

SSA Sensor Simulator (SSIM) Space object environment simulator and measurements

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27/09/2012

SSA
Concept

SSIM
Concept

SSIM
Architecture

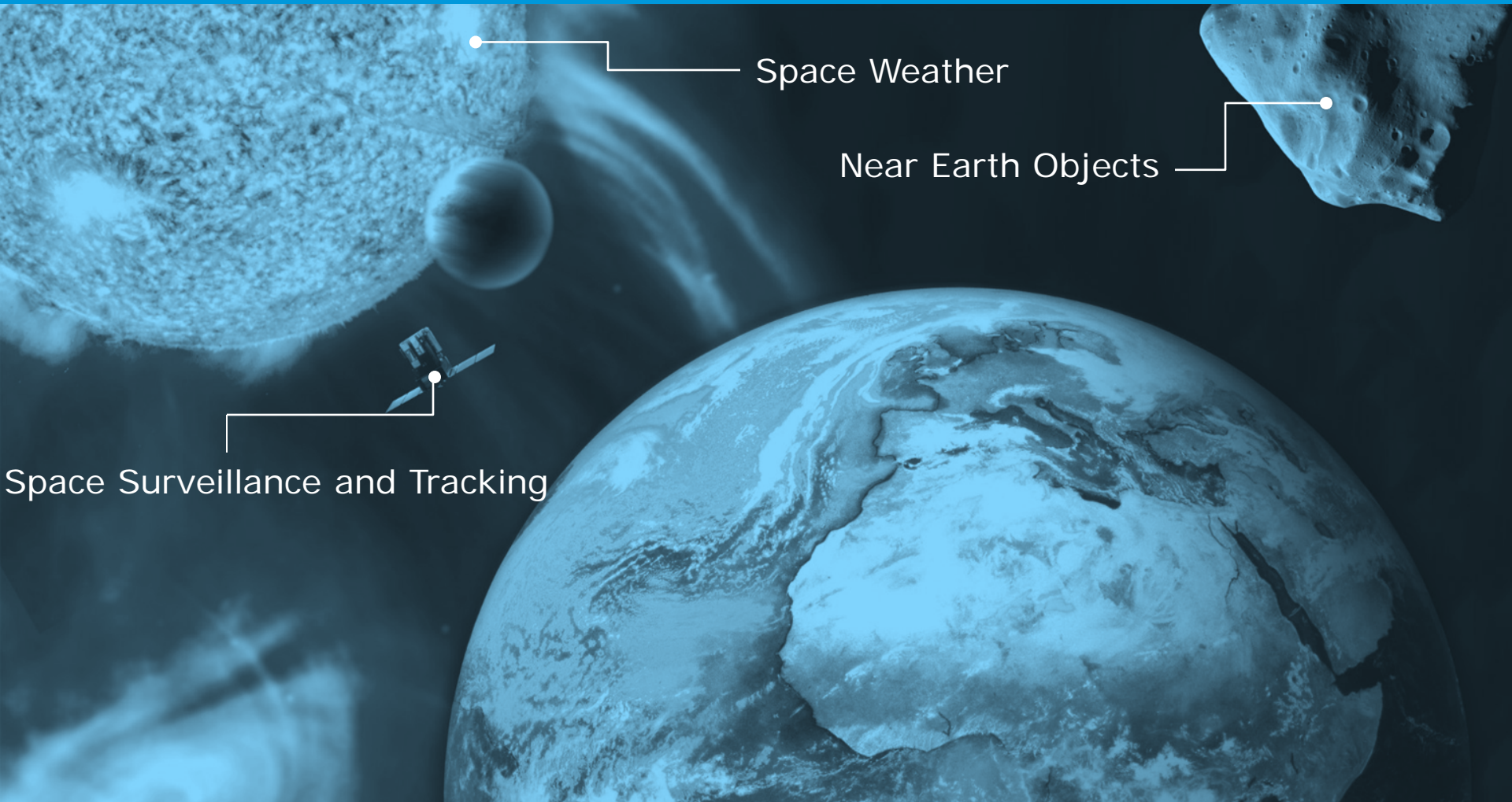
SSIM
Results

SSIM
Conclusions

“ The objective of the Space Situational Awareness (SSA) programme is to support the **European independent utilisation** of, and **access to, space** for research or services, through the **provision of timely and quality data**, information, services and knowledge regarding the **space environment**, the **threats** and the sustainable exploitation of the outer space **surrounding our planet Earth** “

**ESA Ministerial Council
November 2008**

Space Situational Awareness (SSA)

