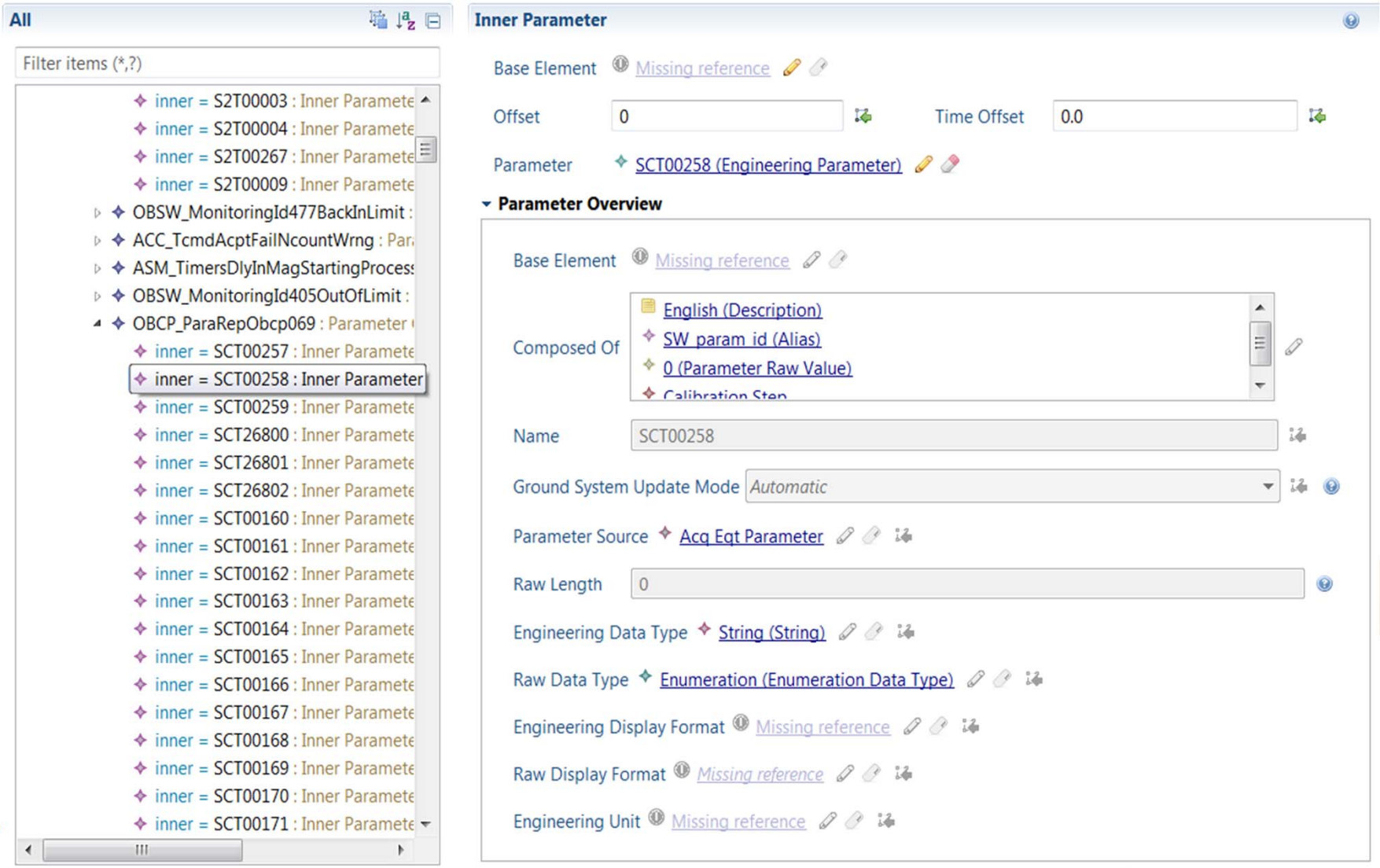
      UML metamodel for data base

      QVTO to define mapping between the 2

UML TM/TC Meta model example



EMF TM/TC editor example



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Java

- Current solution at Astrium Satellites to validate the On Board SoftWare
- Well known language, easy to learn, state of the art development environment (editor and debugger)
- Compliant with ECSS E70 32
  - Specific features are implemented using a base class
  - Compiled and typed
- Compliant with EGS-CC requirements for debugging and command retry
- And much more:
  - Scripting language interface
  - Annotations