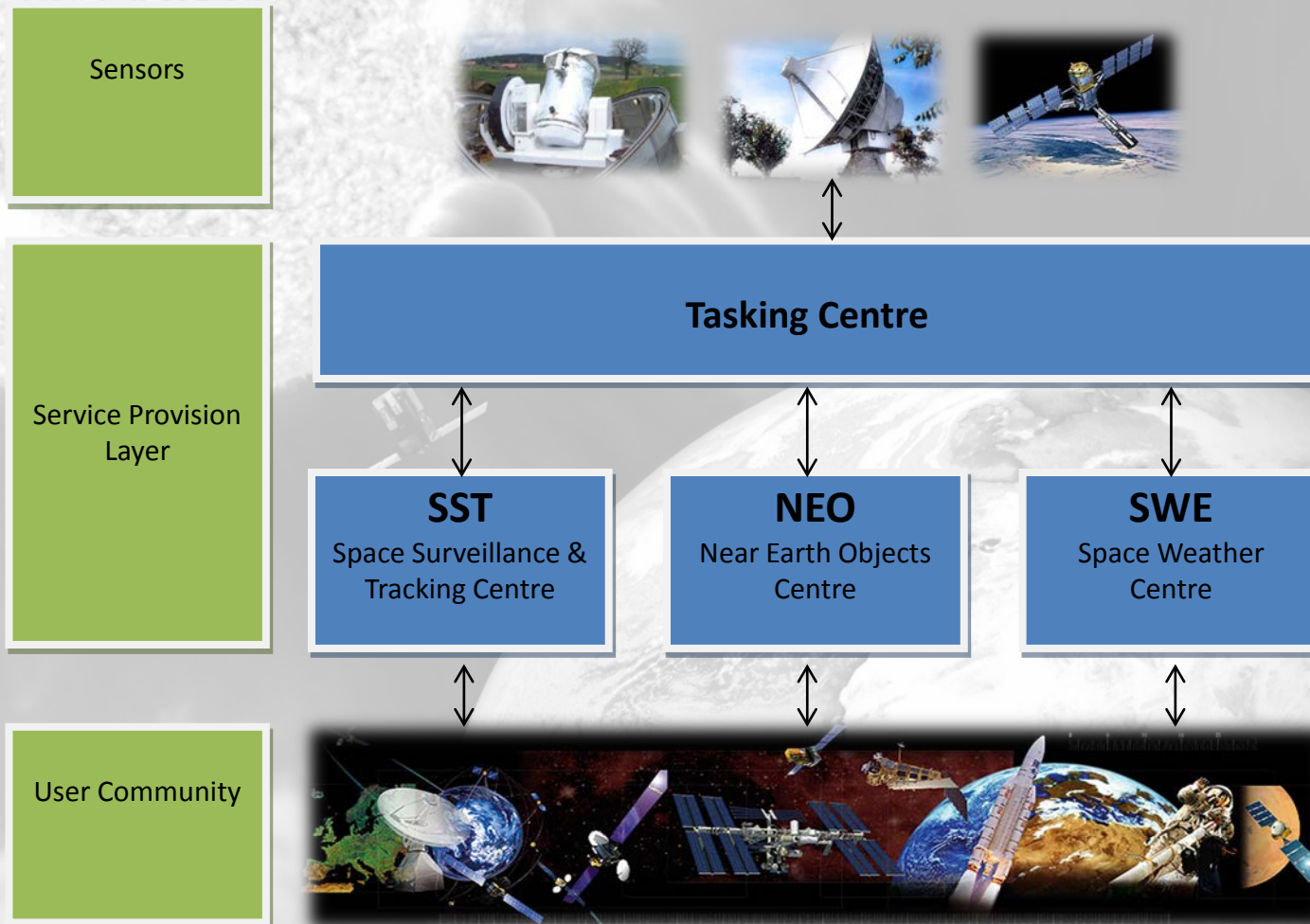


Space Weather

Near Earth Objects

Space Surveillance and Tracking

SSA System Concept



SSA
Concept

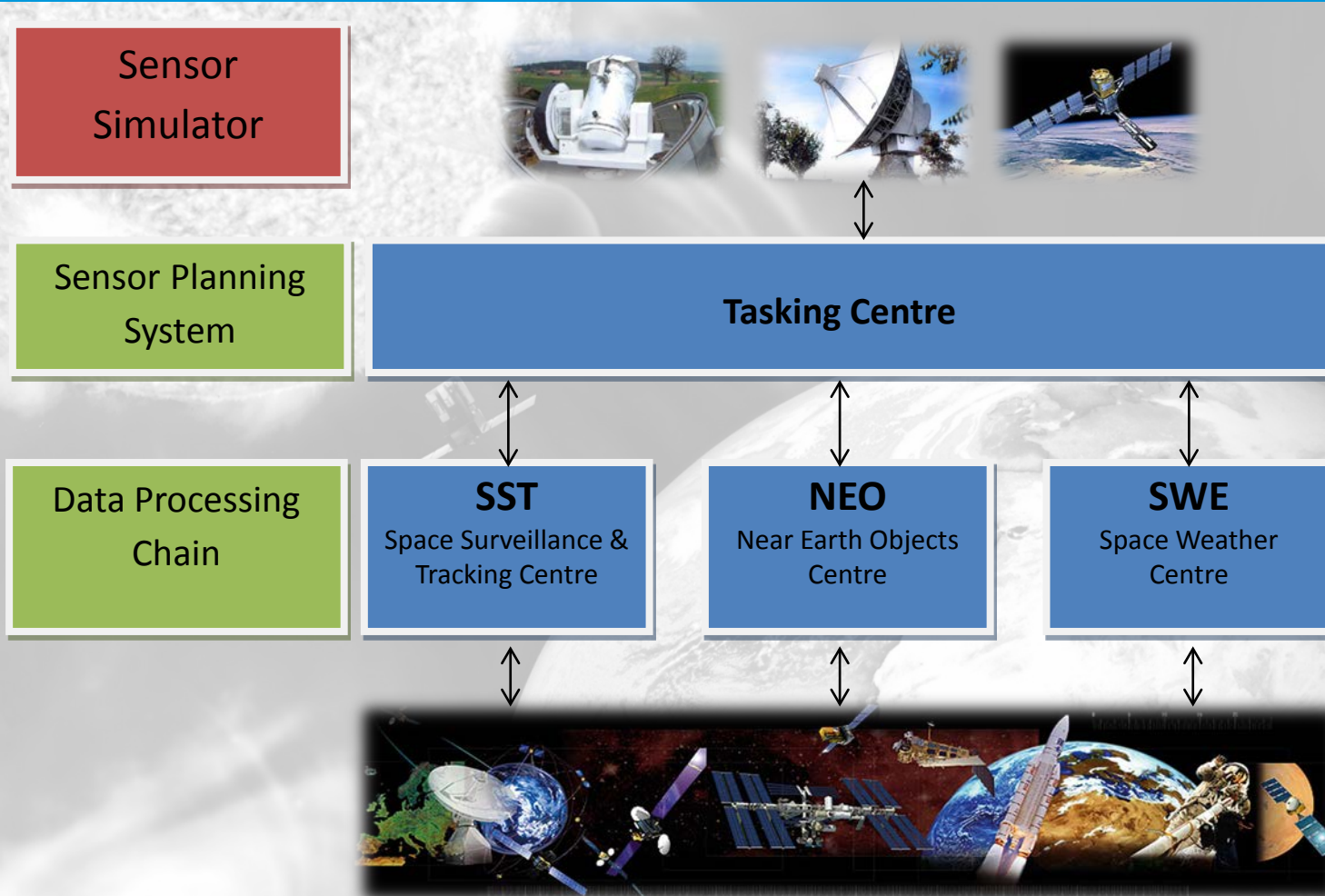
SSIM
Concept

SSIM
Architecture

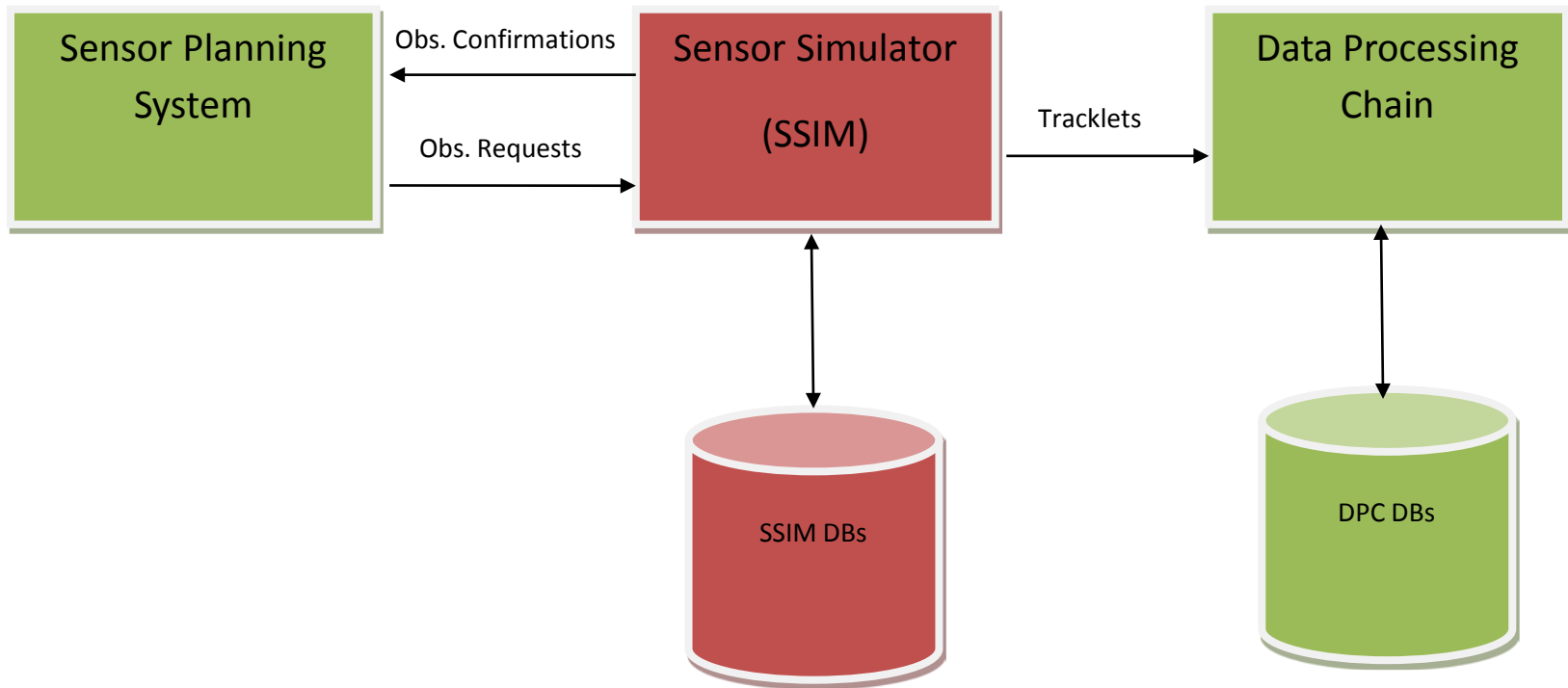
SSIM
Results

SSIM
Conclusions

SSIM Use Case



SSIM System Context



SSA
Concept

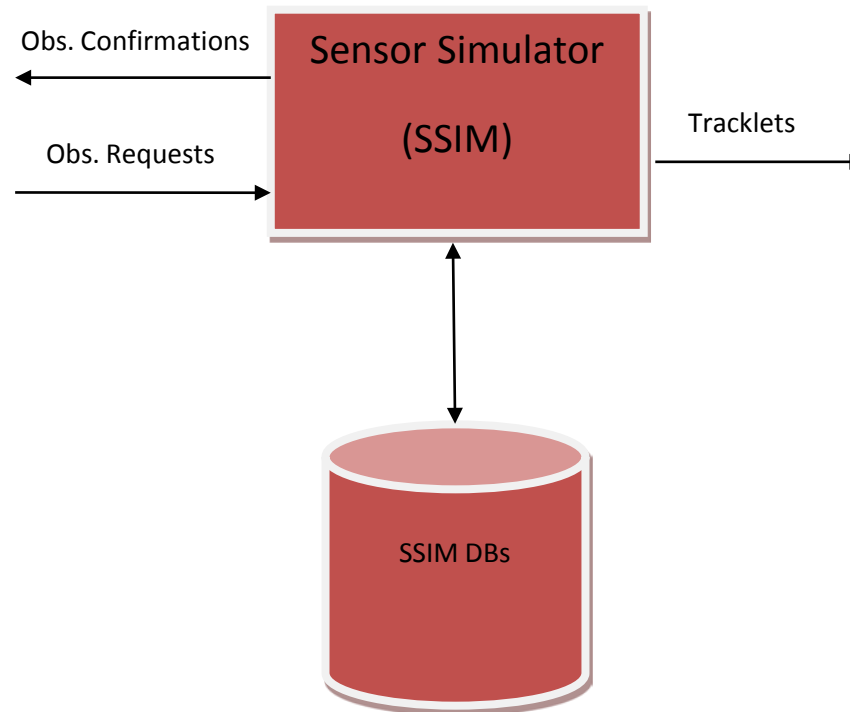
SSIM
Concept

SSIM
Architecture

SSIM
Results

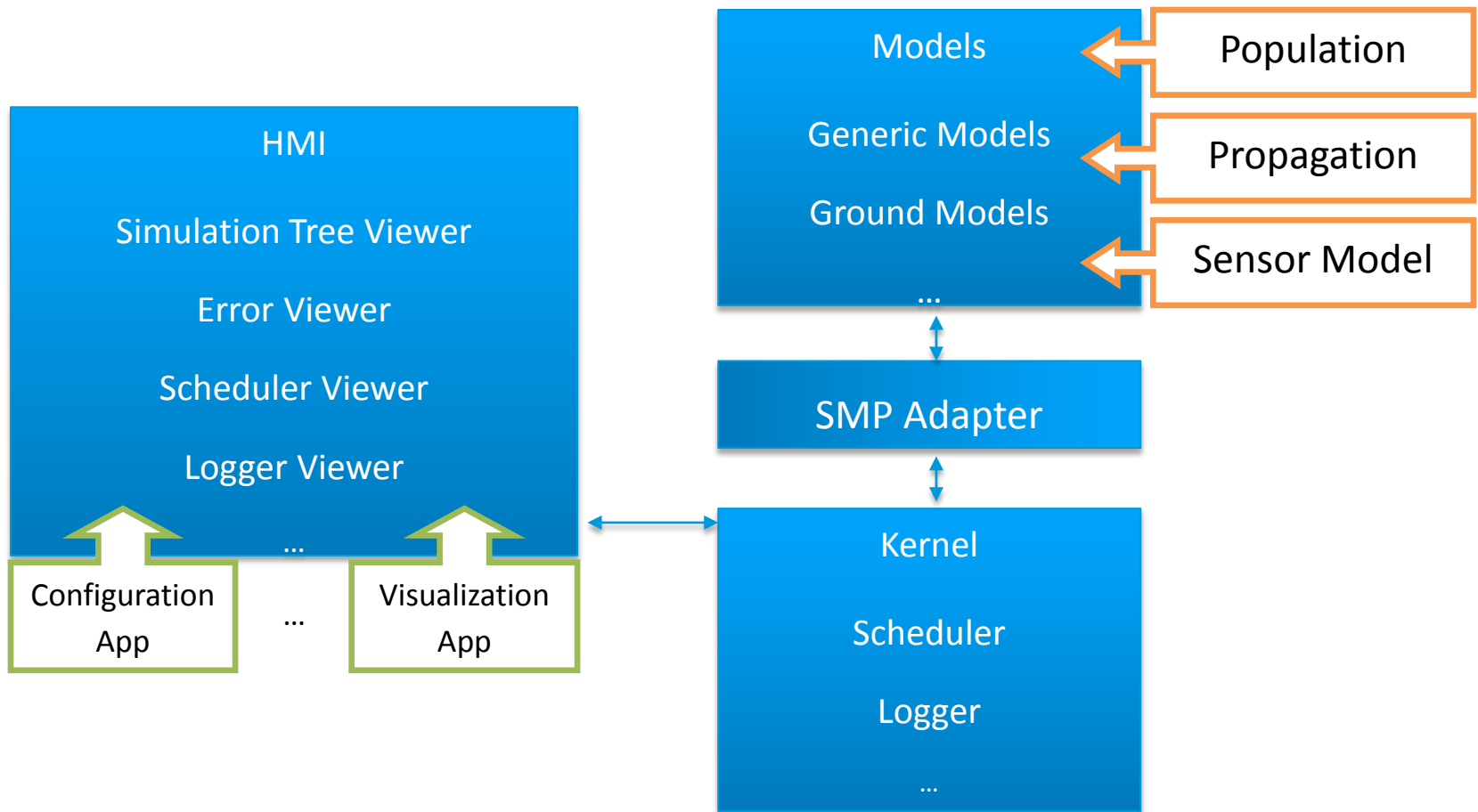
SSIM
Conclusions

SSIM System Context



SIMULUS

SSIM's Conceptual Extension of SIMSAT



Population model

This includes all functionalities related to the catalogues: creation of a catalogue, providing an object of the catalogue, and applying an event or a filter on the catalogue.

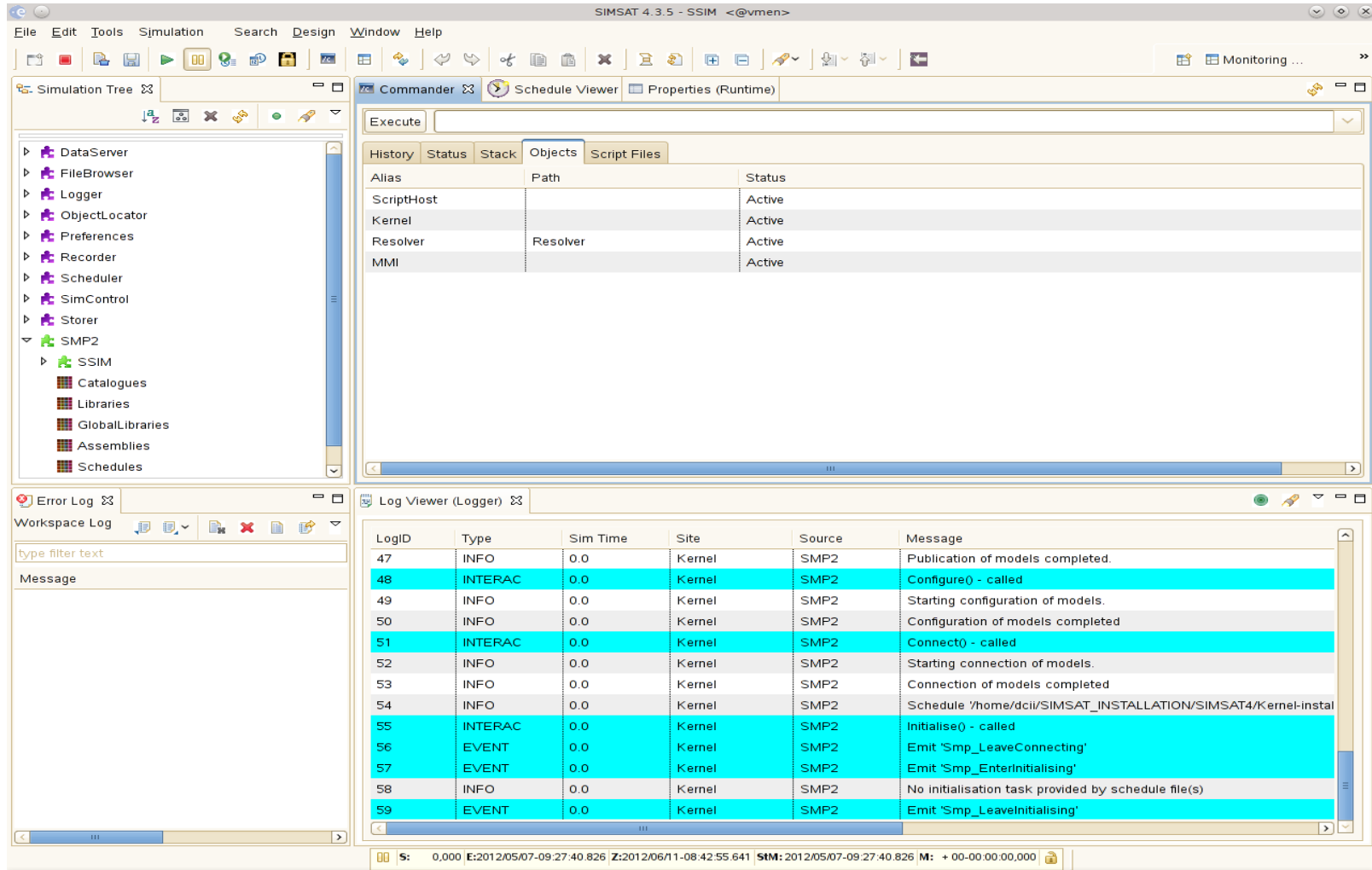
Propagation orbit model

This is composed of the functionalities necessary to provide an orbit at requested time.

Sensor model

This includes all functionalities required to both determine whether or not an object is observed/detected by a sensor, and to generate the corresponding tracklet for the observation.





The screenshot displays the SIMSAT 4.3.5 - SSIM runtime interface. The main window is titled "SIMSAT 4.3.5 - SSIM <@vmen>" and features a menu bar (File, Edit, Tools, Simulation, Search, Design, Window, Help) and a toolbar. The interface is divided into several panes:

- Simulation Tree:** A hierarchical tree view on the left showing components like DataServer, FileBrowser, Logger, ObjectLocator, Preferences, Recorder, Scheduler, SimControl, Storer, and SMP2 (containing SSIM, Catalogues, Libraries, GlobalLibraries, Assemblies, and Schedules).
- Commander:** A central pane with tabs for Execute, History, Status, Stack, Objects, and Script Files. The "Objects" tab is active, displaying a table of active objects.
- Log Viewer (Logger):** A pane at the bottom right showing a log of events with columns for LogID, Type, Sim Time, Site, Source, and Message.
- Workspace Log:** A pane at the bottom left for filtering and viewing messages.
- Status Bar:** A bar at the very bottom showing simulation time and other metrics.

The "Objects" table in the Commander pane shows the following data:

Alias	Path	Status
ScriptHost		Active
Kernel		Active
Resolver	Resolver	Active
MMI		Active

The "Log Viewer (Logger)" pane displays the following log entries:

LogID	Type	Sim Time	Site	Source	Message
47	INFO	0.0	Kernel	SMP2	Publication of models completed.
48	INTERAC	0.0	Kernel	SMP2	Configure() - called
49	INFO	0.0	Kernel	SMP2	Starting configuration of models.
50	INFO	0.0	Kernel	SMP2	Configuration of models completed
51	INTERAC	0.0	Kernel	SMP2	Connect() - called
52	INFO	0.0	Kernel	SMP2	Starting connection of models.
53	INFO	0.0	Kernel	SMP2	Connection of models completed
54	INFO	0.0	Kernel	SMP2	Schedule /home/dcii/SIMSAT_INSTALLATION/SIMSAT4/Kernel-instal
55	INTERAC	0.0	Kernel	SMP2	Initialise() - called
56	EVENT	0.0	Kernel	SMP2	Emit 'Smp_LeaveConnecting'
57	EVENT	0.0	Kernel	SMP2	Emit 'Smp_EnterInitialising'
58	INFO	0.0	Kernel	SMP2	No initialisation task provided by schedule file(s)
59	EVENT	0.0	Kernel	SMP2	Emit 'Smp_LeaveInitialising'

The status bar at the bottom shows: S: 0,000 E:2012/05/07-09:27:40.826 Z:2012/06/11-08:42:55.641 SIM: 2012/05/07-09:27:40.826 M: + 00:00:00.00,000

HMI - Visualization



The screenshot displays the SIMSAT 4.3.5 software interface. The main window has a menu bar (File, Edit, Search, Design, Window, Help) and a toolbar. The interface is divided into several panels:

- Status Viewer:** A table with columns: Simulator Name, Mode, Simulation Time, Epoch Time, Zulu Time, Start Mission Time, Mission Time, Locked Status, Scheduler Priority, Simulation Priority, and Speed. The table is currently empty.
- Observation Data:** A panel with a "Tracklets" section listing Tracklet A, Tracklet B, and Tracklet Z.
- Configuration:** A panel with the following data:
 - Tracklet Generations with Timeout: 5
 - Objects in Catalogue: 27Below this is a tabbed interface with four tabs: "Received Observation Requests" (selected), "Active Tracklet Generations", "Completed Tracklet Generations", and "Completed Observation Confirmations". The content area below the tabs is empty.
- Log Viewer:** A panel with a table header: LogID, Type, Sim Time, Site, Source, and Message. The table is currently empty.

At the bottom of the window, a status bar displays the following information: S: 0.000 E:0000/00/00-00-00:00.000 Z:0000/00/00-00-00:00.000 SIM: 0000/00/00-00-00:00.000 M: + 00-00:00:00.000

HMI - Configuration

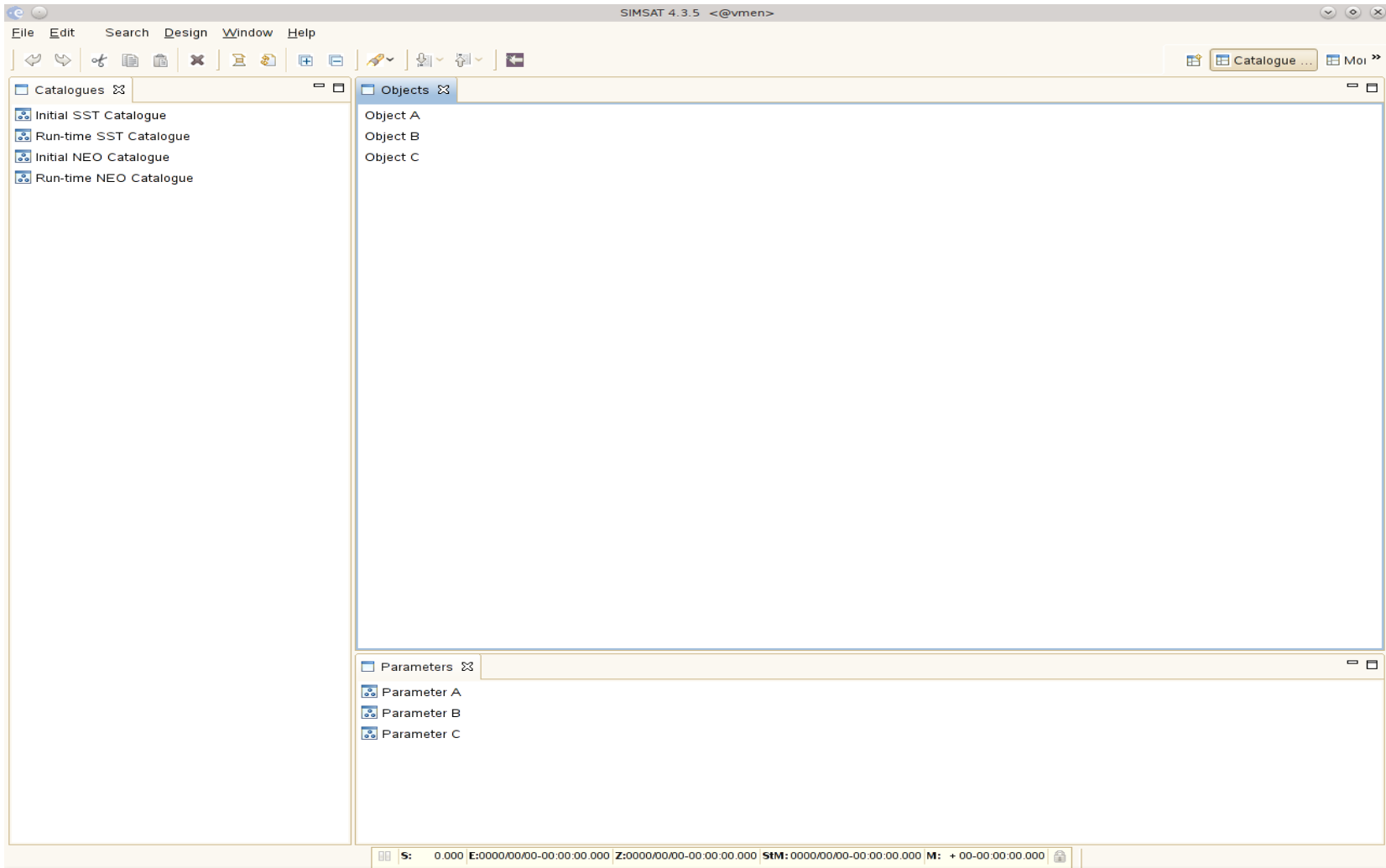


The screenshot shows the SIMSAT 4.3.5 application window. The main area displays the XML configuration for 'Sensor3.xml'. The configuration is structured as follows:

```
version="1.0" encoding="UTF-8"
tns:SensorConfigurationType2
  xmlns:tns http://esa.ssa.sst/test/SensorConfigurationType
  xmlns:xsi http://www.w3.org/2001/XMLSchema-instance
  tns:name Sensor3
  tns:author Shankar
  tns:data
    tns:type invalid
    tns:time 2001-12-31T12:00:00
```

The left sidebar shows a tree view of configurations under 'Sensor_Config', including 'Sensor3' and 'Sensor1'. The status bar at the bottom indicates the current configuration path: 'tns:SensorConfigurationType2/tns:data'.

HMI - Catalogue



SIMSAT 4.3.5 - SSIM <@vmen>

File Edit Search Design Window Help

Monitoring ...

Status Viewer

Simulator Name	Mode	Simulation Time	Epoch Time	Zulu Time	Start Mission Time	Mission Time	Locked Status	Scheduler Priority	Simulation Priority	Speed
SSIM	RUN	70.440	2012/05/07-09:2	2012/06/29-07:3	2012/05/07-09:27:40.8	+ 00-00:01:10.44C	Unlocked	Normal	Normal	1.0

Simulation Scenario

- Scenario A
- Scenario B
- Scenario C
- Scenario D

Observation Data Log Viewer (Logger)

Received Observation Requests Completed Observation Confirmations

Select Time Range 2012-05-02 01:05:11.000 2012-06-29 09:37:46.308 Apply

Number of Observation Requests: 15

Id	Reception Date	Sensor Type	Sensor ID	Start Date	End Date	Pointing P
1	2000-01-01 12:00:00.001	NEO	Sensor1	2000-01-01 12:00:00.001	2000-01-01 12:00:00.000	[3.14159,
2	2000-01-01 12:00:00.001	SST	Sensor2	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
3	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
4	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
5	2000-01-01 12:00:00.001	NEO	Sensor1	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
6	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
7	2000-01-01 12:00:00.001	SST	Sensor2	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
8	2000-01-01 12:00:00.001	NEO	Sensor1	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
9	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
10	2000-01-01 12:00:00.001	SST	Sensor2	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
11	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
12	2000-01-01 12:00:00.001	NEO	Sensor1	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
13	2000-01-01 12:00:00.001	NEO	Sensor1	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
14	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,
15	2000-01-01 12:00:00.001	NEO	Sensor10	2000-01-01 12:00:00.001	2000-01-01 12:00:00.001	[3.14159,

S: 70.440 E:2012/05/07-09:28:51.266 Z:2012/06/29-07:38:53.437 SIM: 2012/05/07-09:27:40.826 M: + 00-00:01:10.440



That's it!