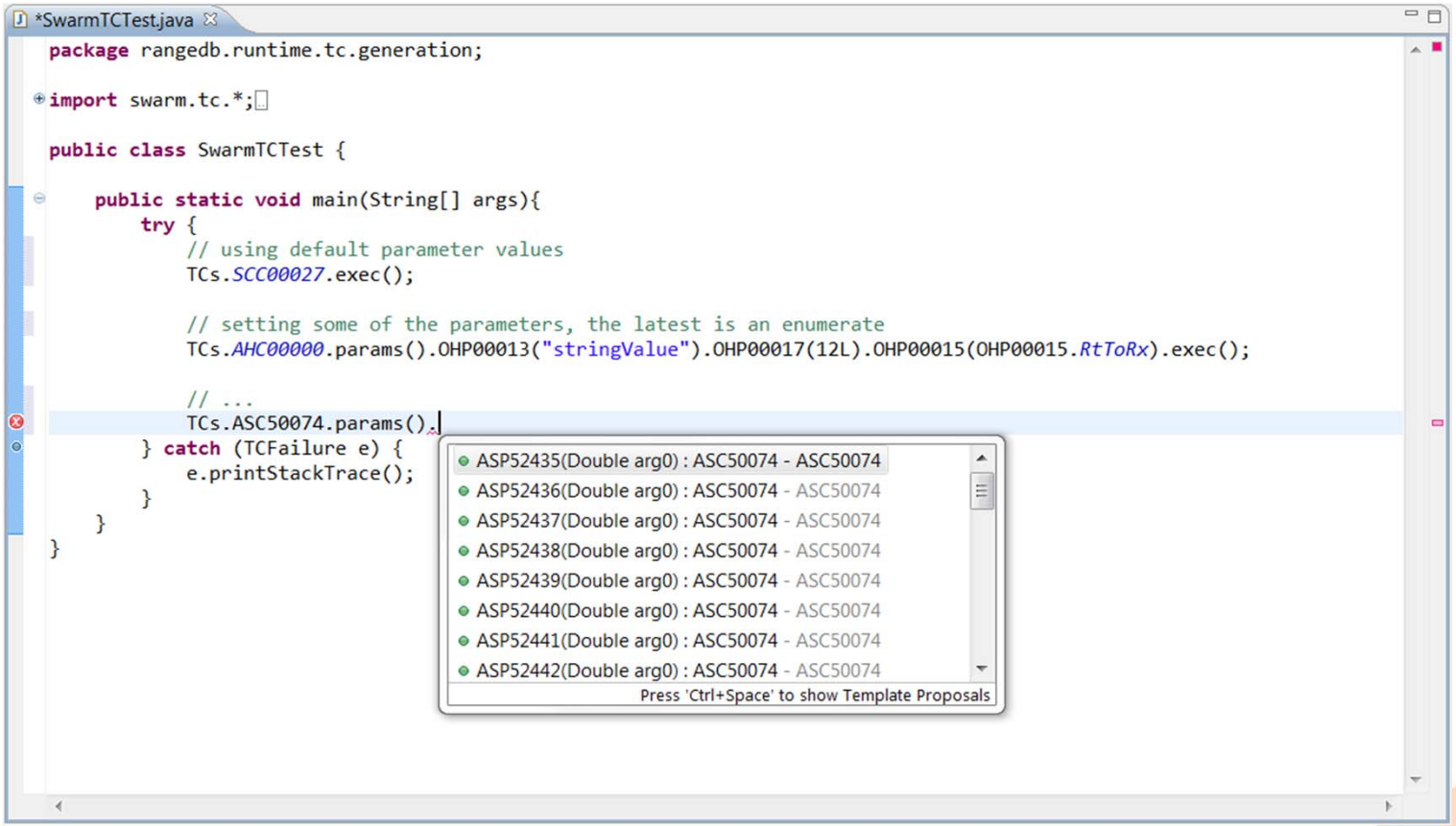
Current approach: TCs are intrepreted

- Based on MIB files information

OldSwarmTCTest.java

```
package rangedb.runtime.tc.generation;

import simtg.simops.tc.TCs;

public class OldSwarmTCTest {

    public static void main(String[] args){
        try {
            // using default parameter values
            TCs.exec("SCC00027");

            // setting some of the parameters, the latest is an enumerate
            TCs.exec("AHC00000 OHP00013=\"stringValue\" OHP00017=12 OHP00015=RtToRx");

            // ...
            TCs.exec("ASC50074 ASP52437=");
        } catch (TCFailure e) {
            e.printStackTrace();
        }
    }
}
```

New approach, TCs interface is compiled



- Example of implementation using ASM byte code generator and RangeDB
  - <10 seconds to generate 3000 TCs
  - 3KB per TC (average)

Conclusion

- Activities are to support Astrium activities in EGS-CC Systems Engineering Team
  - All results to be contributed to EGS-CC
- Prototypes confirm the benefits of these three technologies
- Potential next domains to be analyzed:
  - Component Framework (OSGI + ?)
  - Data archiving
  - User defined displays
  - Scripting language
  - Service integration platforms

Thanks for your attention

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