Federation

Interoperability

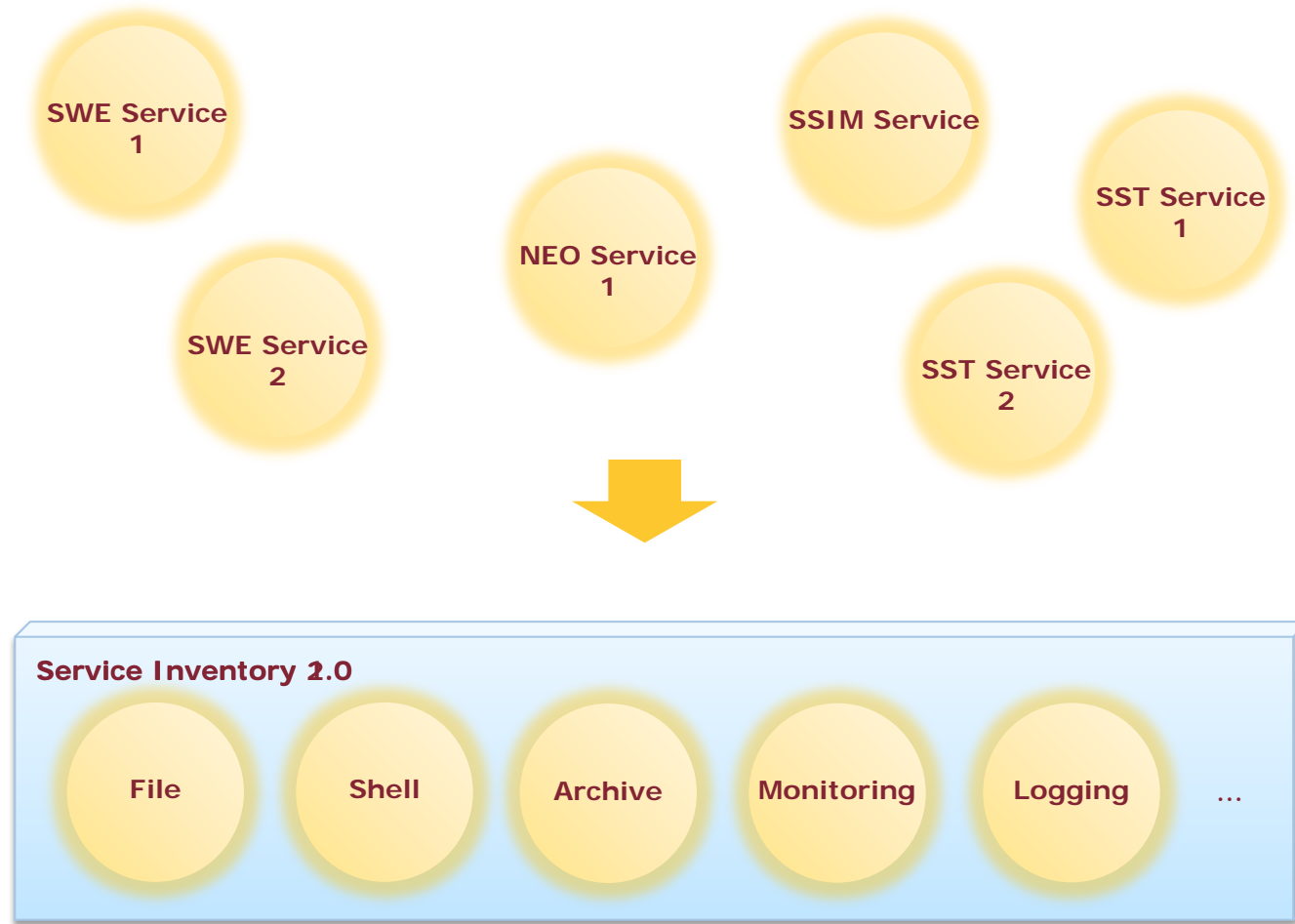


Business Technology
Alignment

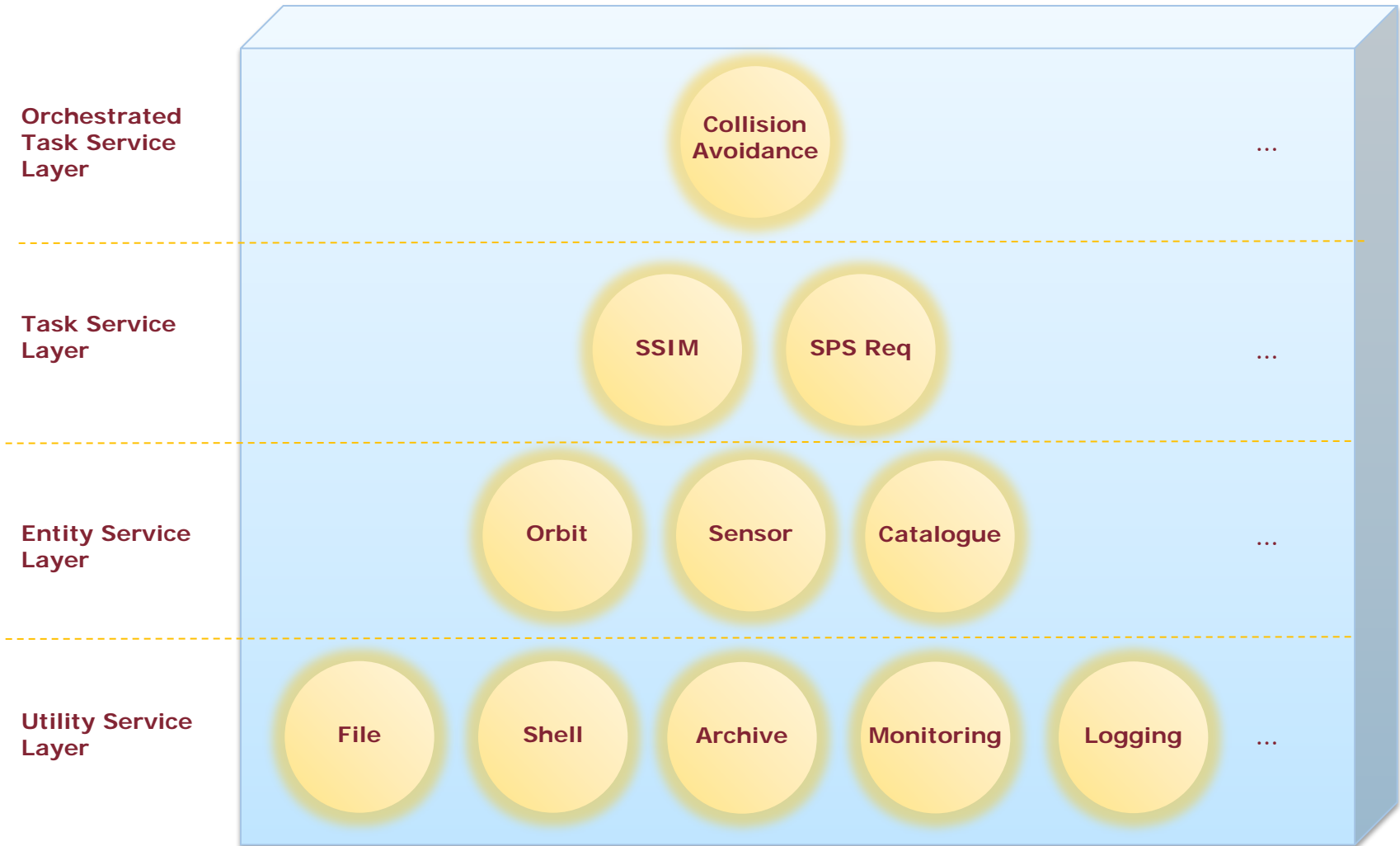
Organisational
Agility

and others ...

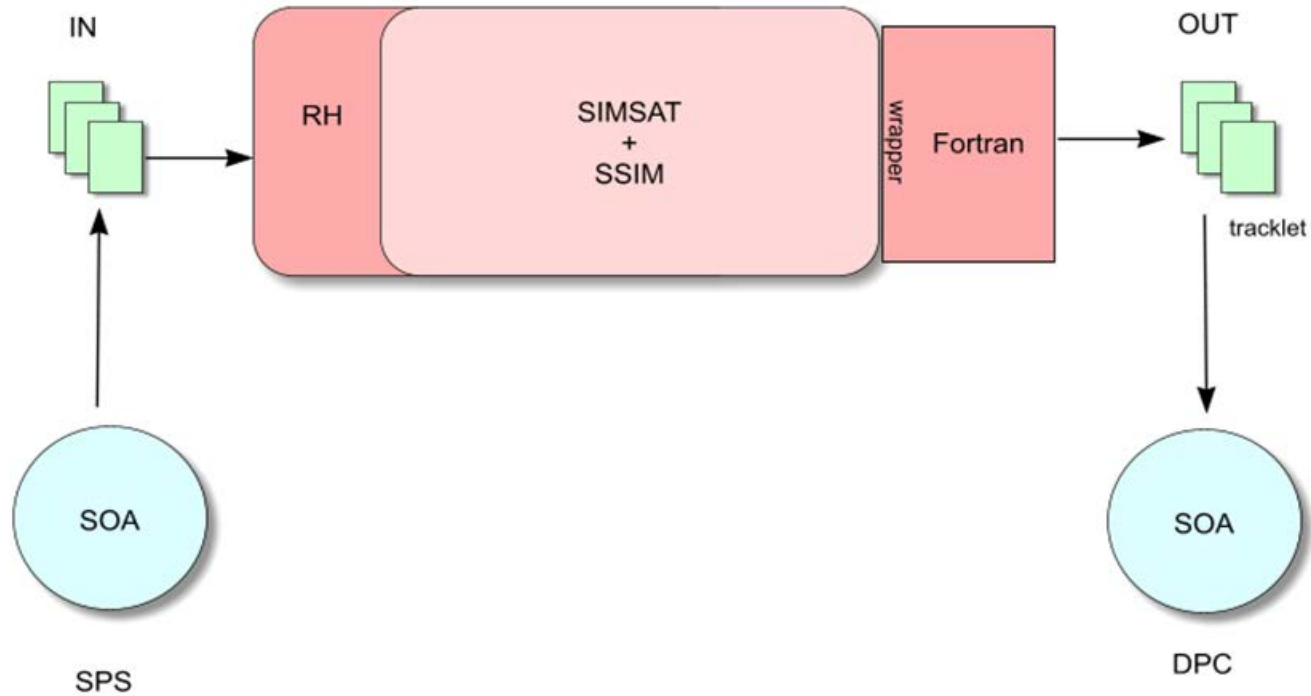
Our SOA Approach



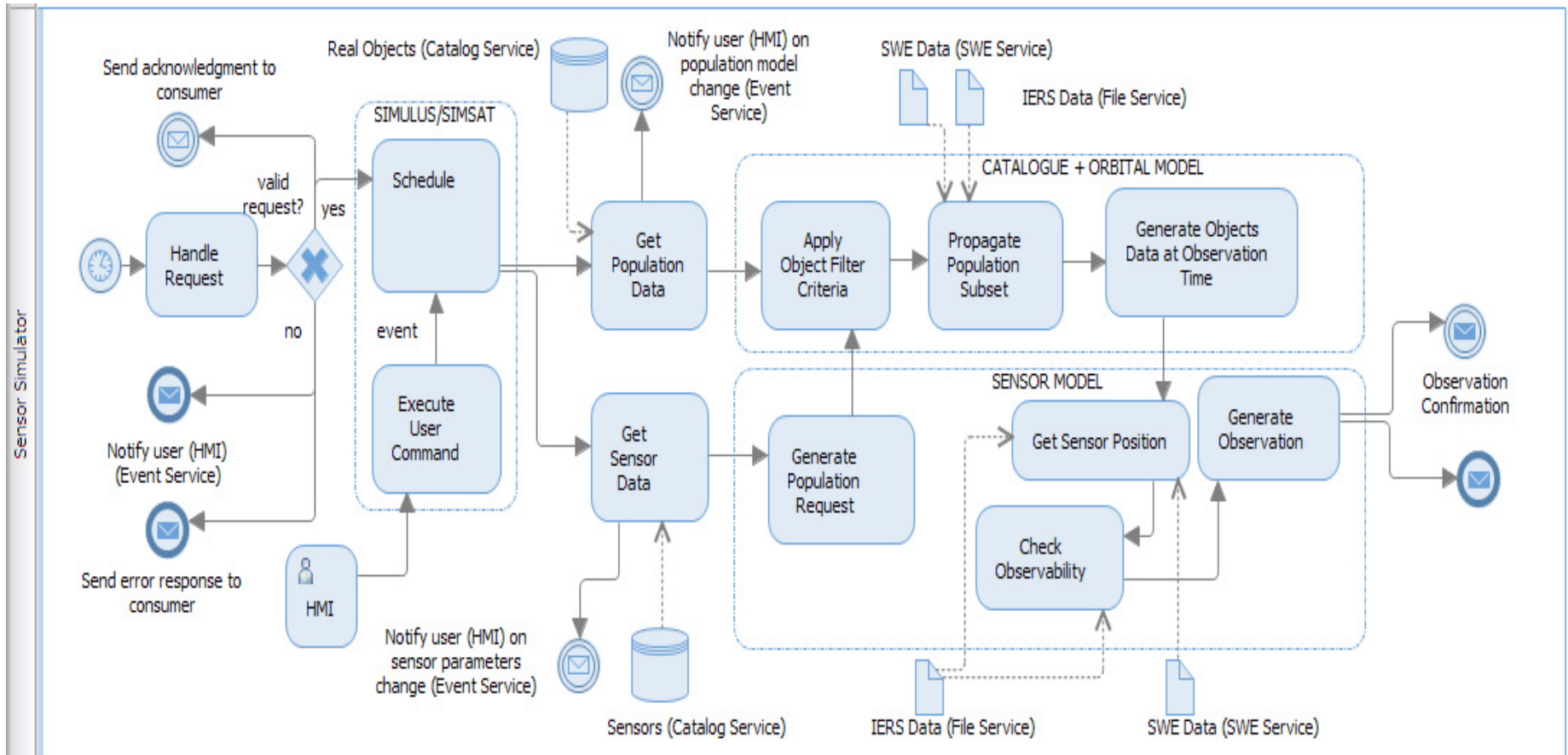
Target SSA Service Enterprise Model



Integration Design Patterns



SSIM High Level Business Process



SSA
Concept

SSIM
Concept

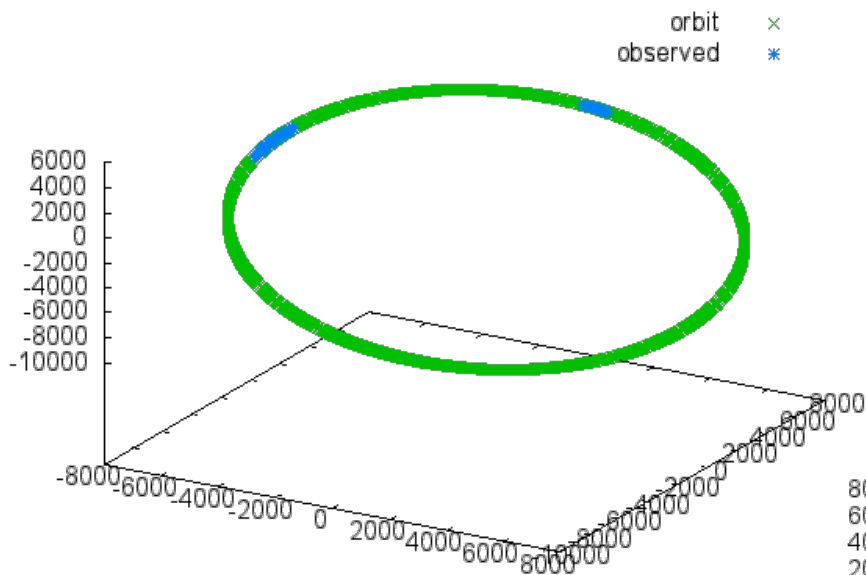
SSIM
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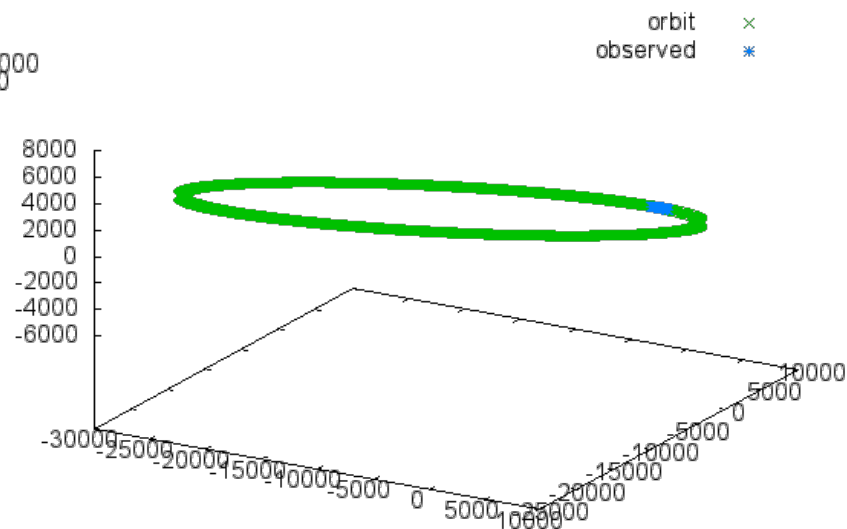
SSIM
Conclusions

Preliminary Results: SSIM Surveillance Radar Model

Position of LEO object



Position of GTO object



SSA
Concept

SSIM
Concept

SSIM
Architecture

SSIM
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SSIM
Conclusions

Coming soon



Autumn 2012

- *Integration of SOA*



Early 2013

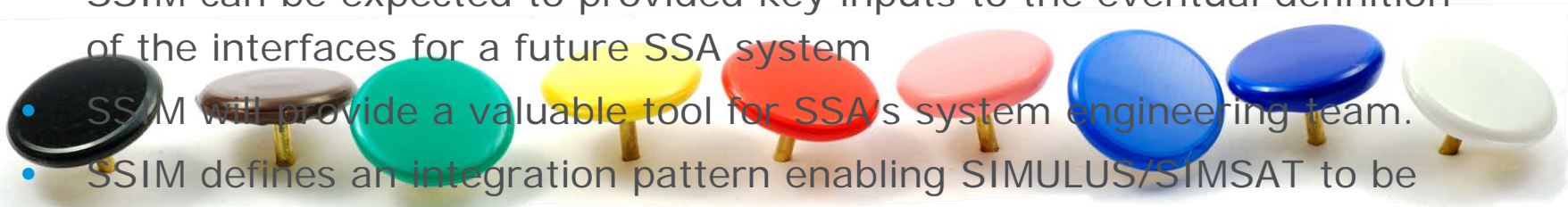
- Overall Performance assessment



Mid 2013

- Maintenance and evolution

- SSIM used SIMULUS as starting point, reducing the risk and effort associated to the implementation compared to a development from scratch.
- SSIM can be expected to provide key inputs to the eventual definition of the interfaces for a future SSA system
- SSIM will provide a valuable tool for SSA's system engineering team.
- SSIM defines an integration pattern enabling SIMULUS/SIMSAT to be integrated as part of a SOA solution based on COSIF.
- SSIM has successfully integrated models currently in the form of Fortran libraries in SIMSAT as SMP2 models.



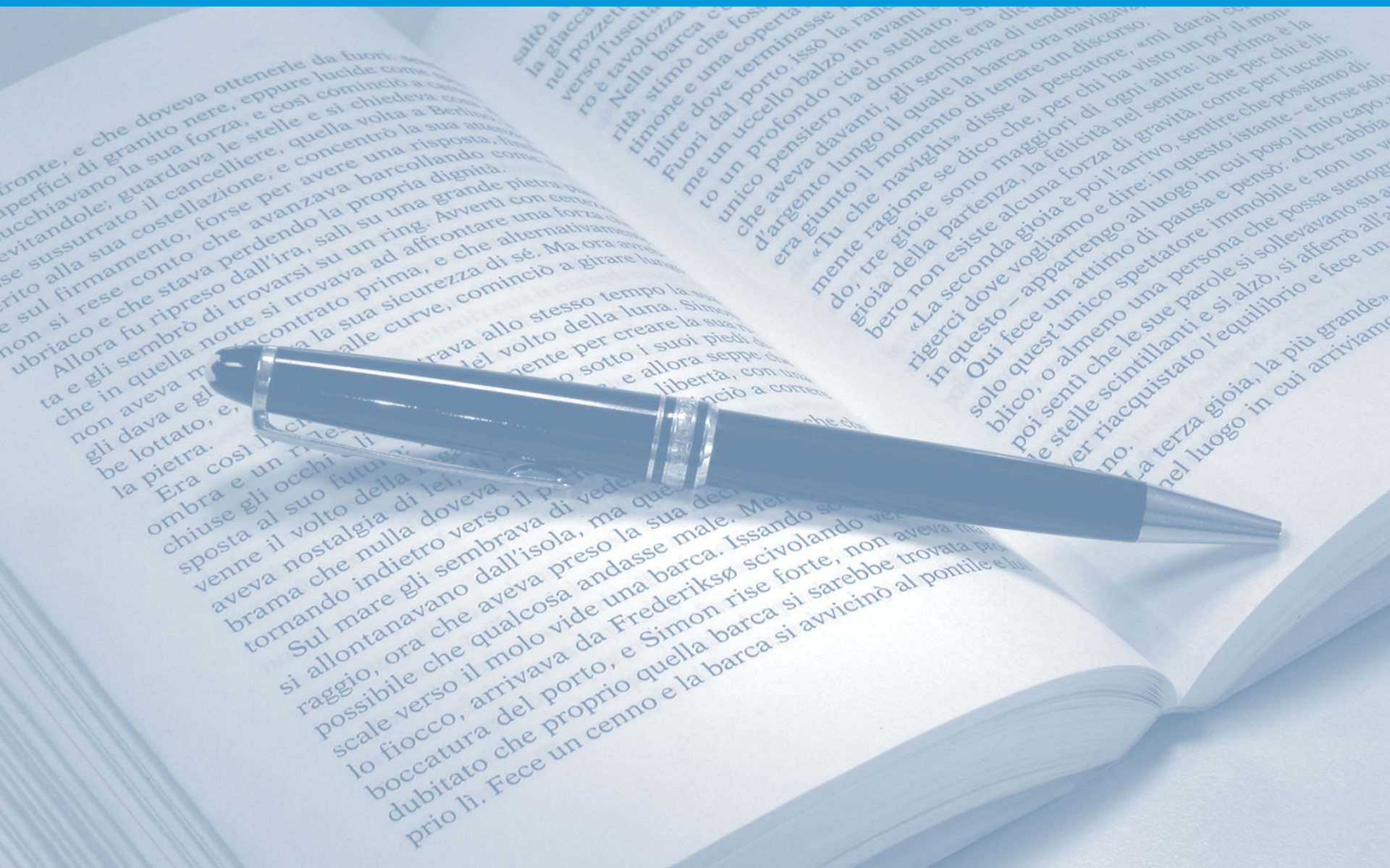


THANK YOU!

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Backups



- Support model portability
- Promote the reuse of simulation models between:
 - different project phases
 - different projects
 - different simulation platforms
- Improve model integration support – code generation
- Support integration of system engineering data
- Support for modern software technologies
- Support of dynamic simulations
- Make use of open standards
- Decrease sensitivity to platform change

UMF - platform:/resource/umf/Sawtooth.umiclass#_eZ8qADIOEd6jJdIdACwEwA - Eclipse Platform

File Edit Diagram Navigate Search Project MagicDraw Run Window Help

Sans 9 B I A

100%

Navigator Containment Tree

- umf
 - gen
 - cat
 - Catalogue
 - Catalogue.cat
 - smpcat.cat
 - STR_model.cat
 - UMFCatalogue.uml
 - xmi
 - Sawtooth.xmi
 - UMFCatalogue.xmi
 - sampleFolder
 - Sample.uml
 - CatalogueGenerationExample.mdxml
 - Sawtooth.uml
 - Sawtooth.umiclass
 - Sawtooth.umicomp
 - SawtoothSampler.cat
 - SawtoothService.cat
 - UMFCatalogue.uml
 - UMFCatalogue.umiclass
 - UMFCatalogue.umicomp

Package Service

```

classDiagram
    class SampleSuperClass {
        <<SMP2class>>
        attributes
        operations
        classes
    }
    class SampleClass1 {
        <<SMP2class>>
        attributes
        value : int
        operations
        getValue() : int
        classes
    }
    class SampleClass2 {
        <<SMP2ignore>>
        attributes
        operations
        classes
    }
    class Model {
        <<SMP2model>>
        Model
        attributes
        value : float
        operations
        getValue() : Integer
        classes
    }
    class ISawtooth2 {
        <<interface>>
        ISawtooth2
        attributes
        SAW : String
        operations
        getSaw() : String
        classes
    }
    SampleSuperClass <|-- SampleClass1
    SampleSuperClass <|-- SampleClass2
    Model ..> ISawtooth2 : ISawtooth
    
```

Palette

- Enumeration
- DataType
- PrimitiveType
- Constraint
- Association Class
- Interface
- Attribute
- Operation
- Enum Literal
- Port
- Template Signature
- Element Import
- Association
- Dependency
- Generalization
- Provided Interface
- Required Interface

Problems Console Error Log Properties

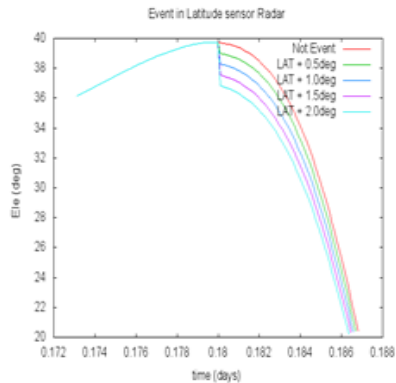
<Operation> getValue () : Int

Core	Property	Value
	UML	
	Body Condition	
	Client Dependency	
	Concurrency	Sequential
	Is Abstract	false
	Is Leaf	false
	Is Ordered	false
	Is Query	false
	Is Static	false
	Is Unique	true
	Lower	1

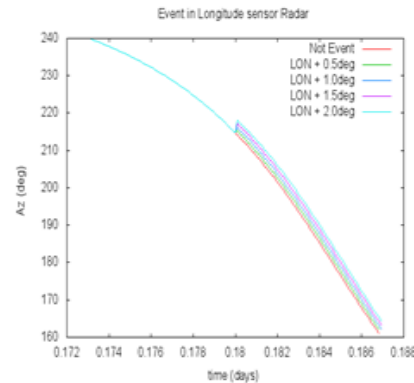
Documentation Properties

MagicDraw integration is not started.

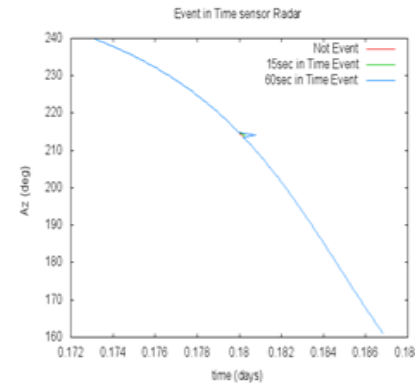
Surveillance Radar Simulation Events



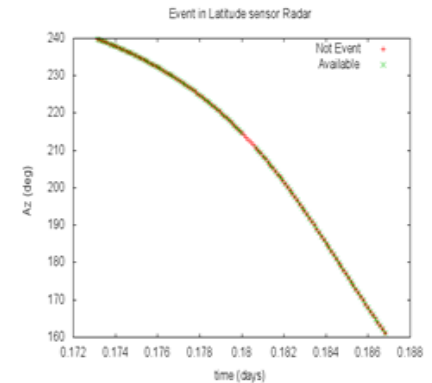
Change of the latitude of the radar.



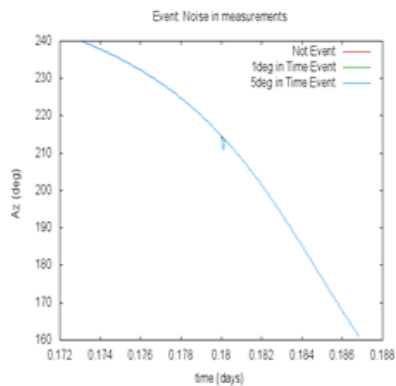
Change of the longitude of the radar.



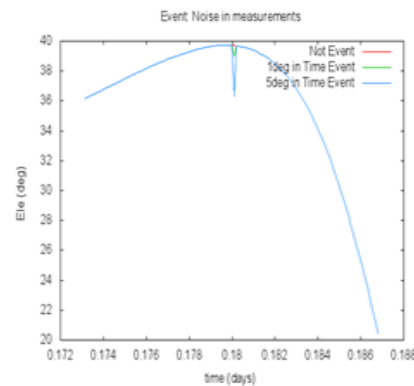
A delay in the time of the observation.



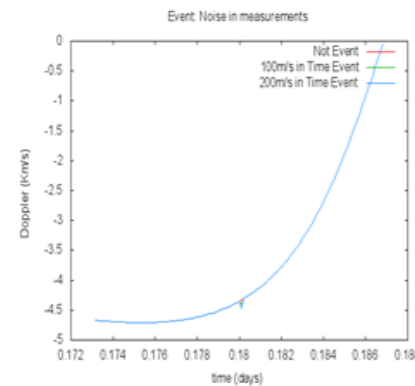
Non-availability of the sensor during a time interval.



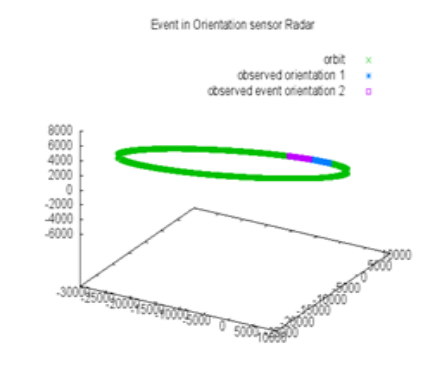
Additional noise in the detected azimuth.



Additional noise in the detected elevation.



Additional noise in the detected Doppler.

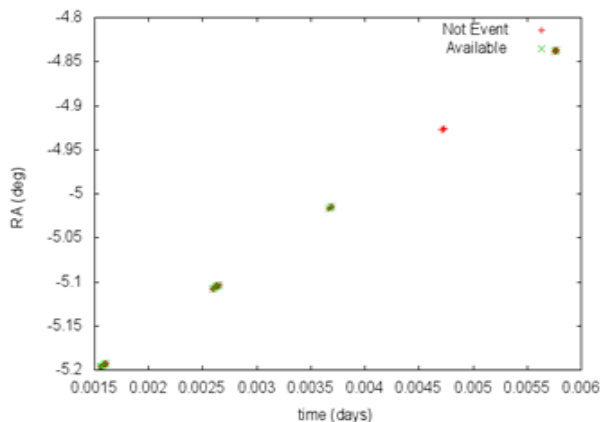


Change in the surveillance radar orientation.

Surveillance Optical G-B Simulation Events

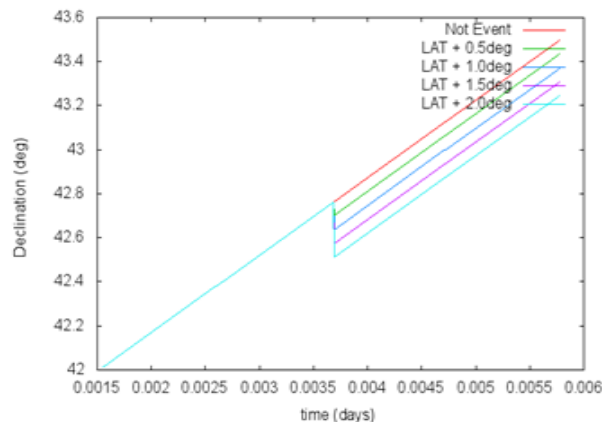


Event in Latitude sensor GBtel



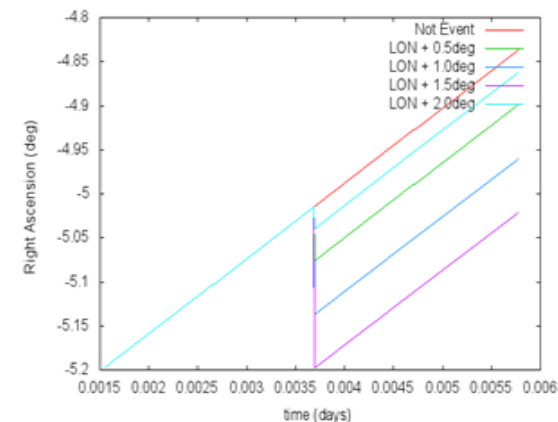
Non-availability of the sensor

Event in Latitude sensor GBtel



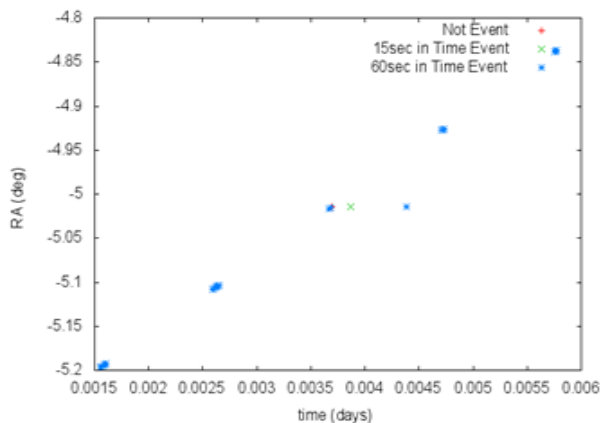
Change in latitude of the sensor

Event in Longitude sensor GBtel



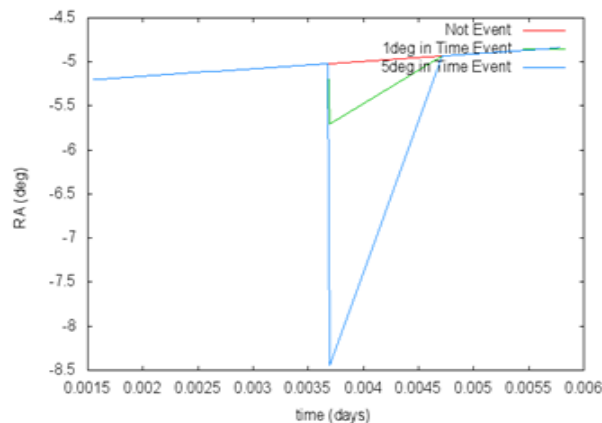
Change in longitude of the sensor

Event in Time sensor GBtel



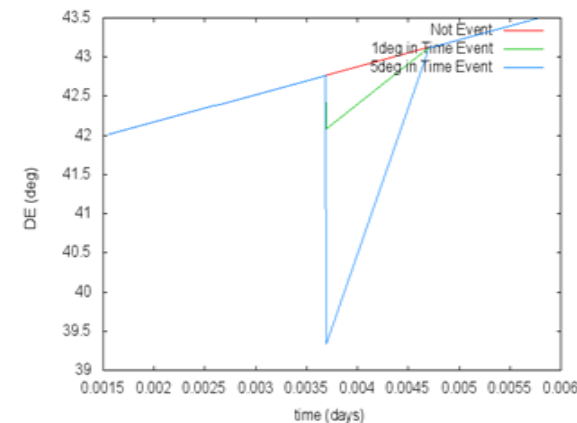
Delay in tracklet generation

Event Noise in measurements



Noise in Right ascension

Event Noise in measurements



Noise in Declination